

# A new aerosol profile retrieval algorithm for high-altitude MAX-DOAS measurements and the application to the long-term observation on Zugspitze, Germany

Zhuoru Wang

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1. Priv.-Doz. Dr.-Ing. habil. Adrian Doicu
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## Abstract

In this thesis, a new parametrization multi-axis differential optical absorption spectroscopy (MAX-DOAS) aerosol profile retrieval algorithm was developed to analyze the long-term time series measured by the MAX-DOAS instrument at the Environmental Research Station Schneefernerhaus (UFS), located near Zugspitze. The measurement site is located at an altitude of 2,650 m. As there are no significant emissions at this altitude, it is usually referred as background site.

A cloud screening method was developed to filter out cloudy measurements. This cloud screening method uses the intensity ratio between two wavelength points, also referred as the color index (CI), measured at the zenith direction to determine if the sky is blue (clear) or white (cloudy). The threshold of CI to identify cloudy skies is a function of solar zenith angle and was approximated from the long-term statistic of calibrated CIs. Details of the cloud screening method are presented in Chapter 4. This cloud screening method was applied to the entire measurement period from Feb 2012 to Feb 2016.

As conventional optimal estimation algorithms are not suitable to be applied to high altitude measurements due to the poor signal to noise ratio of the differential slant column densities (DSCDs) of  $O_4$ , a new parametrization MAX-DOAS aerosol profile retrieval algorithm dedicated for high altitude measurements was developed and the detail is presented in Chapter 5. The sensitivity of  $O_4$  absorption to several parameters was first investigated. Aerosol profiles were parametrized as the aerosol extinction coefficients of three layers. We defined a profiles set which is assumed to include all possible aerosol profiles under cloud-free conditions. DSCDs of  $O_4$  at 360 and 477 nm were simulated with all the profiles in the profile set and all possible viewing geometries. The simulated data were stored in a look-up table (LUT), which was used as the forward model. In the retrieval of each measurement cycle, simulated  $O_4$  DSCDs corresponding to all the possible profiles were obtained from the LUT. The cost function ( $\chi^2$ ) of each possible profile was then calculated according to the simulated and measured  $O_4$  DSCDs as well as the measurement uncertainties. We performed a comprehensive error analysis to estimate the total uncertainty, in which seven error sources were considered. Valid profiles were selected according to the cost functions. The optimal solution was defined as the weighted mean of all the

valid profiles. Based on the assumption that the LUT covers all possible profiles, we determined  $O_4$  DSCD scaling factors for different elevations and wavelengths. The retrieval algorithm was applied to synthetic measurement data, and the retrieved profiles can reproduce the true profiles. In addition, the retrieval is insensitive to measurement noise. The aerosol optical densities (AODs) retrieved from the long-term measurements correlates well with the sun photometer measurements at the UFS, with correlation coefficients ( $R$ ) of 0.733 and 0.798 for measurements at 360 and 477 nm, respectively. However, especially in summer the sun photometer AODs are systematically higher than the MAX-DOAS results by a factor of  $\sim 2$ . The MAX-DOAS measurements indicate the aerosol extinction decreases with increasing altitude during all seasons, which agrees with the co-located ceilometer measurements. The results show maximum AOD and maximum Ångström exponent in summer, which is consistent with the observations at an Aerosol Robotic Network (AERONET) station near the UFS.

The zenith measurements during twilight periods were used to determine the total vertical column densities (VCDs) of  $O_3$  and  $NO_2$ . Details of the retrieval and total column results can be found in Chapter 6. The air mass factors (AMFs) of  $O_3$  and  $NO_2$  were obtained from LUTs developed at the Belgian Institute for Space Aeronomy (BIRA-IASB). Langley plots (DSCDs versus AMFs) of  $O_3$  and  $NO_2$  were applied to the long-term measurements. For most measurements, the AMFs of  $O_3$  are highly correlated with the DSCDs; while for  $NO_2$ , the correlation is on average weaker. For both  $O_3$  and  $NO_2$ , the SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from individual Langley plots vary in large ranges. The values of  $\langle S_{\text{ref}} \rangle$  were determined from the long-term results using Gaussian fits. The VCDs of  $O_3$  and  $NO_2$  were then calculated by directly dividing the SCDs (derived by adding  $\langle S_{\text{ref}} \rangle$  to the twilight DSCDs) by the AMFs. The long-term VCDs of  $O_3$  and  $NO_2$  derived by both Langley plots and direct dividing were compared to satellite measurements. The comparisons show that the VCDs of  $O_3$  measured by MAX-DOAS in both mornings and evenings agree well with the satellite results, and the results calculated using direct dividing agree with the satellite data better than the results derived by Langley plots. For the comparison of  $NO_2$ , the agreement is weaker than  $O_3$ , regardless of the calculation method. The long-term measurements show that the VCD of  $O_3$  is highest in spring and lowest in autumn, while the VCD of  $NO_2$  is highest in summer and lowest in winter. The VCD of  $NO_2$  has a much larger yearly amplitude than that of  $O_3$ .

## Zusammenfassung

Im Rahmen dieser Arbeit wurde ein Algorithmus zur Parametrisierung von Aerosol Profilen bei Multi-axis Differential Optical Absorption Spectroscopy (MAX-DOAS) Messungen entwickelt und erfolgreich auf die Zeitreihe der MAX-DOAS Messungen an der Umweltforschungsstation Schneefernerhaus (UFS) nahe der Zugspitze angewendet. Die Station liegt auf 2.650 m Höhe und ist eine Hintergrundstation die normalerweise von unverschmutzter Luft angeströmt wird.

Um wolkenfreie Messungen zu suchen, wurde ein Wolken-Screening-Verfahren entwickelt. Dieses verwendet das Intensitätsverhältnis zwischen zwei Wellenlängen, auch bekannt als Farbindex (CI), der Zenitmessungen. Daran erkennt man, ob der Himmel blau (wolkenlos) ist oder weiß (bedeckt). Wir haben CI-Schwellenwerte für das Wolken-Screening für verschiedene Sonnenzenitwinkel (SZAs) gemäß der langfristigen Häufigkeitsverteilung der kalibrierten CIs bestimmt. Einzelheiten zum Wolken-Screening-Verfahren werden in Kapitel 4 vorgestellt. Dieses Wolken-Screening-Verfahren wurde erfolgreich auf den gesamten Messzeitraum von Februar 2012 bis Februar 2016 angewendet.

In Kapitel 5 stellen wir unseren Algorithmus zur Bestimmung von Aerosolprofilen vor. Wir haben erkannt, dass die bekannten Algorithmen, die auf der optimalen Schätzmethode basieren, nicht für Höhenmessungen geeignet sind. Daher haben wir einen neuen Algorithmus entwickelt, der auf einem Parametrisierungsansatz basiert. Zunächst wurde mittels synthetischer Messdaten die Empfindlichkeit der  $O_4$ -Absorption gegenüber unterschiedlichen Parametern untersucht. Aerosolprofile wurden als Aerosol-Extinktionskoeffizienten von drei Höhenschichten parametrisiert. Wir nehmen an, dass der von uns definierte Profilsatz alle notwendigen Aerosolprofile enthält, die die realen Bedingungen unter wolkenfreiem Himmel beschreiben. Die differentiellen schrägen Säulendichten (DSCDs) von  $O_4$  bei 360 und 477 nm wurden mit dem kompletten Profilsatz und allen real auftretenden Betrachtungsgeometrien simuliert. Die simulierten Daten wurden in einer Nachschlagetabelle (LUT) gespeichert. Diese wurde anschließend als Vorwärtsmodell verwendet. Für jeden Messzyklus wurden die simulierte  $O_4$ -DSCDs für diese Beobachtungsgeometrie und alle Profile aus der Tabelle abgerufen. Unser Algorithmus bestimmt eine Kostenfunktion ( $\chi^2$ ) für jedes Profil gemäß den simulierten und gemessenen  $O_4$ -DSCDs sowie den Messunsicherheiten.

Zur Abschätzung der Gesamtunsicherheit haben wir eine umfassende Fehleranalyse durchgeführt, bei der wir sieben Hauptfehlerquellen berücksichtigt haben. Gültige Profile wurden gemäß den Kostenfunktionen mittels Schwellwerten ausgewählt. Die optimale Lösung berechnet sich als gewichteter Mittelwert aller gültigen Profile. Basierend auf der Annahme, dass die LUT alle realen Aerosolprofile ausreichend beschreibt, haben wir  $O_4$ -DSCD-Skalierungsfaktoren für verschiedene Beobachtungsgeometrien und Wellenlängen bestimmt. Die Anwendung des Algorithmus auf synthetische Messdaten ergab eine sehr gute Übereinstimmung mit den wahren Profilen. Die Robustheit unseres Algorithmus gegenüber Messrauschen macht ihn besonders geeignet für die Messungen in großer Höhe. Die aus den Langzeitmessungen gewonnenen aerosoloptischen Dichten (AODs) korrelierten sehr gut mit den Sonnenphotometermessungen an der UFS, mit Korrelationskoeffizienten ( $R$ ) von 0,733 und 0,798 für Messungen bei 360 bzw. 477 nm. Allerdings liegen die Sonnenphotometer-AODs gerade im Sommer mit einem Faktor  $\sim 2$  deutlich über den MAX-DOAS-Ergebnissen. Die MAX-DOAS-Messungen zeigen, dass die Aerosol-Extinktion mit zunehmender Höhe zu allen Jahreszeiten abnimmt, was mit den Messungen des UFS-Ceilometers übereinstimmt. Nach unseren Beobachtungen treten die maximale AOD und der maximalen Ångström-Exponenten im Sommer auf. Das stimmt auch mit den Beobachtungen an einer Station des Aerosol Robotic Network (AERONET) in der Nähe der UFS überein.

Abschließend präsentieren wir Messungen der totalen vertikalen Säulendichten (VCDs) von  $O_3$  und  $NO_2$  aus den Zenithbeobachtungen während der Dämmerungsperioden. Die Luftmassenfaktoren (AMFs) von  $O_3$  und  $NO_2$  wurden aus LUTs erhalten, die am Belgischen Institut für Weltraum-Aeronomie (BIRA-IASB) entwickelt wurden. Aus Langley-Korrelationen oder -Plots (DSCDs gegen AMFs) lässt sich die totale VCD bestimmen. Auf die gesamte Zeitreihe angewendet zeigen die Langley-Plots von  $O_3$ , dass die AMFs für die meisten Messungen stark mit den DSCDs korrelieren; die Korrelation für  $NO_2$  ist dabei im Durchschnitt schwächer als bei  $O_3$ . Sowohl für  $O_3$  als auch für  $NO_2$  variieren die SCDs des Referenzspektrums ( $S_{\text{ref}}$ ), die von Langley-Plots abgeleitet wurde, in großen Bereichen. Mittels Gauß-Fits haben wir aus den einzelnen Referenz SCDs einen Mittelwert  $\langle S_{\text{ref}} \rangle$  bestimmt. Dann haben wir die VCDs von  $O_3$  und  $NO_2$  berechnet, indem wir die SCDs (abgeleitet durch Addieren von  $\langle S_{\text{ref}} \rangle$  zu den Dämmerungs-DSCDs) direkt durch die AMFs dividiert haben. Für den Vergleich mit Satellitenbeobachtungen haben wir die Langley-Plots morgens und Abends sowie die Methode der direkten AMF-Division herangezogen. Zusammenfassen können wir

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dabei sagen, dass die von MAX-DOAS sowohl morgens als auch abends gemessenen VCDs von  $O_3$  gut mit den Satellitenergebnissen übereinstimmen. Die beste Übereinstimmung mit den Satellitendaten erreichten jedoch die durch direkte Division berechneten Ergebnisse. Beim Vergleich von  $NO_2$  ist die Übereinstimmung unabhängig von der Berechnungsmethode schwächer als bei  $O_3$ . Die Langzeitmessungen zeigen, dass die  $O_3$  VCD im Frühjahr am höchsten und im Herbst am niedrigsten ist. Die stratosphärische  $NO_2$  VCD ist hingegen im Sommer am höchsten und im Winter am niedrigsten ist. Die  $NO_2$  VCD hat eine viel größere Jahresamplitude als die von  $O_3$ .



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# Chapter 1

## Introduction

### 1.1 Atmospheric constituents

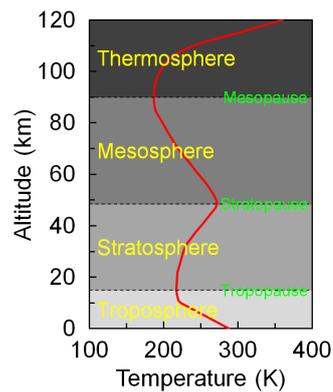


Figure 1.1: Vertical temperature profile of the atmosphere (U.S. standard atmosphere 1976).

The earth's atmosphere consists of five major layers, which are distinguished by the average temperature profile with altitude, see Figure 1.1. The lowest layer of the atmosphere is called troposphere, it extends from the earth's surface up to the tropopause. The altitude of the tropopause varies between 10 and 15 km, depending on the latitude and the season. In the troposphere, the temperature decreases with increasing altitude, and rapid vertical mixing of air therefore exists in the layer. The layer above the troposphere is the stratosphere, it extends from the tropopause up to the stratopause. The stratopause is usually located from 45 to 55 km above the earth's surface. The stratosphere is characterized by increasing temperature with altitude and relative slow vertical mixing. The third

layer is the mesosphere which extends from the stratopause up to the mesopause. The mesopause is located at  $\sim 80\text{--}90$  km above ground, and it is the coldest point of the atmosphere. The layer above the mesopause is the thermosphere. The temperature of the thermosphere is very high due to the absorption of short wavelength radiation by nitrogen ( $\text{N}_2$ ) and oxygen ( $\text{O}_2$ ). Photoionization occurs in the lower thermosphere and upper mesosphere, and the ionosphere is therefore formed. The outermost layer of the atmosphere is the exosphere where gas molecules with sufficient energy can escape from gravity. The exosphere is located between 700 and 10000 km.

### 1.1.1 Troposphere

The troposphere extends from the earth's surface to the altitude of about 8 km at the poles to 18 km at the equator. The troposphere contains  $\sim 80\%$  of the total mass of the atmosphere and  $\sim 99\%$  of the total mass of water vapor and aerosols (Levine, 1984). It is also the layer where most weather phenomena occur. In the layer, the temperature decreases with increasing altitude at a rate of 6–10 K/km, depending on the humidity (Lampel, 2014). At middle latitudes, the temperature in the troposphere decreases from an average value of  $\sim 288$  K at sea level to  $\sim 220$  K at the tropopause (Lydolph et al., 1985). Due to the temperature gradient, strong vertical convection exists in the layer.

The troposphere can be further subdivided into the planetary boundary layer (PBL) and the free troposphere.

#### 1.1.1.1 Planetary boundary layer

The planetary boundary layer (PBL), also known as the atmospheric boundary layer (ABL), is the lowest part of the atmosphere. The behavior of the PBL is directly influenced by its contact with the ground surface. The formation of the PBL is mainly due to the roughness of the ground surface. On the one hand, the obstacles on the surface can directly reduce the wind speed; on the other hand, the obstacles can introduce random turbulence and convection which can also reduce the wind speed (Ahrens and Henson, 2021). In addition, the turbulence can cause vertical mixing between the air moving horizontally at one level and the air at the neighboring levels, which is important in dispersion of pollutants and in soil erosion. The height of the PBL varies depending on the solar energy input and the surface roughness. It varies between 50 m in Polar Regions and up

to 2 km under tropical conditions (Lampel, 2014).

#### 1.1.1.2 Free troposphere

The free troposphere is the layer of the atmosphere between the PBL and the tropopause. The free troposphere is the location of important weather and climate processes. In this layer, horizontal and vertical transport of energy, mass, and momentum take place. In addition, the layer holds greenhouse gases, water vapor and clouds. Therefore, the free troposphere plays an important role in global climate feedback processes. Comparing to the PBL, the free troposphere is less influenced by the ground surface. However, strong turbulent mixing in the PBL couples the surface and free troposphere, resulting in the material and energy vertical transport and redistribution (Jin et al., 2021). Materials in the PBL can also be transported into the free troposphere through large biomass burning such as wild fires, through sand storms in the desert or volcanic eruptions (Jurgschat, 2011).

### 1.1.2 Stratosphere

The stratosphere is the second layer of the atmosphere. It extends from the tropopause at 8–18 km to the stratopause at the height of  $\sim 50$  km. The stratosphere contains the ozone layer and it is therefore heated by the solar ultraviolet (UV) radiation. In this layer, the temperature rises with increasing altitude by 2–5 K/km. The temperature ranges from an average of  $\sim 220$  K at the tropopause to an average of  $\sim 260$  K near the mesosphere. The temperature inversion strongly reduces air exchange in the vertical direction and makes the stratosphere a stable layer with low convection and mixing. However, winds in the stratosphere can be much stronger than those in the troposphere, the speed can be up to  $\sim 60$  m/s in the Southern polar vortex.

### 1.1.3 Aerosols in the atmosphere

Aerosols refer to the fine solid particles or liquid droplets suspending in the air. The diameter of aerosol particles usually varies from 1 nm to tens of micrometers (Seinfeld and Pandis, 2016). Atmospheric aerosols can be from either natural or anthropogenic sources, and can be composed by many different materials and chemicals.

Aerosols are usually classified into two main categories by their size. Particles with diameter varies from 2.5 to 10  $\mu\text{m}$  are identified as coarse particles ( $\text{PM}_{10}$ ). They are usually found in near roadways and industrial area. Particles with diameter less than 2.5  $\mu\text{m}$  are identified as fine particles ( $\text{PM}_{2.5}$ ). They are mostly likely to be emitted directly from sources.

Atmospheric aerosols play an important role in the climate and weather system. They influence the atmospheric radiation budget directly by absorbing and scattering radiation and indirectly by providing nuclei for cloud formation (Charlson et al., 1992; Hansen et al., 1997; Li and Kou, 2011; Li, 1998; Haywood and Boucher, 2000; Ramanathan and Crutzen, 2003; Bellouin et al., 2005; Heald et al., 2014). In addition, as fine particles are small enough to be inhaled into the lung, atmospheric aerosols have adverse effects on human health (Ghio and Devlin, 2001; Valavanidis et al., 2008; Brook et al., 2010; Li et al., 2010a).

Aerosols are not only released to the atmosphere through direct emissions, but also possible to be secondarily formed through gas to particle conversion and photochemical processes (Hinds, 2012). In the recent decades, a significant increasing amount of anthropogenic aerosols and precursors have been released into the atmosphere, which makes it one of the largest uncertainties in assessments of climate change (IPCC, 2012). Natural and anthropogenic particles emitted into the atmosphere do not only have local impacts, but also influence regions far from the sources through transportation (Schütz et al., 1981; Ganor and Mamane, 1982; Hsu et al., 2009; Wiegner et al., 2011; Almeida-Silva et al., 2013; Lee et al., 2013; Tsai et al., 2014; Zhang et al., 2014; Chan and Chan, 2017; Chan, 2017).

Moreover, the spatial distribution of aerosols varies strongly with time. Therefore, it is crucial to measure the spatial and temporal variations of aerosols in order to provide a better understanding of physical and chemical processes of aerosols in the atmosphere. Aerosols can be measured by in situ instruments such as aerosol mass spectrometer (AMS), differential mobility analyzer (DMA), electrical aerosol spectrometer (EAS), aerodynamic particle sizer (APS), aerodynamic aerosol classifier (AAC), wide-range particle spectrometer (WPS), condensation particle counter (CPC), etc., as well as remote sensing instruments such as sun photometer, ceilometer, Lidar, imaging spectroscopy and multi-axis differential optical absorption spectroscopy (MAX-DOAS). This study mainly focuses on the measurement of aerosol optical extinction profiles by MAX-DOAS. In addition, sun photometer and ceilometer measurements were used as auxiliary data (see Chapters 3 and 5).

### 1.1.4 Trace gases in the atmosphere

The major chemical components of the atmosphere are nitrogen ( $N_2$ ), oxygen ( $O_2$ ), water vapor ( $H_2O$ ), noble gases (mainly Ar) and carbon dioxide ( $CO_2$ ). Besides these major constituents, there are many kinds of trace gases with mixing ratios in the order of 1 part per millions parts of air by volume (ppmv,  $10^{-6} m^3/m^3$ ) down to less than 1 part per trillions parts of air by volume (pptv,  $1^{-12} m^3/m^3$ ). Despite their low abundances, trace gases like ozone ( $O_3$ ), nitrogen oxides ( $NO_x$ ) and halogens play important roles in the physical and chemical processes in the atmosphere. These trace species are responsible for many important phenomena in the atmosphere, such as photochemical smog, ozone layer depletion, acid deposition and climate change.

The composition of the atmosphere is changing. The atmospheric concentration of many gaseous pollutants (e.g.  $SO_2$ ,  $NO_x$ ) and greenhouse gases (e.g.  $CO_2$ ,  $CH_4$ ,  $N_2O$ ) were reported to be increasing remarkably after the industrial revolution. These changes are altering the physical and chemical processes in the atmosphere and affecting the conditions of lives on the earth.

In this PhD work, the total column densities of  $NO_2$  and  $O_3$  were measured by MAX-DOAS instrument (see Chapter 6).

#### 1.1.4.1 Nitrogen dioxide ( $NO_2$ )

Nitrogen dioxide ( $NO_2$ ) is a reddish-brown gas with a pungent, acrid odor. It is one of the several kinds of nitrogen oxides and also a member of the so-called  $NO_x$  family ( $NO_x = NO_2 + NO$ ), as  $NO_2$  and  $NO$  can rapidly convert into each other in the atmosphere.

$NO_2$  has negative influence on human health and ecosystem. It can irritate the mucous membranes of eyes, nose, throat and respiratory tract. Exposure to low concentrations of  $NO_2$  can cause bronchial allergies and aggravate asthma patients' reactions to allergens. In addition,  $NO_2$  can also worsen the condition of patients with chronic respiratory diseases. Prolonged exposure to  $NO_2$  may weaken lung function and reduce the ability of the respiratory system to fight disease.  $NO_2$  is also a precursor of the formation of photochemical smogs, which are more harmful than  $NO_2$  itself.

$NO_x$  are of great importance for chemical processes in the atmosphere as they have a strong impact on the oxidative capacity of the atmosphere by influencing the abundance and distribution of  $HO_x$  radicals ( $HO_x = OH + HO_2$ ). Moreover,

they can act as a catalyst in the formation of ozone ( $O_3$ ) in the troposphere. However, in the stratosphere,  $NO_x$  can enhance the degradation of the ozone layer (Crutzen, 1970).  $NO_x$  in the atmosphere are mostly removed in the form of nitric acid ( $HNO_3$ ), which is an important component of acid rain.

The largest source of atmospheric  $NO_x$  is combustion. Anthropogenic fossil fuel combustion in industrial activities and traffic plays the most important part in the global inventory of  $NO_x$  emission (Lee et al., 1997).  $NO_x$  can be generated by either the burning of nitrogenous compounds in the fuel or the reaction of atmospheric nitrogen and oxygen at high temperature. Atmospheric  $NO_x$  can also come from soil emission, thunderstorms, etc. In addition,  $NO_x$  can diffuse from the stratosphere into the troposphere.

$NO_2$  can be measured by various techniques such as spectrophotometry, chemiluminescence (CL), tunable diode laser absorption spectroscopy (TDLAS), Lidar, as well as different kinds of differential optical absorption spectroscopy (DOAS) instruments (e.g., long-path DOAS, zenith sky DOAS, MAX-DOAS, satellite borne DOAS). In the past decade, the global distribution of  $NO_2$  has been measured by several satellites such as Global Ozone Monitoring Experiment (GOME) on board ERS-2 (Burrows et al., 1999) satellite, Scanning Imaging Absorption SpectroMeter for Atmospheric ChartographY (SCIAMACHY) (Bovensmann et al., 1999) on Envisat, Ozone Monitoring Instrument (OMI) (Levelt et al., 2006) on EOS-Aura, GOME-2 (Callies et al., 2000; Munro et al., 2016) on MetOp and Tropospheric Monitoring Instrument (TROPOMI) (Veefkind et al., 2012) on Sentinel-5 Precursor.

#### 1.1.4.2 Ozone ( $O_3$ )

Ozone ( $O_3$ ) is a colorless gas with a distinctively pungent smell. It is a powerful oxidant and plays an important role in the atmospheric chemistry and physics. As shown in Figure 1.2,  $\sim 90\%$  of the atmospheric ozone is located in the stratosphere, and the concentration peaks between 20 and 25 km. This layer is called the ozone layer. Ozone in the stratosphere can absorb the radiation in UV-B band (280–315 nm) which is harmful to the ecosystem but cannot be absorbed by other constituents of the atmosphere. The depletion of the ozone layer has been a worldwide concern since the 1970s. However, ozone near ground is harmful to human, animals, crops and other materials. Exposure to high concentrations of ozone can cause physical discomfort and damage to the respiratory system.

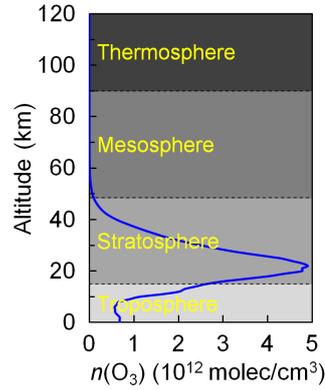
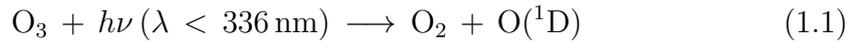


Figure 1.2: Vertical profile of the number density of atmospheric ozone (U.S. standard atmosphere 1976).

Sunlight in UV band can photolyze ozone and generates excited singlet oxygen atoms [ $O(^1D)$ ]:

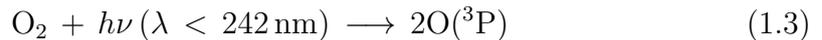


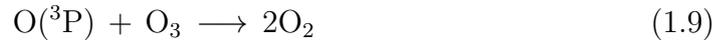
$O(^1D)$  can then combine with water vapor and produce OH radicals:



This is the most important source of atmospheric OH radicals, which are important intermediates and catalysts of many atmospheric reactions (Warneck, 1999).

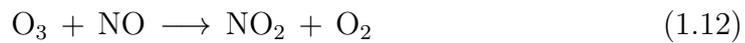
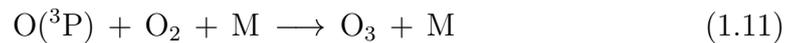
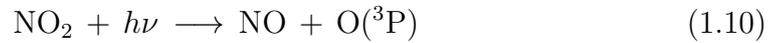
The formation mechanisms of ozone are different in troposphere and stratosphere. Stratospheric ozone is produced by photo dissociation of oxygen molecules ( $O_2$ ), however, ozone can also be destroyed by photolysis. The net production of ozone depends on the available photons for photolysis and the ambient pressure. This process is called Chapman-cycle, which was first described by Chapman (1930):





Reactive halogen species (RHS) (e.g., Chlorofluorocarbons) in the atmosphere can shift the equilibrium by introducing another ozone destruction mechanism and hence lead to the depletion of ozone layer.

In the troposphere, ozone is mainly produced by the photochemical reactions of oxygen and nitrogen oxides.  $\text{NO}_2$  can be photolysed by photons at low energies, producing  $\text{NO}$  and atomic oxygen [ $\text{O}({}^3\text{P})$ ], which can produce  $\text{O}_3$  by the combination with  $\text{O}_2$ . On the other hand,  $\text{NO}$  can also destroy ozone, hence there is an equilibrium between  $\text{NO}_2 + \text{O}_2$  and  $\text{NO} + \text{O}_3$ :



When a compound (e.g., certain volatile organic compounds) which can remove  $\text{NO}$  exists, the equilibrium will be shifted towards higher ozone levels.

Ozone can be measured by in-situ methods such as spectrophotometry, UV absorption spectroscopy, CL, Fourier transform infrared (FTIR) spectroscopy, as well as remote sensing methods such as different kinds of DOAS. Since the launch of Global Ozone Monitoring Experiment (GOME) (Burrows et al., 1999), the DOAS measurement technique has been successfully applied on satellite-based remote sensing measurements. Several DOAS-based satellite instruments have been launched, such as SCIAMACHY (Bovensmann et al., 1999), Optical Spectrograph and InfraRed Imager System (OSIRIS) (Murtagh et al., 2002), Improved Limb Atmospheric Spectrometer (ILAS) (Sasano et al., 1995), OMI (Levelt et al.,

2006), etc.

## 1.2 Thesis outline

This study is based on the MAX-DOAS measurements at the Environment Research Station Schneefernerhaus (UFS), Germany.

Chapter 2 presents the principle of DOAS method.

Chapter 3 presents the information about the measurement site and the MAX-DOAS instrument, as well as auxiliary measurements.

Chapter 4 presents a new cloud screening method developed by us.

Chapter 5 presents how the aerosol extinction profiles are retrieved from MAX-DOAS measurements. As we found the commonly used retrieval algorithms are not suitable for the high-altitude site, we developed a new algorithm based on the parametrization approach.

Chapter 6 presents the retrieval of the total VCDs of  $O_3$  and  $NO_2$  from the MAX-DOAS zenith measurements during twilight periods.

Chapter 7 summarizes the results and findings of this work and provides directions for future research.

## Chapter 2

# Differential Optical Absorption Spectroscopy (DOAS)

DOAS (Differential Optical Absorption Spectroscopy) is a technique for measuring the concentration or amount of trace gases along a light path. It is widely used because of the advantages of high sensitivity, good selectivity, low cost, as well as the possibility to measure certain kinds of trace gases and free radicals which are difficult to be measured by in situ instruments (Sigrist et al., 1994). DOAS technique was first demonstrated in the late 1970s for the simultaneous measurement of  $\text{CH}_2\text{O}$ ,  $\text{O}_3$ , and  $\text{NO}_2$  in the atmosphere (Platt et al., 1979; Platt and Perner, 1983). In the past decades, DOAS technique has been applied to the first measurements of many kinds of trace gases and free radicals in the atmosphere, such as OH (Perner et al., 1976), HONO (Perner and Platt, 1979),  $\text{NO}_3$  (Platt et al., 1980), BrO (Frieß et al., 2011), IO (Alicke et al., 1999), CHOCHO (Volkamer et al., 2005a), etc.

### 2.1 Scattering processes in the atmosphere

As the atmosphere consists of molecules and particles, when a light beam travels through the atmosphere, the photons may encounter several kinds of scatterings. The main scattering processes in the atmosphere are Rayleigh and Raman scatterings by air molecules and Mie scattering by aerosol, cloud or ice particles.

### 2.1.1 Rayleigh Scattering

Rayleigh scattering is the elastic scattering caused by air molecules. Elastic scattering means the scattering does not change the photon's energy (i.e., the wavelength or frequency). In spectroscopy studies, Rayleigh scattering is usually treated as an absorption process, although it is not really an absorption process. The cross section of Rayleigh scattering  $\sigma_R(\lambda)$  in  $\text{cm}^2$  can be described as (Rayleigh, 1899):

$$\sigma_R(\lambda) = \frac{24\pi^3}{\lambda^4 N_{\text{air}}^2} \cdot \frac{[n_0^2(\lambda) - 1]^2}{[n_0^2(\lambda) + 2]^2} \cdot F_K(\lambda), \quad (2.1)$$

where  $\lambda$  is the wavelength in cm,  $n_0(\lambda)$  is the wavelength-dependent index of the refraction of air,  $N_{\text{air}}$  is the number density of air in  $\text{molec}/\text{cm}^3$ , and  $F_K(\lambda) \approx 1.061$  is a correction factor for the anisotropy of air molecules. Since  $n_0 \approx 1$ ,

$$\sigma_R(\lambda) \approx \frac{8\pi^3}{3\lambda^4 N_{\text{air}}^2} \cdot [n_0^2(\lambda) - 1]^2 \cdot F_K(\lambda). \quad (2.2)$$

Note that  $[n_0(\lambda) - 1] \propto N_{\text{air}}$ , therefore  $[n_0^2(\lambda) - 1] \approx 2[n_0(\lambda) - 1] \propto N_{\text{air}}$ , hence  $\sigma_R(\lambda)$  is almost independent of  $N_{\text{air}}$ .

For simple estimations,  $\sigma_R(\lambda)$  can be calculated as

$$\sigma_R(\lambda) \approx \sigma_{R0} \cdot \lambda^{-4}, \quad (2.3)$$

where  $\sigma_{R0} \approx 4.4 \times 10^{-16} \text{ cm}^2 \cdot \text{nm}^4$  for air.

Rayleigh scattering is very sensitive to the wavelength, and the scattering is strong for short wavelength. As blue light has shorter wavelength than red light, the clear sky is blue.

### 2.1.2 Mie Scattering

Mie scattering refers to the elastic scattering of radiation by particles. Radiation can be both absorbed and scattered by particles in the atmosphere, and these processes are described by the absorption coefficient  $\varepsilon_a(\lambda)$  and the scattering coefficient  $\varepsilon_s(\lambda)$ :

$$dI_a = -I(\lambda) \cdot \varepsilon_a(\lambda) \cdot ds, \quad (2.4)$$

$$dI_s = -I(\lambda) \cdot \varepsilon_s(\lambda) \cdot ds, \quad (2.5)$$

where  $I(\lambda)$  is the radiation flux, and  $dI(\lambda)$  is the change of  $I(\lambda)$  after passing through a layer of aerosol of thickness  $ds$ . The single scattering albedo of the aerosol is defined as:

$$A_S = \frac{\varepsilon_s(\lambda)}{\varepsilon_a(\lambda) + \varepsilon_s(\lambda)}, \quad (2.6)$$

And the Mie scattering extinction coefficient is defined as:

$$\varepsilon_M(\lambda) = \varepsilon_a(\lambda) + \varepsilon_s(\lambda). \quad (2.7)$$

Mie scattering was first described by Gustav Mie (Mie, 1908). It was defined as the interaction of light with particles of sizes comparable to the wavelength of the incident light. It can be regarded as the radiation resulting from a large number of coherently excited molecules in a particle. As the linear dimension of the particle is comparable to the wavelength of the incident light, interference effects occur. The most noticeable differences of Mie scattering compared to Rayleigh scattering are the much weaker wavelength dependence (typically proportional to  $\lambda^{-1.3}$ ) and a strong dominance of the forward direction in the scattered light. Therefore, the cloudy sky is white or gray.

The calculation of the Mie scattering cross-section can be very complicated, however, the Mie theory has been well developed and a number of numerical models can calculate the scattering phase functions and extinction coefficients for given aerosol types and particle size distributions (van de Hulst, 1980). The computational effort can be greatly reduced by the introduction of a parametrized expression of the scattering phase function, which only depends on a few observable parameters. The most commonly used parametrized expression is the Henyey-Greenstein (Henyey and Greenstein, 1941) function:

$$p(\theta) = \frac{1}{4\pi} \cdot \frac{1 - g^2}{[1 + g^2 - 2g \cdot \cos(\theta)]^{3/2}}, \quad (2.8)$$

where  $p(\theta)$  is the scattering probability for scattering angle  $\theta$ , which is the angle between the directions of the photon before and after a scattering event.  $\theta$  is 0 and  $\pi$  for forward and backward scattering, respectively.  $g$  is the asymmetry factor, which is defined as

$$g \equiv \langle \cos(\theta) \rangle = \int_0^\pi \cos(\theta) \cdot p(\theta) \cdot 2\pi \cdot \sin(\theta) \cdot d\theta. \quad (2.9)$$

The Henyey-Greenstein phase function only depends on the asymmetry factor. For isotropic scattering,  $p(\theta)$  is constant, and  $g = 0$ . For complete forward scattering,  $g$  would be 1. Typical values of  $g$  for tropospheric aerosols are between 0.6 and 0.7. Parameters for typical aerosol scenarios can be found in the LOWTRAN database (Isaacs et al., 1987), which includes the extinction coefficients and the asymmetry factors, as well as their spectral dependence.

