

Algorithm Selection Strategies for Short-Range Particle Simulations

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A Heated Sphere





A Heated Sphere





To simulate this efficiently, we need a:

• Neighbour Identification Algorithm/Particle Container. E.g.



Linked Cells

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Images from Newcome et al., 2023



To simulate this efficiently, we need a:

- Neighbour Identification Algorithm/Particle Container.
- Shared Memory Traversal e.g. cell colouring schemes



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C08 Image from Newcome et al., 2023 C04 and C04_HCP Images are from Tchipev, 2020



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- Neighbour Identification Algorithm/Particle Container.
- Shared Memory Traversal.
- Data Layout e.g. Array-of-Structures or Structure-of-Array



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We also have various parameters to tune:

- Size of Cells
- Verlet Skin size





A thin slice of molecules is placed at the centre of a long domain split into 6 MPI ranks.





It explodes outwards, leaving behind small clusters of molecules.





There are different computational profiles in each region, leading to different best algorithms that change over the course of the simulation





It explodes outwards, leaving behind small clusters of molecules.



Rayleigh-Taylor Instability



- Simulation starts with "blue" molecules of higher mass and density and smaller size above the "red" molecules.
- 40 MPI ranks are used with MPI load balancing.



Rayleigh-Taylor Instability



• The optimal algorithmic configuration is different depending on the mixture of red/blue particles and empty space, and therefore also changes over time and in different regions.



No "Silver Bullet"



=> There is no best algorithmic configuration

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* This configuration timed out. Expected 1-2 order of magnitude worse than best.

** This experiment is still running, but currently expected ~1 order of magnitude worse than best.



AutoPas: A Rank-Level Algorithm Selection Library

- General **black-box** short-range particle simulation library.
- Users can build their simulator by providing a particle class and an interaction functor class. They don't need to choose an optimal algorithm.
- 100+ configurations & growing
 - Neighbour Identification Algorithms
 - Shared Memory Parallel Traversals
 - Data Layouts
 - Tunable Parameters e.g. cell-size factor



AutoPas & Distributed Memory



- AutoPas is rank-level
- Each rank get its own AutoPas container and can make its own choices.



Algorithm Selection

- AutoPas periodically makes algorithm selection choices every number of timesteps. We call the selection process a *tuning phase*.
- By default, in each tuning phase, each algorithm is trialled for a few iterations.
- The best is used until the next tuning phase.
- Best = Fastest Time or Least Energy Consumed
- No accuracy difference between algorithms => timesteps spent trialling can still advance the simulation.



Algorithm Selection

As previously seen, the worst algorithms can be orders of magnitude worse.

=> We need methods to avoid trialling bad algorithms.



Algorithm Selection Strategies

















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Pros:

- Easy to use (requires no user input or training).
- => Generalises easily to any arbitrary user simulator.

Cons:

- Predictions can be very unsuitable.
- Requires some naive full searches.



Expert-Knowledge Fuzzy Logic Tuning

- Take "information" from simulation: E.g.
 - Mean number of particles per cell
 - \circ Median
 - Standard Deviation
- An expert develops (fuzzy logic) rules to describe how suitable a method is depending on this information.
- If a method passes a suitability threshold, it will be trialled.



Expert-Knowledge Fuzzy Logic Tuning

Pros:

- Highly performant with suitable rules.
- Use of fuzzy logic helps realise "fuzzy" understandings of relationships between statistics and algorithm performance.

Cons:

- Relative algorithm performance varies between interaction models and hardware => A universal set of rules is not feasible
- Relationship between statistics and best algorithm is highly complex => Requires a lot of human-effort even with same model and hardware.
- => Develop rules that are targeted towards the type of simulations being run.



Random Forest Tuning

- Train a Random Forest model that predicts optimal algorithm from statistics.
- Random Forest to deal with overfitting of Decision Trees.
- Provides single supposedly optimal configuration.
- Implemented through C/Python API to aid in extensibility.
- Trained on "fake" simulations generated with (random) statistical distributions that are easy to obtain.



Results



Results







- Expert-Knowledge Fuzzy Logic best.
- Not necessarily any better than picking a single best configuration.
- Random Forests not far behind, and generally more user-friendly.
- Predictive Tuning is the worst.



Conclusion & Future Work

- We have a portfolio of tuning strategies to serve a range of different effort levels of users.
- But overall, these results suggest a ML-driven approach for future development would be best:
 - Much less effort than expert-knowledge
 - Not much worse performance.
 - No reason why similar or better performance could be achieved with more development or data.
- Coming up with suitable training data depends on use case => Online Learning?