Particles of different dimensions show different wavelength dependencies. The wavelength dependence is expressed by the Ångström coefficient  $\alpha$ :

$$\varepsilon_M(\lambda) = \varepsilon_{M0} \cdot \lambda^{-\alpha}, \quad (2.10)$$

$\alpha$  is inversely related to the mean aerosol particle radius.  $\alpha$  typically varies between 0.5 and 2.5, with an average value of  $\sim 1.3$  (Ångström, 1930), however, very low values were found at certain high-altitude sites (see Section 5.11.5).

### 2.1.3 Raman Scattering

Raman scattering is the inelastic scattering of photons by matter, which means there is both an exchange of energy and a change in the light's direction during the scattering process. The photon either transfers a part of its energy to the molecule (Stokes lines,  $\Delta J = +2$ , S-branch) or takes over a part of the molecule's excitation energy (Anti-Stokes,  $\Delta J = -2$ , O-branch). If only the rotational excitation is affected ( $\Delta\nu = 0$ ), the scattering is called rotational Raman scattering (RRS). On the other hand, if the vibrational state also changes ( $\Delta\nu = \pm 1$ ), then the scattering is called rotational vibrational Raman scattering (RVRS).

Only discrete amounts of energy given by the difference between the discrete excitation levels can be transferred between the photons and the molecules. For air molecules (mainly  $N_2$  and  $O_2$ ), RRS frequency shifts of up to  $\pm 200 \text{ cm}^{-1}$  occur; for RVRS, a vibrational shift of  $\pm 2331 \text{ cm}^{-1}$  for  $N_2$  and  $\pm 1555 \text{ cm}^{-1}$  for  $O_2$  needs to be added (Burrows et al., 1996; Haug, 1996; Sioris and Evans, 1999). As the RRS is one order of magnitude stronger than the RVRS, it dominates the Raman scattering and the RVRS can be neglected in calculating the Ring spectrum (see Section 2.5.2). Comparing to Rayleigh scattering, Raman scattering accounts to a few per cent and depends on the wavelength (Haug, 1996). As Raman scattering does not play an important role in the radiative transfer, it is not taken into account in the radiative transfer model (see Section 5.1.2) in this study.

## 2.2 Principle of DOAS method

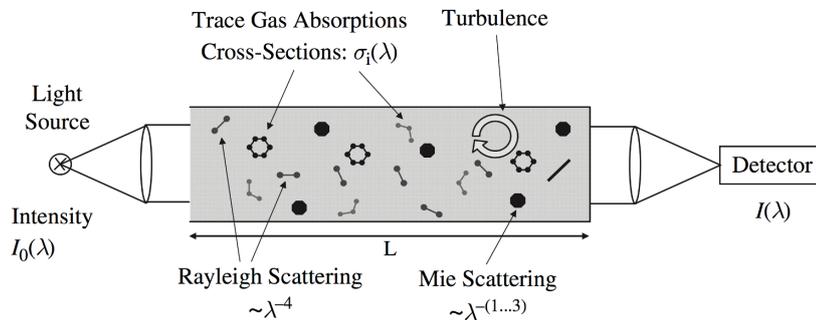


Figure 2.1: Sketch of an experiment to measure trace gas absorptions in the open atmosphere (Platt and Stutz, 2008).

DOAS method is an application of the Beer-Lambert Law, which describes the attenuation of light to the properties of the material through which the light is travelling. As illustrated in Figure 2.1, light intensity (denoted as a function of wavelength) can be changed (usually decreased) mainly due to molecular absorption, Rayleigh scattering and Mie scattering. The change can be described as the following equation:

$$\ln \left[ \frac{I_0(\lambda)}{I(\lambda)} \right] = \int_0^L \left[ \sum \sigma_i(\lambda) \cdot n_i(s) + k_R(\lambda, s) + k_M(\lambda, s) + b(\lambda) \right] ds, \quad (2.11)$$

where  $\lambda$  denotes the wavelength,  $I_0(\lambda)$  refers to the intensity of the incident light at the wavelength  $\lambda$ , while  $I(\lambda)$  is the intensity of the transmitted light. The left part of the equation is also called optical density and can be denoted as  $D(\lambda)$ . The right part of the equation refers to the absorption, where  $L$  is the length of the light path,  $\sigma_i$  is the molecular absorption cross section of the  $i^{\text{th}}$  absorption species,  $n_i(s)$  is the number density of the  $i^{\text{th}}$  absorption species at the position  $s$ ,  $k_R$  and  $k_M$  are the coefficients of Rayleigh scattering and Mie scattering, respectively, and  $b$  represents the instrumental effects.

The key idea of DOAS method is to filter out the broad band structures (i.e., the structures vary slowly with the wavelength) from both sides of Eq. (2.11) and derive the absorption information only from the narrow band structures (i.e., the structures vary fast with the wavelength). The separation is done with a mathematical filter, usually by dividing both parts by a polynomial of appropriate

degree and/or applying a high-pass filter (Stutz and Platt, 1996). In the right part of Eq. (2.11),  $k_R$ ,  $k_M$  and  $b$  are broad band structures and can be filtered out. Molecular absorption cross sections consists of both broad band and narrow band structures, which can be described as:

$$\sigma_i(\lambda) = \sigma_{0,i}(\lambda) + \sigma'_i(\lambda), \quad (2.12)$$

where  $\sigma_0$  represents the broad band structure, while  $\sigma'$  refers to the narrow band (or differential) structure. Correspondingly, the optical density can also be described as the sum of broad band and narrow band parts:

$$D(\lambda) = \ln \left[ \frac{I_0(\lambda)}{I(\lambda)} \right] = D_0(\lambda) + D'(\lambda), \quad (2.13)$$

where  $D_0$  represents the broad band part, and  $D'$  is the narrow band part, i.e., differential optical density. After broad band structures are removed from both sides of Eq. (2.11) in the same way, the left part would become the differential optical density, and only the differential molecular absorptions would remain in the right part. The relation between them can be described as:

$$D'(\lambda) = \int_0^L \left[ \sum \sigma'_i(\lambda) \cdot n_i(s) \right] ds. \quad (2.14)$$

As shown in Figure 2.2, many kinds of trace gas molecules have optical absorption cross sections in UV – VIS (visible) band. The accurate value of  $\sigma(\lambda)$  can be determined in the laboratory, and the data of common atmospheric species are available from literature. DOAS method takes advantage of the characteristic differential absorption cross sections. In DOAS measurements,  $I_0(\lambda)$  and  $I(\lambda)$  are measured by the same spectrometer, and  $D'$  is then calculated. With the absorption cross sections of the major absorbers included in the retrieval, the concentration or amount of each absorber can be determined by least-square fitting.

In DOAS measurements, the light intensities at a number of individual wavelengths are measured, therefore the measurement result is less influenced by the spectrum noise comparing to the traditional spectroscopy measurements methods which are based on the measurements at only one or a few wavelengths. As the differential absorption cross section of each absorption species is unique like a fingerprint, the retrieval has good selectivity. In addition, since the broad band absorptions are filtered out, the measurement is hardly influenced by scattering

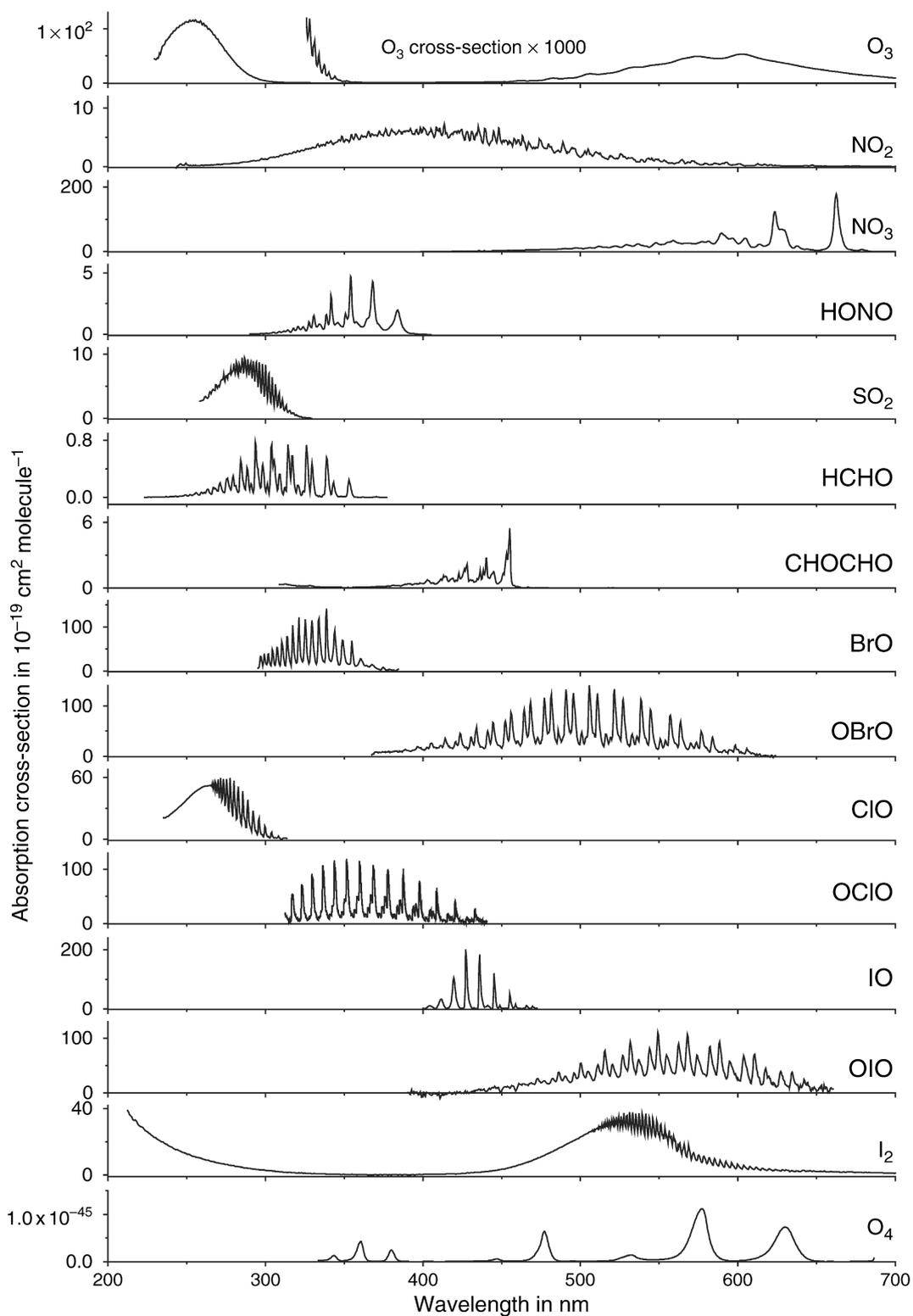


Figure 2.2: Absorption cross sections of some molecules (Platt and Stutz, 2008).

or instrument function.

## 2.3 Example of DOAS evaluation

An example of DOAS evaluation is shown in Figure 2.3. In the case, the concentration of SO<sub>2</sub> is to be retrieved from the spectra measured by an active long-path DOAS instrument. The instrument uses a Xenon short-arc lamp as the light source, and has a fixed light path of 1.36 km in the atmosphere. The fitting window is selected as 291.5–305 nm, since SO<sub>2</sub> has strong differential absorption in this band and it can be hardly influenced by other atmospheric species (see Figure 2.2). Panel (a) shows the spectra of the light before and after it travels through the atmosphere, which are  $I_0$  (purple curve) and  $I$  (blue curve), respectively. Each spectrum is an array of light intensities at 54 wavelength points, as the fitting window covers 54 channels of the photodetector of the spectrometer. Then, the optical density  $D$  can be calculated by taking the logarithm of  $I_0/I$ , shown as the blue curve in Panel (b). By applying a 3<sup>rd</sup> order polynomial regression to  $D$  and  $\lambda$ ,  $D_0$  — the broad band optical density — is derived, shown as the gray curve in Panel (b). Correspondingly, the difference between  $D_0$  and  $D$  is the differential optical depth  $D'$ , shown as the blue curve in Panel (c).

On the other hand, the cross section of SO<sub>2</sub> molecules obtained from literature (Vandaele et al., 2009) is shown in Panel (d). As the resolution of the standard cross section is much higher than the spectrometer of the DOAS instrument, it is first convolved with the instrument function, so that it is comparable to the measured optical depth. The convolved standard cross section is then converted to the reference optical density  $D_{\text{ref}}$ , which refers to the optical density corresponding to an average SO<sub>2</sub> VMR of 1 ppbv (part per billion by volume, i.e.,  $10^{-9} \text{ m}^3/\text{m}^3$ ) and the same light path of the instrument (1.36 km). As the number density of air at 273.15 K and 1 atm is  $2.6868 \times 10^{25} \text{ molec}/\text{m}^3$ , the number density corresponding to 1 ppbv is

$$n_{\text{ref}} = 2.6868 \times 10^{25} \cdot 10^{-9} = 2.6868 \times 10^{16} \text{ molec}/\text{m}^3. \quad (2.15)$$

Therefore the conversion factor between the reference optical density  $D_{\text{ref}}$  and the convolved standard cross section  $\sigma_{\text{conv}}$  (in  $\text{cm}^2/\text{molec}$ ) is

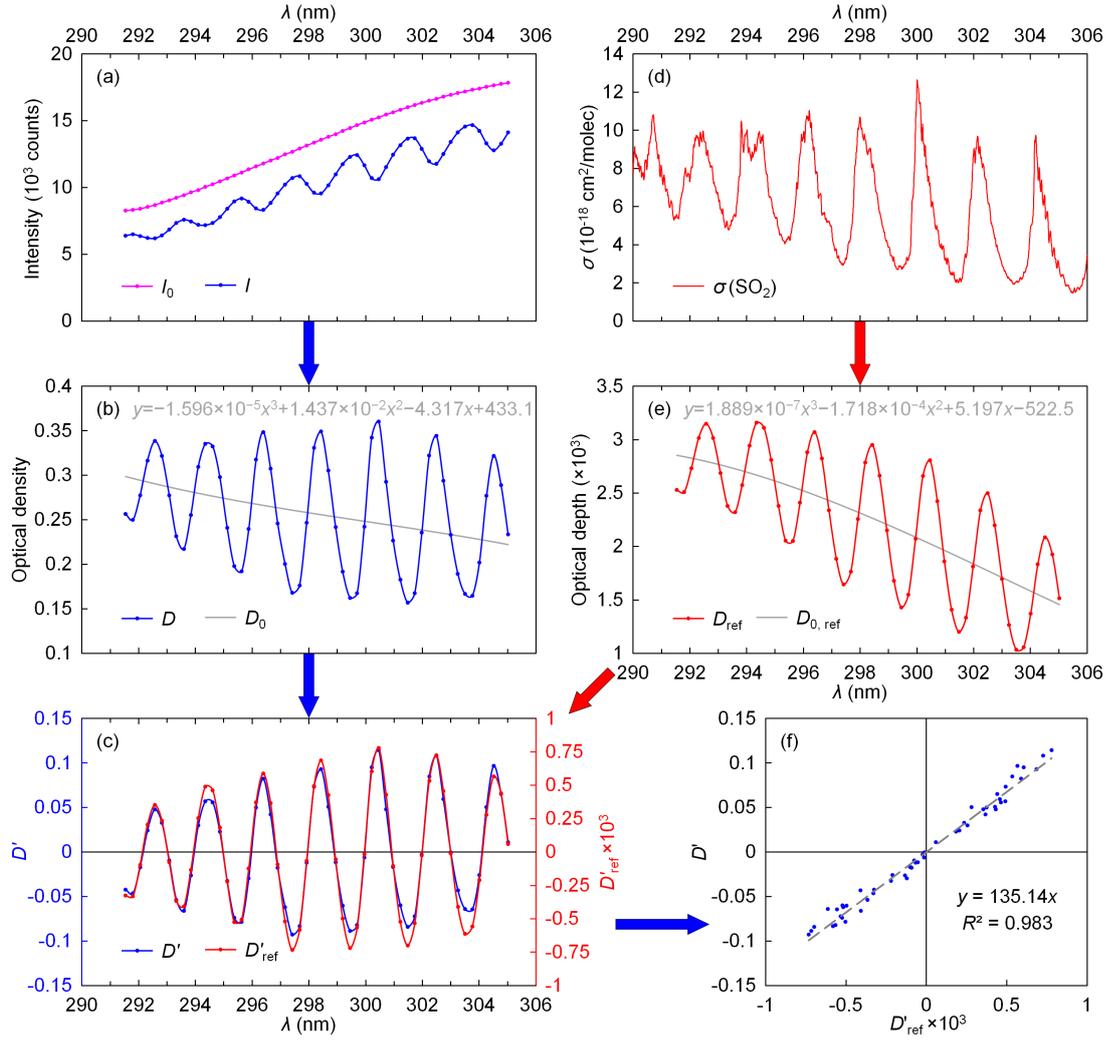


Figure 2.3: An example of DOAS evaluation, the process of the retrieval of SO<sub>2</sub> concentration from an active long-path DOAS measurement. (a) Spectra of the light before ( $I_0$ ) and after ( $I$ ) transmitting in the air. (b) Optical depth ( $D$ ) and its broad band part ( $D_0$ ). The equation shown in the panel is the equation of  $D_0$ . (c) Differential optical depth ( $D'$ ) and reference differential optical depth ( $D'_{\text{ref}}$ , which refers to the differential optical density corresponding to an average SO<sub>2</sub> VMR (volume mixing ratio) of 1 ppbv and the same light path of the instrument). (d) Standard cross section ( $\sigma$ ) of SO<sub>2</sub> obtained from literature. (e) Reference optical depth ( $D_{\text{ref}}$ ) and its broad band part ( $D_{0,\text{ref}}$ ). The equation shown in the panel is the equation of  $D_{0,\text{ref}}$ . (f) Scattered plot of  $D'$  against  $D'_{\text{ref}}$  and the linear regression result.

$$\begin{aligned}
 \frac{D_{\text{ref}}}{\sigma_{\text{conv}}} &= L \cdot n_{\text{ref}} \\
 &= 1.36 \text{ km} \cdot 2.6868 \times 10^{16} \text{ molec/m}^3 \\
 &= 1.36 \times 10^5 \text{ cm} \cdot 2.6868 \times 10^{10} \text{ molec/cm}^3 \\
 &= 3.654 \times 10^{15} / (\text{cm}^2/\text{molec}).
 \end{aligned} \tag{2.16}$$

$D_{\text{ref}}$  is shown as the red curve in Panel (e). Using the same method as  $D_0$  and  $D'$ , the broad band part  $D_{0,\text{ref}}$  and narrow band part  $D'_{\text{ref}}$  are separated from  $D_{\text{ref}}$ , shown as the gray curve in Panel (e) and the red curve in Panel(c), respectively. As  $\text{SO}_2$  is the only major absorber in this wavelength range, it can be seen that  $D'(\lambda)$  and  $D'_{\text{ref}}(\lambda)$  have similar shapes, but only different ‘amplitudes’. In Panel (f), the data points of  $D'$  are plotted against the data points of  $D'_{\text{ref}}$ . The linear regression shows very good correlation ( $R^2 = 0.983$ ), and the slope of the trend line is 135.14, which implies that the average  $\text{SO}_2$  VMR along the light path is 135.14 times as high as the reference, i.e., 135.14 ppbv.

In most cases, the fitting process is more complicated than this example. For instance, more than one absorbers may contribute to the absorption in the DOAS fitting range, and both spectra and cross sections can be slightly shifted or stretched due to the change of temperature or pressure. There can be quite a few variable parameters in actual DOAS fittings, however, the key idea is still the same — to make the fitting residual as low as possible. The fitting window also need to be optimized for a better retrieval.

## 2.4 Applications of DOAS technique

Based on the basic principle of DOAS method, several different types of DOAS experimental setups have been developed during the past decades. According to the light source, the experimental setups can be distinguished to active and passive DOAS.

Active DOAS instruments use man-made light sources. They have the advantage that the light can be available all the time, while passive measurements rely on natural light sources which are only available under certain circumstances, e.g. daytime, cloud free condition, etc. In addition, the spectral range of the man-made light sources can be customized for different applications. For example, there is virtually no available sunlight below 280 nm on the ground due to the absorption of the atmosphere, and therefore measurement in the deep UV range is only available by using man-made light source.

Passive DOAS instruments use natural light sources, usually the sun. The main advantage of passive DOAS is the ability to measure trace gases at unreachable areas such as the free troposphere and the stratosphere. In addition, passive DOAS instruments are able to measure the total column densities of trace gases and radicals.

### 2.4.1 Long-path DOAS (LP-DOAS)

Long-path DOAS (LP-DOAS) is the simplest experimental setup of active DOAS. It measures the concentration of trace gases in the troposphere by using a man-made broad wavelength band light source and measures the optical absorption over a designed long optical path in the open atmosphere. The length of the optical path varies from several hundred meters up to several kilometers. LP-DOAS technique was first demonstrated in the late 1970s for measuring the concentration of atmospheric  $\text{CH}_2\text{O}$ ,  $\text{O}_3$  and  $\text{NO}_2$  (Platt et al., 1979; Platt and Perner, 1983).

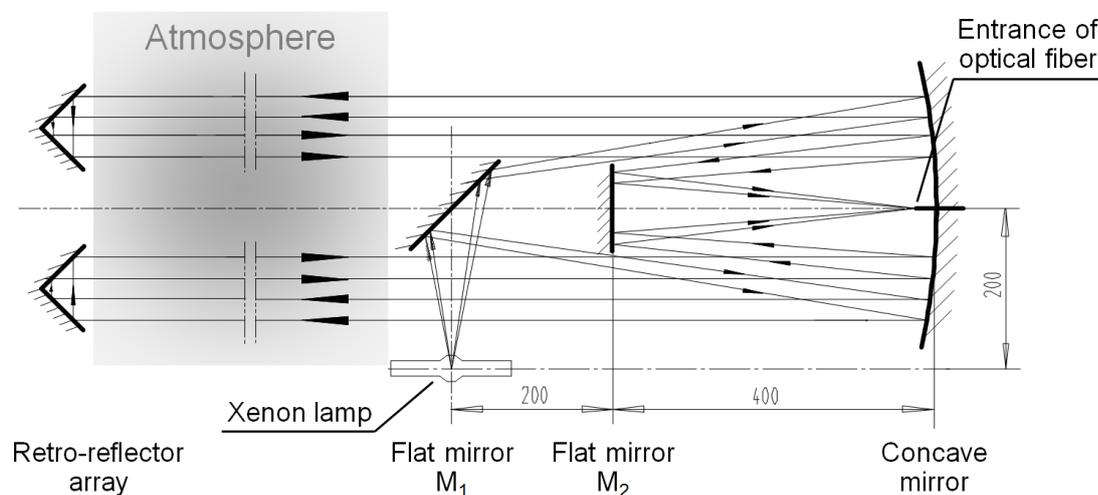


Figure 2.4: Schematic diagram of a coaxial LP-DOAS setup with combined transmitting and receiving optics in a single telescope (Wang et al., 2011).

Typical LP-DOAS instrument includes a transmitting unit which consists of an artificial light source and an emitting telescope, as well as a receiving unit which usually regards to a receiving telescope and a spectrograph. In the transmitting unit, light from the light source is coupled to the emitting telescope and sent out to the atmosphere. In the receiving unit which is at the end of the light path, the transmitted light is collected by the receiving telescope and redirected to the spectrometer. In practice, the transmitting and receiving units are usually located at the same side, and the light beam is folded back by a retro-reflector or a retro-reflector array. This design is called coaxial LP-DOAS. Figure 2.4 shows the schematic diagram of a coaxial LP-DOAS (Wang et al., 2011). The flat mirror  $M_1$  and the concave mirror constitutes a Newtonian telescope. The xenon

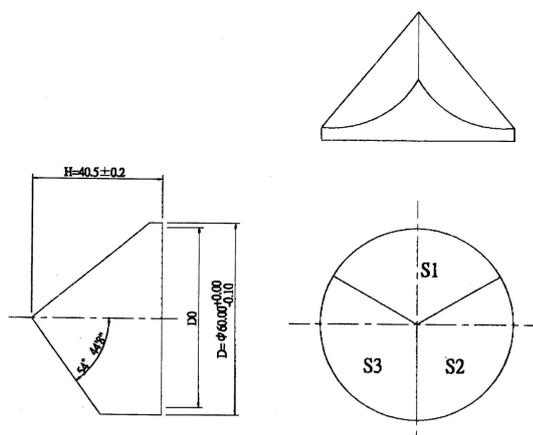


Figure 2.5: Drawing of a quartz corner cube reflector.

short-arc lamp is located at the focal point of the telescope, therefore the light is collimated to a parallel ray and projected to the retro-reflector array. The retro-reflector array consists of a few corner cube reflectors. As shown in Figure 2.5, each corner cube reflector is a quartz-glass prism with three perpendicular intersecting flat surfaces. Light can be reflected by the surfaces by total internal reflection, and its shape ensures that the reflected ray is parallel to the incident ray, but not in the same way. Therefore, the reflected light is still in a parallel ray which can reach the telescope, but would not return to the lamp; instead, some of the returned light can be reflected by the flat mirror  $M_2$ .  $M_2$  folds the light focused by the concave mirror back, so that the returned light would not be blocked by  $M_1$ . The entrance of optical fiber is at the focal point, and the returned light is transmitted to the spectrometer. The design of combining the transmitting and receiving telescopes together can not only lower down the cost of the instrument, but also simplify the maintenance of the instrument, as only the retro-reflector is installed at the remote side. In addition, coaxial LP-DOAS allows the measurement of the spectrum of the light source ( $I_0$ ) by simply laying a retro-reflector near the telescope.

### 2.4.2 Cavity-enhanced DOAS (CE-DOAS)

LP-DOAS measures the optical absorption over a long optical path in the open atmosphere, however, the reliance on the long optical path makes it infeasible for small-scale measurements such as indoor measurements and mobile measurements. In order to overcome such limitation, another kind of active DOAS in-

strument, Cavity-enhanced DOAS (CE-DOAS) was developed, which provides an alternative option for small-scale measurements (Platt et al., 2009). CE-DOAS produces a long light path with an optical resonator, so as to enhance the absorption signal within a limited space (Engeln et al., 1998; Brown, 2003; Ball et al., 2004; Fiedler et al., 2003).

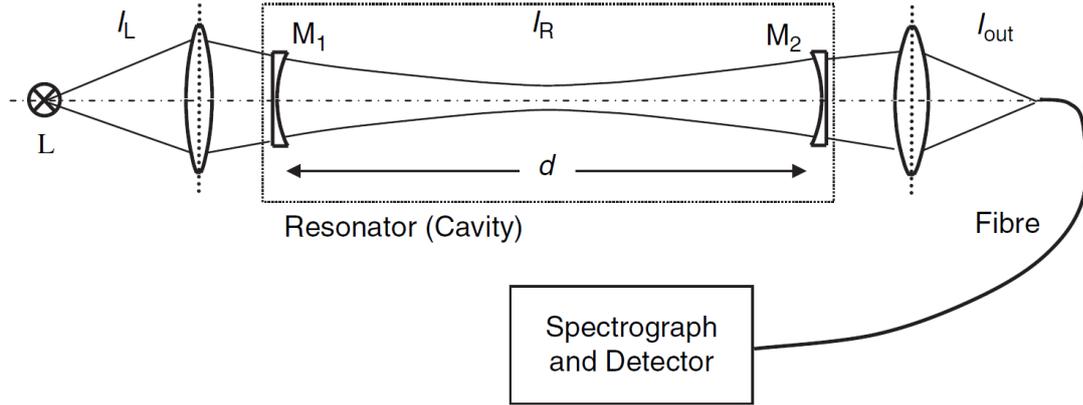


Figure 2.6: Sketch of a CE-DOAS system (Platt and Stutz, 2008).

As shown in Figure 2.6, a typical CE-DOAS system consists of a light source, an optical resonator and a spectrometer. The optical resonator consists of two mirrors with reflectivity  $R$ . Light from the light source (intensity denoted as  $I_L$ ) is coupled into the resonator through a focusing lens at one side of the resonator ( $M_1$ ), and only a fraction of  $1 - R$  of the light will enter the resonator. If other losses are neglected, light in the resonator would be reflected  $1 / (1 - R)$  times in the cavity. Half of the light will leave the resonator through the mirror at the other side ( $M_2$ ) and be coupled to the spectrometer for spectra measurement. The intensity of the transmitted light can be described as

$$I_{out}(\lambda) = I_L(\lambda) \cdot \frac{1 - R(\lambda)}{2}. \quad (2.17)$$

If additional (broad band) extinction is considered, the average length of the absorption path would be:

$$\bar{L} = \frac{d}{(1 - R) + \varepsilon_B \cdot d}, \quad (2.18)$$

where  $\varepsilon_B$  denotes the broadband extinctions due to Mie and Rayleigh scattering as well as trace gas broad band absorption, and  $d$  is the length of the resonator.

Presently, mirrors with  $R > 0.9999$  can be manufactured. By using such mirrors with  $d=1$  m, the average light path  $\bar{L}$  would be larger than 10 km, and the intensity of the transmitted light ( $I_{\text{out}}$ ) would be about  $5 \times 10^{-5}$  times of the initial light intensity ( $I_L$ ). The transmitted fraction seems to be small but it is indeed comparable to LP-DOAS in the open atmosphere. In order to have accurate measurements, the effective optical path length of CE-DOAS need to be calibrated, e.g. by measuring an absorbing gas sample with known concentration (Langridge et al., 2006; Venables et al., 2006).

### 2.4.3 Zenith scattered light DOAS (ZSL-DOAS)

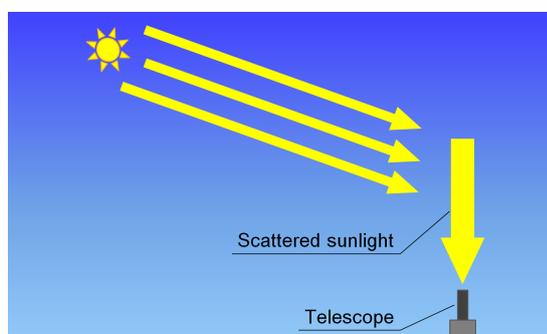


Figure 2.7: Schematic diagram of zenith scattered light DOAS.

Zenith scattered light DOAS (ZSL-DOAS) is the simplest application of passive DOAS. ZSL-DOAS measures the spectra of scattered sunlight at the zenith direction. A schematic diagram of zenith scattered light DOAS is shown in Figure 2.7. The system consists of a receiving telescope pointing to the zenith and a spectrometer. The light collected by the telescope is transmitted to the spectrometer through an optical fiber. In order to cover a wider wavelength range, some ZSL-DOAS instruments have more than one spectrometer (Hönninger and Platt, 2002).

ZSL-DOAS has several advantages in atmospheric measurements. First, the experimental setup is relatively simple, as it consists of only a spectrograph and a receiving telescope, and adjustment of the telescope is not required. Second, tropospheric trace species can be measured, even if they are distributed over the entire troposphere. Third, ground-based zenith DOAS measurements are sensitive to trace gases in the stratosphere even in the presence of cloud cover. However, these advantages come along with the rather complicated radiative

transfer calculations of the effective optical path in the atmosphere. In addition, correction has to be made to compensate for the effects due to light scattering process in the atmosphere.

ZSL-DOAS has been widely used for the measurement of vertical column densities (VCDs) of trace gases and free radicals in the past a few decades, such as  $\text{O}_3$ ,  $\text{NO}_2$  (Pommereau, 1982; Mount et al., 1987; Wahner et al., 1990; Johnston et al., 1992; Chen et al., 2009; Roscoe et al., 2010; Constantin et al., 2013),  $\text{NO}_3$  (Sanders et al., 1987; Solomon et al., 1989a), OClO (Solomon et al., 1987a; Schiller et al., 1990; Perner et al., 1991; Kreher et al., 1996; Otten et al., 1998), BrO (Solomon et al., 1989b; Kreher et al., 1997; Eisinger et al., 1997; Richter et al., 1999; Hendrick et al., 2007) and  $\text{O}_4$  (Sarkissian et al., 1991; Erle et al., 1995; Wang et al., 2012a).

Since ZSL-DOAS instruments can be made portable and do not rely on fixed light paths, they can be installed on vehicles or ships, and hence mobile measurements are available. Mobile ZSL-DOAS measurements can provide information on the spatial distribution of air pollutants (Wu et al., 2013; Zhu et al., 2016). Moreover, the total pollutant emission from a certain region can be estimated from circular mobile-DOAS measurements in combination with meteorological data (Wang et al., 2012b).

Chapter 6 of this thesis presents the retrieval of the total VCDs of  $\text{O}_3$  and  $\text{NO}_2$  from the zenith measurements of the MAX-DOAS instrument at the UFS. In such measurements, the MAX-DOAS is virtually used as a ZSL-DOAS.

#### 2.4.4 Multi-axis DOAS (MAX-DOAS)

Multi-axis differential optical absorption spectroscopy (MAX-DOAS) is the variant of ZSL-DOAS. MAX-DOAS measures the spectra of scattered sunlight at not only the zenith direction, but also off-zenith directions. Since measurements at different observation angles have different sensitivities to trace gases at different altitudes, MAX-DOAS can provide more information about the vertical distribution of trace gases comparing to ZSL-DOAS.

A simplified MAX-DOAS measurement sketch is illustrated in Figure 2.8. Typical MAX-DOAS instrument consists of a spectrometer and a receiving telescope equipped with one or two stepper motors, so that the viewing direction of the telescope can be precisely adjusted. Usually, the telescope scans in a predefined cycle which includes several different viewing angles, and each cycle takes

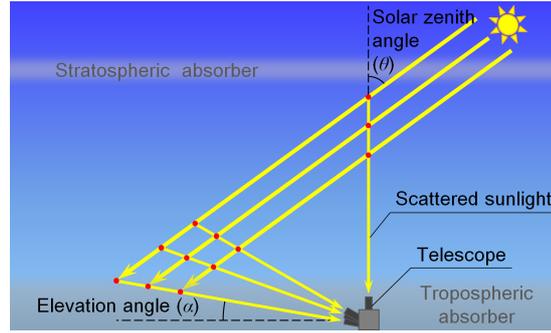


Figure 2.8: Schematic diagram of MAX-DOAS measurement in the single scattering case. The red points indicate scattering events along the line of sight of the telescope.

a few minutes. Since it is impossible to measure the spectrum of the initial sunlight, typical MAX-DOAS retrieval treats the zenith spectrum as the reference spectrum ( $I_0$ ), while the spectra measured at other elevations ( $I$ ) are divided by the zenith reference spectrum before applying the DOAS retrieval. Subsequently, a logarithm is taken to convert the quotient to the optical density. By applying DOAS evaluation to the optical density, the differential slant column densities (DSCDs,  $\Delta S$ ) of trace gases are derived, which refer to the differences between the slant column densities (SCDs,  $S$ ) along the off-zenith and the zenith measurements. According to the definitions of SCD and DSCD, the DOAS equation Eq. (2.14) can be written as:

$$D'(\lambda) = \sum \sigma'_i(\lambda) \cdot \Delta S_i, \quad (2.19)$$

and

$$\Delta S_i = S_i - S_{\text{ref},i} = \int_0^L n_i(s) ds - \int_0^{L_{\text{ref}}} n_{\text{ref},i}(s) ds, \quad (2.20)$$

where  $S_i$ ,  $L$  and  $n_i$  are the SCD, light path length and number density of the  $i^{\text{th}}$  absorber of the off-zenith measurement, while  $S_{\text{ref},i}$ ,  $L_{\text{ref}}$  and  $n_{\text{ref},i}$  are those of the zenith reference measurement.

The red points in Figure 2.8 illustrate the scattering of the sunlight in the line of sight of the MAX-DOAS telescope. In this figure, the single scattering case is assumed, i.e., each photon is scattered only once in the atmosphere. In reality, multiple scattering may also occur. The upper and lower gray layers in the figure refer to atmospheric absorbers in the stratosphere and the troposphere,

respectively. As illustrated in the figure, if the zenith and off-zenith spectra are measured at the same time or within a short time span (e.g., in the same scanning cycle), their absorptions in the stratosphere are supposed to be the same. Therefore, the stratospheric absorptions are canceled in the above-mentioned DSCDs, and the DSCDs are only sensitive to tropospheric absorptions. In addition, since the scattered sunlight observed at lower elevations usually has longer light paths in the troposphere, the absorption intensities of trace gases are stronger at lower elevations and hence lead to larger DSCDs.

As DSCDs are affected by the effective light path in the atmosphere, they cannot directly reflect the real concentration or amount of atmospheric trace gases and need to be converted. The effective light path in the atmosphere depends on the radiation transfer in the atmosphere in which aerosols play an important role. Accurate retrieval of aerosol information requires the inversion of a series of underlying radiative transfer equations which cannot be linearized. Commonly, aerosol information is retrieved by fitting the forward simulated DSCDs of an absorber with well-known and stable concentration profile — the oxygen dimer complex,  $O_4$  — to the measurements (Wagner et al., 2002; Hönninger et al., 2004; Wagner et al., 2004; Sinreich et al., 2005; Frieß et al., 2006). This study is based on the MAX-DOAS measurements at the UFS, and the principle of aerosol optical extinction profile retrieval is presented in detail in Chapter 5.

As the experimental setup of MAX-DOAS is relatively simple and inexpensive, it has been widely used to measure the vertical distribution of atmospheric aerosols and trace gases in the past two decades (e.g., Hönninger et al., 2004; Irie et al., 2008; Li et al., 2010b; Clémer et al., 2010; Frieß et al., 2011; Halla et al., 2011; Irie et al., 2011; Vlemmix et al., 2011; Wagner et al., 2011; Li et al., 2013; Ma et al., 2013; Wang et al., 2014a; Chan et al., 2015; Jin et al., 2016; Wang et al., 2016; Chan et al., 2017).

### 2.4.5 Satellite borne DOAS

The DOAS measurement technique has also been applied in satellite-based remote sensing measurements. Several DOAS-based satellite instruments have been launched in the past decades, such as the Global Ozone Monitoring Experiment (GOME) (Burrows et al., 1999), the Scanning Imaging Absorption Spectrometer for Atmospheric Chartography (SCIAMACHY) (Bovensmann et al., 1999), the Optical Spectrograph and InfraRed Imager System (OSIRIS) (Murtagh et al.,

2002), the Improved Limb Atmospheric Spectrometer (ILAS) (Sasano et al., 1995) and the Ozone Monitoring Instrument (OMI) (Levelt et al., 2006).

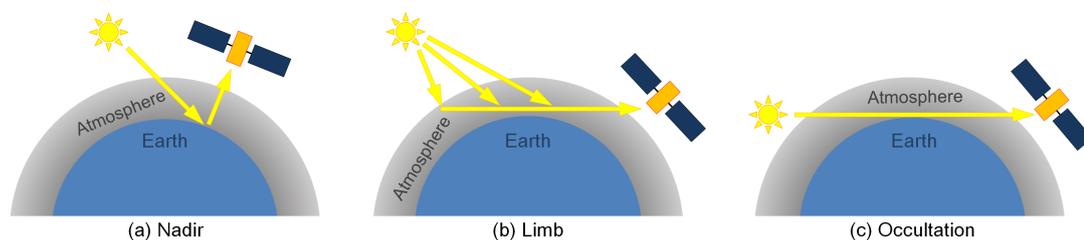


Figure 2.9: Different viewing geometries of satellite measurements, (a) Nadir, (b) Limb, and (c) Occultation.

As shown in Figure 2.9, different viewing geometries are used in satellite-based DOAS observations. The most commonly used satellite viewing geometry is the nadir view (Figure 2.9a), which means looking down from space towards the earth's surface in the nadir direction and measuring the reflected solar radiation from the surface or atmosphere of the earth. Nadir observation can be used to measure the column densities of atmospheric trace gases. Several satellite instruments including GOME, ILAS and OMI use nadir viewing geometry in atmospheric measurements. Other satellite viewing geometries include limb and occultation geometries. Limb geometry means measuring the scattered light from the atmosphere (Figure 2.9b), while occultation viewing geometry means measuring the direct solar radiation through the atmosphere during sunrise or sunset (Figure 2.9c). These two viewing geometries are useful for the measurements of the vertical profiles of trace gases. The SCIAMACHY instrument combines all the three viewing geometries (Beirle et al., 2010). By applying the limb-nadir matching, the stratospheric contribution of total slant columns of  $\text{NO}_2$  can be corrected from the total slant columns retrieved from nadir measurements (Hilboll et al., 2013).

Satellite measurements are important for atmospheric studies in providing the spatial distribution of atmospheric trace gases (Burrows et al., 1999; Bovensmann et al., 1999; Callies et al., 2000; Levelt et al., 2006). The spatial coverage and resolution of satellite measurements have been improved a lot in the recent decades. Nadir-view satellites can provide a global coverage in six days for SCIAMACHY, three days for GOME and one day for OMI. The spatial resolutions of these satellite instruments have also been improved by more than 10 times, which are from  $\sim 3200 \text{ km}^2$  ( $40 \text{ km} \times 80 \text{ km}$ ) for GOME,  $\sim 1800 \text{ km}^2$  ( $30 \text{ km} \times 60 \text{ km}$ ) for SCIA-

MACHY to  $\sim 320 \text{ km}^2$  ( $13 \text{ km} \times 24 \text{ km}$ ) for OMI. These satellite measurements have been widely used in the studies of the emissions and dynamics of trace gases from both natural and anthropogenic sources (Wenig et al., 2003; Richter et al., 2005; Zhang et al., 2007; van der A et al., 2008; Pujadas et al., 2011).

## 2.5 Passive DOAS Characteristics

### 2.5.1 Fraunhofer lines

Most passive DOAS instruments use sunlight as the light source. The shape of solar spectrum at the top of the earth's atmosphere is determined by the physical and chemical composition of the sun's surface, especially its atmosphere. As a first approximation, the solar radiation can be described as the emission of a black body with a surface temperature of  $\sim 5800 \text{ K}$ . However, this continuous spectrum is overlaid by many strong absorption lines which are caused by the selective absorption and re-emission of radiation in the sun's photosphere. These absorption structures are called the Fraunhofer lines (first discovered by Joseph von Fraunhofer, 1787–1826). Fraunhofer lines can cause strong variations in the intensity of the solar spectrum. In the UV-VIS wavelength range (300–600 nm), the optical densities of the Fraunhofer lines are typically two to three orders of magnitude higher than the optical densities of the trace gas absorptions in the earth's atmosphere.

In passive DOAS studies, in order to minimize the influence from the Fraunhofer lines, a Fraunhofer reference spectrum (which also serves as  $I_0$ ) should be always included in the DOAS fitting process. For MAX-DOAS, as the off-zenith and reference spectra are measured within a short time span, the influence from Fraunhofer lines does not play an important role. A sample of Fraunhofer spectrum is shown in Figure 2.10.

### 2.5.2 The Ring effect

The Ring effect (Grainger and Ring, 1962) describes a reduction of the observed optical densities of the Fraunhofer lines. The Ring effect is primarily caused by the inelastic rotational Raman scattering of photons with air molecules (Fish and Jones, 1995; Burrows et al., 1996) (see Section 2.1.3). Such scattering processes cause changes in not only the photons' directions but also their wavelengths,

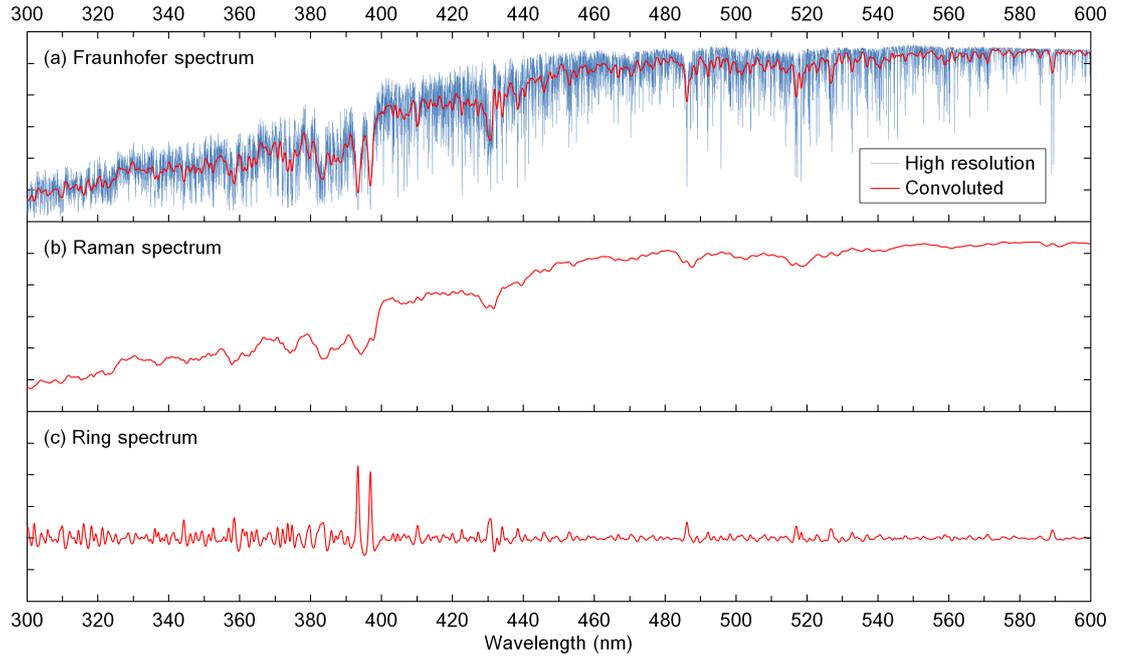


Figure 2.10: Samples of Fraunhofer, Raman and Ring spectra. In Panel (a), the blue curve shows the high resolution Fraunhofer spectrum, and the red curve shows the Fraunhofer spectrum convoluted with a Gaussian slit function with 0.75 nm FWHM (full width at half maximum). In Panel (b), the Raman spectrum is convoluted with the same function. In Panel (c), the Ring spectrum is calculated from the convoluted Raman and Fraunhofer spectra.

therefore the spectrum of scattered sunlight is smoothed, and the Ring effect is also called ‘filling-in’ of Fraunhofer lines. In addition, the intensity of the Ring effect increases with longer atmospheric light paths and accordingly with larger solar zenith angles (SZAs).

The Ring effect can significantly affect passive DOAS measurements, therefore it must be thoroughly corrected from the spectra of scattered sunlight. Usually, the Ring effect is treated as a pseudo absorber, and a so-called Ring spectrum is included in the DOAS fitting process.

The scattered sunlight measured by passive DOAS instruments comes from either elastic scattering processes (Rayleigh and Mie scattering) or Raman scattering. Their intensities can be written as:

$$\begin{aligned}
 I_{\text{meas}} &= I_{\text{Rayleigh}} + I_{\text{Mie}} + I_{\text{Raman}} \\
 &= I_{\text{elastic}} + I_{\text{Raman}}.
 \end{aligned}
 \tag{2.21}$$

As presented in Section 2.2, the logarithm of the measured spectrum need to be taken for the DOAS evaluation, therefore,

$$\begin{aligned}\ln(I_{\text{meas}}) &= \ln(I_{\text{elastic}} + I_{\text{Raman}}) \\ &= \ln(I_{\text{elastic}}) + \ln\left(1 + \frac{I_{\text{Raman}}}{I_{\text{elastic}}}\right).\end{aligned}\quad (2.22)$$

Since  $I_{\text{Raman}} \ll I_{\text{elastic}}$ ,

$$\ln(I_{\text{meas}}) \approx \ln(I_{\text{elastic}}) + \frac{I_{\text{Raman}}}{I_{\text{elastic}}}.\quad (2.23)$$

Then the Ring spectrum can be calculated as:

$$I_{\text{Ring}} = \frac{I_{\text{Raman}}}{I_{\text{elastic}}}.\quad (2.24)$$

Ring reference spectrum can be derived by either measurement or modeling. The the rotational Raman scattered intensity can be obtained by measuring scattered sunlight spectra at different viewing directions, and therefore a Ring spectrum can be derived (Solomon et al., 1987b). However, this method can be interfered by Mie scattering, and it is also dependent on the polarization direction. On the other hand, by including Raman scattering into radiative transfer models, the cross section of rotational Raman scattering can be calculated from the known energies of the rotational states of O<sub>2</sub> and N<sub>2</sub> (Fish and Jones, 1995; Chance and Spurr, 1997). In this way, the shortcomings of measured Ring spectrum can be overcome. Moreover, modeled Ring spectrum was found to be consistent with highly resolved atmospheric observations (Aben et al., 2001). In this study, modeled Ring spectra were used in the DOAS evaluation. The calculation of Ring spectra was performed by the the spectra evaluation software QDOAS developed at BIRA-IASB (Belgian Institute for Space Aeronomy, <http://uv-vis.aeronomie.be/software/QDOAS/>). A sample of Raman and Ring spectra is shown in Figure 2.10.

### 2.5.3 The $I_0$ effect

In DOAS measurements, the resolution of measured spectra is limited by the spectral resolution of the spectrometer, which typically varies from a few tenths to several nanometers. Accordingly, the absorption cross sections of trace gases also need to be convolved with the same slit function. Therefore, the natural line

widths of the Fraunhofer spectrum and the atmospheric absorptions cannot be resolved. Since both  $I(\lambda)$  and  $I_0(\lambda)$  in the DOAS equation (Eq. 2.11) have been filtered by the slit function before taking the ratio, the Fraunhofer structures can not be totally removed, introducing the so-called  $I_0$  effect (Johnston, 1996).

The  $I_0$  effect can be corrected in the following way: First, a highly resolved solar spectrum  $I_0(\lambda)$  is convolved with the slit function of the DOAS instrument (the convolved spectrum is denoted as  $I_0^*(\lambda)$ ). In the next step, a modeled absorption spectrum is calculated from the highly resolved solar spectrum and a highly resolved absorption cross section, and the modeled spectrum is then convolved with the slit function as well (the convolved spectrum is denoted as  $I^*(\lambda)$ ). In the calculation, an atmospheric SCD of the trace gas ( $S$ ) need to be assumed. Finally, the  $I_0$  corrected cross section is derived as:

$$\sigma_{\text{corrected}}(\lambda, S) = - \ln \left[ \frac{I^*(\lambda)}{I_0^*(\lambda)} \right] \cdot \frac{1}{S}. \quad (2.25)$$

In principle, the  $I_0$  corrected absorption cross section perfectly matches the absorptions in the measured spectrum only if the SCD used for the calculation matches the actual SCD in the atmosphere. However, in most studies, fixed SCD values which are typical of the maximum were used for  $I_0$  corrections, and the errors were found to be insignificant (Aliwell et al., 2002). In addition, the  $I_0$  effect is only significant for strong absorbers, while it can be neglected for weak absorbers. In this study, we followed the common settings of other studies that only  $\text{NO}_2$  and  $\text{O}_3$  were corrected for  $I_0$  effect, and fixed SCDs were used.

# Chapter 3

## Instrumentation

In this section, we present the information about the measurement site and the MAX-DOAS instrument, as well as auxiliary measurements.

### 3.1 Measurement site — the UFS

The Environmental Research Station Schneefernerhaus (UFS, German: Umweltforschungsstation Schneefernerhaus) ( $47.417^{\circ}\text{N}$ ,  $10.980^{\circ}\text{E}$ ) is located close to the summit of the Zugspitze (2962 m above sea level), at an altitude of 2,650 m above sea level (a.s.l.). As it is surrounded by the mountainous area of Alps and there are no significant emissions at this altitude, the ambient air around the UFS is mostly clean and unpolluted. Therefore the station is usually referred as a background site. The UFS is located in the free troposphere and allows measurements above the PBL, which is very special for atmospheric environment study. The location of the UFS is shown in Figure 3.1 and Figure 3.2.

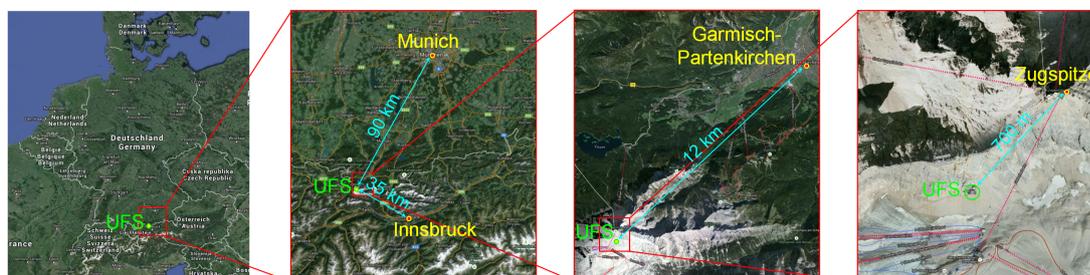


Figure 3.1: Location of the UFS. Images captured from Google Maps.



Figure 3.2: The Environmental Research Station Schneefernerhaus, seen from the cable car station on Zugspitzplatt. The red circle indicates the location of the MAX-DOAS telescope.

Zugspitze is the highest peak of the Wetterstein Mountains and also the highest mountain in Germany. It lies in the northern Alps and to the southwest of Garmisch-Partenkirchen. The Austria-Germany border runs over its western summit. South of the mountain is the Zugspitzplatt, a high karst plateau with numerous caves. The UFS is located on the south slope of Zugspitze, around 250 m below the summit. The closest populated area is the town of Garmisch-Partenkirchen which is located  $\sim 12$  km away in the northeast direction. The big cities of Innsbruck and Munich are located about 35 and 90 km away, respectively.

The Schneefernerhaus (literally means ‘snow far house’) was originally a tourist hotel and the top station of the rack railway from Garmisch-Partenkirchen (Bayerische Zugspitzbahn). It was opened in 1931 together with a short cable car that took the guests all the way to the summit. When the Schneeferner glacier retreated in the 1960s, the slope below Schneefernerhaus became too steep for most skiers. A fatal avalanche in 1965 marked the beginning of the decline of the hotel. After a new rack railway station was opened on the Zugspitzplatt in 1988 and the restaurant SonnAlpin enlarged in 1989, the hotel was finally closed

in 1992 due to the lack of guests. In 1992, the Rio Earth Summit addressed for the first time the issue of climate change and 172 nations agreed on the Climate Change Convention. As a result, the former hotel Schneefernerhaus was modified to become a modern research station in 1993. The research station was officially opened in 1999 after about 8 million Euros had been spent.

The station is currently operated by the Betriebsgesellschaft UFS GmbH (Operating Company of UFS Co., Ltd.) and supported by the Umweltministerium Bayern (Bavarian Environment Ministry). Scientists from many different institutions carry out continuous measurements or work on research projects at the station. The UFS is not only a center for environment and climate research and observatory, but also a communication and conference center for teaching, education and sustainability strategies.

## 3.2 MAX-DOAS instrumental setup

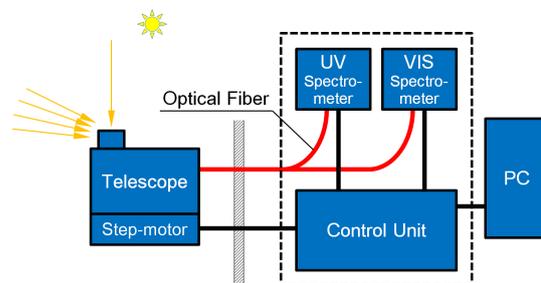


Figure 3.3: Schematic view of the MAX-DOAS instrument operated at the UFS.

This study is mainly based on the long-term MAX-DOAS measurements at the UFS. Figure 3.3 shows the components of the MAX-DOAS instrument operated at the UFS. The instrument includes a scanning telescope and two spectrometers. The control unit and the spectrometers are installed in a 19-inch rack. Scattered sunlight collected by the telescope is redirected by a prism reflector and then transmitted to the spectrometers through an optical fiber bundle. A desktop PC controls the entire instrument and can be remotely accessed. The instrument started operation in 2011.

### 3.2.1 Telescope

The telescope was set up on the roof of the UFS, about 20 m above ground level, see Figure 3.2. In a previous study (Jurgschat, 2011), the field of view (FOV) of the telescope was measured to be  $0.98^\circ$ . As shown in Figure 3.4, the lens of the telescope is driven by two stepper motors and can allow a  $360^\circ$  azimuth and elevation movement. One motor moves the upper part of the telescope around the optical axis, while the other one is mounted on the upper part and can rotate the incoming prism with its enclosure. The light collected by the telescope is redirected by the two prisms and then focused by a concave mirror with a diameter of 25.4 mm and a focal length of 76.2 mm. The entrance of the optical fiber bundle is placed at the focal point. There is a moveable sand-blasted glass shutter which can be placed in front of the fiber entrance, so as to block the moon and starlight when measuring the dark current and offset spectra at night (see Section 3.2.5). The shutter can also be used for direct-sun measurements when required. In addition, the telescope can also be directed to the built-in mercury and halogen lamps, so as to measure the Hg-Ne spectra which are useful in the pixel-to-wavelength calibration.

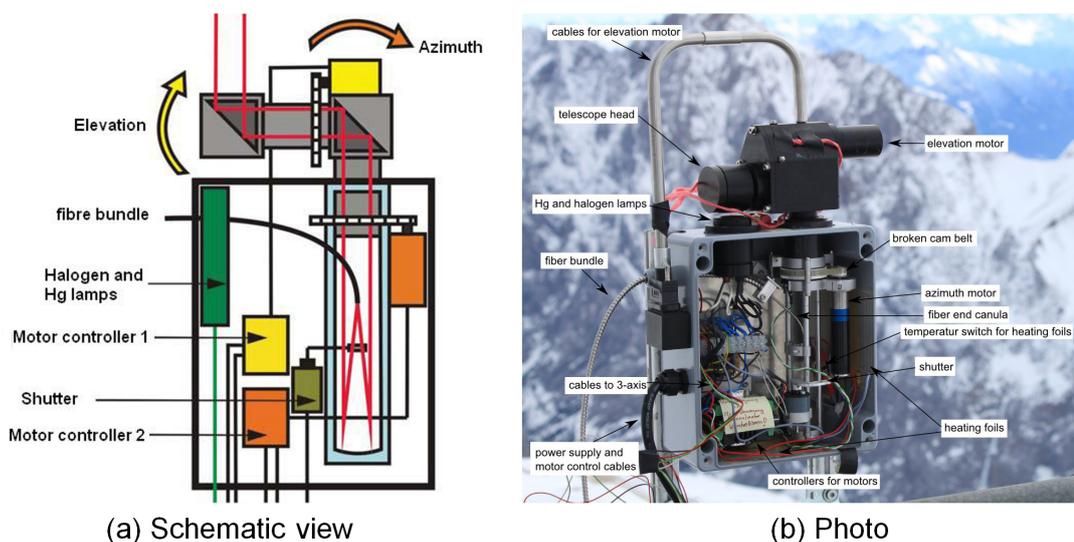


Figure 3.4: Components of the MAX-DOAS telescope. (a) Schematic view, from Niebling (2010); (b) Photo, from Jurgschat (2011).

In the study, the telescope always looked to the due south ( $180^\circ$ ) and scanned only in vertical direction. This viewing azimuth was least influenced by the surrounding mountains. As shown in Figure 3.5, with an FOV of  $0.98^\circ$  considered,

the telescope could see the unblocked sky when the elevation angle varies between  $1^\circ$  and  $90^\circ$ . The horizon of the telescope was mostly above the mountainous area of the Alps, see Figure 3.6.

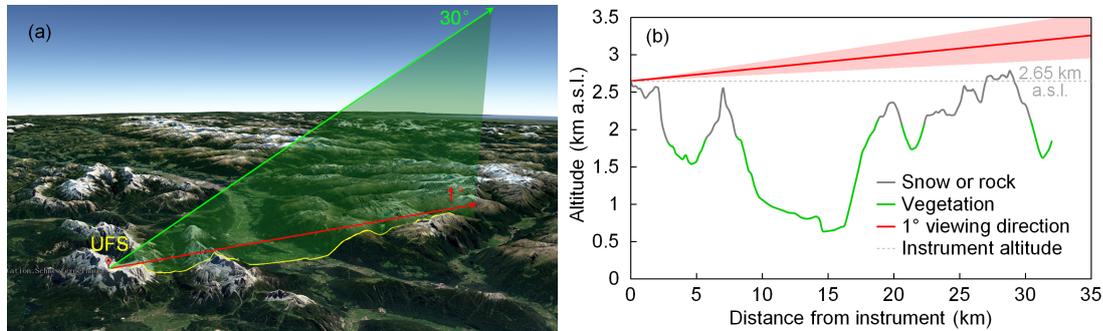


Figure 3.5: Topography around the UFS. (a) Image of the land around the UFS from Google Earth in 3D view, together with the viewing directions of  $1^\circ$  and  $30^\circ$ . The yellow curve indicates the projection of the viewing direction on the ground. (b) Altitude and type of the ground surface under the viewing direction, altitude data are obtained from Google Earth. The shadow beside the line of  $1^\circ$  viewing direction indicates the FOV of the telescope which was measured to be  $0.98^\circ$ .



Figure 3.6: View from the MAX-DOAS observation azimuth. The red arrow indicates the viewing direction of the MAX-DOAS telescope.

### 3.2.2 Optical fiber bundle

The light collected by the telescope is transmitted to the two spectrometers through an optical fiber bundle. The optical fibers are made of hydrogen-doped quartz, so as to minimize the solarization degradation. As shown in Figure 3.7,



Table 3.1: Parameters of the two spectrometers used in the study.

Code name	UV	VIS
Grating	1800 / nm	1302 / nm
Wavelength range (nm)	~320–478	~427–649
Width of entrance slit ( $\mu\text{m}$ )	75	50
FWHM (nm)	~1.1	~0.6

from 0 to 65,535 ( $2^{16} - 1$ ). The spectrometers were temperature-stabilized to 258 K by Peltier coolers during the measurement, so as to lower down the dark current of photodetectors, as well as to avoid the change of the actual wavelength calibration caused by the thermal expansion of the optical bench.

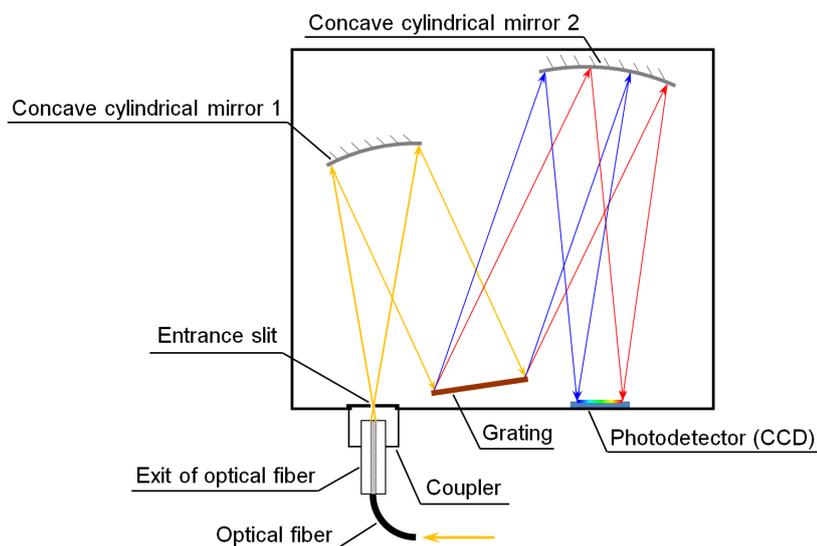


Figure 3.8: Schematic view of the optical system of the OMT ctf-60 spectrometer.

The UV and VIS spectrometers have the same design, but only differ in the diffraction grating and the width of entrance slit, hence they have different wavelength ranges and different instrument functions. Table 3.1 shows the parameters of the two spectrometers.

### 3.2.4 Software

All the components of the MAX-DOAS instrument — including the stepper-motors, photodetector, Peltier cooler, etc. — were controlled by the computer program MS-DOAS developed by the Institute of Environmental Physics of Heidelberg University.

During daytime ( $SZA < 85^\circ$ ), the instrument ran with a fixed cycle. Each cycle consists of measurements of scattered sunlight spectrum at elevation angles ( $\alpha$ ) of  $1^\circ$ ,  $2^\circ$ ,  $5^\circ$ ,  $10^\circ$ ,  $20^\circ$ ,  $30^\circ$  and  $90^\circ$  (zenith). A single measurement at each elevation lasts for  $\sim 1$  min, and a full scanning cycle takes about 10 min. The recorded spectrum of each measurement is the sum of many readouts during the measurement period. In order to optimize the measurement signal-to-noise ratio (SNR), avoid saturation, and achieve a constant signal level, the data acquisition software automatically adjusts the exposure time of each readout to make the maximum count close to 70% of saturation level (65,535 counts). Depending on the intensity of received light, the exposure time of each readout varies from tens of milliseconds to a few seconds. The measurements of UV and VIS bands were taken by the two spectrometers simultaneously, but their exposure times were adjusted individually. The instrument took measurements continuously during daytime, but during the noon ( $175^\circ < SAA$  (solar azimuth angle)  $< 185^\circ$ ) and twilight periods ( $85^\circ < SZA < 92^\circ$ ), the instrument took only zenith measurements. At each night, the instrument measured five offset spectra and five dark current spectra (see Section 3.2.5).

### 3.2.5 Offset and dark current correction

The counts in the spectrum files directly obtained from the spectrometers contain offset and dark current. These two components bring bias to the spectrum, therefore they need to be corrected from the spectra, so that the counts can reflect the light intensity more precisely. Figure 3.9 and Figure 3.10 show examples of offset and dark current correction for a UV spectrum and a VIS spectrum, respectively.

Offset is a semi-constant value added to the photodetector in order to make sure that the measured light intensity is always positive, since the A/D converter can only work with positive analog signals, while it is possible to encounter negative signals due to detector noise. Offset spectra can be measured in dark (either cover the lens of the telescope or block the light path by the shutter) with very short exposure time and very large number of measurements so as to minimize the noise. In this study, offset spectra were measured with an exposure time of 13 ms per scan and each spectrum is the sum of 1,000 continuous scans. Figure 3.9 (b) and Figure 3.10 (b) show the offset spectra of UV and VIS bands measured on 07 December 2015. Since an offset is added to each scan, the measured spectra

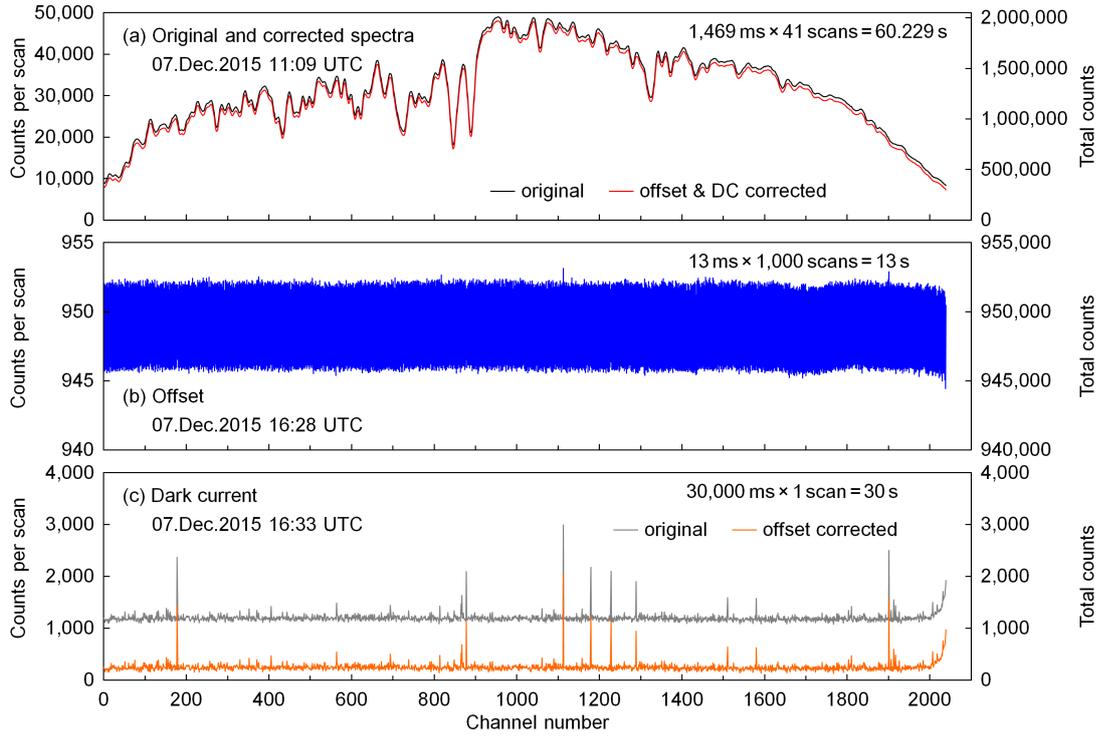


Figure 3.9: Example of offset and dark current correction for a UV spectrum measured on 07 Dec 2015. (a) Measured spectrum, before (black) and after (red) offset and dark current correction; (b) Offset spectrum; (c) Dark current spectrum, before (gray) and after (orange) offset correction. The y-axes on the left side refer to the counts per each scan, while the y-axes on the right side refer to the total counts of each spectrum.

are corrected with the following equation,

$$I_{\text{OFS\_corrected}}(n) = I(n) - \frac{N_{\text{meas}}}{N_{\text{ofs}}} \cdot O(n), \quad (3.1)$$

where  $n$  is the channel number,  $I(n)$  and  $I_{\text{OFS\_corrected}}(n)$  are the light intensity counts of the original and corrected spectra at the  $n^{\text{th}}$  channel, respectively.  $N_{\text{meas}}$  is the number of scans of the measured spectrum, and  $N_{\text{ofs}}$  is the number of scans of the offset spectrum, which is 1,000 in the study.  $O(n)$  is the total intensity count of the offset spectrum at the  $n^{\text{th}}$  channel, which is the sum of  $N_{\text{ofs}}$  scans.

Dark current is the result of thermal excitation of the electrons in the valence band of the semiconducting CCD into the conduction band without the influence of photons. Dark current spectra can also be measured in dark but with very long exposure time, so as to accumulate the influence from dark current. In

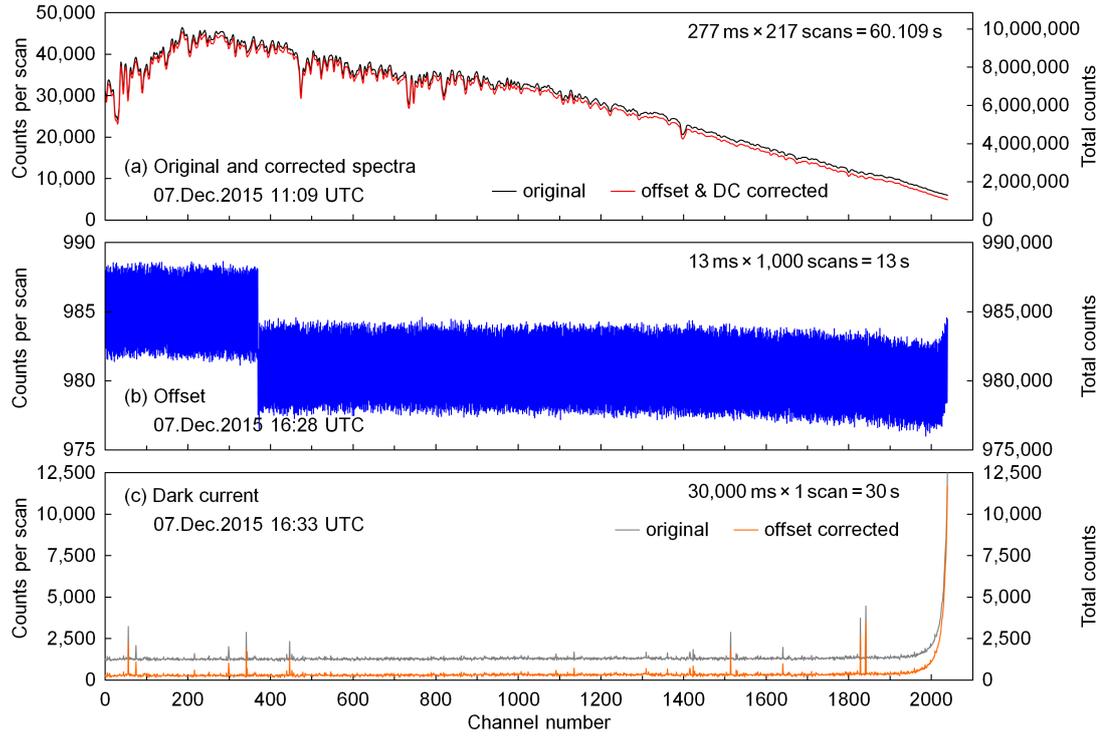


Figure 3.10: Same as Figure 3.9, but for a VIS spectrum measured on 07 Dec 2015.

this study, offset spectra were measured with an exposure time of 30 s and each offset spectrum records the result of only one scan. The dark current spectra also contain offset and need to be firstly corrected with Eq. (3.1), where  $N_{\text{meas}}$  is 1. (But it is unnecessary to correct dark current from the offset spectra, because the influence from dark current is already minimized.) Figure 3.9 (c) and Figure 3.10 (c) show the dark current spectra of UV and VIS bands measured on 07 December 2015, the gray and orange curves show the offset spectra before and after offset correction, respectively. Dark current is assumed to be proportional to exposure time, therefore the offset-corrected spectra are then corrected for dark current with the following equation,

$$I_{\text{OFS\&DC\_corrected}}(n) = I_{\text{OFS\_corrected}}(n) - \frac{t_{\text{meas}}}{t_{\text{DC}}} \cdot D_{\text{OFS\_corrected}}(n), \quad (3.2)$$

where  $t_{\text{meas}}$  and  $t_{\text{DC}}$  are the total exposure times of the measured spectrum and the dark current spectrum, respectively.  $D_{\text{OFS\_corrected}}(n)$  is the offset-corrected intensity count of the dark current spectrum at the  $n^{\text{th}}$  channel.  $I_{\text{OFS\&DC\_corrected}}(n)$

represents the light intensity count of the measured spectrum at the  $n^{\text{th}}$  channel after both offset and dark current corrections.

Figure 3.9 (a) and Figure 3.10 (a) show examples of UV and VIS spectra before and after the offset and dark current correction. The black curves represent the original spectra, while the red curves refer to the corrected spectra. The corresponding offset and dark current spectra are shown in Figure 3.9 (b, c) and Figure 3.10 (b, c).

Offset and dark current may slightly change from time to time, therefore we measure offset and dark current spectra every night, and the spectra measured during daytime are corrected with the offset and dark current measured on the same day.

### 3.2.6 Wavelength calibration

Each data point of the spectrum represents the light intensity at a certain wavelength. However, the exact wavelength corresponding to each point is unknown from the raw data. Usually, wavelength information can be obtained from the spectrum of the light with well-known structures like the sunlight or the light from mercury-vapor lamp. In this study, our calibrations were preformed by fitting measured solar spectrum to literature solar reference. Comparing to mercury-vapor lamp, the solar spectrum is continuous and has much more characteristic points, so that the calibration can be more accurate.

Figure 3.11 shows an example of wavelength calibration for the UV spectrometer. The blue curve in Panel (a) shows the high-resolution (0.01 nm) solar spectrum obtained from literature (Chance and Kurucz, 2010). It was first convolved with the slit function of the spectrometer, which is a Gaussian function with  $\text{FWHM} = 1.1 \text{ nm}$ . The convolved spectrum is shown as the red curve in Panel (a). Panel (b) shows the spectrum of scattered sunlight measured by the UV spectrometer on 07 December 2015 at 11:09 UTC, which has a similar structure as the convolved solar spectrum in Panel (a). The characteristic peaks of the measured spectrum can be mapped with the corresponding points of the convolved solar spectrum. In this way, we selected 41 characteristic points and obtained their corresponding wavelengths from the literature spectrum, marked as gray lines in Figure 3.11. As shown in Figure 3.12, a 3<sup>rd</sup> order polynomial regression was applied between the channel numbers of the characteristic points and their corresponding wavelengths. The regression function and the correlation

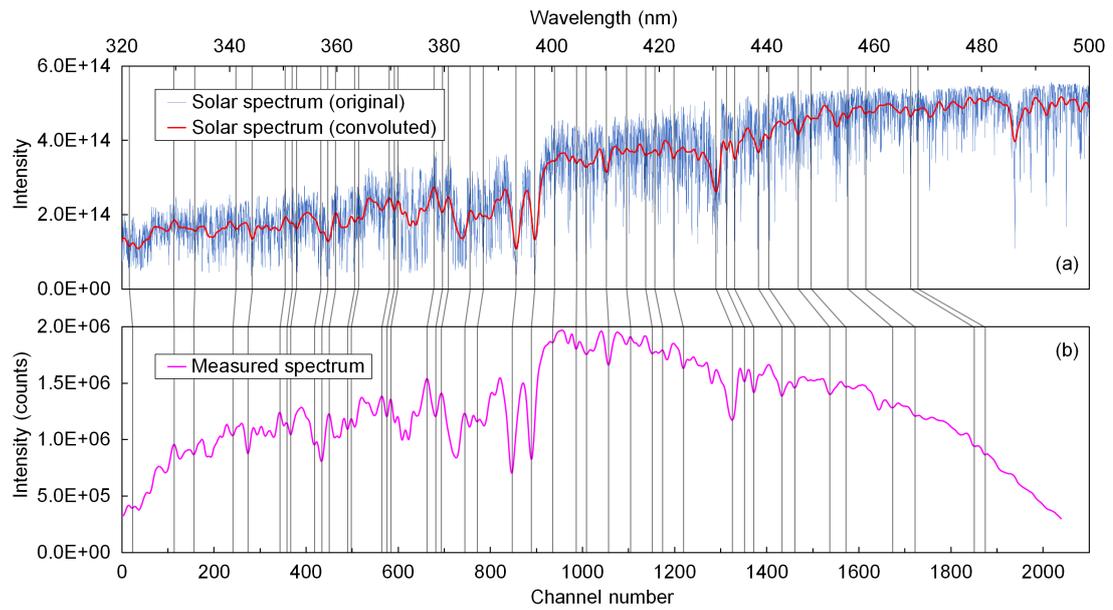


Figure 3.11: An example of wavelength calibration. (a) Standard solar spectrum from literature (Chance and Kurucz, 2010), the blue curve shows the original high-resolution (0.01 nm) spectrum, the red curve shows the spectrum convoluted with the slit function of the UV spectrometer (a Gaussian function with FWHM = 1.1 nm); (b) Scattered sunlight spectrum measured by the UV spectrometer on 07 Dec 2015 at 11:09 UTC. The gray lines mark the correspondence between the characteristic points of the measured spectrum and the convoluted literature spectrum.

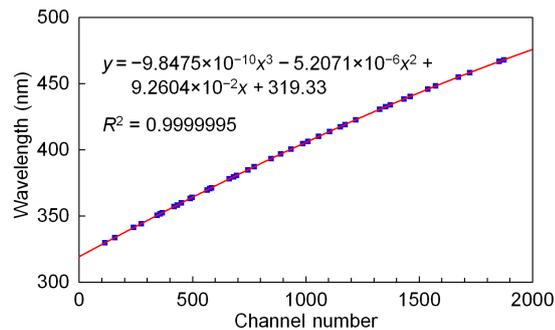


Figure 3.12: 3<sup>rd</sup> order polynomial regression of the channel numbers of the selected characteristic points shown in Figure 3.11 versus their corresponding wavelengths.

coefficient are shown in the figure. The regression shows very good correlation, therefore the accurate wavelengths corresponding to all the photodetector channels can be derived from the regression function. The VIS spectrometer was

calibrated in the same way.

### 3.3 Auxiliary measurements

#### 3.3.1 Sun photometer

Next to the MAX-DOAS instrument, a sun photometer was installed at the UFS, which provided measurements of radiances at 12 wavelengths between 340 and 1640 nm with a temporal resolution of 1 s. The instrument was developed at the Meteorological Institute of Ludwig Maximilian University of Munich (LMU) based on a system operated in the framework of the SAMUM campaigns (Toledano et al., 2009, 2011) but with improved electronics and data acquisition developed by Physikalische Messsysteme Ltd.

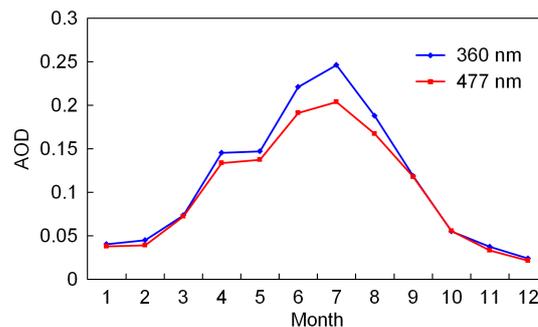


Figure 3.13: Annual variation pattern of AODs measured by the sun photometer at the UFS, averaged from the data from Jan 2012 to Feb 2016. Only the data from 10:00 to 14:00 UTC and under cloud-free conditions were used. The data of 360 nm were interpolated from the measurements at 340 and 380 nm, while the data of 477 nm were interpolated from the measurements at 440 and 500 nm.

In this study, the AODs derived from sun photometer measurements applying the well-established Rayleigh calibration method were used for the intercomparison with the MAX-DOAS retrieval. For this purpose, AOD measurements at 340 and 380 nm were interpolated to 360 nm while AODs at 477 nm were interpolated from the measurements at 440 and 500 nm. The interpolation followed the Ångström exponent method. Measurements were given as hourly averages. Due to the reduced accuracy under large SZAs, only the measurements between 10:00 and 14:00 UTC each day were used. In order to ensure the data quality, only cloud-free conditions and periods of stable aerosol abundance (variability

of radiances below 5% within 1 h) were considered. These requirements reduce the number of available sun photometer measurements considerably. Note that the AOD is often below 0.02 at the relevant wavelengths with an uncertainty on the order of  $\pm 0.015$  due to calibration errors, Rayleigh correction, and radiometric accuracy. Figure 3.13 shows the annual variation pattern of the interpolated AODs at 360 and 477 nm. The results show that the AOD at the UFS is high in summer and low in winter. For both wavelengths, the average AOD in July is higher than that in December by a factor of  $\sim 10$ . In addition, the AOD at 360 nm is slightly higher than the one at 477 nm.

As the uncertainty of the AOD measured by the sun photometer is relatively large, the uncertainty of the Ångström exponent would be further amplified. Consequently, they were not used in this study.

### 3.3.2 Aerosol optical property data from AERONET

The aerosol optical property data such as the single scattering albedos and phase functions are also required by the radiative transfer simulation for the MAX-DOAS aerosol retrieval. However, they were not available from the sun photometer at the UFS. In this study, these data were estimated from the AERONET (Aerosol Robotic Network, Holben et al. (1998); Dubovik et al. (2000)) measurements at Hohenpeißenberg ( $47.802^\circ\text{N}$ ,  $11.090^\circ\text{E}$ ), which is located at an altitude of 980 m and approximately 43 km north of the UFS, see Figure 3.14.

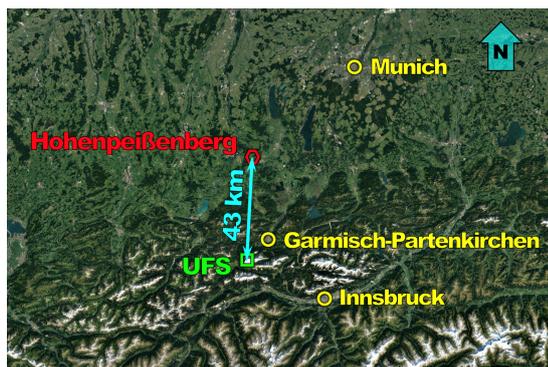


Figure 3.14: Location of the Hohenpeißenberg AERONET station, satellite image from Google Earth.

AERONET is a network of ground-based sun photometers which provides the spectral AODs from direct sun observations. The AERONET project has been

initiated by NASA (National Aeronautics and Space Administration, USA) and expanded by the federation with many other institutions. For more than two decades, AERONET has provided long-term, continuous and readily accessible database of aerosol optical, microphysical and radiative properties, which provides valuable information for aerosol research and characterization, validation of satellite retrievals, as well as the synergism with other databases.

The measurement system of the AERONET consists of the CIMEL Electronique CE318 multiband sun photometers. The latest CE318-T model has been employed since 2014, which also performs lunar measurements during nighttime. Each sun photometer consists of a sensor head fitted with a 25 cm collimator, which is attached to a 40 cm robot base that systematically points the sensor head at the sun, the sky and the moon according to a preprogrammed routine. The other components including the control unit, batteries, and Sutron satellite transmission equipment are deployed in a weatherproof plastic case.

The AERONET data are available at 440, 675, 870 and 1,020 nm, however, the data at 360 and 477 nm are needed in our study. Therefore, the data at 360 nm were extrapolated, while the data at 477 nm were interpolated.

### 3.3.3 Ceilometer

The UFS was also equipped with a Lufft (previously Jenoptik) ceilometer (model: CHM15kx, see Wiegner and Geiß (2012)) operated by the German Weather Service (DWD). Ceilometers are single-wavelength backscatter lidars, and the received signals follow the well-known lidar equation (Wiegner et al., 2014). The CHM15kx is eye-safe and fully automated which allows unattended 24/7 operation. It can be used to monitor aerosol layers (e.g., volcanic ash, see Schäfer et al. (2011)), validating meteorological and chemistry transport models (see, e.g., Emeis et al. (2011)), and is foreseen for model assimilation (e.g., Wang et al., 2014b; Warren et al., 2018; Chan et al., 2018).

The CHM15kx ceilometer is equipped with a diode-pumped Nd:YAG laser emitting laser pulses at 1,064 nm. The received backscatter signals are stored in 1,024 range bins with a resolution of 15 m. The temporal resolution was set to 15 s. The signals were corrected for incomplete overlap by a correction function provided by the manufacturer.

A strict retrieval of the particle extinction coefficient from ceilometer measurements is not possible due to the unknown lidar ratio; furthermore, exploitation

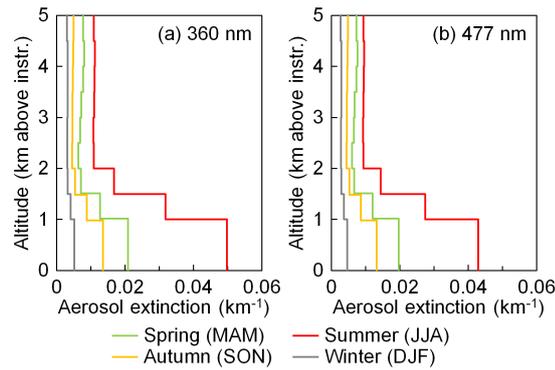


Figure 3.15: Seasonal average aerosol extinction profiles extracted from ceilometer measurements.

of the signal in the range of incomplete overlap is subject to errors. Thus, in order to convert the ceilometer measurements to aerosol extinction profiles, we followed an approach mentioned in Wagner et al. (2019). The range corrected attenuated backscatter data from July 2016 to December 2017 were seasonally averaged. Data of the altitude between 500 m and 5 km above instrument were averaged with a vertical grid resolution of 500 m. Data below 500 m were assumed to be constant, following the values at 500 m. The extinction coefficients were first calculated by scaling the attenuated backscatter profiles ( $\beta^*$ ) to the seasonal average AODs at 360 and 477 nm obtained from the sun photometer. The extinction profiles were then used to correct for the attenuation of the backscatter profiles following the lidar equation (Klett, 1981; Fernald, 1984). The corrected backscatter profiles ( $\beta$ ) were then scaled to the AODs at 360 and 477 nm measured by the sun photometer to obtain the extinction profiles, see Figure 3.15. Note that the ceilometer measures at 1,064 nm and the optical properties of aerosols depend on the wavelength. Therefore, the uncertainties of these profiles are very large and they should be considered as qualitative only.

The results shown in Figure 3.15 indicate that the aerosol load at the UFS is highest in summer (June, July and August) and lowest in winter (December, January and February). The seasonal results also indicate large variations of the aerosol load from the surface up to 2 km. The variability of aerosol extinction above 2 km is smaller, however, their contribution to the total column is still substantial ( $\sim 30 - 50\%$ ).

# Chapter 4

## Cloud screening

The aerosol profile retrieval requires the forward simulation of the radiative transfer in the atmosphere. As the radiative transfer is rather complicated for cloudy sky condition, the forward simulation usually assumes a cloud-free atmosphere. The aerosol retrieval might result in large uncertainty under cloudy or foggy conditions. Therefore, it is important to filter out the measurements taken under cloudy or foggy conditions. In this study, we developed a new cloud screening method based on the color index (CI) (Wagner et al., 2014, 2016) in order to filter out cloudy measurements.

### 4.1 Definition of color index

In this study, CI is defined as the ratio between the radiative intensities at 330 and 390 nm. Larger CI indicates the UV/VIS intensity ratio is higher, hence, the sky is bluer. Lower CI on the other hand indicates the UV intensity is much smaller than the VIS intensity, hence the sky is white (cloudy).

Measured CIs (denoted as  $CI_{\text{meas}}$ ) were calculated from the zenith UV spectra (offset and dark current corrected) by taking the ratio of the counts at 330 and 390 nm. Figure 4.1 shows the time series of  $CI_{\text{meas}}$  calculated from all the zenith spectra with  $30^\circ < \text{SZA} < 70^\circ$  during the entire study. The results show that the variation range of  $CI_{\text{meas}}$  is stable within the two periods. However, the optical throughput of the instrument in the UV spectral range has been enhanced after a regular maintenance of the optical system in 2013. Hence, the CI increased systematically in the second period. Therefore, calibration of  $CI_{\text{meas}}$  is necessary in order to make the  $CI_{\text{meas}}$  measured during the two periods comparable to each

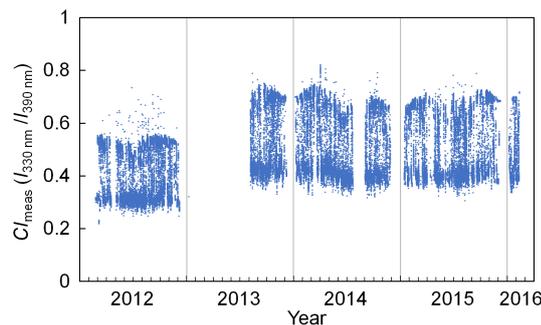


Figure 4.1: Time series of  $CI_{\text{meas}}$  (measured color indices) calculated from the zenith UV spectra measured during the entire study with  $30^\circ < \text{SZA} < 70^\circ$ .

other.

## 4.2 Calibration of color index

The calibration followed the method suggested in Wagner et al. (2016), with which  $CI_{\text{meas}}$  under overcast skies were fitted to the simulated minimum CIs ( $CI_{\text{sim, min}}$ ). In this way, measured CIs would also be comparable with simulated values. Simulated CIs were calculated using the radiative transfer model LIDORT (see Section 5.1.2). Intensities at 330 and 390 nm were simulated under given aerosol profiles and measurement geometries, and simulated CIs ( $CI_{\text{sim}}$ ) were then derived by taking the ratios of the simulated intensities at 330 and 390 nm. The other simulation parameters followed the settings used in the aerosol retrieval: the single scattering albedo was set to 0.93, the phase function was defined as the ‘median’ phase function (see Section 5.6.3), the surface albedo was set to 0.1, and the ground was defined as a flat surface at the altitude of 2,650 m. For each integer SZA between  $24^\circ$  and  $85^\circ$ , we calculated the  $CI_{\text{sim}}$  with profiles corresponding to cloud optical depths (CODs) of 2, 3, 4, 8, 12 and 50, and the minimum  $CI_{\text{sim}}$  is used as  $CI_{\text{sim, min}}$ . The cloud layer was defined as a homogeneous aerosol layer between 1 and 2 km above instrument.  $CI_{\text{sim, min}}$  under different SZAs are shown as the red curve in Figure 4.2. When SZA varies between  $30^\circ$  and  $60^\circ$ ,  $CI_{\text{sim, min}}$  varies within a very narrow range of  $0.83986 \pm 0.00088$ . This result mostly agrees with the result reported in Wagner et al. (2016), that  $CI_{\text{sim}}$  varies between 0.816 and 0.847 when SZA varies between  $30^\circ$  and  $60^\circ$ .

For each period, all the  $CI_{\text{meas}}$  with  $30^\circ < \text{SZA} < 60^\circ$  were divided by the  $CI_{\text{sim, min}}$  under the corresponding SZA, and the results are denoted as

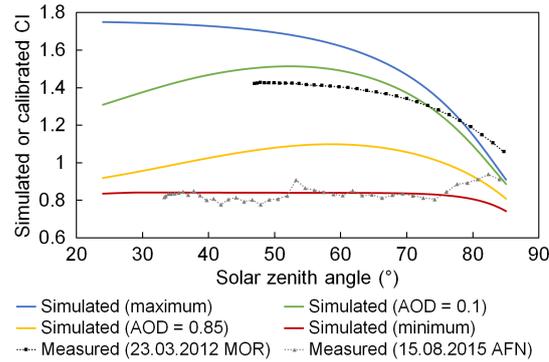


Figure 4.2: Comparison of  $CI_{\text{sim}}$  (simulated color indices) and  $CI_{\text{cal}}$  (calibrated measured color indices). The blue curve shows the maximum  $CI_{\text{sim}}$  under different SZAs, which were simulated with an aerosol-free profile. The green curve shows the  $CI_{\text{sim}}$  for  $\text{AOD} = 0.1$ , simulated with a homogeneous aerosol layer between 0 and 1 km above ground. The orange curve shows the  $CI_{\text{sim}}$  for  $\text{AOD} = 0.85$ , simulated with a homogeneous aerosol layer between 0 and 1 km above ground. The red curve indicates the  $CI_{\text{sim}, \text{min}}$  (minimum simulated color indices) under different SZAs, derived from the minimum value among the  $CI_{\text{sim}}$  for CODs of 2, 3, 4, 8, 12 and 50. The black square markers show the  $CI_{\text{cal}}$  on the morning of 23 Mar 2012 which was cloud-free, and the AOD measured by the sun photometer around the noon was  $\sim 0.1$ . The gray triangle markers show the  $CI_{\text{cal}}$  on the afternoon of 15 Aug 2015, during which the site was covered by heavy fog.

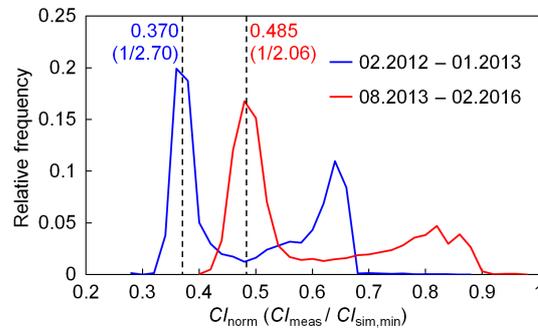


Figure 4.3: Frequency distribution (for bins of 0.02) of  $CI_{\text{norm}}$  (normalized color indices) with  $30^\circ < \text{SZA} < 60^\circ$ .  $CI_{\text{norm}}$  is the ratio between  $CI_{\text{meas}}$  and  $CI_{\text{sim}, \text{min}}$  under the same SZA.

$CI_{\text{norm}}$ . The frequency distribution of the  $CI_{\text{norm}}$  during the two periods are shown in Figure 4.3. During each period, there is a clear peak at the lower  $CI_{\text{norm}}$  value, corresponding to measurements under overcast skies. For each period, the inverse of the peak value was used as the CI correction factor  $\beta$ , and  $CI_{\text{meas}}$  was converted to  $CI_{\text{cal}}$  by multiplying the factor:

$$CI_{\text{cal}} = CI_{\text{meas}} \cdot \beta. \quad (4.1)$$

By fitting each peak to a Gaussian function,  $\beta$  was determined to be 2.70 and 2.06 for the periods of 02.2012–01.2013 and 08.2013–02.2016, respectively. For each period, the  $CI_{\text{meas}}$  of all the zenith measurements (also including the measurements with  $\text{SZA} < 30^\circ$  or  $> 60^\circ$ ) were calibrated with the same factor.

### 4.3 Definition of cloud screening threshold

Wagner et al. (2016) suggested to use the  $CI_{\text{sim}}$  under  $\text{AOD} = 0.85$  as the threshold for distinguishing a cloud covered sky. However, comparing to the  $CI_{\text{cal}}$  measured at the UFS, it is found that  $CI_{\text{sim}}$  is significantly underestimated under large SZAs. As shown in Figure 4.2, when the SZA is larger than  $80^\circ$ ,  $CI_{\text{cal}}$  measured under clear sky (the black curve) can exceed the maximum  $CI_{\text{sim}}$  (the blue curve, simulated under aerosol free condition), and  $CI_{\text{cal}}$  measured in foggy weather (the gray curve) can also exceed  $CI_{\text{sim}}$  under  $\text{AOD} = 0.85$  (the yellow curve). Therefore, we have to either use another threshold or further calibrate the measured CIs.

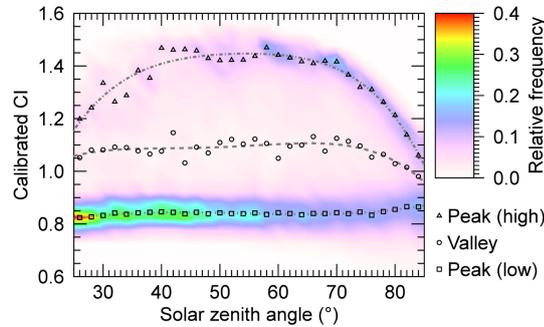


Figure 4.4: Distribution pattern of  $CI_{\text{cal}}$  (calibrated color indices) during the entire study. Data were grouped by SZA with an interval of  $2^\circ$ . For each group, frequency was counted for bins of 0.05. Peak and valley values (shown as markers) were determined by Gaussian fit. The curves are the results of 4<sup>th</sup> order polynomial regressions of each data series.

In order to determine the threshold for cloud screening, we first analyzed the distribution pattern of  $CI_{\text{cal}}$  from the long-term data, see Figure 4.4. The  $CI_{\text{cal}}$  from the long-term measurement were grouped by SZA with a step size of  $2^\circ$ . The relative frequency distributions are color coded in Figure 4.4. Regardless of the

SZA,  $CI_{\text{cal}}$  shows bimodal frequency distributions. The two peaks with lower and higher CI (square and triangle markers) correspond to the measurements under overcast and clear skies, respectively. This pattern is similar to the CI measured on Jungfraujoch (a mountain saddle in the Swiss Alps, located at an altitude of 3,570 m a.s.l) reported in Gielen et al. (2014), but different from the results measured at the low-altitude sites reported in Gielen et al. (2014) and Wagner et al. (2016). This is because the high-altitude sites are seldom influenced by anthropogenic aerosols, hence the sky is either clear or covered by clouds or fog during most of the time.

Based on this feature, we defined SZA-dependent CI thresholds for cloud screening according to the long-term frequency distribution of  $CI_{\text{cal}}$ . For each SZA ( $24^\circ$ – $85^\circ$ ), the threshold was defined as the  $CI_{\text{cal}}$  with the minimum probability (i.e., the valley of distribution) between the two distribution peaks, denoted as  $CI_{\text{cal, valley}}$ .  $CI_{\text{cal, valley}}$  was determined by fitting the probability density function to a Gaussian function. The circle markers shown in Figure 4.4 indicate the determined  $CI_{\text{cal, valley}}$ . In order to minimize the noise, the SZA- $CI_{\text{cal, valley}}$  curve was smoothed by a 4<sup>th</sup> order polynomial fitting, shown as dashed curve in Figure 4.4. Finally, the smoothed  $CI_{\text{cal, valley}}$  at each SZA was used as the threshold of  $CI_{\text{cal}}$  for cloud screening. The threshold values can be calculated as

$$CI_{\text{threshold}}(\theta) = -1.304 \times 10^{-7}\theta^4 + 2.551 \times 10^{-5}\theta^3 - 1.822 \times 10^{-3}\theta^2 + 5.699 \times 10^{-2}\theta + 0.4246, \quad (4.2)$$

where  $\theta$  is the SZA in degrees.

## 4.4 Summary of results

The cloud screening results during the entire measurement period ( $SZA < 85^\circ$ ) are summarized in Table 4.1. Among the four seasons, the percentage of cloudy measurements is highest in summer and lowest in winter. In total, about 60% of the zenith measurements were identified as cloudy scenes, and the corresponding scanning cycles were not used in the aerosol profile retrieval.

Table 4.1: Summary of cloud screening results (SZA &lt; 85°).

Season	Number of		Percentage of
	measurements	cloudy measurements	
Spring (Mar, Apr, May)	17,728	10,677	60.2%
Summer (Jun, Jul, Aug)	21,360	14,259	66.8%
Autumn (Sep, Oct, Nov)	24,259	13,519	55.8%
Winter (Dec, Jan, Feb)	17,007	9,264	54.5%
Annual	80,354	47,719	59.4%

# Chapter 5

## Retrieval of aerosol profiles

In this chapter, we present the retrieval of aerosol extinction profiles from MAX-DOAS measurements. We found the algorithms based on the optimal estimation method are not suitable for the measurements at the UFS. Therefore, we developed a new aerosol profile retrieval algorithm based on the parametrization approach.

### 5.1 Basic principle of aerosol profile retrieval

#### 5.1.1 Influence of aerosols on $O_4$ absorption

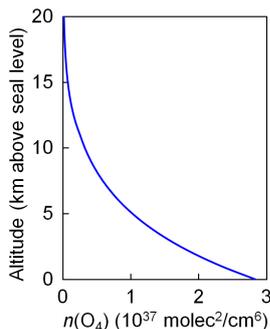


Figure 5.1: Vertical profile of  $O_4$  (oxygen dimer) in the atmosphere (Anderson et al., 1986).

As already mentioned in Section 2.4.4, the retrieval of aerosol profiles from MAX-DOAS measurements takes advantage of  $O_4$  absorption.  $O_4$ , also denoted as  $O_2-O_2$ , is the dimer of oxygen molecule ( $O_2$ ), and its concentration is in

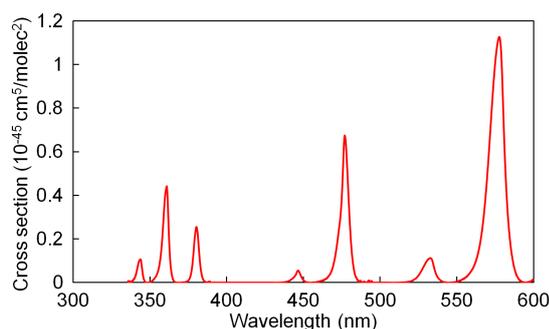


Figure 5.2: Absorption cross section of  $O_4$  at 273 K (Thalman and Volkamer, 2013).

direct proportion to the square of the concentration of  $O_2$ . As the actual concentration of  $O_4$  is unknown, the concentration of  $O_4$  is usually denoted as the square of the concentration of  $O_2$  (i.e.,  $(\text{molec}/\text{cm}^3)^2 = \text{molec}^2/\text{cm}^6$ ) in atmospheric studies. Therefore, the commonly used unit of  $O_4$  SCD and DSCD is  $\text{molec}^2/\text{cm}^5$ , which comes from  $(\text{molec}^2/\text{cm}^6) \cdot \text{cm}$ . As the vertical distribution of  $O_2$  in the atmosphere is stable and well-known, the vertical profile of  $O_4$  is also stable and well-known, see Figure 5.1. In addition, the concentration of  $O_4$  decreases with increasing altitude more rapidly than that of  $O_2$ .  $O_4$  molecules have optical absorption peaks at 360, 477, 577 and 630 nm (see Figure 5.2), and the absorption can be detected by DOAS instruments. Since MAX-DOAS instruments measure the spectra of scattered sunlight at the bottom of the atmosphere,  $O_4$  can be used as the tracer of the light path of the received photons.

Unlike direct sun instruments, all the photons received by MAX-DOAS telescopes are scattered by atmospheric molecules and aerosols. As illustrated in Figure 5.3, the total light path of the received photons can be divided into three segments:

a. In Segment (1), the incident sunlight penetrates into the atmosphere along a direct path. The penetration depth is determined by the optical depth with respect to Rayleigh and Mie scattering. It is in general larger for larger wavelength (due to the wavelength dependence of Rayleigh scattering), lower aerosol load and smaller SZA.

b. In Segment (2), the photons might enter a multiple scattering layer. Especially inside thick clouds, multiple Mie-scattering can cause extended layers of diffuse radiation in which the direction of photons would become random, see Figure 5.3 (a). However, when there are very few particles in the atmosphere, the

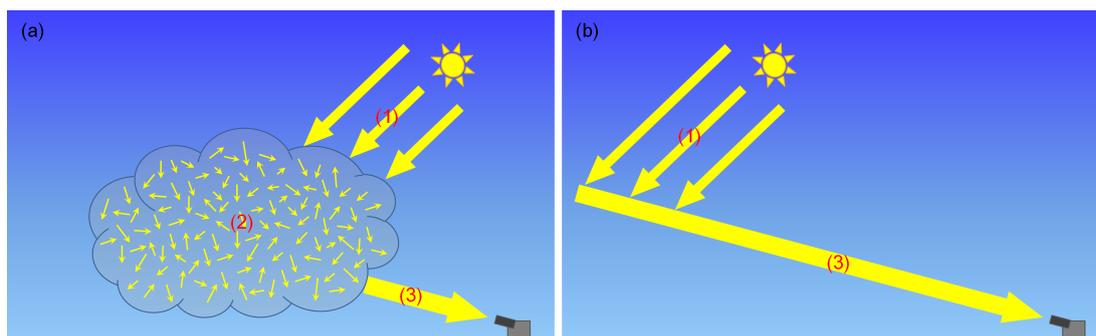


Figure 5.3: Scheme of the different segments of the atmospheric light paths for MAX-DOAS observations. Panel (a) shows the situation in an atmosphere with aerosol scattering, and Panel (b) shows the situation in an atmosphere without aerosol scattering. In each panel, (1) refers to the segment of incident direct solar radiation, (2) refers to the segment of diffuse photon scattering caused by aerosols, and (3) refers to the line of sight of the telescope.

optical depth of the atmosphere would be rather small and no significant multiple scattering layer would be established, see Figure 5.3 (b).

c. In Segment (3), the photons are scattered into the field of view of the telescope. Similar to the first segment, the length of the direct light path along the line of sight of the telescope depends on the optical depth with respect to Rayleigh and Mie scattering. For low elevations, the length of the direct light path along the line of sight is directly related to the visibility of the atmosphere close to the ground.

In a word, atmospheric aerosols can change the light path of the photons received by the MAX-DOAS telescope. Since the concentration of  $O_4$  decreases rapidly with increasing altitude, different light paths in the atmosphere would result in different  $O_4$  absorptions measured by MAX-DOAS instruments. The influence also differs at different measurement geometries. As the majority of the atmospheric  $O_4$  is distributed close to the ground, the observed  $O_4$  absorption is mostly correlated to the length of the direct line of sight of the telescope (Segment (3) mentioned above), especially for low elevations. Comparing Panel (a) to Panel (b) of Figure 5.3, additional aerosol scattering would decrease the length of the direct line of sight and hence decrease the  $O_4$  absorption. In addition, the reduction is more significant for low elevations. On the other hand, aerosols can increase the number of scattering events, especially in the case of extended clouds. This effect would result in a simultaneous increase of the  $O_4$  absorptions measured

at all elevations. Moreover, the characteristic distribution of atmospheric O<sub>4</sub> makes MAX-DOAS O<sub>4</sub> measurements sensitive to the vertical distribution of atmospheric aerosols. The quantitative influence of aerosols on O<sub>4</sub> absorption is shown in Sections 5.6.4, 5.6.5, and 5.6.6.

In order to observe the vertical distribution of aerosols in the atmosphere, MAX-DOAS instruments measure the spectra at the zenith direction and several off-zenith directions in each scanning cycle. In the retrieval, the zenith spectrum of each scanning cycle is used as the reference spectrum, and the DSCDs of O<sub>4</sub> are derived from the off-zenith spectra using the DOAS method. The aerosol extinction profile is then retrieved from the DSCDs of O<sub>4</sub>.

### 5.1.2 Radiative transfer modeling

In order to retrieve aerosol extinction profiles from MAX-DOAS O<sub>4</sub> measurements, it is necessary to obtain simulated O<sub>4</sub> DSCDs corresponding to given atmosphere scenarios. In MAX-DOAS studies, the simulation is based on radiative transfer modeling.

The radiative transfer in the atmosphere is determined by the interactions of radiation with the atmospheric compounds and the surface of the earth. These interactions include absorption, scattering, refraction, thermal emission and reflection. The Radiative Transfer Equation (RTE) (e.g., Chandrasekhar, 1960; Stamnes et al., 1988) describes their influences on the radiance intensity. Radiative transfer models (RTMs) are aimed at solving the RTE in order to calculate the radiance intensity acquired by a specific instrument under a certain atmospheric scenario. For O<sub>4</sub> and other optically thin absorbers, simulated SCDs can be derived by the following equation:

$$S = \frac{\ln \left[ \frac{I_0(\lambda)}{I(\lambda)} \right]}{\sigma(\lambda)}, \quad (5.1)$$

where  $I_0(\lambda)$  denotes the radiance intensity at the wavelength  $\lambda$  simulated without the absorber of interest considered but with all the other absorbers considered, while  $I(\lambda)$  refers to the intensity simulated with all absorbers considered.  $\sigma(\lambda)$  is the absorption cross section of the absorber of interest. According to the definition of DSCD, simulated DSCDs can be obtained by subtracting the simulated SCD at the zenith viewing angle from the simulated SCDs at off-zenith viewing angles.

In this study, the Linearized Discrete Ordinate Radiative Transfer (LIDORT)

model (Spurr et al., 2001; Spurr, 2008) was used to simulate  $O_4$  DSCDs and radiance intensities (except the three-dimensional simulations carried out in Section 5.5). LIDORT solves the RTE based on the discrete ordinate method. This model considers a pseudo-spherical multi-layered atmosphere which includes several anisotropic scatters. The formulation implemented corrects for the atmosphere curvature in the solar and single-scattered beams, however the multiple scattering term is treated in the plane-parallel approximation. The properties of each of the atmospheric layers are considered homogenous. Using finite differences for the altitude derivatives, this linearized code converts the problem into a linear algebraic system. Through first-order perturbation theory, it is able to provide radiance field and radiance derivatives with respect to atmospheric and surface variables (Jacobians) in a single call. LIDORT has been used in several MAX-DOAS studies to retrieve vertical profiles of aerosols or trace gases (e.g., Cl  mer et al., 2010; Hendrick et al., 2014; Franco et al., 2015; Wang et al., 2014a).

## 5.2 Retrieval based on the optimal estimation method

In most of the other MAX-DOAS studies (e.g. Frie   et al. (2006); Cl  mer et al. (2010); Frie   et al. (2011); Irie et al. (2011); Wang et al. (2014a, 2016); Chan et al. (2017), aerosol profiles were retrieved using the optimal estimation method (OEM) (Rodgers, 2000).

### 5.2.1 Principle

In OEM-based retrievals, the aerosol profile is regarded as the state parameter ( $\mathbf{x}$ ), the measured  $O_4$  DSCDs of each scanning cycle are regarded as the measurement vector ( $\mathbf{y}$ ), the simulation of  $O_4$  DSCDs is described as the forward model ( $\mathbf{F}$ ), and the profile retrieval is an inverse problem. As the sensitivity of  $O_4$  DSCD to aerosol extinction varies strongly with altitude, the retrieval is a non-linear problem. Moreover, the inverse problem is ill-posed, which means the information contained in the observation is insufficient to determine a unique solution.

The inversion of the aerosol profile is solved iteratively using the Gauss-Newton method,

$$\mathbf{x}_{i+1} = \mathbf{x}_i + (\mathbf{S}_a^{-1} + \mathbf{K}_i^T \mathbf{S}_\epsilon^{-1} \mathbf{K}_i)^{-1} \cdot [\mathbf{K}_i^T \mathbf{S}_\epsilon^{-1} (\mathbf{y} - \mathbf{F}(\mathbf{x}_i)) - \mathbf{S}_a^{-1} (\mathbf{x}_i - \mathbf{x}_a)], \quad (5.2)$$

where  $\mathbf{x}_i$  denotes the state vector of the  $i^{\text{th}}$  iteration, and  $\mathbf{x}_a$  is the a priori profile.  $\mathbf{K}_i$  is the weighting function matrix (Jacobi matrix) of the  $i^{\text{th}}$  iteration, which describes the sensitivity of the O<sub>4</sub> DSCDs to the changes in the aerosol profile.  $\mathbf{S}_a$  and  $\mathbf{S}_\epsilon$  are the uncertainty covariance matrices of a priori and measurements, respectively.  $\mathbf{S}_a$  and  $\mathbf{S}_\epsilon$  have different definitions in different studies (Frieß et al., 2016). In the retrieval of each scanning cycle, the state vector is first set as the a priori profile ( $\mathbf{x}_0 = \mathbf{x}_a$ ). The forward model is then applied to the state vector, and the state vector is corrected with Eq. (5.2). A cost function which is used to judge the convergence of the iteration is usually defined as

$$\chi^2 = [\mathbf{y} - \mathbf{F}(\mathbf{x})]^T \cdot \mathbf{S}_\epsilon^{-1} \cdot [\mathbf{y} - \mathbf{F}(\mathbf{x})] + (\mathbf{x} - \mathbf{x}_a)^T \cdot \mathbf{S}_a^{-1} \cdot (\mathbf{x} - \mathbf{x}_a). \quad (5.3)$$

The inversion works iteratively until the cost function is smaller than a pre-defined threshold.

### 5.2.2 Limitations

The MAX-DOAS aerosol profile retrieval algorithms based on the OEM have some limitations. First, as the retrieval is ill-posed and errors exist in the measurement and simulation, the profile with the lowest cost function may not be the one closest to the true profile. In addition, due to the limitation of computing power, the iteration stops once the cost function is smaller than a pre-defined threshold, which means the retrieved profile is actually not the one with the lowest cost function.

An a priori profile is needed in the OEM-based retrieval. The a priori profile not only provides the initial state vector for the iteration, but also plays a part in calculating the cost function. According to Eq. (5.3), the cost function is determined by both the difference between the measured and simulated O<sub>4</sub> DSCDs and the difference between the state vector and the a priori profile. This means the retrieval minimizes both of the two differences. As a result, if the a priori profile is largely different from the true profile, the retrieval might be misled. Moreover, as the measurement sensitivity decreases rapidly with increasing altitude, the

higher part of the retrieved profile is mostly dominated by the a priori profile. The constrain from the a priori profile can be adjusted by changing the definition of its uncertainty covariance matrix  $\mathbf{S}_a$ . The constrain should be neither too strong nor too weak. If the constrain is too strong, the retrieval would be much too dependent on the a priori profile; on the other hand, a weak constrain might result in unreasonable results with large vibrations. The optimal definition of  $\mathbf{S}_a$  differs for different sites and different aerosol loads. In some cases, the balance between freedom and restrain can hardly be reached.

At the UFS and other high-altitude sites, the aerosol profile retrieval is more challenging for several reasons:

a. Due to the high altitude, the  $\text{O}_4$  concentration is much lower than the typical low-altitude sites, therefore the measurement sensitivity is systematically lower. The  $\text{O}_4$  concentration at the altitude of the UFS is 41% lower than at sea level.

b. The complicated ground topography at mountainous sites can also bring errors to the radiative transfer simulations (see Section 5.5).

c. It is found in many MAX-DOAS studies that  $\text{O}_4$  DSCDs need to be corrected by a scaling factor (see Section 5.10). However, the scaling factors for high altitude measurements are unclear.

d. The aerosol load at high-altitude sites is usually much lower than urban areas, so that the vertical gradient of aerosol extinction is also much smaller and the influence from aerosols above the retrieval height is hence much stronger.

As a result, the SNR of such high-altitude MAX-DOAS measurements is often insufficient to have a stable retrieval.

### 5.2.3 Retrieval of synthetic measurement data

In order to test the performance of OEM-based aerosol profile retrieval algorithms for the MAX-DOAS measurements at the UFS, we generated some synthetic  $\text{O}_4$  DSCDs and then retrieved aerosol profiles from the synthetic data using an OEM-based algorithm.

With each true aerosol extinction profile,  $\text{O}_4$  DSCDs at 360 and 477 nm and at the elevations of  $1^\circ$ ,  $2^\circ$ ,  $5^\circ$ ,  $10^\circ$ ,  $20^\circ$  and  $30^\circ$  were first simulated using LIDORT. In the simulation, the ground surface was defined as a flat surface at the altitude of the UFS, i.e., 2,650 m above sea level. The definitions of surface albedo, single scattering albedo, phase function and climatology followed the common settings

of the further simulations in this chapter, listed in Table 5.5. For the example shown in this section, the solar position was set as  $\text{SZA} = 60^\circ$  and  $\text{RAA}$  (relative solar azimuth angle)  $= 60^\circ$ .

Aerosol profiles were then retrieved from the synthetic  $\text{O}_4$  DSCDs using the BePRO profiling tool developed at BIRA-IASB (Cl mer et al., 2010; Hendrick et al., 2014). BePRO uses LIDORT as the forward model, which is the same as the RTM used in generating the synthetic data. The parameters related to forward simulation were also defined as same as those in generating the synthetic data. The retrieval grid was defined as 20 layers of 200 m thickness each.

BePRO constructs the uncertainty covariance matrix of a priori ( $\mathbf{S}_a$ ) as follows: in each iteration, the diagonal element of  $\mathbf{S}_a$  corresponding to the bottom layer,  $\mathbf{S}_a(1, 1)$ , is set as the square of a scaling factor  $\beta$  times the maximum partial AOD of the profiles; the other diagonal elements decrease linearly with increasing altitude to  $0.2 \times \mathbf{S}_a(1, 1)$ ; the off-diagonal elements are defined using Gaussian functions with a correlation length  $\gamma$ :

$$\mathbf{S}_a(i, j) = \sqrt{\mathbf{S}_a(i, i) \cdot \mathbf{S}_a(j, j) \cdot \exp\left[-(\ln 2) \cdot \left(\frac{z_i - z_j}{\gamma}\right)^2\right]}, \quad (5.4)$$

where  $z_i$  and  $z_j$  are the altitudes of the  $i^{\text{th}}$  and  $j^{\text{th}}$  layers, respectively (Cl mer et al., 2010; Wang et al., 2014a). The constrain from a priori profile can be adjusted by changing  $\beta$  and  $\gamma$ .

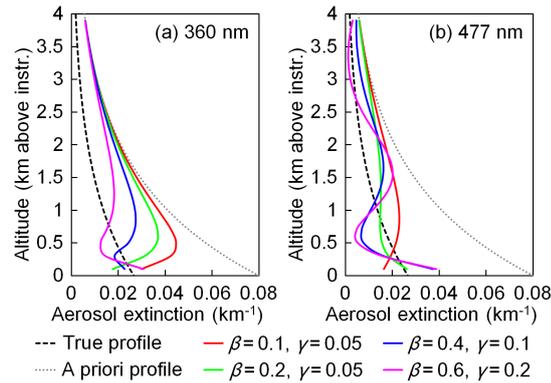


Figure 5.4: Retrieval results of a set of synthetic data at (a) 360 nm and (b) 477 nm, retrieved using BePRO. In each chart, the black dashed curve shows the true profile, the gray dotted curve shows the a priori profile of retrieval, and the solid curves in four different colors show the aerosol profiles retrieved with four different definitions of the uncertainty covariance matrix of a priori ( $\mathbf{S}_a$ ).

Figure 5.4 shows an example of the retrieval. Panels (a) and (b) show the results of 360 and 477 nm, respectively. In each panel, the black dashed curve shows the true profile, with which the synthetic O<sub>4</sub> DSCDs were simulated. In this example, the true profile is an exponential profile of which the total AOD ( $\tau$ ) is 0.04 and the scaling height (SH) is 1.5 km. The aerosol extinction at each altitude follows the following expression:

$$\sigma(z) = \frac{\tau}{SH} \cdot \exp\left(-\frac{z}{SH}\right), \quad (5.5)$$

where  $\sigma(z)$  is the aerosol extinction coefficient at  $z$  km above the MAX-DOAS instrument (2,650 m above sea level). Therefore, the surface aerosol extinction coefficient is 0.0267 km<sup>-1</sup>. The gray dotted curve shows the a priori profile of retrieval, which was defined as an exponential profile with  $\tau = 0.12$  and SH = 1.5 km. The solid curves in four different colors show the aerosol profiles retrieved with four different definitions of  $\mathbf{S}_a$ . Among the four profiles, the red curve was retrieved with the strongest constrain from the a priori profile, while the magenta curve was retrieved with the weakest constrain.

The results show that at both of the two bands, none of the retrieved profiles can reproduce the true profile. Especially at higher altitudes, even if the constrain from the a priori is set to be rather weak, the retrieved profile is still dominated by the a priori. This is because the MAX-DOAS measurements can provide very limited information for the aerosols at higher altitude. At lower altitudes, the true profile cannot be well reproduced with any of the four settings, either. In real retrievals, due to the existence of error and noise in measurement and simulation, it is even more difficult to get reliable results.

### 5.3 Retrieval using the parametrization approach

Besides the OEM-based algorithms, in some other MAX-DOAS studies (e.g., Lee et al., 2009; Li et al., 2010b; Vlemmix et al., 2011; Wagner et al., 2011; Wang, 2012; Sinreich et al., 2013), aerosol profiles were retrieved using the parametrization approach. Based on the fact that the information content of each MAX-DOAS measurement cycle is typically limited to only 2–3 independent pieces of information for the retrieved vertical profiles (Frieß et al., 2006; Clémer et al., 2010), aerosol profiles were simplified as a few parameters in these studies. These retrieval algorithms are usually based on the look-up table (LUT) method, which

means the  $O_4$  DSCDs corresponding to a limited number of aerosol profiles and viewing geometries (with discrete values of the profile parameters and viewing geometry) are pre-calculated and stored. The LUT was used as the forward model, so that the computational effort can be reduced.

In the study of Li et al. (2010b), it was assumed that the aerosol extinction coefficient within the PBL does not change with the altitude, while the aerosol extinction coefficient in the free troposphere exponentially decreases with the increasing altitude with a fixed SH. Aerosol profiles were defined by only three parameters: the AOD, the fraction of aerosols in the PBL, and the height of the PBL. The modeled  $O_4$  DSCDs corresponding to 720 possible aerosol profiles and 13 SZA-RAA combinations were pre-calculated and stored in a LUT. The aerosol profiles were retrieved by minimizing the difference between modeled and measured  $O_4$  DSCDs. The minimization procedure was conducted using the Levenberg-Marquardt algorithm.

In the study of Wagner et al. (2011), aerosol profiles were also defined by three parameters: the AOD, the layer height, and the shape parameter which describes the relative shape of aerosol profiles. Profiles with elevated layers were also considered. A LUT which includes 250,000  $O_4$  DAMF (differential air mass factor, in direct proportion to DSCD) data was created. In the aerosol profile inversion process, only the AOD and the layer height were varied, while the shape parameter was fixed. In a first step, the optimum AOD was determined for the discrete values of the aerosol layer height defined for the LUT. In a second step, a low order polynomial as a function of the aerosol layer height was fitted to the determined residual sum of squares between the measured and modeled  $O_4$  DAMFs. The optimum AOD and layer height were derived according to the minimum of the polynomial. The fitting process was conducted for different shape parameters.

Comparing to the optimal estimation approach, the parametrization approach was found to be more stable and robust, however, it cannot retrieve complex profiles (Wagner et al., 2011). In this chapter, we present a new aerosol profile retrieval algorithm developed by us. The algorithm is also based on the parametrization approach, and the LUT method is used in the retrieval.

## 5.4 O<sub>4</sub> DSCD calculation

O<sub>4</sub> DSCDs were retrieved from both UV and VIS spectra using the DOAS method (see Chapter 2). The fitting windows were determined according to both the absorption signal of O<sub>4</sub> and the SNR of the spectrometer. The fitting window of the UV spectra was defined as 338–370 nm, which is the same as most of the other MAX-DOAS studies, and it covers the strong absorption peak at 360.8 nm and a weak absorption peak at 344 nm. For the VIS spectra, because the spectral range of our spectrometer starts from 427 nm and the SNR near the border is low, the fitting window was determined to be 440–490 nm, which is somewhat narrower than the fitting window of 425–490 nm commonly used in other MAX-DOAS studies (e.g., Cl mer et al., 2010; Chan et al., 2017; Kreher et al., 2019). The VIS fitting window covers the strong absorption peak at 477 nm and a weak absorption peak at 446.5 nm.

In the aerosol profile retrieval, the DSCD is defined as the difference between the SCD of each off-zenith spectrum (elevation angle  $\alpha \neq 90^\circ$ ) and the SCD of the zenith spectrum ( $\alpha = 90^\circ$ ) measured at the same time. As the off-zenith and zenith spectra could not be measured simultaneously in the real measurements, we temporally interpolated the zenith spectra before and after each scanning cycle to the measurement time of each off-zenith spectrum, and the interpolated spectrum was used as the reference spectrum.

Details of the DOAS fit settings for both bands are listed in Table 5.1. The broad band spectral structures caused by Rayleigh and Mie scattering were removed by including a low order polynomial in the DOAS fit. Absorption cross sections of several trace gases as well as a synthetic Ring spectrum were included in the DOAS fit (See Section 2.5.2). The so-called intensity offset refers to the Fraunhofer reference spectrum included in the DOAS fit, which is used to minimize the influence from the Fraunhofer lines (see Section 2.5.1). As the temperature at the UFS typically varies between 263 K and 279 K (Risius et al., 2015), trace gas absorption cross sections measured at 273 K were used in the DOAS fit. For NO<sub>2</sub> and O<sub>3</sub>, as their absorption cross sections vary strongly with the temperature, two cross sections at different temperatures were included in the fitting. This setting was first suggested in Van Roozendaal et al. (2002) and commonly used in other MAX-DOAS studies. Small shift and squeeze of the wavelengths were allowed in the wavelength mapping process in order to compensate small uncertainties caused by the instability of the spectrograph. In this study, the

spectra evaluation software QDOAS (version 3.2) developed at BIRA-IASB was used for the spectral fitting analysis.

The root mean square (RMS) of fitting residual was used to evaluate the performance of the DOAS fit. DSCDs with a residual RMS larger than  $1 \times 10^{-3}$  were filtered out in the following analysis. Under cloud-free conditions, the residual RMS of most of the UV spectra varies between  $5 \times 10^{-4}$  and  $9 \times 10^{-4}$ , while the residual RMS of most of the VIS spectra varies between  $2 \times 10^{-4}$  and  $5 \times 10^{-4}$ . This is because both the light intensity and the O<sub>4</sub> absorption are stronger at the VIS band; hence the measurement SNR is higher.

Figure 5.5 and Figure 5.6 show examples of the DOAS fitting in the UV and VIS bands, respectively. In each figure, the off-zenith spectrum ( $\alpha = 1^\circ$ ) is shown as the red curve in Panel (a), and the reference spectrum (i.e., the interpolated zenith spectrum at the same time) is shown as the blue curve. Both of the two spectra have been corrected for offset and dark current. In Panel (b), the red curve is the total optical density ( $D$ ), which is the negative of the logarithm of the ratio between the off-zenith and reference spectra, while the blue curve is the 5<sup>th</sup> order polynomial derived by the DOAS fitting. The difference between the total optical density and the polynomial is shown as the red curve in Panel (c), and the black curve in Panel (c) is the sum of all the absorptions. The difference between the two curves in Panel (c) is the fitting residual, shown as the gray curve in Panel (d). The RMS of the fitting residual is indicated at the bottom of Panel (d). The absorptions of all the fitting species derived by the DOAS fitting are shown in Panels (e<sub>1</sub>) and (e<sub>2</sub>). Panel (e<sub>2</sub>) is the magnification of Panel (e<sub>1</sub>), in which the absorptions of minor species can be seen clearly.

Figure 5.7 shows the O<sub>4</sub> DSCDs at the UV and VIS bands measured during the daytime of 07 December 2015. The SZAs and RAAs are also shown in Panels (a) and (b), respectively. The sky was clear without clouds during the entire day. The results indicate that at both bands, the O<sub>4</sub> DSCDs are lowest at noon and decrease with increasing viewing elevation angle.

Table 5.1: The DOAS fit settings for UV (338–370 nm) and VIS (440–490 nm) bands.

Species	Temperature	Fitting window		Reference
		UV	VIS	
CHOCHO	296 K		✓	Volkamer et al. (2005b)
HCHO	273 K	✓		Chance and Orphal (2011)
H <sub>2</sub> O	296 K	✓	✓	HITEMP 2010, Rothman et al. (2010)
NO <sub>2</sub> <sup>(a)</sup>	273 K	✓	✓	Bogumil et al. (2003)
NO <sub>2</sub> <sup>(a)</sup>	220 K	✓	✓	Bogumil et al. (2003)
O <sub>3</sub> <sup>(b)</sup>	273 K	✓	✓	Serdyuchenko et al. (2014)
O <sub>3</sub> <sup>(b)</sup>	223 K	✓	✓	Serdyuchenko et al. (2014)
O <sub>4</sub>	293 K	✓	✓	Thalman and Volkamer (2013)
Ring		✓	✓	Calculated by QDOAS
Polynomial		5 <sup>th</sup> order	5 <sup>th</sup> order	
Intensity offset		linear	linear	

<sup>(a)</sup> I<sub>0</sub> correction is applied with SCD of  $1 \times 10^{17}$  molec/cm<sup>2</sup> (Aliwell et al., 2002).

<sup>(b)</sup> I<sub>0</sub> correction is applied with SCD of  $1 \times 10^{20}$  molec/cm<sup>2</sup> (Aliwell et al., 2002).

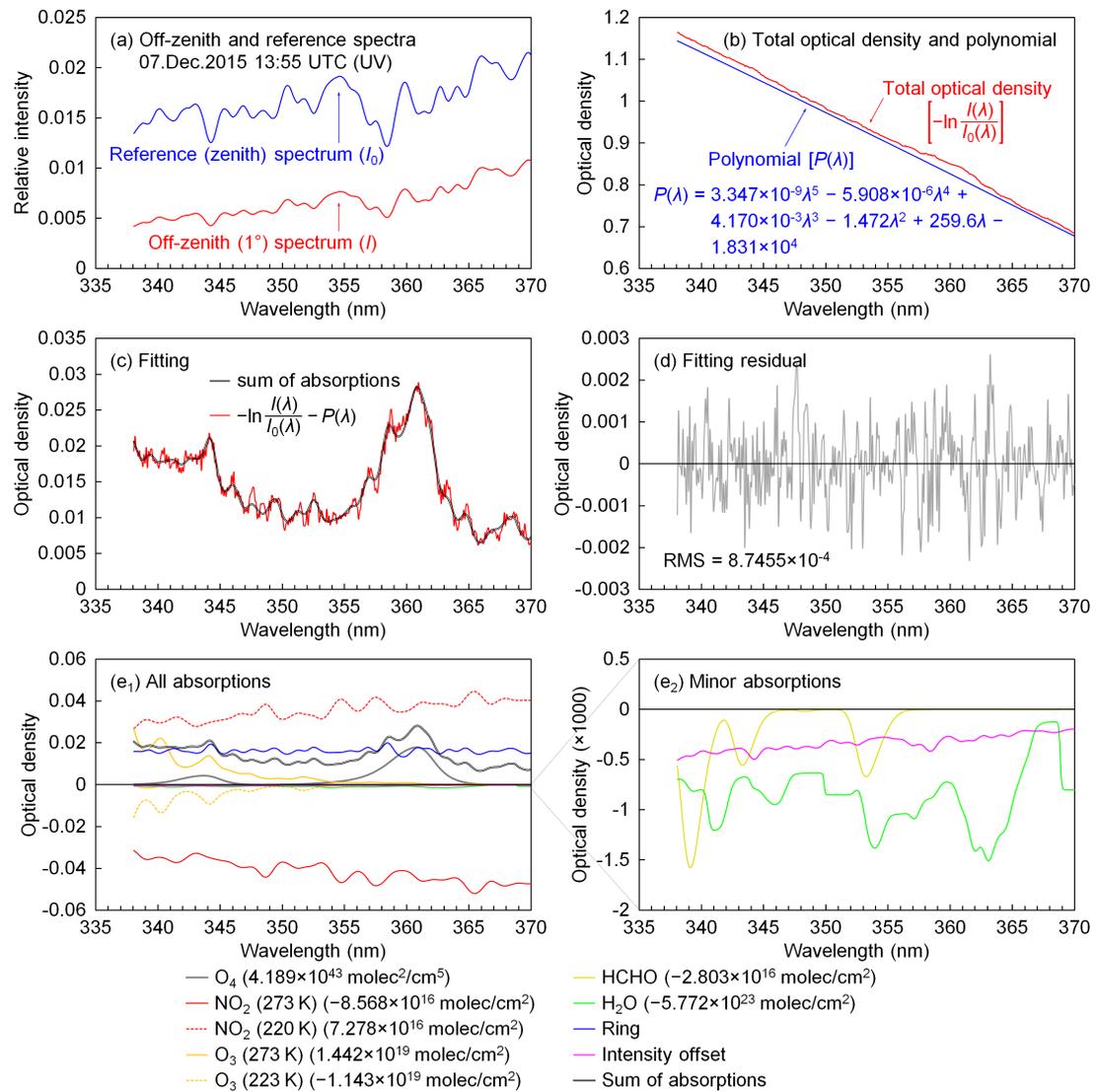


Figure 5.5: An example of the DOAS fitting in the UV band. The off-zenith spectrum was measured on 07 Dec 2015 at 13:55 UTC, at the elevation of  $1^\circ$ . (a) Off-zenith spectrum ( $I$ , red curve) and zenith reference spectrum ( $I_0$ , blue curve). (b) Total optical depth ( $D$ , red curve) and the fitted polynomial ( $P$ , blue curve). (c) Sum of all absorptions (black curve) and the difference between the total optical depth and fitted polynomial (red curve). (d) Fitting residual. (e<sub>1</sub>) Absorptions of all the fitting species derived by the DOAS fitting. (e<sub>2</sub>) Magnification of Panel (e<sub>1</sub>), absorptions of minor species.

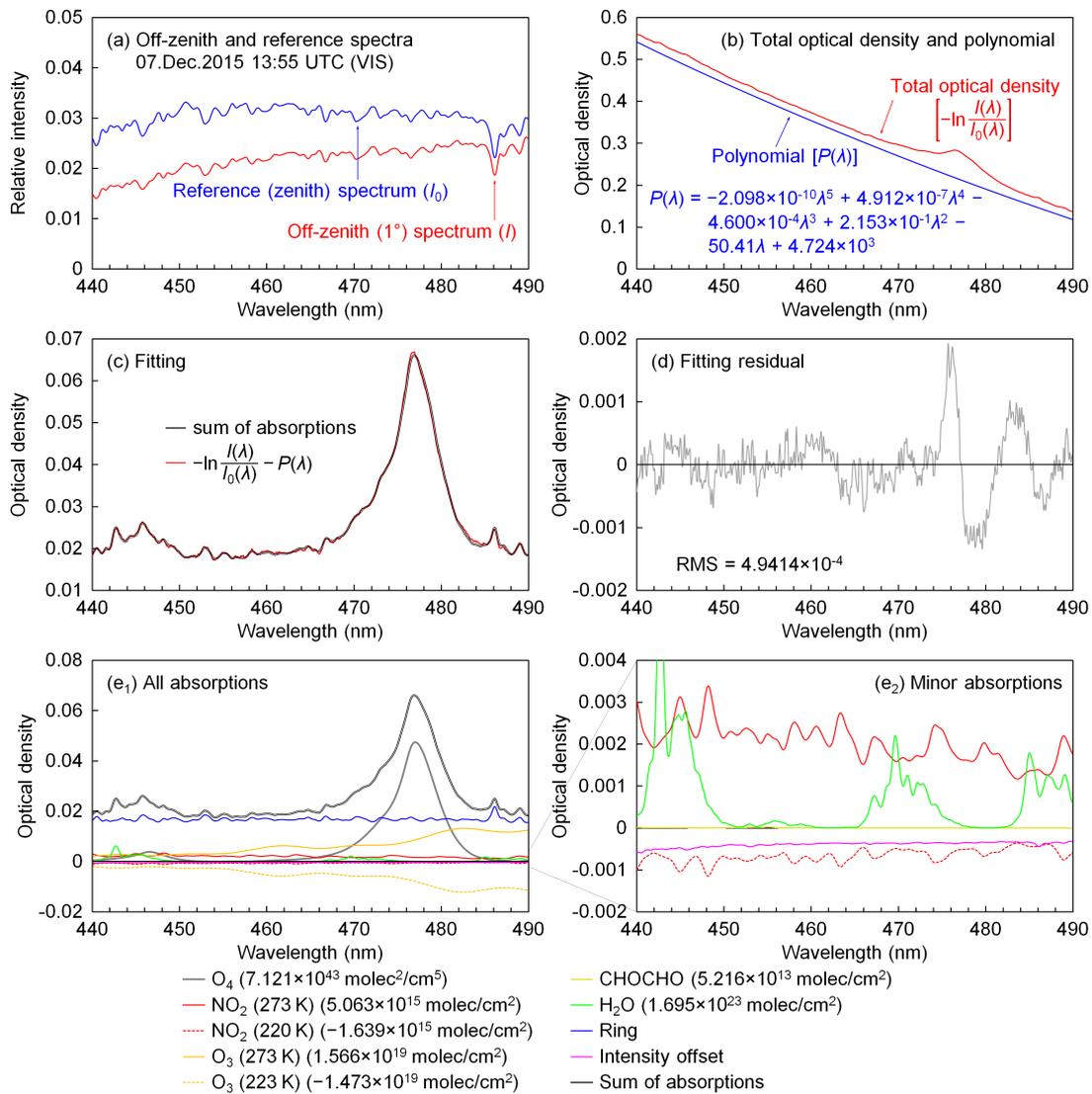


Figure 5.6: Same as Figure 5.5, but for the VIS band.

## 5.5 Topography effect and the simplification in RTM

1

The topography around the UFS is quite complex, which complicates the radiative transfer simulations. As shown in Figure 3.5, the surface altitude varies between 600 and 2,800 m a.s.l. along the viewing direction of the MAX-DOAS

<sup>1</sup>Due to the complexity of TRACY-2, the radiative transfer simulations presented in this section were performed by Prof. Dr. Thomas Wagner (MPIC-Mainz).

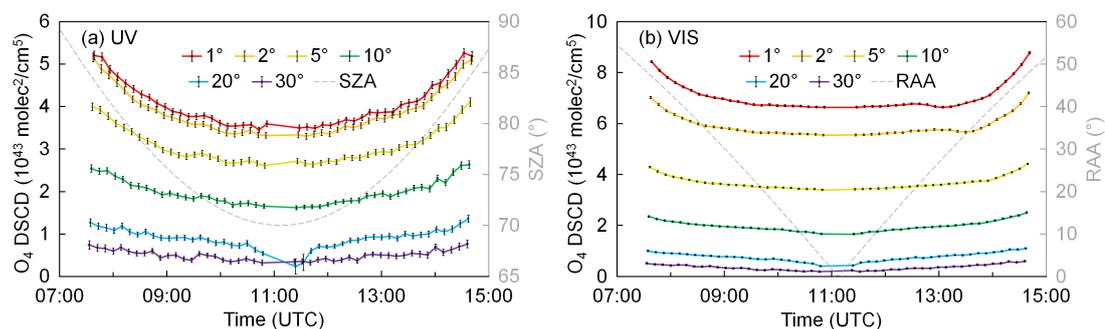


Figure 5.7: O<sub>4</sub> DSCDs at (a) UV and (b) VIS bands measured during the daytime of 07 Dec 2015, as well as the SZAs and RAAs. The error bars represent the uncertainty calculated from the RMS of fitting residual.

instrument. Figure 3.5 (b) also shows the type of surface in different colors which includes forests, meadows, rocks, etc. Some parts of the surface are seasonally or permanently covered by snow, while some steep slopes cannot be covered by snow even in winter.

Three-dimensional RTMs can consider such a complex terrain, but they are computational expensive and unaffordable for retrieval. Due to the limitation of the two-dimensional RTM LIDORT used in the study, we simplified the ground topography to a flat surface at an altitude of 2,650 m a.s.l in the radiative transfer simulations. In order to estimate the error caused by this simplification, we investigated the error using the three-dimensional RTM TRACY-2.

TRACY-2 is a full spherical Monte-Carlo atmospheric RTM (Deutschmann, 2008; Wagner et al., 2007), which allows to simulate three-dimensional radiative transport as well as two-dimensional variation of the surface height. The model was compared to other RTMs and very good agreement was found (Wagner et al., 2007). We also did an inter-comparison with LIDORT. The result shows that with the same definition of topography and atmosphere, the difference between the O<sub>4</sub> DSCDs simulated by the two RTMs is less than 3%.

For the three-dimensional simulations carried out in this study, a pseudo-reality topography was defined with the exact ground altitude (obtained from Google Earth) in the azimuth direction of the MAX-DOAS measurements taken into account, whereas in the dimension orthogonal to this direction, the surface altitude was set constant. This simplification was chosen to reduce the computational effort. Since the atmospheric light paths in the viewing direction of the instruments can be very long (up to several tens of kilometers), whereas the in-

fluence of the orography perpendicular to this direction is expected to be small, the influence from only the topography along the viewing direction is quantified in a first step.

Simulations were performed with all combinations of three different SZAs ( $30^\circ$ ,  $50^\circ$  and  $70^\circ$ ), three different RAAs ( $30^\circ$ ,  $60^\circ$  and  $90^\circ$ ) and two different aerosol extinction profiles (an aerosol-free profile and a box-shape profile with  $\text{AOD} = 0.12$  and box height = 3 km), i.e., altogether 18 cases. For each case,  $\text{O}_4$  DSCDs at 360 and 477 nm were simulated with both the flat surface at 2,650 m and the pseudo-reality topography using TRACY-2. The relative differences of  $\text{O}_4$  DSCDs simulated with the flat surface comparing to those simulated with the pseudo-reality topography were then calculated. A fixed surface albedo of 0.07 was used in the simulations. For both wavelengths, the single scattering albedo was set to 0.93 and the phase function was defined as a Henyey-Greenstein phase function with the asymmetry parameter set to 0.68. The atmospheric profile was defined as the US standard mid-latitude atmosphere (Anderson et al., 1986). Figure 5.8 shows the results of some of the cases: (a) and (b) show the results of six cases with  $\text{SZA} = 50^\circ$  and different RAAs and both aerosol extinction profiles; (c) and (d) show the results of six cases with  $\text{RAA} = 60^\circ$  and different SZAs and also both aerosol extinction profiles.

Table 5.2: Systematic and random errors caused by the topography simplification. Results were calculated from the relative differences of  $\text{O}_4$  DSCDs simulated with a flat surface at 2,650 m comparing to those simulated with the pseudo-reality surface in 18 cases (see text). The mean of the relative difference of each elevation and each wavelength was considered as the systematic error. The standard deviation of the relative difference was considered as the random error.

Elevation angle	UV (360 nm)		VIS (477 nm)	
	Systematic error (%)	Random error (%)	Systematic error (%)	Random error (%)
$1^\circ$	-3.19	1.99	-2.30	2.24
$2^\circ$	-3.69	1.64	-1.90	2.21
$5^\circ$	-3.42	1.60	-2.48	1.57
$10^\circ$	-4.12	2.32	-3.51	2.24
$20^\circ$	-4.74	3.09	-3.93	4.63
$30^\circ$	-5.08	5.44	-3.91	5.84

As shown in all the panels of Figure 5.8 as well as in all the other cases which are not shown,  $\text{O}_4$  DSCDs simulated with the flat surface are in general

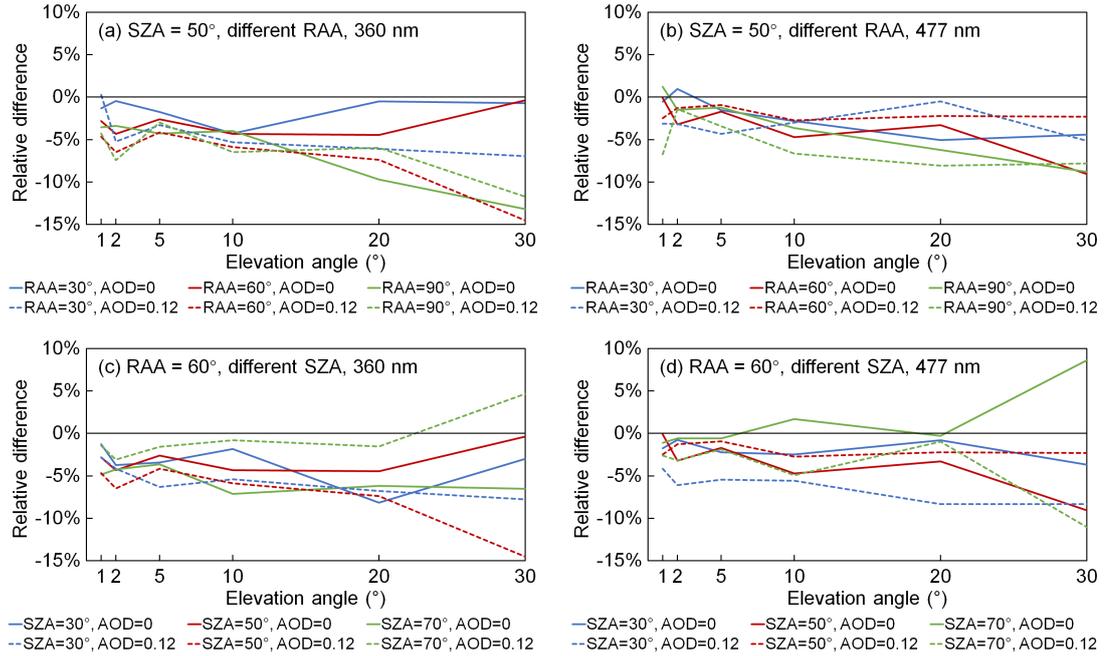


Figure 5.8: Relative differences of  $O_4$  DSCDs at (a, c) 360 nm and (b, d) 477 nm simulated with a flat surface at 2,650 m comparing to the  $O_4$  DSCDs simulated with the pseudo-reality topography. (a) and (b) show the results simulated with the same SZA of 50° and different RAAs of 30°, 60° and 90°; (c) and (d) show the results simulated with the same RAA of 60° and different SZAs of 30°, 50° and 70°. Solid lines are the results simulated under aerosol-free condition, and dashed lines are the results simulated with a box-shape profile with AOD = 0.12 and box height = 3 km.

slightly underestimated comparing to the pseudo-reality topography. The difference could be explained by the scattering in the valleys where the concentration of  $O_4$  is higher. For the flat surface at 2,650 m, the light paths below 2,650 m would not be taken into account, and hence the  $O_4$  DSCDs would be underestimated. Moreover, the relative error has no obvious correlation with the elevation angle, SZA, RAA or aerosol load. This is because the light path below 2,650 m is influenced by the topography, and the influence differs with the observation geometry. In addition, the light path is also influenced by the aerosols both below and above 2,650 m. Concerning the fact that only a pseudo-reality surface and a constant surface albedo was used in the study, the actual error caused by the topography simplification is expected to be much more complicated.

In order to make the compensation feasible, we considered the error as the combination of a systematic error and a random error. Based on the results of all

the 18 cases in this study, the mean bias of each elevation and each wavelength was considered as the systematic error, while the standard deviation of the relative difference was considered as the random error, see Table 5.2. In the aerosol profile retrieval, systematic errors were first corrected from the measured  $O_4$  DSCDs, while random errors were included in the error budget in the calculation of cost functions (see Section 5.8.2). In the following text of this chapter, measured  $O_4$  DSCDs refer to the values corrected by the systematic error unless otherwise mentioned.

## 5.6 Sensitivity analysis

In order to make full use of the measurement sensitivity and reduce unnecessary computational efforts, our retrieval algorithm was designed according to the sensitivity of  $O_4$  absorption. We performed several sensitivity tests to determine the optimal vertical grid, step size of the aerosol extinction for each layer and the maximum aerosol extinction. In addition, these sensitivity tests also help to estimate the measurement and model errors which are very important for the retrieval. The sensitivity tests are based on the forward simulations of  $O_4$  DSCDs using LIDORT.

We investigated the sensitivity of  $O_4$  absorption to surface albedo, single scattering albedo (SSA), scattering phase function, aerosol layer thickness, aerosol extinction above retrieval height, and surface aerosol extinction. In the test of each parameter,  $O_4$  DSCDs at 360 and 477 nm and at the six off-zenith elevations were simulated with the parameter being tested set as different values, while all the other parameters were fixed. In this section, we only present the results of the sensitivity tests under the common settings listed in Table 5.3 (except for Section 5.6.1, in which the results of an additional test with an aerosol-free profile are also shown). In the following subsections, all the unmentioned simulation parameters followed the common settings. The extreme and median values of each parameter are also discussed in the following subsections.

### 5.6.1 Sensitivity to surface albedo

It is difficult to determine the exact surface albedo around the measurement site. In other studies, the surface albedo at low-altitude sites was usually estimated to be 0.05–0.1 (e.g., Irie et al., 2008; Ma et al., 2013; Wagner et al., 2011; Chan et al.,

Table 5.3: The common settings for sensitivity studies.

Parameter	Value or definition
Topography	A flat surface at an altitude of 2,650 m a.s.l.
Solar zenith angle (SZA)	60°
Relative solar azimuth angle (RAA)	60°
Surface albedo	0.1
Single scattering albedo (SSA)	0.93 (360 nm) / 0.92 (477 nm)
Phase function	The 'median' phase function defined in Section 5.6.3
Aerosol extinction profile	Box-shape profile with AOD = 0.12 and box-height = 3 km (i.e., $\sigma = 0.04 \text{ km}^{-1}$ for 2,650–5,650 m a.s.l. and $\sigma = 0$ for altitude > 5,650 m)
Climatology	US standard profiles for profile, temperature and trace gas profiles

2017; Li et al., 2010b; Cl  mer et al., 2010; Li et al., 2013; Wang et al., 2016), while at a high-altitude site, it was estimated to be 0.2 (Franco et al., 2015). As for the UFS, on the one hand, the snow covers and naked rocks are more reflective than the typical urban and rural surfaces; on the other hand, the deep valleys close to the site can significantly decrease the surface albedo. In addition, the measurements at different elevations might be sensitive to different parts of the surface. The effective surface albedo also depends on the observation geometry. The forming and melting of the snow cover can affect the surface albedo as well. However, the RTM can only assume a constant surface albedo. Therefore, we have to estimate a variation range of the surface albedo and consider the possible uncertainty in the retrieval. In this study, we empirically estimated that the surface albedo varies between 0.025 and 0.2 with a median value of 0.1 for both 360 and 477 nm.

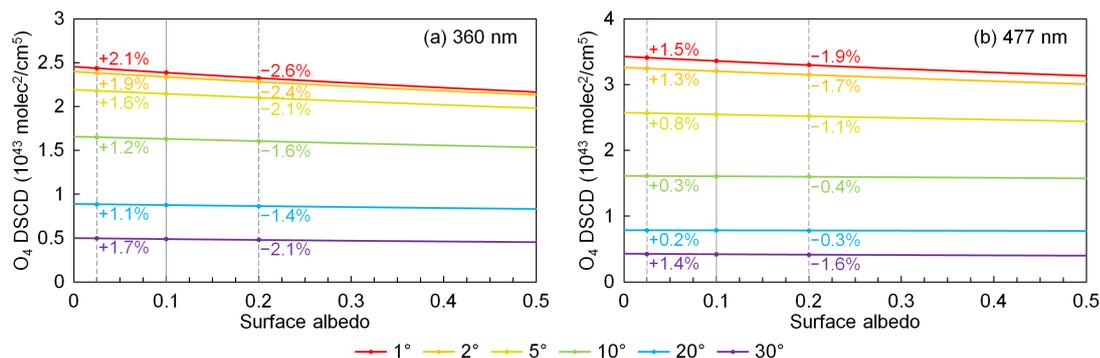


Figure 5.9: O<sub>4</sub> DSCDs at (a) 360 nm and (b) 477 nm simulated with different surface albedo values between 0 and 0.5. The other simulation parameters followed the settings listed in Table 5.3. The gray solid line refers to the empirically estimated median surface albedo value of 0.1, and the gray dashed lines refer to the extreme values of 0.025 and 0.2 defined in the study. The relative differences between the O<sub>4</sub> DSCDs simulated with extreme surface albedo values (0.025 and 0.2) and the ones simulated with the median value (0.1) are noted in the charts.

Figure 5.9 shows the O<sub>4</sub> DSCDs simulated with the surface albedo varying between 0 and 0.5 (with a step size of 0.025), while the other parameters were fixed as the settings listed in Table 5.3. The empirically estimated median surface albedo value of 0.1 is marked as the gray solid line, and the extreme values of 0.025 and 0.2 are marked as the gray dashed lines. For each elevation, the relative percentage differences of the O<sub>4</sub> DSCDs simulated with the extreme surface albedo values comparing to the one simulated with the median value are marked

beside the data points. The results show that at all the elevations and at both 360 and 477 nm,  $O_4$  DSCD slowly decreases with increasing surface albedo.

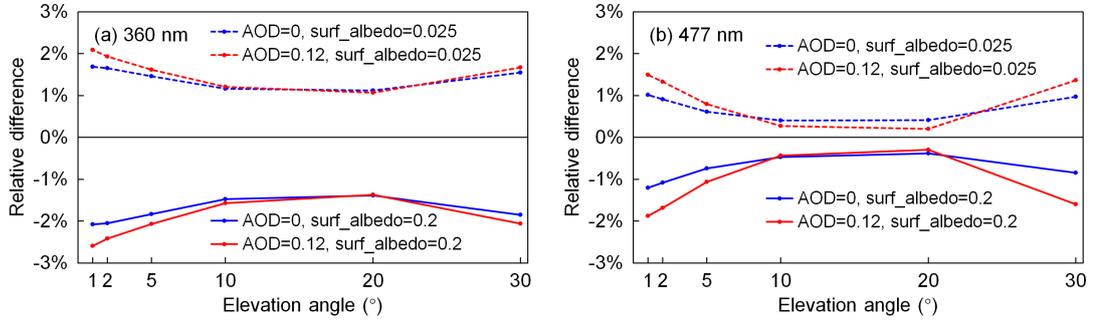


Figure 5.10: Relative differences of  $O_4$  DSCDs at (a) 360 nm and (b) 477 nm simulated with extreme surface albedo values (solid lines for 0.2 and dashed lines for 0.025) comparing to  $O_4$  DSCDs simulated with the median value (0.1). The blue lines refer to the results under aerosol-free condition, while the red lines refer to the results with a box-shape profile with  $AOD = 0.12$  and box height = 3 km. The other simulation parameters followed the settings listed in Table 5.3.

Besides the box-shape aerosol profile with  $AOD = 0.12$  defined in the common settings, we also did a similar test with an aerosol-free profile. The percentage differences of the  $O_4$  DSCDs corresponding to extreme surface albedo values from both of the tests are summarized in Figure 5.10.

The results show that at both wavelengths and under both aerosol profiles,  $O_4$  DSCDs at all the six elevations slightly decrease with increasing surface albedo, and the variation rate differs with different elevation angles and different aerosol loads. Based on our estimation of the median value and variation range of surface albedo, the uncertainty caused by surface albedo would be less than 3%, and the positive and negative errors are nearly equal. Further simulations show that the uncertainty caused by surface albedo also depends on the observation geometry.

### 5.6.2 Sensitivity to single scattering albedo

As the aerosol optical property data at the UFS were not available, we estimated the aerosol optical properties from the AERONET data at Hohenpeißenberg (see Section 3.3.2). As shown in Figure 5.11, according to the long-term single scattering albedo (SSA) data, 90% of the SSA at 360 nm vary between 0.87 and 0.997, and the median value is 0.93; for the SSA at 477 nm, 90% of the data vary between 0.85 and 0.997, and the median value is 0.92.

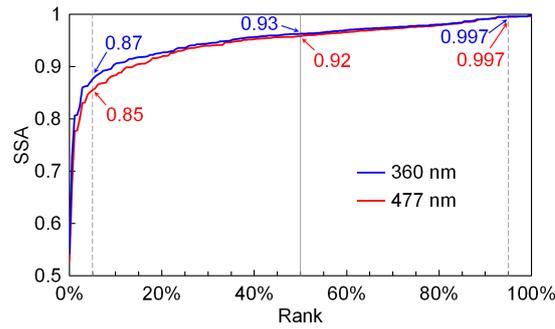


Figure 5.11: Cumulative distribution of the single scattering albedo (SSA) at 360 and 477 nm, derived from the AERONET data at Hohenpeißenberg from 2013 to 2014.

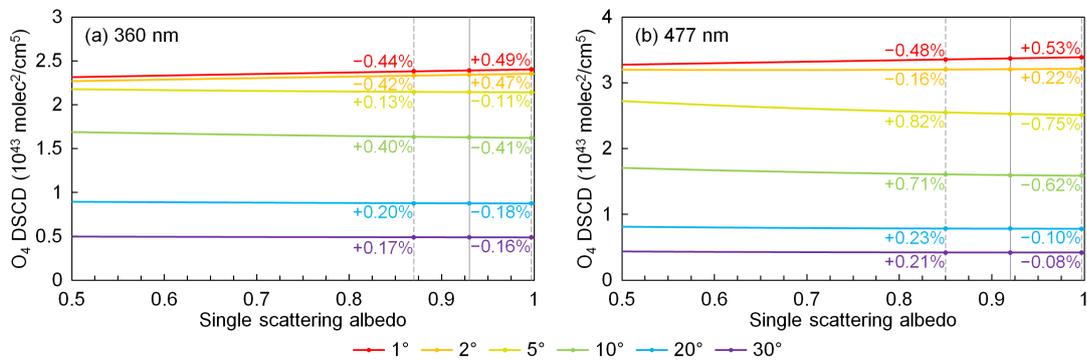


Figure 5.12: O<sub>4</sub> DSCDs at (a) 360 nm and (b) 477 nm simulated with different single scattering albedo values between 0.5 and 1 (step size 0.025, the extreme and median values were also included). The other simulation parameters followed the settings listed in Table 5.3. The gray solid line indicates the empirically estimated median single scattering albedo value (0.93 for 360 nm and 0.92 for 477 nm), and the gray dashed lines indicate the extreme values (0.87 and 0.997 for 360 nm, 0.85 and 0.997 for 477 nm). The relative differences between the O<sub>4</sub> DSCDs simulated with extreme single scattering albedo values and the one simulated with the median value are noted in the charts.

In order to estimate the uncertainty of simulated O<sub>4</sub> DSCD due to the SSA, we simulated O<sub>4</sub> DSCDs with the SSA varies from 0.5 to 1 (with a step size of 0.025, and the above-mentioned extreme and median values were also included), while the other parameters were fixed as the settings listed in Table 5.3. The results are shown in Figure 5.12. In each chart, the gray solid line indicates the median SSA value, while the gray dashed lines indicate the extreme values. For each elevation, the relative percentage differences of the O<sub>4</sub> DSCDs simulated

with the extreme SSA values comparing to the one simulated with the median value are marked beside the data points.

The results show that at different elevations,  $O_4$  DSCD either slowly decreases or slowly increases with increasing SSA. The results also indicate that using the median SSA value in the forward simulation would result in less than 1% error in  $O_4$  DSCDs in 90% of the cases. In addition, the positive and negative errors are mostly equal. Since the simulation error attributed to SSA is rather small, using the SSA data from Hohenpeißenberg should not have a big influence on the retrieval, although that site is located at a much lower altitude comparing to the UFS.

### 5.6.3 Sensitivity to scattering phase function

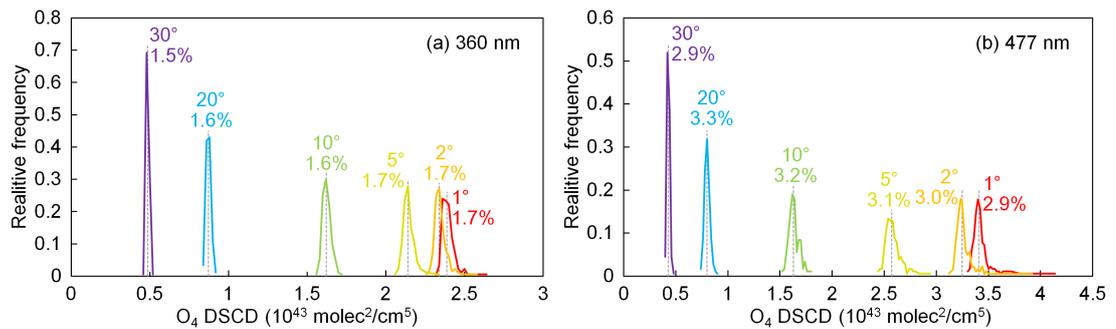


Figure 5.13: Frequency distributions of  $O_4$  DSCDs at (a) 360 nm and (b) 477 nm simulated with all the phase functions during 2013–2014. The other simulation parameters followed the settings listed in Table 5.3. The percentage standard deviation of the simulated  $O_4$  DSCDs at each elevation is labeled in the plots. The gray dashed lines represent the median values of simulated  $O_4$  DSCDs at each elevation.

The estimation of the uncertainty of simulated  $O_4$  DSCD due to scattering phase function is also based on the AERONET data at Hohenpeißenberg. Unlike most of the other simulation parameters which can be defined by a single number, the parameter of scattering phase function is defined by function values at different scattering angles. In order to estimate the uncertainty, we simulated  $O_4$  DSCDs with all the phase function data from 2013 to 2014 (altogether 179 available data), while the other parameters were fixed as the settings listed in Table 5.3. The frequency distributions of simulated  $O_4$  DSCDs are shown in Figure 5.13. For each elevation, the percentage standard deviation is marked beside the curve,

and the gray dashed line indicates the median value. The results indicate that the distributions of the simulated  $O_4$  DSCDs follow the normal distribution, and the standard deviations at 477 nm are larger comparing to 360 nm. In addition, the simulation uncertainty caused by phase function is 3–5 times larger than that caused by SSA and comparable to the uncertainty caused by the surface albedo.

Based on the simulation results, the phase function with which the simulated  $O_4$  DSCDs at all the elevations are closest to the median values was chosen as the so-called ‘median’ phase function for each wavelength.

### 5.6.4 Sensitivity to aerosol layer thickness

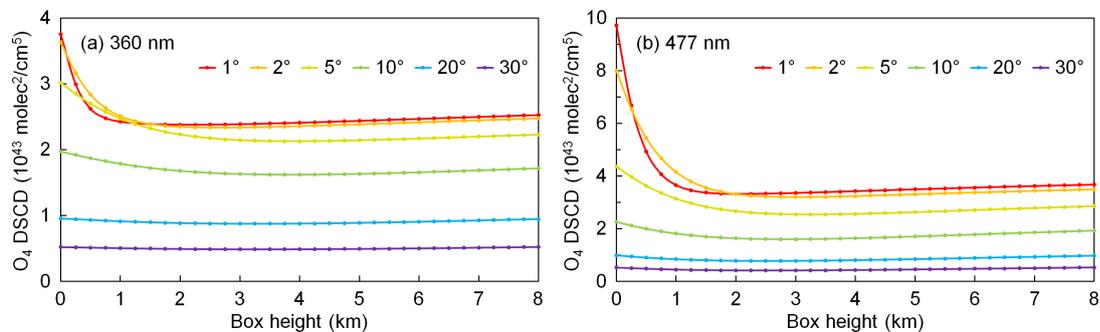


Figure 5.14: Simulated  $O_4$  DSCDs at (a) 360 nm and (b) 477 nm for box-shape profiles with the same surface aerosol extinction coefficient of  $0.04 \text{ km}^{-1}$  and different box heights from 0 to 8 km. The other simulation parameters followed the settings listed in Table 5.3.

The sensitivity of  $O_4$  DSCD to aerosol layer thickness was estimated by simulating  $O_4$  DSCDs with box-shape aerosol profiles with the same aerosol extinction coefficient of  $0.04 \text{ km}^{-1}$  and different box heights varying from 0 to 8 km. The other parameters were fixed as the settings listed in Table 5.3. The simulated  $O_4$  DSCDs are shown in Figure 5.14.

The results indicate that the sensitivity of  $O_4$  DSCD at all the elevations decreases rapidly with increasing aerosol layer thickness (and also increasing AOD). Furthermore,  $O_4$  DSCDs at all the elevations are almost constant when the thickness varies between 2 and 8 km, which indicates that  $O_4$  absorption is insensitive to the aerosols above 2 km. Taking the  $O_4$  DSCD at 360 nm and at the elevation of  $2^\circ$  as an example, the sensitivity to aerosols at 2 km is lower than that at the surface level by a factor of  $\sim 40$ . In addition, measurements at lower elevations are more sensitive to aerosols close to the ground comparing to higher elevations.

This result coincides with the results reported in the MAX-DOAS studies based on the OEM (e.g., Frieß et al., 2006; Clémer et al., 2010; Frieß et al., 2016; Bösch et al., 2018). In these studies, the averaging kernels — which indicate the measurement sensitivities to aerosols at different altitudes — are all close to zero at the altitudes above 2 km.

### 5.6.5 Sensitivity to aerosol extinction above retrieval height

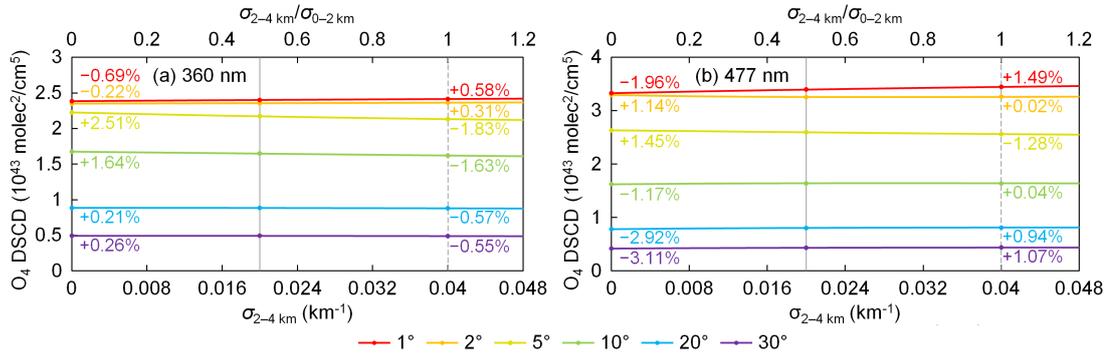


Figure 5.15: Simulated O<sub>4</sub> DSCDs at (a) 360 nm and (b) 477 nm for profiles with the same aerosol extinction coefficient of 0.04 km<sup>-1</sup> between 0 and 2 km above instrument and different aerosol extinction coefficients varying from 0 to 0.048 km<sup>-1</sup> between 2 and 4 km. The other simulation parameters followed the settings listed in Table 5.3. The gray solid line refers to the empirically estimated median  $\sigma_{2-4\text{km}}$  value of 0.02 km<sup>-1</sup> (i.e., 50% of  $\sigma_{0-2\text{km}}$ ), and the gray dashed lines refer to the extreme values of 0 and 0.04 km<sup>-1</sup> (i.e., 0% and 100% of  $\sigma_{0-2\text{km}}$ ). The relative differences between the O<sub>4</sub> DSCDs simulated with extreme  $\sigma_{2-4\text{km}}$  values and the ones simulated with the median  $\sigma_{2-4\text{km}}$  are noted in the charts.

According to the conclusion of Section 5.6.4, our retrieval of aerosol profiles would mainly focus on aerosols below 2 km above instrument. However, as the aerosol load on Zugspitze is usually very low and the aerosol extinction coefficient above 2 km is usually in the same order of magnitude with the one below 2 km. We estimate that the aerosol extinction coefficient between 2 and 4 km (denoted as  $\sigma_{2-4\text{km}}$ ) varies from 0 to 100% of the aerosol extinction coefficient below 2 km (denoted as  $\sigma_{0-2\text{km}}$ ), and the median value is 50% of  $\sigma_{0-2\text{km}}$ . In order to estimate the sensitivity of O<sub>4</sub> absorption to  $\sigma_{2-4\text{km}}$ , we simulated O<sub>4</sub> DSCDs with profiles with the same  $\sigma_{0-2\text{km}}$  of 0.04 km<sup>-1</sup> and different  $\sigma_{2-4\text{km}}$  varying from 0 to 0.048 km<sup>-1</sup> (i.e., 1.2 times of  $\sigma_{0-2\text{km}}$ ), and the other parameters were fixed as the settings listed in Table 5.3. The results are shown in Figure 5.15

The results indicate that the aerosols above 2 km can affect the  $O_4$  DSCDs by up to  $\sim 3\%$ , which is similar to the surface albedo. Therefore, we considered the influence from the aerosols above 2 km as a kind of measurement uncertainty, and treated it in the same way as the errors caused by surface albedo, single scattering albedo and phase function uncertainties.

### 5.6.6 Sensitivity to surface aerosol extinction

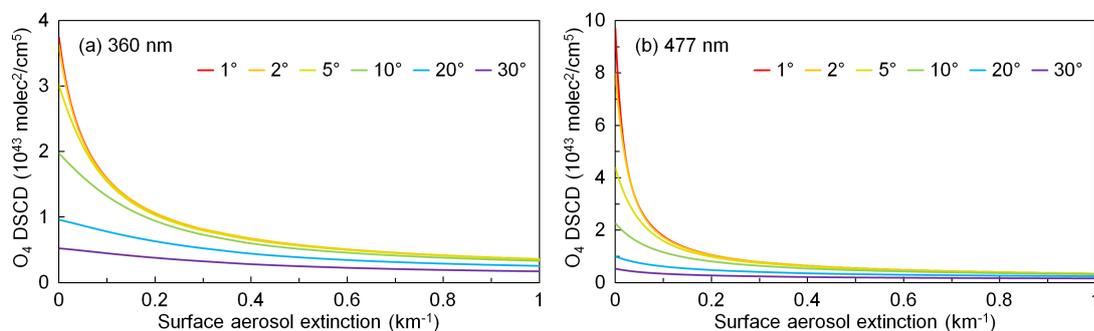


Figure 5.16: Simulated  $O_4$  DSCDs at (a) 360 nm and (b) 477 nm for box-shape profiles with the same box height of 2 km and different surface aerosol extinction coefficients varying from 0 to  $1 \text{ km}^{-1}$ . The other simulation parameters followed the settings listed in Table 5.3. Note that the curves of  $1^\circ$  and  $2^\circ$  are quite close to each other.

In order to estimate the sensitivity of  $O_4$  DSCD to surface aerosol extinction, we simulated  $O_4$  DSCDs with box-shape profiles with a constant box height of 2 km and different aerosol extinction coefficients vary from 0 to  $1 \text{ km}^{-1}$ . The other parameters were fixed as the settings listed in Table 5.3. The simulated  $O_4$  DSCDs are shown in Figure 5.16.

The results indicate that the  $O_4$  DSCDs at all elevations and both wavelengths decrease monotonically with increasing aerosol extinction, and the sensitivity of  $O_4$  DSCD to surface aerosol extinction also decreases with increasing aerosol extinction. The sensitivity is very low when the surface aerosol extinction coefficient exceeds  $0.3 \text{ km}^{-1}$ . In addition, measurements at lower elevations are much more sensitive.

## 5.7 Design of the look-up table

In this study, we retrieved aerosol profiles from MAX-DOAS measurements using the LUT method. The basic idea of the LUT method is to replace repetitive time-consuming computation by a pre-calculated database. In this study, we replaced the forward simulation of  $O_4$  DSCDs by a LUT, so that numerous aerosol profiles could be considered in each retrieval with an affordable computational effort.

We considered five input parameters for the look-up function which replaces the forward simulation,

$$\Delta S_s = f(\mathbf{x}, \lambda, \alpha, \theta, \phi), \quad (5.6)$$

where  $\Delta S_s$  represents the simulated  $O_4$  DSCD,  $\mathbf{x}$  is the aerosol extinction profile,  $\lambda$  is the wavelength,  $\alpha$  is the elevation angle,  $\theta$  is the SZA, and  $\phi$  is the RAA. All the input parameters are well-known in the retrieval.

In order to formulate the pre-calculated database, the five input parameters need to be parametrized as a grid with finite nodes.

### 5.7.1 Parametrization of the aerosol extinction profile

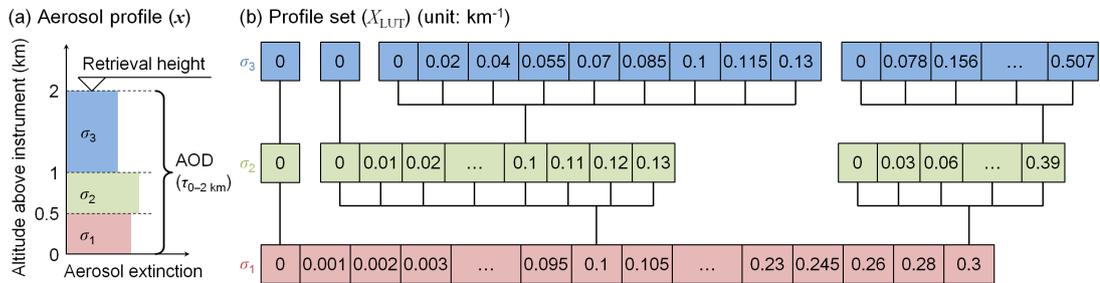


Figure 5.17: Definitions of (a) the parametrized aerosol profile ( $\mathbf{x}$ ) and (b) the profile set ( $X_{LUT}$ ). Note that only some representative nodes are shown in Panel (b).

As discussed in Section 5.6.4,  $O_4$  absorption is insensitive to aerosols above 2 km. Therefore, our retrieval would mainly focus on the aerosols between 0 and 2 km above the MAX-DOAS instrument (i.e., 2,650–4,650 m a.s.l.). In order to limit the complexity of the retrieval, avoid unreasonable results, and make full use of the measurement sensitivity, we parametrized the aerosol extinction profile as aerosol extinction coefficients in three layers. The thicknesses of the lower two

layers were defined as 0.5 km. Due to the lower sensitivity at high altitudes, the thickness of the third layer was set to 1 km. The aerosol profile is denoted as a three-dimensional state vector  $\mathbf{x}$ ,

$$\mathbf{x} = \begin{pmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \end{pmatrix}, \quad (5.7)$$

where  $\sigma_1$  is the aerosol extinction coefficient between 0 and 0.5 km (2,650–3,150 m a.s.l.),  $\sigma_2$  is the aerosol extinction coefficient between 0.5 and 1 km (3,150–3,650 m a.s.l.), and  $\sigma_3$  is the aerosol extinction coefficient between 1 and 2 km (3,650–4,650 m a.s.l.). The definition of  $\mathbf{x}$  is illustrated in Figure 5.17 (a).

### 5.7.2 Definition of the profile set

In order to formulate the LUT, we defined a profile set (denoted as  $X_{\text{LUT}}$ ) which is assumed to include all possible aerosol extinction profiles under cloud-free condition.  $X_{\text{LUT}}$  is a finite set of  $\mathbf{x}$ , and the variation steps of  $\sigma_1$ ,  $\sigma_2$  and  $\sigma_3$  were determined according to the sensitivity and accuracy of measurements.  $X_{\text{LUT}}$  includes only the profiles with reasonable shapes, and the variation range of  $\sigma_1$ ,  $\sigma_2$  and  $\sigma_3$  covers the actual aerosol load at the UFS. In this way, unreasonable and unrealistic retrieval results can be avoided.

As discussed in Section 5.6.6, the measurement sensitivity decreases with increasing surface aerosol extinction, and the sensitivity is very low when the surface aerosol extinction coefficient exceeds  $0.3 \text{ km}^{-1}$ . Therefore,  $\sigma_1$  was defined to vary between 0 and  $0.3 \text{ km}^{-1}$ . The variation step increases from  $0.001 \text{ km}^{-1}$  per step to  $0.02 \text{ km}^{-1}$  per step with increasing aerosol extinction, so that the difference of  $\text{O}_4$  DSCD per step is similar to the average spectral fitting error ( $\sim 2\%$ ). In total, we defined 65 values for  $\sigma_1$ , see Table 5.4.

As illustrated in Figure 5.17 (b), the values of  $\sigma_2$  and  $\sigma_3$  were defined like a tree, which means we defined different values of  $\sigma_2$  for different  $\sigma_1$ , and the values of  $\sigma_3$  were also defined depending on  $\sigma_2$ . According to the ceilometer observations at the UFS, strong elevated aerosol layers are unlikely to exist under cloud-free conditions, therefore we allowed only weak elevated layers in designing the profile set. We assume that for reasonable profiles,  $\sigma_2$  should not exceed  $\sigma_1$  by more than 30%, and  $\sigma_3$  should not exceed  $\sigma_2$  by more than 30%, either. According to the sensitivity, for each value of  $\sigma_1$  ( $\sigma_1 > 0$ ), we defined 14 possible values

for  $\sigma_2$  which varies from 0 to  $1.3\sigma_1$  with a step size of  $0.1\sigma_1$ . In case  $\sigma_1 = 0$ , elevated layers are not considered, then  $\sigma_2$  and  $\sigma_3$  can only be 0. Similarly,  $\sigma_3$  varies between 0 and  $1.3\sigma_2$ . Due to the lower measurement sensitivity at higher altitude, we defined 9 possible ratios between  $\sigma_3$  and  $\sigma_2$  (see Table 5.4). In case  $\sigma_2 = 0$ ,  $\sigma_3$  can only be 0.

$X_{\text{LUT}}$  includes the profiles with all the combinations of  $\sigma_1$ ,  $\sigma_2/\sigma_1$  and  $\sigma_3/\sigma_2$ . For each of the 64 nonzero values of  $\sigma_1$ , there are  $1 + (13 \times 9) = 118$  corresponding profiles. For  $\sigma_1 = 0$ , there is only one profile with  $\sigma_1 = \sigma_2 = \sigma_3 = 0$ . Therefore, the profile set consists of  $1 + 64 \times 118 = 7,553$  aerosol extinction profiles in total.

### 5.7.3 Definitions of other dimensions of the look-up table

As already presented above, the five input parameters of the look-up function need to be parametrized as a grid with finite nodes. As discussed in Section 5.7.2, the aerosol extinction profile ( $\boldsymbol{x}$ ) has been parametrized as a profile set which consists of 7,553 possible profiles. For the other four input parameters, we also need to define finite representative nodes.

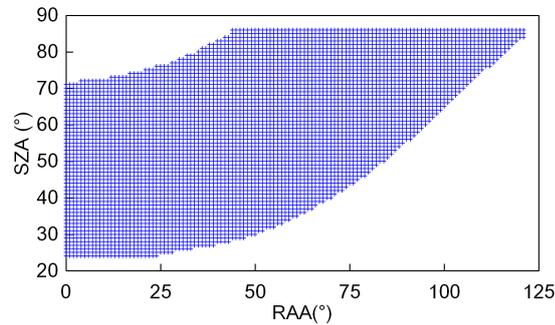


Figure 5.18: The SZA-RAA grid of the LUT.

Since the simulated  $O_4$  DSCDs were to be fitted to the measured ones, only the data at 360 and 477 nm and at the six off-zenith elevation angles of the measurement cycles ( $1^\circ$ ,  $2^\circ$ ,  $5^\circ$ ,  $10^\circ$ ,  $20^\circ$ ,  $30^\circ$ ) were needed and hence included in the LUT. For SZA ( $\theta$ ) and RAA ( $\phi$ ), we defined a grid with  $1^\circ \times 1^\circ$  resolution. The grid includes 5,005 combinations of SZA and RAA, which can cover all possible solar positions for the daytime measurements at the UFS, see Figure 5.18. When we obtained data from the LUT, as the input SZA and RAA are not integers, the output  $\Delta S_s$  was interpolated from the data of the four adjacent nodes of the SZA-RAA grid. In total, the five input parameters were parametrized as a grid with

Table 5.4: Definition of input parameters of the O<sub>4</sub> DSCD LUT.

Parameter	Symbol	Number of grid points	Grid values			
Aerosol extinction coefficient of 0–0.5 km above instrument (km <sup>-1</sup> )	$\sigma_1$	65	0, 0.001, 0.002, ..., 0.009, (0.001/step, 10 values)			
			0.01, 0.0115, 0.013, ..., 0.0265, (0.0015/step, 12 values)			
			0.028, 0.03, 0.032, ..., 0.038, (0.002/step, 6 values)			
			0.04, 0.0425, 0.045, 0.0475, (0.0025/step, 4 values)			
			0.05, 0.053, 0.056, ..., 0.077, (0.003/step, 10 values)			
Aerosol extinction coefficient of 0.5–1 km above instrument (km <sup>-1</sup> )	$\sigma_2$	14 ( $\sigma_1 > 0$ ) 1 ( $\sigma_1 = 0$ )	0, 0.1 $\sigma_1$ , 0.2 $\sigma_1$ , ..., 1.3 $\sigma_1$ (0.1 $\sigma_1$ /step)			
			0, 0.2 $\sigma_2$ , 0.4 $\sigma_2$ , 0.55 $\sigma_2$ , 0.7 $\sigma_2$ , 0.85 $\sigma_2$ , $\sigma_2$ , 1.15 $\sigma_2$ , 1.3 $\sigma_2$			
			Wavelength (nm)	$\lambda$	2	360, 477
			Elevation angle (°)	$\alpha$	6	1, 2, 5, 10, 20, 30
			Solar zenith angle (SZA) (°)	$\theta$	63	24, 25, 26, ..., 86 (1/step)
Relative solar azimuth angle (RAA) (°)	$\phi$	122	0, 1, 2, ..., 121 (1/step)			

$7,553 \times 2 \times 6 \times 5,005 = 453,633,180$  nodes. Details of the parametrization of the input parameters are summarized in Table 5.4.

As discussed in Section 5.6, besides the input parameters we defined, O<sub>4</sub> DSCDs can also be affected by other parameters such as the ground albedo, aerosol optical properties, and others. Since accurate measurements of these parameters are not available and their influence is relatively small, they are considered as uncertainties. In creating the LUT, these parameters were fixed to the median values discussed in Section 5.6. Details of the simulation settings are listed in Table 5.5. O<sub>4</sub> DSCDs corresponding to all nodes of the LUT were simulated using LIDORT.

As discussed in Section 5.6.5, the influence from the aerosols above 2 km was also considered as a kind of uncertainty and treated in a similar way as the other unknown parameters. In the simulations for creating the LUT, the aerosol extinction coefficient between 2 and 4 km was defined as  $0.5\sigma_3$ , so that this so-called parameter was fixed to the ‘median’ value. Note that the aerosol extinction coefficient in this layer is not considered as a part of the retrieved profile and does not play a part in calculating the retrieved AOD.

## 5.8 O<sub>4</sub> DSCD uncertainty estimation

The uncertainties of O<sub>4</sub> DSCDs are required in the aerosol profile retrieval. Most of the other MAX-DOAS studies only considered the spectral fitting error in their retrieval. However, the fitting error only contributes to a small part of the total uncertainty. In addition, the total uncertainty is not directly proportional to the spectral fitting error. As the measurement and simulation uncertainties play an important part in our inversion method, we performed a comprehensive error analysis for the MAX-DOAS measurements and radiative transfer simulation of O<sub>4</sub> DSCDs. In this study, error from seven major sources were taken into account in estimating the total uncertainty.

### 5.8.1 Error in measured O<sub>4</sub> DSCDs

Two error sources related to measured O<sub>4</sub> DSCDs were taken into account in the total uncertainty estimation, which are the DOAS fitting error ( $\epsilon_{\text{fit}}$ ) and the error caused by temperature variation ( $\epsilon_{\text{temp}}$ ).

Table 5.5: Settings of fixed parameters in calculating the O<sub>4</sub> DSCD LUT.

Parameter	Value or definition
Topography	A flat surface at an altitude of 2,650 m a.s.l.
Surface albedo	0.1
Single scattering albedo (SSA)	$0.93 (360 \text{ nm}) / 0.92 (477 \text{ nm})$
Phase function	The 'median' phase function defined in Section 5.6.3
Climatology	US standard profiles for profile, temperature and trace gas profiles
Aerosol extinction coefficient of 2–4 km above instrument	50% of the aerosol extinction coefficient of 1–2 km above instrument (i.e., $0.5\sigma_3$ )
Aerosol extinction coefficient above 4 km from instrument	0

### 5.8.1.1 DOAS fitting error

$\epsilon_{\text{fit}}$  is the byproduct of the DSCD calculation, derived from the fitting residual and the absorption cross section of O<sub>4</sub>. It is proportional to the RMS of the fitting residual. For low elevations (1°, 2°, 5°), the percentage of  $\epsilon_{\text{fit}}$  comparing to the DSCD typically varies between 1% and 3% at the UV band and between 0.3% and 0.7% at the VIS band, which is rather small compared to other sources of error. However, for the elevation of 30°, as the absolute DSCD values are much smaller, the percentage of  $\epsilon_{\text{fit}}$  can be up to ~25% and ~10% at the UV and VIS bands, respectively.

### 5.8.1.2 Error caused by temperature variation

As discussed in Section 5.4, O<sub>4</sub> absorption cross section measured at 273 K was used in the DOAS fitting. However, the effective temperature of the MAX-DOAS measurements could be significantly different from 273 K. Previous studies have shown that O<sub>4</sub> absorption has a strong and systematic dependence on temperature (Thalman and Volkamer, 2013; Wagner et al., 2019).

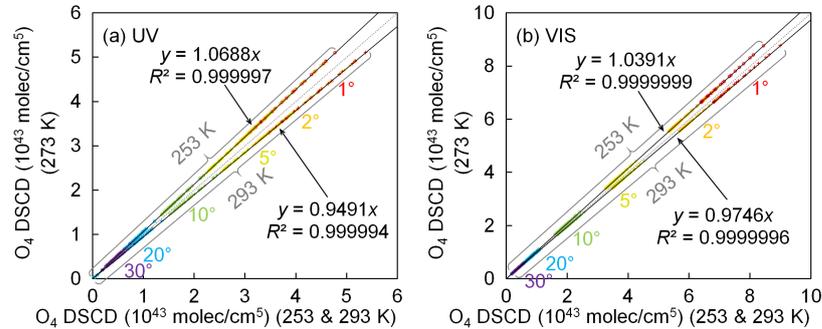


Figure 5.19: Comparison of O<sub>4</sub> DSCDs calculated using cross sections measured at 273 K and the ones calculated using cross sections measured at 253 and 293 K, calculated from all the spectra measured on 07 Dec 2015. Panels (a) and (b) show the data of UV and VIS bands, respectively. The data of 253 K are shown as X markers, while the data of 293 K are shown as circle markers. Data points are plotted in different colors according to their elevation angles.

In order to estimate the error in O<sub>4</sub> DSCDs caused by the variation of temperature, we compared the O<sub>4</sub> DSCDs calculated using the cross sections measured at 273 K to the ones calculated using the cross sections measured at 253 K and 293 K. Figure 5.19 shows the comparison based on the data of an entire day. The

results indicate that  $O_4$  DSCDs calculated using different cross sections are linearly correlated, regardless of the measurement geometry. The linear regression results indicate that when the effective temperature is 293 K,  $O_4$  DSCDs calculated using the cross sections measured at 273 K are underestimated by 5.09% and 2.54% for UV and VIS bands, respectively; when the effective temperature is 253 K,  $O_4$  DSCDs are overestimated by 6.88% and 3.91% for UV and VIS bands, respectively. Between 253 and 293 K, the average variation rate of  $O_4$  DSCD at UV band is 0.3%/K. This result is in general agreement with Wagner et al. (2019). They found that with the fitting window of 352–387 nm,  $O_4$  DSCDs retrieved using the cross section at 203 K are 30% smaller than those retrieved using the cross section at 293 K, i.e., 0.33%/K on average.

As we assume the error is linear to the temperature difference, based on the fact that the temperature at the measurement site varies between  $\sim 258$  and 288 K during daytime in most cases, we estimated the  $\epsilon_{\text{temp}}$  of all measurements to be 4.5% and 2.4% of the  $O_4$  DSCDs at UV and VIS band, respectively.

### 5.8.2 Error in simulated $O_4$ DSCDs

Five error sources related to simulated  $O_4$  DSCDs were taken into account in estimating the total uncertainty. They are the random error caused by the simplification of the topography definition ( $\epsilon_{\text{topo}}$ ), the error caused by surface albedo ( $\epsilon_{\text{SA}}$ ), the error caused by single scattering albedo ( $\epsilon_{\text{SSA}}$ ), the error caused by phase function ( $\epsilon_{\text{PF}}$ ) and the error caused by aerosols above retrieval height ( $\epsilon_{2-4\text{ km}}$ ).

As discussed in Section 5.5, the random error caused by the simplification of the topography definition ( $\epsilon_{\text{topo}}$ ) of each elevation and each wavelength was derived from the standard deviation of the relative errors of the 18 cases simulated using the three-dimensional RTM TRACY-2. Values of  $\epsilon_{\text{topo}}$  are listed in Table 5.2.

For the uncertainties from the other four sources ( $\epsilon_{\text{SA}}$ ,  $\epsilon_{\text{SSA}}$ ,  $\epsilon_{\text{PF}}$  and  $\epsilon_{2-4\text{ km}}$ ), as discussed in Section 5.6, they can be estimated by radiative transfer simulations. Since they differ under different observation geometries and different aerosol loads, we determined them using simple LUTs in the retrieval. In order to simplify the error estimation process, we assume that the uncertainties from the four sources are only influenced by the AOD, while the influence from different vertical distribution of aerosols is neglected. In addition, from the  $O_4$  DSCD LUT, we found that  $O_4$  DSCD at  $5^\circ$  is almost negatively correlated with AOD, while it is

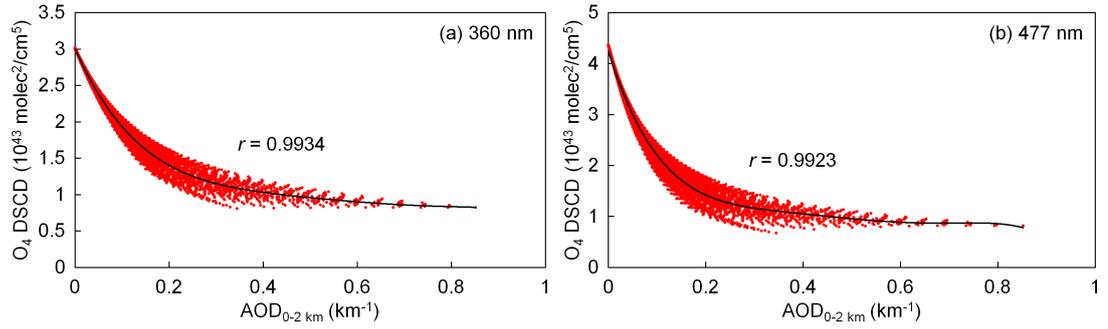


Figure 5.20: Correlation between O<sub>4</sub> DSCD at 5° and AOD between 0 and 2 km for all the profiles in  $X_{LUT}$  (SZA = RAA = 60°). The  $r$  value shown in each chart is the Pearson correlation coefficient of the trend line.

insensitive to the shape of profile (an example is shown in Figure 5.20). Therefore, we used the O<sub>4</sub> DSCD measured at 5° as the indicator for estimating the AOD in deriving uncertainty values from the error LUTs.

The error LUTs consist of the values of  $\epsilon_{SA}$ ,  $\epsilon_{SSA}$ ,  $\epsilon_{PF}$  and  $\epsilon_{2-4km}$  for all combinations of SZA and RAA (with 1° × 1° resolution) and 65 profiles of the  $X_{LUT}$  with  $\sigma_1 = \sigma_2 = \sigma_3$ . The calculation of the error LUTs was similar to the sensitivity study. In order to estimate the uncertainty caused by each parameter, O<sub>4</sub> DSCDs were simulated under both median and extreme values, while all the other parameters were fixed as the median settings listed in Table 5.5. For each scenario, the relative difference between the two simulations was treated as the uncertainty and stored in the LUT.

As discussed in Section 5.6.1, the uncertainty caused by surface albedo ( $\epsilon_{SA}$ ) was derived from the relative difference of the O<sub>4</sub> DSCDs simulated with the surface albedo set to 0.2 (extreme value) and 0.1 (median value).

As discussed in Section 5.6.2, in the estimation of the uncertainty caused by single scattering albedo ( $\epsilon_{SSA}$ ), the extreme value was chosen as 0.997 for both the UV and VIS bands, while the median value was chosen as 0.92 and 0.93 for UV and VIS bands, respectively.

As discussed in Section 5.6.3, from all the phase functions measured by the AERONET station in Hohenpeißenberg during the period of 2013–2014, the phase function with which the simulated O<sub>4</sub> DSCDs at all elevations are closest to the median values was chosen as the so-called ‘median’ phase function. The phase function with which the simulated O<sub>4</sub> DSCDs are closest to the rank of 95% (i.e.,  $2\sigma$ ) was chosen as the ‘extreme’ phase function.  $\epsilon_{PF}$  was derived from the

relative difference between O<sub>4</sub> DSCDs simulated with ‘extreme’ and ‘median’ phase functions.

As discussed in Section 5.6.5, the error caused by aerosols above 2 km ( $\epsilon_{2-4\text{km}}$ ) was treated like  $\epsilon_{\text{SA}}$ ,  $\epsilon_{\text{SSA}}$  and  $\epsilon_{\text{PF}}$  in the study. The so-called ‘median’ O<sub>4</sub> DSCDs were simulated with profiles with  $\sigma_{2-4\text{km}}$  (the aerosol extinction coefficient between 2 and 4 km) equals to  $0.5\sigma_3$  (50% of the aerosol extinction coefficient between 1 and 2 km), while the ‘extreme’ values were simulated with profiles with  $\sigma_{2-4\text{km}} = \sigma_3$ .  $\epsilon_{2-4\text{km}}$  was derived from the relative difference between the ‘extreme’ and ‘median’ results.

### 5.8.3 Total uncertainty

As the seven kinds of errors mentioned in Sections 5.8.1 and 5.8.2 are independent to each other and we assume they follow the normal distribution, the total uncertainty of each band and each elevation can be determined by the RMS of the seven errors as

$$\epsilon = \sqrt{\epsilon_{\text{fit}}^2 + \epsilon_{\text{temp}}^2 + \epsilon_{\text{topo}}^2 + \epsilon_{\text{SA}}^2 + \epsilon_{\text{SSA}}^2 + \epsilon_{\text{PF}}^2 + \epsilon_{2-4\text{km}}^2}. \quad (5.8)$$

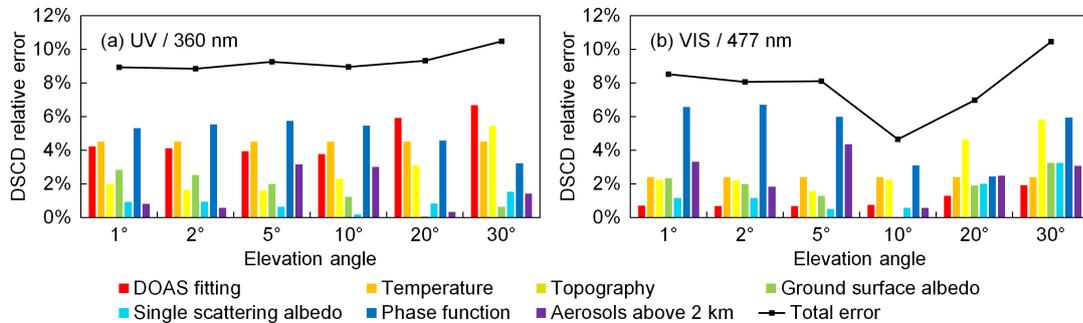


Figure 5.21: Error budgets of (a) UV and (b) VIS bands of the scanning cycle on 05 Jul 2015 at  $\sim 16:26$  UTC (SZA  $\sim 64^\circ$ , RAA  $\sim 97^\circ$ ). Y-axes refer to the relative error of O<sub>4</sub> DSCDs.

Examples of the error budgets of two measurement cycles at both wavelength bands are shown in Figure 5.21 and Figure 5.22. The cycle shown in Figure 5.21 was measured in summer under relatively high aerosol load (AOD at 440 nm measured by the sun photometer around the noon of that day was  $\sim 0.2$ ), while the cycle shown in Figure 5.22 was measured in winter under relatively low aerosol load (AOD at 440 nm measured by the sun photometer around the noon of that

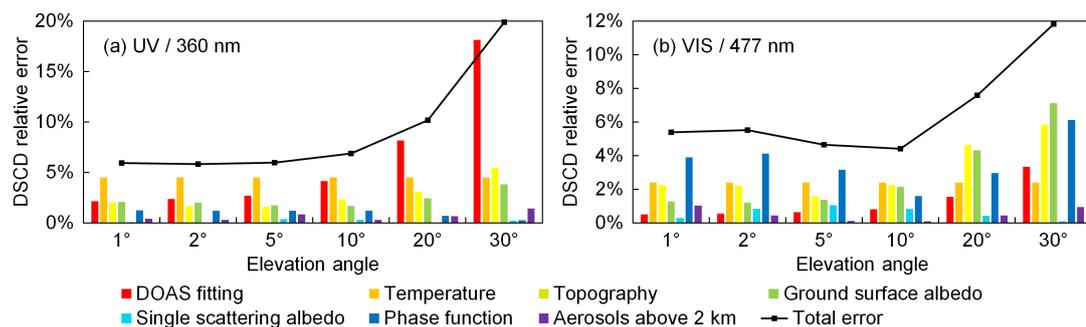


Figure 5.22: Same as Figure 5.21, but for the scanning cycle on 07 Dec 2015 at  $\sim 13:55$  UTC (SZA  $\sim 79^\circ$ , RAA  $\sim 39^\circ$ ).

day was  $\sim 0.015$ ). In addition, The former cycle was measured under a smaller SZA comparing to the latter ( $64^\circ$  and  $79^\circ$ , respectively), while the RAA was much larger than the latter ( $97^\circ$  and  $39^\circ$ , respectively). The results show that contributions from different error sources are quite different in different measurement cycles, at different wavelengths and at different elevation angles.

#### 5.8.4 Other possible error sources

Besides the seven error sources mentioned above, there are still some other sources of error which are difficult to be estimated and hence not included in the error estimation. For example:

a. Error in O<sub>4</sub> DSCD scaling factors: in this study, we found that elevation-dependent O<sub>4</sub> DSCD scaling factors are needed to bring measurements and modeled results into agreement. We determined the factors based on the statistical analysis of the long-term measurement, see Section 5.10. However, as it is still difficult to estimate the uncertainties of the scaling factors, they are currently not taken into account in calculating the total uncertainties.

b. Error caused by horizontal gradients of the aerosol extinction: besides its direct effect on the measurements, the complex topography might also cause systematic horizontal gradients of the aerosol extinction. For example, polluted air masses from the valleys might be transported to higher altitudes according to the vertical mixing and the prevailing wind direction. Such effects can be especially important for the measurements discussed here because of the rather low AOD. Further quantification of the effects of possible horizontal gradients is beyond the scope of this study, but might be one reason for the observed elevation

dependence of the O<sub>4</sub> DSCD scaling factor.

c. Error caused by the variation of atmospheric profile: the O<sub>4</sub> DSCD LUT was calculated using the US standard climatology data, but the change of atmospheric temperature and pressure can slightly affect the O<sub>4</sub> absorption. However, since it is difficult to estimate the accurate uncertainty and real-time measurements of temperature and pressure profiles were not available, the error caused by the variation of the atmospheric profile was not taken into account in calculating the total uncertainties.

d. Systematic effect of the surface albedo on the measurements at the high-altitude station: due to the dependence of the snow coverage on altitude, the surface albedo close to the instrument is typically higher than at locations far away. Since the measurements at high elevations are usually more sensitive to air masses closer to the instrument, they are probably more strongly affected by snow and ice comparing to the measurements at low elevations. In this study, this effect could not be further quantified, but it might be one reason for the need of different O<sub>4</sub> DSCD scaling factors for different elevations, see Section 5.10.

In order to avoid the underestimation of the measurement uncertainty, we set a relatively relaxed threshold of cost functions for choosing valid profiles, see Section 5.9.

## 5.9 Aerosol profile inversion method

Aerosol extinction profiles were retrieved from the measured O<sub>4</sub> DSCDs of each scanning cycle. The measurements of the UV and VIS bands were retrieved separately. The measured O<sub>4</sub> DSCDs at the UV and VIS bands were fitted to the O<sub>4</sub> DSCDs simulated at 360 and 477 nm, respectively. In the retrieval, we assume the state of atmosphere is stable during a scanning cycle, and the distribution of aerosols is homogeneous in horizontal direction. For a single scanning cycle, the measured O<sub>4</sub> DSCDs at the wavelength  $\lambda$  are denoted as a measurement vector

$$\mathbf{y}_m = \begin{pmatrix} \Delta S_{\lambda,1} \\ \Delta S_{\lambda,2} \\ \vdots \\ \Delta S_{\lambda,M} \end{pmatrix}, \quad (5.9)$$

where  $M$  is the number of off-zenith measurements in each scanning cycle, which

is 6 in this study.  $\Delta S_{\lambda,1}, \Delta S_{\lambda,2}, \dots, \Delta S_{\lambda,6}$  are the  $O_4$  DSCDs measured at the wavelength band  $\lambda$  and at the viewing elevation angles of  $1^\circ, 2^\circ, 5^\circ, 10^\circ, 20^\circ$ , and  $30^\circ$ , respectively.

The simulated  $O_4$  DSCDs corresponding to each possible aerosol extinction profile in  $X_{\text{LUT}}$  can be obtained from the LUT. Similar to  $\mathbf{y}_m$ , the simulation vector  $\mathbf{y}_s$  for each possible profile  $\mathbf{x}$  is denoted as

$$\mathbf{y}_s(\mathbf{x}) = \begin{pmatrix} f(\mathbf{x}, \lambda, \alpha_1, \theta_1, \phi_1) \\ f(\mathbf{x}, \lambda, \alpha_2, \theta_2, \phi_2) \\ \vdots \\ f(\mathbf{x}, \lambda, \alpha_M, \theta_M, \phi_M) \end{pmatrix}, \text{ for } \mathbf{x} \in X_{\text{LUT}}. \quad (5.10)$$

Aerosol extinction profiles can be derived by fitting the forward simulation to the measured  $O_4$  DSCDs. Typically, the optimal solution can be determined by minimizing the cost function, which was defined as

$$\chi^2(\mathbf{x}) = [\mathbf{y}_m - \mathbf{y}_s(\mathbf{x})]^T \cdot \mathbf{S}_\epsilon^{-1} \cdot [\mathbf{y}_m - \mathbf{y}_s(\mathbf{x})], \quad (5.11)$$

where  $\mathbf{S}_\epsilon$  is the data error covariance matrix. Assuming the measurement of each viewing elevation is independent,  $\mathbf{S}_\epsilon$  is a diagonal matrix and its diagonal elements equal to the square of the total uncertainties of each elevation defined in Eq. (5.8),

$$\mathbf{S}_\epsilon = \begin{bmatrix} \epsilon_1^2 & 0 & \dots & 0 \\ 0 & \epsilon_2^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \epsilon_M^2 \end{bmatrix}. \quad (5.12)$$

Our cost function definition is similar to the cost functions used in many of the MAX-DOAS studies based on the OEM (e.g., Cl mer et al., 2010; Frie  et al., 2016; Wang et al., 2016; Chan et al., 2017), but only includes the item related to measurement error, while the item related to the a priori profile is omitted. This is because the a priori profile is not needed in our retrieval algorithm.

$\chi^2$  indicates the difference between  $\mathbf{y}_s$  and  $\mathbf{y}_m$ , however, as the retrieval is ill-posed and the SNR of the measurement at the UFS is low, the single profile with the lowest  $\chi^2$  is not necessarily the one closest to the true profile. In order to overcome this limitation, we consider all the profiles in  $X_{\text{LUT}}$  with  $\chi^2(\mathbf{x}) \leq 1.5M$  (9 in this study) as valid profiles and calculate the weighted mean profile as the

optimal result. A profile with  $\chi^2 \leq M$  indicates that the measured and simulated  $O_4$  DSCDs agree within the measurement uncertainties, but in order to avoid underestimation of the measurement uncertainties, we defined the threshold as  $1.5M$ . The weight of each valid profile in the calculation of the optimal solution is defined based on its cost function:

$$w(\mathbf{x}) = \frac{1/\chi^2(\mathbf{x})}{\sum [1/\chi^2(\mathbf{x})]}, \text{ for } \mathbf{x} \in X_{\text{LUT}} \text{ and } \chi^2(\mathbf{x}) \leq 1.5M. \quad (5.13)$$

The optimal solution is then defined as the weighted mean of all the valid profiles, which can be calculated as

$$\hat{\mathbf{x}} = \sum w(\mathbf{x}) \cdot \mathbf{x}, \text{ for } \mathbf{x} \in X_{\text{LUT}} \text{ and } \chi^2(\mathbf{x}) \leq 1.5M. \quad (5.14)$$

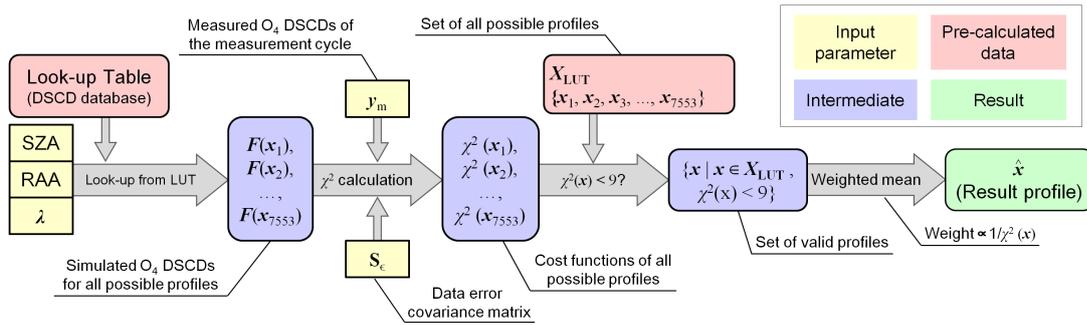


Figure 5.23: Procedure of the aerosol profile inversion method.

The procedure of the aerosol profile inversion method is summarized in Figure 5.23.

## 5.10 $O_4$ DSCD correction

Discrepancies between measured and simulated  $O_4$  DSCDs have been found in many other MAX-DOAS studies (Wagner et al., 2009; Clémer et al., 2010; Chan et al., 2015; Wang et al., 2016; Chan et al., 2017; Wagner et al., 2019). The discrepancies were often explained by the systematic errors of the absorption cross section of  $O_4$  as well as the radiative transfer simulation, and a correction is therefore necessary. Some previous studies suggested to multiply a constant scaling factor to the measured  $O_4$  DSCD for all elevations to correct for the

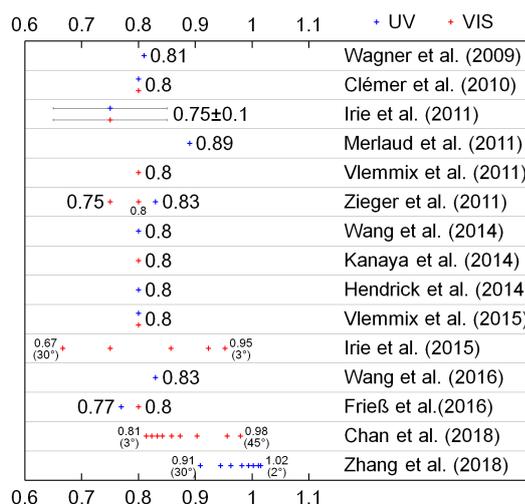


Figure 5.24: O<sub>4</sub> DSCD scaling factors suggested by some previous studies.

systematic error. The scaling factor typically varies between 0.75 and 0.9, and the most common value is 0.8 (e.g., Wagner et al., 2009; Clémer et al., 2010; Irie et al., 2011; Merlaud et al., 2011; Vlemmix et al., 2011; Zieger et al., 2011; Wang et al., 2014a; Kanaya et al., 2014; Hendrick et al., 2014; Vlemmix et al., 2015; Wang et al., 2016; Frieß et al., 2016). Some recent studies suggested elevation-dependent scaling factors: Irie et al. (2015) suggested a set of scaling factors for 477 nm which gradually decreases with increasing elevation angle, varying from 0.952 for 3° to 0.667 for 30°; Zhang et al. (2018) suggested a set of scaling factors for 360 nm which also decreases with increasing elevation angle, varying from from 1.02 for 1° to 0.909 for 30°; Chan et al. (2017) derived a set of elevation-dependent scaling factors for 477 nm by comparing modeled and measured (relative) intensities, varying from 0.792 for 1° to 0.957 for 30°. The scaling factors suggested by some previous studies are summarized in Figure 5.24. On the other hand, some other MAX-DOAS studies did not find it necessary to apply any corrections to O<sub>4</sub> DSCDs. For example, Frieß et al. (2011) reported that for the MAX-DOAS measurements in an Arctic area, the measured and simulated O<sub>4</sub> DSCDs are in good agreement without any correction. Note that the scaling factor mentioned here refers to the ratio between simulated and measured O<sub>4</sub> DSCDs, which is opposite to some other studies.

In order to assess whether an O<sub>4</sub> DSCD correction is necessary for the MAX-DOAS measurements at the UFS, we compared the measured O<sub>4</sub> DSCDs to the simulated ones in the LUT. Assuming our profile set ( $X_{LUT}$ ) covers all possi-

ble aerosol profiles under cloud-free conditions, we derived the  $O_4$  scaling factor for each elevation angle and each wavelength based on statistical analysis. The AODs measured by the sun photometer were used to restrict the range of possible profiles.

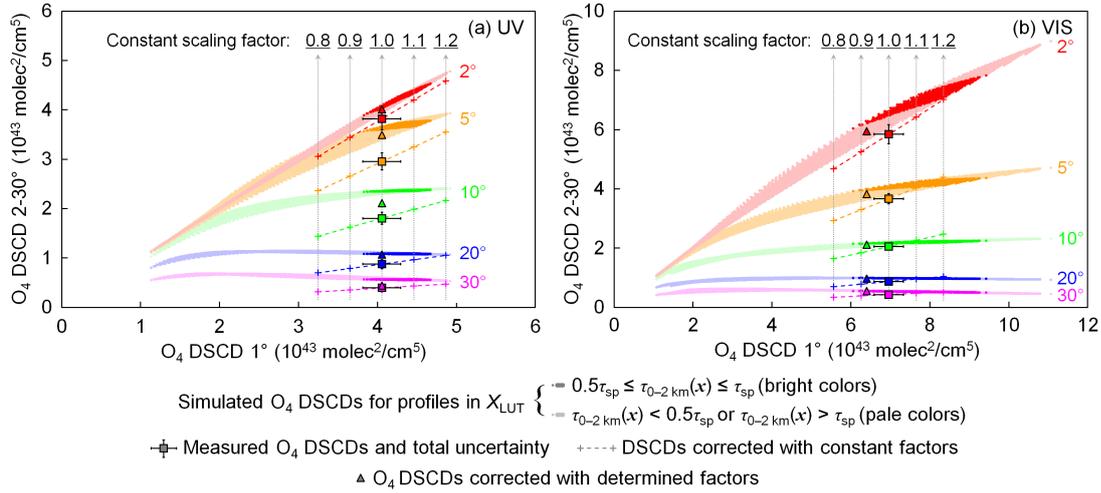


Figure 5.25: Distribution of simulated, measured and corrected  $O_4$  DSCDs of (a) UV and (b) VIS bands of the scanning cycle on 07 Dec 2015 at  $\sim 13:55$  UTC (SZA  $\sim 79^\circ$ , RAA  $\sim 39^\circ$ ). The  $x$ -axes indicate the  $O_4$  DSCDs measured (or simulated) at the elevation of  $1^\circ$ , while the  $y$ -axes represent the  $O_4$  DSCDs measured (or simulated) at the other five elevations. Different colors indicate measurements at different elevations. The colored dots show the simulated  $O_4$  DSCDs of all possible profiles in the profile set ( $X_{LUT}$ ). The data points of the profiles with AOD between 0 and 2 km ( $\tau_{0-2\text{ km}}(\mathbf{x})$ ) varies between 50% and 100% of the total AOD measured by the sun photometer ( $\tau_{sp}$ ) are shown in bright colors, while the dots of the other profiles are shown in pale colors. The square markers represent measured  $O_4$  DSCDs, and the error bars show the total uncertainties. Systematic errors caused by the topography simplification are already corrected from the measured  $O_4$  DSCDs. The plus signs along the dashed lines show the measured  $O_4$  DSCDs corrected with constant factors of 0.8, 0.9, 1.1 and 1.2. The triangle markers show the measured  $O_4$  DSCDs corrected with the finally determined scaling factors listed in Table 5.6.

Figure 5.25 shows the scattered plots of measured and simulated  $O_4$  DSCDs of the scanning cycle measured on 07 December 2015 at  $\sim 13:55$  UTC. The measurements of both (a) UV and (b) VIS bands are shown. According to the cloud screening as well as the skycam images, this day was absolutely cloud free. The total AOD measured by the sun photometer at that time was 0.02 and 0.017 at 360 and 477 nm bands, respectively. In each plot, the  $x$  axis indicates the  $O_4$  DSCDs

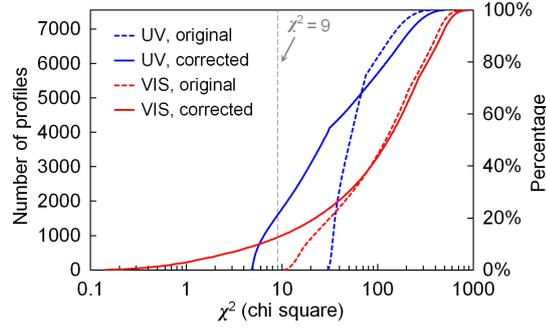


Figure 5.26: Cumulative distribution of the  $\chi^2$  of all profiles in  $X_{\text{LUT}}$  for the scanning cycle at 07 Dec 2015  $\sim$ 13:55 UTC (SZA  $\sim$ 79°, RAA  $\sim$ 39°). Dashed and solid curves refer to the results before and after the O<sub>4</sub> DSCD correction, respectively. Blue and red curves refer to the results of the UV and VIS bands, respectively. Note that the  $x$  axis is logarithmically scaled.

measured (or simulated) at the elevation of 1°, while the  $y$  axis represents the O<sub>4</sub> DSCDs at the other five off-zenith elevations. Different colors indicate measurements at different elevations. The simulated O<sub>4</sub> DSCDs ( $\mathbf{y}_s(\mathbf{x})$ ) of all the possible profiles in  $X_{\text{LUT}}$  are shown as colored dots. We assume the MAX-DOAS measurement of AOD between 0 and 2 km above instrument (denoted as  $\tau_{0-2\text{km}}$ ,  $\tau_{0-2\text{km}}(\mathbf{x}) = 0.5\sigma_1(\mathbf{x}) + 0.5\sigma_2(\mathbf{x}) + \sigma_3(\mathbf{x})$ ) varies between 50% and 100% of the total AOD measured by the sun photometer (denoted as  $\tau_{\text{sp}}$ ) in most cases, and the data points of the profiles fulfilling this assumption are highlighted in the plots. The measured O<sub>4</sub> DSCDs (already corrected for the systematic errors caused by the topography simplification) are plotted as square markers with error bars showing the total uncertainties. It is obvious that at most of the elevations, the measured O<sub>4</sub> DSCD does not agree with the simulations within the total error. As a result, at both UV and VIS bands, no profiles in  $X_{\text{LUT}}$  satisfy the selection requirement ( $\chi^2 \leq 9$ , see dashed curves in Figure 5.26). No profiles matching the measurement is unlikely to happen under such clear sky condition, hence, implies a systematic error and correction of the error is necessary.

In order to determine whether the O<sub>4</sub> scaling factor is constant for all the elevations or dependent on the viewing elevation angles, we first assume it is constant and plot the corrected O<sub>4</sub> DSCD measurements in Figure 5.25. The plus signs indicate the measured O<sub>4</sub> DSCDs corrected with constant scaling factors of 0.8, 0.9, 1.1 and 1.2. Furthermore, the corrected O<sub>4</sub> DSCDs should vary along the colored dashed lines simultaneously if any other constant scaling factor is applied

to the measurements. However, the forward simulation of  $O_4$  DSCDs does not overlap with the dashed lines in most of the cases (especially for  $5^\circ$  and  $10^\circ$  of the UV band), indicating that a constant  $O_4$  scaling factor for all viewing elevations could not resolve the systematic error. Therefore, different scaling factors should be applied to different elevations.

In this study, the  $O_4$  DSCD scaling factors for each viewing elevation and each wavelength were determined through the statistical analysis of the long-term observations. We assume the scaling factors mainly depend on the viewing elevation angle, while being less sensitive to other factors such as solar geometry, aerosol load, temperature etc.

### 5.10.1 Determination of scaling factors of high elevations

Figure 5.25 shows that the simulated  $O_4$  DSCDs at high elevations (e.g.  $20^\circ$  and  $30^\circ$ ) vary in very narrow ranges. Based on the assumption that  $X_{LUT}$  covers all possible aerosol profiles, the measured  $O_4$  DSCDs should lie within the ranges. Therefore, the scaling factors can be derived by taking the ratio of the simulated and measured values. As the simulated values vary in narrow ranges, the uncertainties of the derived scaling factors should also be low. In order to determine more convincing scaling factors, we derived optimal results from the big data of the long-term measurements. In addition, only the measurements taken under cloud-free and low aerosol load ( $\tau_{sp} \leq 0.03$ ) conditions were used, so as to avoid accounting data contaminated by clouds in the analysis. Here it should be noted that the measurements with  $AOD \leq 0.03$  are almost entirely found during winters due to the strong seasonal variation of aerosol load at the UFS.

Subsequently, for the wavelength  $\lambda$  and the  $i^{\text{th}}$  elevation of each scanning cycle, we found out the simulated  $O_4$  DSCDs corresponding to all the profiles in  $X_{LUT}$  fulfilling  $0.5\tau_{sp,\lambda} \leq \tau_{0-2\text{km}}(\mathbf{x}) \leq \tau_{sp,\lambda}$  from the LUT. The simulated  $O_4$  DSCDs can be described as a set,

$$Y_{\lambda,i}^* = \{f(\mathbf{x}, \lambda, \alpha_i, \theta_i, \phi_i) \mid \mathbf{x} \in X_{LUT}, 0.5\tau_{sp,\lambda} \leq \tau_{0-2\text{km}}(\mathbf{x}) \leq \tau_{sp,\lambda}\}. \quad (5.15)$$

Only if  $\max(Y_{\lambda,i}^*) \leq 1.1\min(Y_{\lambda,i}^*)$ , then the scanning cycle was taken into account. In most cases, measured  $O_4$  DSCDs at high elevations are lower than simulated ones, therefore we calculated the scaling factor from the minimum in

$Y_{\lambda,i}^*$  to avoid over-estimation of the scaling factor. Hence for each of such scanning cycles, the suggested scaling factor is the ratio between the minimum simulated O<sub>4</sub> DSCD and the measured O<sub>4</sub> DSCD, which can be described as

$$\gamma_{\lambda,i}^* = \frac{\min(Y_{\lambda,i}^*)}{\Delta S_{\lambda,i}}, \quad (5.16)$$

where  $\Delta S_{\lambda,i}$  is the measured O<sub>4</sub> DSCD (already corrected for the systematic errors caused by the topography). For the elevations of 5°, 10°, 20°, and 30° at UV band and 10°, 20°, and 30° at VIS band, numerous scanning cycles from the long-term measurement fulfill the selection criterion, so there are sufficient samples of  $\gamma_{\lambda,i}^*$  for statistical analysis. In order to derive the optimal scaling factors, we analyzed the frequency distribution of  $\gamma_{\lambda,i}^*$  for each elevation and each band. We found that for all of the high elevations and both bands, the distribution of  $\gamma_{\lambda,i}^*$  follows the normal distribution function with a single sharp peak. Subsequently, the optimal scaling factor of each elevation and each wavelength ( $\hat{\gamma}_{\lambda,i}$ ) was defined as the expected value of  $\gamma_{\lambda,i}^*$ , which is the mode of  $\gamma_{\lambda,i}^*$  derived by Gaussian fit,

$$\hat{\gamma}_{\lambda,i} = E[\gamma_{\lambda,i}^*]. \quad (5.17)$$

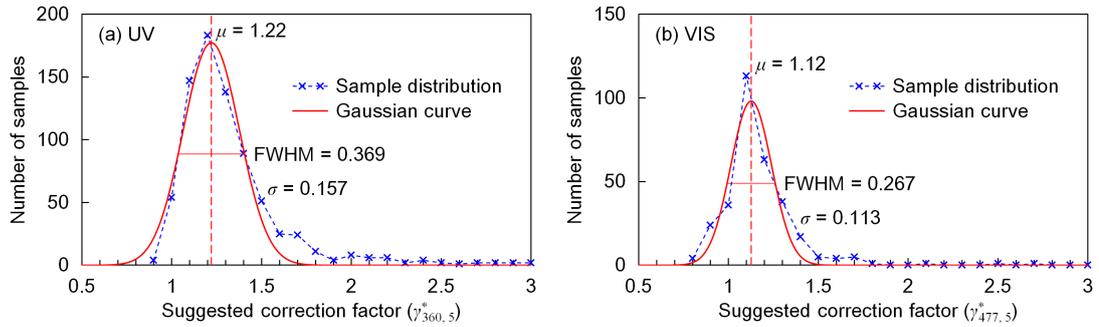


Figure 5.27: Gaussian fits for deriving the O<sub>4</sub> DSCD scaling factors of 20° for (a) UV and (b) VIS bands. The frequency distributions are counted for bins of 0.1. In each plot, the vertical dashed line indicates the mode ( $\mu$ ) of suggested scaling factors derived by the Gaussian fit.

Figure 5.27 shows the Gaussian fits for deriving the scaling factors of 20° for UV and VIS bands.

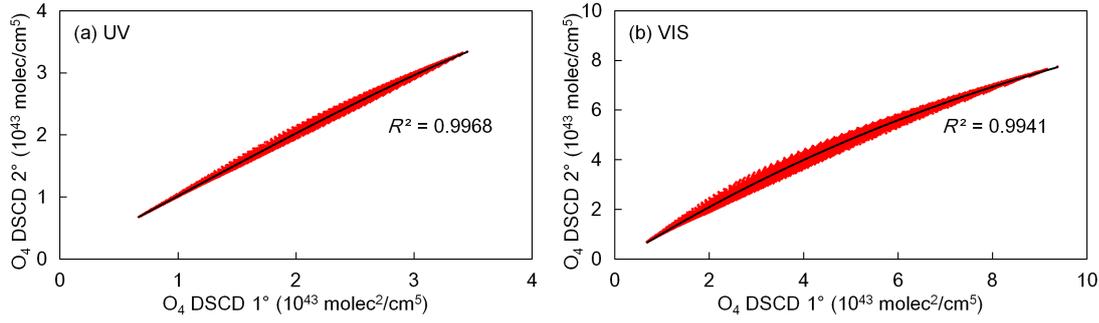


Figure 5.28: Correlation between simulated  $O_4$  DSCDs at  $2^\circ$  and  $1^\circ$  for all the profiles in  $X_{LUT}$  with  $0 \leq \tau_{0-2\text{km}}(\mathbf{x}) \leq 2\tau_{sp}$ , for (a) UV and (b) VIS bands of the measurement cycle on 30 Aug 2015 at  $\sim 11:00$  UTC.

### 5.10.2 Determination of scaling factors of low elevations

For the low elevations ( $1^\circ$  and  $2^\circ$  for UV band and  $1^\circ$ ,  $2^\circ$  and  $5^\circ$  for VIS band), as  $O_4$  DSCDs vary in wide ranges, it is impossible to determine the scaling factor using the method mentioned above. However, it is found that in many scanning cycles, within the possible profiles in  $X_{LUT}$ , the simulated  $O_4$  DSCDs at low elevations are well correlated to those at the neighboring elevation. An example is shown in Figure 5.28. Therefore, once the scaling factor of the higher elevation has been determined, we can derive an expected value of the  $O_4$  DSCD at the lower elevation from the corrected  $O_4$  DSCD at the higher elevation, and the suggested scaling factor can be derived by taking the ratio of the expected and the measured values.

For the wavelength  $\lambda$  and for each scanning cycle, a subset of  $X_{LUT}$  is defined as

$$X^\dagger = \{\mathbf{x} \mid \mathbf{x} \in X_{LUT}, 0 \leq \tau_{0-2\text{km}}(\mathbf{x}) \leq 2\tau_{sp,\lambda}\}, \quad (5.18)$$

and the elements of  $X^\dagger$  are denoted as  $\mathbf{x}_j^\dagger$ . The corresponding simulated  $O_4$  DSCDs at the  $i^{\text{th}}$  elevation are denoted as

$$\Delta S_{i,j}^\dagger = f(\mathbf{x}_j^\dagger, \lambda, \alpha_i, \theta_i, \phi_i), \text{ for } \mathbf{x}_j^\dagger \in X^\dagger. \quad (5.19)$$

For all the profiles in  $X^\dagger$ , a 3<sup>rd</sup> order polynomial regression was applied between  $\Delta S_{i,j}^\dagger$  and  $\Delta S_{i+1,j}^\dagger$ . The regression function is denoted as  $g$ . Only if the correlation coefficient  $R^2 \geq 0.98$ , this scanning cycle was taken into account. As the scaling factor of the  $(i+1)^{\text{th}}$  elevation ( $\hat{\gamma}_{\lambda,i+1}$ ) has already been determined, the expected

value of the O<sub>4</sub> DSCD at the  $i^{\text{th}}$  elevation can be derived from the corrected measured value at the  $(i + 1)^{\text{th}}$  elevation by the regression function:

$$E[\Delta S_{\lambda,i}] = g(\Delta S_{\lambda,i+1} \cdot \hat{\gamma}_{\lambda,i+1}), \quad (5.20)$$

and the scaling factor suggested by this scanning cycle is

$$\gamma_{\lambda,i}^{\dagger} = \frac{E[\Delta S_{\lambda,i}]}{\Delta S_{\lambda,i}}. \quad (5.21)$$

Like the high elevations, we found that for all the low elevations and the both bands, the frequency distribution of  $\gamma_{\lambda,i}^{\dagger}$  derived from the long-term measurements also follows the normal distribution, therefore the optimal scaling factor of each elevation and each wavelength was defined as the expected value of  $\gamma_{\lambda,i}^{\dagger}$  derived by fitting the frequency distribution to a Gaussian function,

$$\hat{\gamma}_{\lambda,i} = E[\gamma_{\lambda,i}^{\dagger}]. \quad (5.22)$$

Once  $\hat{\gamma}_{\lambda,i}$  has been determined, the scaling factor of the  $(i - 1)^{\text{th}}$  (lower) elevation can be derived in the same way. The scaling factors of 1° and 2° at UV band and 1°, 2°, 5° at VIS band were determined using this method.

### 5.10.3 Summary

Table 5.6: The finally determined O<sub>4</sub> DSCD scaling factors.

Elevation angle	Factors for corrected DSCDs <sup>(a)</sup>		Factors for original DSCDs	
	UV (360 nm)	VIS (477 nm)	UV (360 nm)	VIS (477 nm)
1°	1.00	0.92	0.97	0.90
2°	1.05	1.02	1.01	1.00
5°	1.18	1.04	1.14	1.02
10°	1.17	1.03	1.12	0.99
20°	1.22	1.12	1.16	1.08
30°	1.12	1.27	1.06	1.22

<sup>(a)</sup> Means the O<sub>4</sub> DSCDs which are already corrected for the systematic errors caused by the topography simplification.

The O<sub>4</sub> DSCD scaling factors determined by us are listed in Table 5.6. In Figure 5.25, the corrected O<sub>4</sub> DSCDs are indicated as triangles. The scaling factors show that except for the elevation of 1°, the simulated O<sub>4</sub> DSCDs are overestimated comparing to the measured ones. It should be noted that the de-

termination of the scaling factors is based on the measured  $O_4$  DSCDs which are already corrected for the systematic errors caused by the topography simplification (discussed in 5.5). Comparing to the original measurements, the results still indicate that the simulated  $O_4$  DSCDs at high elevations are overestimated. This result is opposite to the results of most of the other studies. At the moment we have no clear explanation for this finding, it might be related to the specific properties of the high-altitude station, e.g. the highly structured topography, horizontal gradients of the aerosol extinction, and the systematic dependence of the surface albedo on altitude.

Figure 5.26 shows the cumulative distribution of  $\chi^2$  of all the profiles in  $X_{LUT}$  for the scanning cycle shown in Figure 5.25. The distributions of  $\chi^2$  before and after the DSCD correction are shown as dashed and solid curves, respectively. The results indicate that for both UV (blue curves) and VIS (red curves) bands, the  $\chi^2$  of most profiles in  $X_{LUT}$  are significantly lower after the correction. As a result, a number of profiles can fulfill the selection criterion ( $\chi^2 \leq 9$ ) after the correction. Note that the AODs measured by MAX-DOAS are still expected to be lower than the sun photometer results due to the fact that the MAX-DOAS only reports the AOD below 2 km while the sun photometer covers the entire atmosphere.

## 5.11 Results and discussions

Our retrieval algorithm was applied to the long-term measurement data of the UFS MAX-DOAS from February 2012 to February 2013 and from July 2013 to February 2016. The results were also compared to sun photometer measurements. This section presents the results as well as their discussions.

### 5.11.1 Dependency of retrieval result on the threshold of cost function

As presented in Section 5.9, we consider all the profiles with  $\chi^2 \leq 9$  as valid profiles, and the retrieved profile is defined as the weighted mean of all the valid profiles. In this section, we investigate the dependency of the retrieval result on the threshold of  $\chi^2$  by comparing the results calculated with different  $\chi^2$  thresholds. Taking the two measurement cycles mentioned in Figure 5.21 and Figure 5.22 for example, Figure 5.29 (05 July 2015 at  $\sim 16:26$  UTC) and Figure 5.30 (07 Decem-

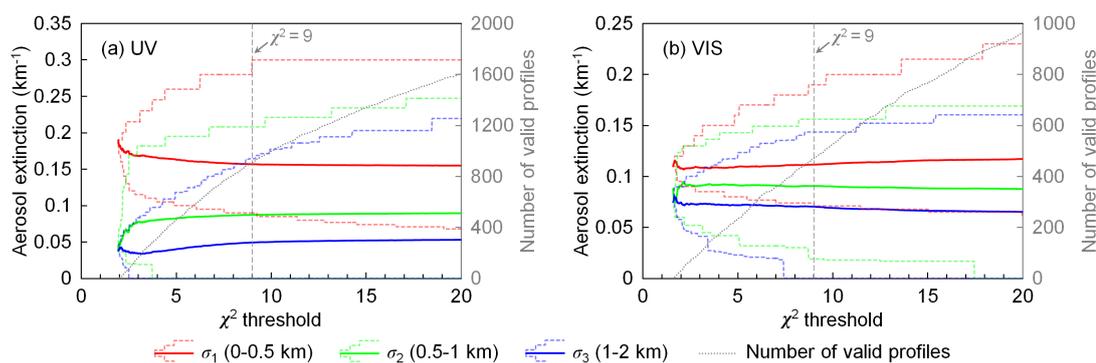


Figure 5.29: Weighted mean profiles, variation ranges of valid profiles and number of valid profiles corresponding to different  $\chi^2$  thresholds, results of (a) UV and (b) VIS bands of the scanning cycle on 05 Jul 2015 at  $\sim 16:26$  UTC (SZA  $\sim 64^\circ$ , RAA  $\sim 97^\circ$ ). The weighted mean profiles are shown as solid curves which indicate the aerosol extinction coefficients in the three layers ( $\sigma_1$ ,  $\sigma_2$ , and  $\sigma_3$ ). The variation ranges of valid profiles are shown as dashed curves which indicate the variation ranges of  $\sigma_1$ ,  $\sigma_2$ , and  $\sigma_3$ . The gray dotted curves indicate the number of valid profiles corresponding to different thresholds of  $\chi^2$ .

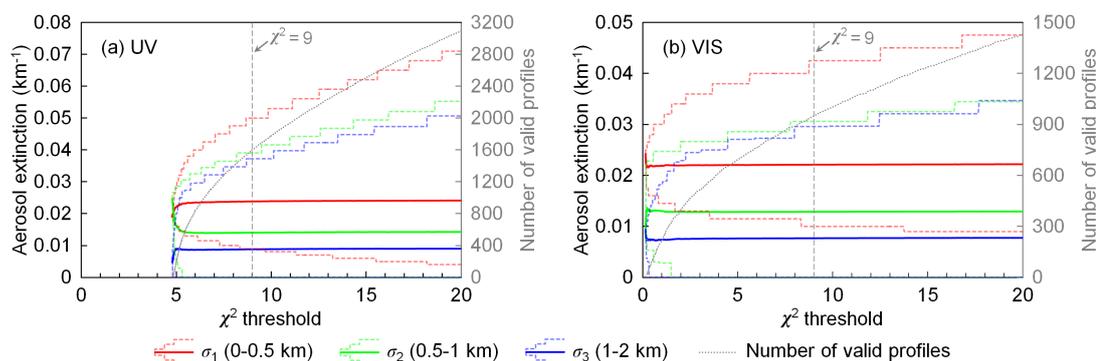


Figure 5.30: Same as Figure 5.29, but for the scanning cycle on 07 Dec 2015 at  $\sim 13:55$  UTC (SZA  $\sim 79^\circ$ , RAA  $\sim 39^\circ$ ).

ber 2015 at  $\sim 13:55$  UTC) show the weighted mean profiles, the variation range of valid profiles, and the number of valid profiles corresponding to different  $\chi^2$  thresholds. The profiles are shown as colored curves which indicate the aerosol extinction coefficients in the three layers (i.e.,  $\sigma_1$ ,  $\sigma_2$ , and  $\sigma_3$ ).

The results of both scanning cycles show that the retrieved profiles are insensitive to the threshold of  $\chi^2$  when there are a sufficient number of valid profiles (number of profiles exceeds  $\sim 800$  and  $\sim 400$  for UV and VIS bands, respectively; see the gray curves in Figure 5.29 and Figure 5.30). This is because the profiles

with larger  $\chi^2$  have lower weight ( $w$ ). In addition, when the threshold value is increased, more profiles with both higher and lower aerosol extinction coefficients are taken into account. As a result, the variation range of valid profiles becomes larger but the weighted mean remains similar. The results show that the retrieval with a  $\chi^2$  threshold of 9 is stable; therefore, it is used in the study.

### 5.11.2 Estimation of the uncertainties of retrieved profiles

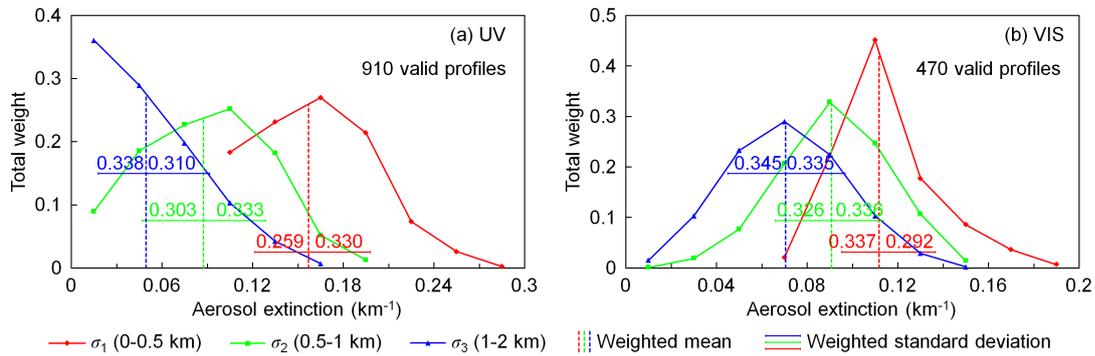


Figure 5.31: Weight distributions of valid profiles of (a) UV and (b) VIS bands, results of the scanning cycle on 05 Jul 2015 at  $\sim 16:26$  UTC (SZA  $\sim 64^\circ$ , RAA  $\sim 97^\circ$ ). The weight distributions of the aerosol extinction coefficients of the three layers ( $\sigma_1$ ,  $\sigma_2$  and  $\sigma_3$ ) are shown as solid curves with different colors. The vertical dashed lines indicate the weighted mean aerosol extinction coefficient of the three layers ( $\sigma_1(\hat{x})$ ,  $\sigma_2(\hat{x})$  and  $\sigma_3(\hat{x})$ ). The error bars indicate the weighted standard deviation calculated with Eq. (5.23) and (5.24). The numbers on the error bars refer to the total weight ( $w$ ) of the profiles covered by each error bar.

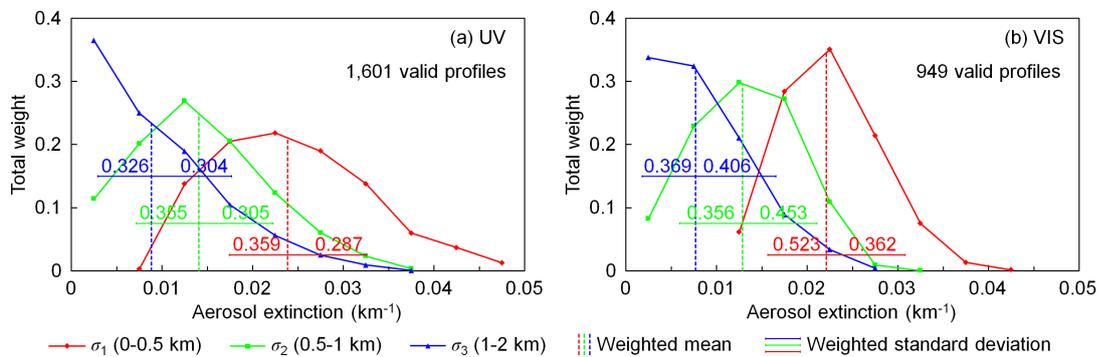


Figure 5.32: Same as Figure 5.31, but for the scanning cycle on 07 Dec 2015 at  $\sim 13:55$  UTC (SZA  $\sim 79^\circ$ , RAA  $\sim 39^\circ$ ).

Still taking the two measurement cycles mentioned in Section 5.11.1 as examples, we analyze the weight distribution of valid profiles, see Figure 5.31 and Figure 5.32. The distributions of aerosol extinction coefficients in the three altitude layers ( $\sigma_1$ ,  $\sigma_2$ , and  $\sigma_3$ ) are shown as solid curves. For each layer, aerosol extinction coefficients of all valid profiles were grouped, and the  $y$  axis refers to the total weight of each group. In each chart, the three vertical dashed lines indicate the weighted mean aerosol extinction coefficient of each layer (i.e.,  $\sigma_1$ ,  $\sigma_2$ , and  $\sigma_3$  of  $\hat{\mathbf{x}}$ ). The results show that the distributions of  $\sigma_1$ ,  $\sigma_2$  and  $\sigma_3$  are all asymmetric for both the UV and VIS bands. In particular for the layer of 1–2 km ( $\sigma_3$ ) at UV band, the weight decreases monotonically with increasing aerosol extinction in both of the two cycles. Taking the cycle shown in Figure 5.32 (07 December 2015 at  $\sim 13:55$  UTC) as an example, there are altogether 205 (12.8%) and 120 (12.6%) valid profiles with  $\sigma_3 = 0$  at UV and VIS bands, respectively. These profiles contribute total weights of 0.122 and 0.101 for the UV and VIS retrievals, respectively.

In order to estimate the uncertainty of  $\hat{\mathbf{x}}$ , we calculated the weighted standard deviations of  $\sigma_1$ ,  $\sigma_2$  and  $\sigma_3$  of all valid profiles. Due to the asymmetric distribution, the weighted standard deviations were calculated separately for the left (negative) and right (positive) sides. For the  $l^{\text{th}}$  ( $l = 1, 2, \text{ or } 3$ ) layer, denote the aerosol extinction coefficient of each valid profile as  $\sigma_l(\mathbf{x})$ , then the weighted standard deviation of the left side was calculated from all the valid profiles with  $\sigma_l(\mathbf{x}) < \sigma_l(\hat{\mathbf{x}})$ ,

$$SD_l^- = \sqrt{\frac{\sum w(\mathbf{x}) \cdot [\sigma_l(\hat{\mathbf{x}}) - \sigma_l(\mathbf{x})]^2}{\sum w(\mathbf{x})}}, \quad (5.23)$$

$$\text{for } \mathbf{x} \in X_{\text{LUT}} \text{ and } \chi^2(\mathbf{x}) \leq 1.5M \text{ and } \sigma_l(\mathbf{x}) < \sigma_l(\hat{\mathbf{x}}),$$

and the weighted standard deviation of the right side was calculated from all the valid profiles with  $\sigma_l(\mathbf{x}) > \sigma_l(\hat{\mathbf{x}})$ ,

$$SD_l^+ = \sqrt{\frac{\sum w(\mathbf{x}) \cdot [\sigma_l(\mathbf{x}) - \sigma_l(\hat{\mathbf{x}})]^2}{\sum w(\mathbf{x})}}, \quad (5.24)$$

$$\text{for } \mathbf{x} \in X_{\text{LUT}} \text{ and } \chi^2(\mathbf{x}) \leq 1.5M \text{ and } \sigma_l(\mathbf{x}) > \sigma_l(\hat{\mathbf{x}}).$$

The uncertainties of  $\hat{\mathbf{x}}$  are indicated as error bars in Figure 5.31 and Figure 5.32. For each layer, the total weight of the profiles covered by the error bar is labeled in the charts. At the UV band, the total weight of the valid profiles

covered by the uncertainties is 59–66%, which is close to the standard normal distribution. However, the percentage can be up to 90% at the VIS band. This is because the SNR of the measurement at the VIS band is higher. Therefore the retrieval of VIS band has higher selectivity, and the weight is more concentrated to the mean value.

### 5.11.3 Retrieval of synthetic measurement data

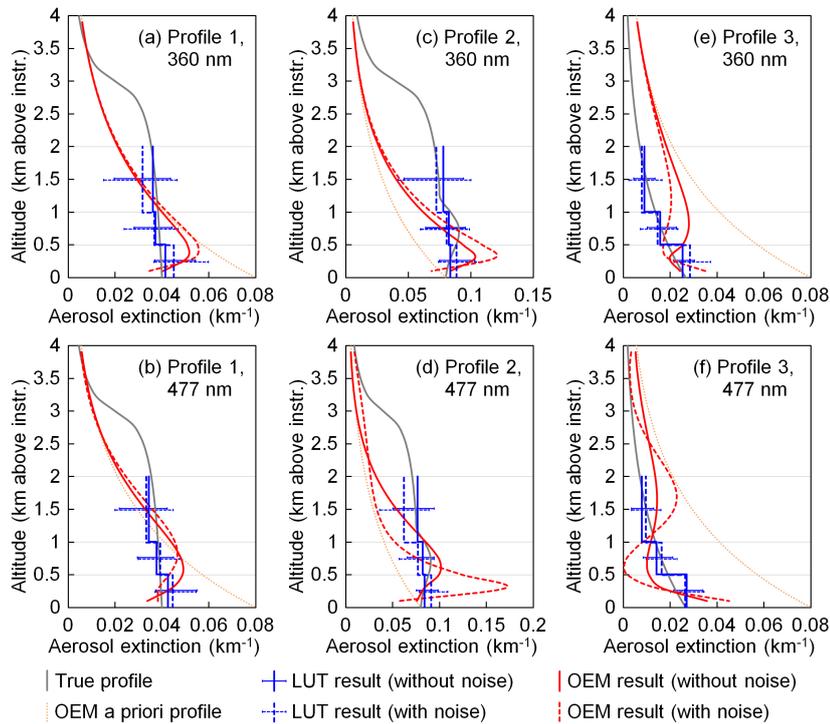


Figure 5.33: Retrieval results of three sets of synthetic data at (a, c, and e) 360 nm and (b, d, and f) 477 nm. The gray curves show the true profiles, with which the synthetic  $O_4$  DSCDs were simulated. The blue and red curves represent the profiles retrieved using our algorithm and BePRO, respectively. The solid blue and red curves represent the profiles retrieved from the original synthetic data, and the dashed curves represent the profiles retrieved from the synthetic data with random noise added. The error bars of the blue curves indicate the uncertainties calculated by Eq. (5.23) and (5.24). The dotted orange curve in each chart is the a priori profile used in the retrievals using BePRO.

In order to test the effectiveness of our retrieval algorithm, we generated some synthetic measurement data and then retrieved using our algorithm. Figure 5.33 shows the results of three representative synthetic profiles at 360 and 477 nm. In

each chart, the true profile is shown as the gray curve. Profile 1 is a tangent curve with aerosols distributed between 0 and 6 km above instrument. The aerosol extinction decreases with increasing altitude, which is  $0.04 \text{ km}^{-1}$  at surface level,  $\sim 89\%$  at 2 km, and 50% at 3 km. The total AOD is 0.12, of which  $\sim 92\%$  is contributed from the altitude below 3 km. Profile 2 has a similar shape as Profile 1, but the aerosol extinction between 0.5 and 1 km above instrument has been enhanced. The aerosol extinction peaks at 0.75 km, and the average aerosol extinction coefficient between 0.5 and 1 km is larger than the bottom layer by  $\sim 10\%$ . In addition, the aerosol extinction coefficients at other altitudes are increased by a factor of 2 comparing to Profile 1. Profile 3 is an exponential profile. The total AOD is 0.04, the SH is 1.5 km, and the surface aerosol extinction coefficient is  $0.0267 \text{ km}^{-1}$ .

We first simulated  $\text{O}_4$  DSCDs at 360 and 477 nm and at the elevations of  $1^\circ$ ,  $2^\circ$ ,  $5^\circ$ ,  $10^\circ$ ,  $20^\circ$  and  $30^\circ$  with each profile. The solar position was set as  $\text{SZA} = 60^\circ$  and  $\text{RAA} = 60^\circ$ , and the other parameters followed the settings used in calculating the LUT listed in Table 5.5 (excluding the aerosol extinction coefficients above 2 km). In order to test the stability of the retrieval, we also generated a set of noisy data for each profile and each wavelength by adding random noise to the simulated  $\text{O}_4$  DSCDs. We assume the measurement noise at all the elevations is at the same level and follows the normal distribution with a standard deviation of 2% of the DSCD at the lowest elevation. This noise level is realistic for the measurements at the UFS.

Aerosol profiles were then retrieved from both the original and noisy synthetic data using our algorithm. In the error estimation, the DOAS fitting error ( $\epsilon_{\text{fit}}$ ) was defined as the average values of the UFS measurements, while the other six kinds of errors followed the common settings presented in Section 5.8.  $\text{O}_4$  DSCD correction was not applied. The solid and dashed blue curves in Figure 5.33 show the profiles retrieved from the original and noisy data, respectively, and the error bars indicate the uncertainties calculated by Eq. (5.23) and (5.24). The results show that for Profile 1 and Profile 3, our retrieval algorithm can well reproduce the true profiles from not only the original data but also the noisy data. For Profile 2, the retrieved profile cannot reproduce the elevated layer, but the error bar covers the aerosol extinction of the true profile. This is because the retrieval is ill-posed, which means the limited input information does not only correspond to one or more profiles with elevated layers; instead, many other profiles without the elevated layer can also fit the input information. Adding noise to the synthetic

data can affect the retrieved aerosol extinction coefficients, however the influence is small in most cases. In addition, the noise can amplify the uncertainty of retrieved profile. The results indicate that our LUT-based retrieval is robust.

As in Section 5.2.3, we also tried to retrieve aerosol profiles from the synthetic data using the bePRO profiling tool. In the retrieval of all the 12 cases (three profiles, with and without noise, 360 and 477 nm), the a priori profile was defined as an exponential profile with  $\text{AOD} = 0.12$  and  $\text{SH} = 1.5$  km, shown as the dotted orange curve in each panel of Figure 5.33. The vertical grid was defined as 20 layers of 200 m thickness each. The definition of the uncertainty covariance matrix of a priori ( $\mathbf{S}_a$ ) is similar to Section 5.2.3. For Profiles 1 and 2, the scaling factor  $\beta$  was defined as 0.2 and the correlation length  $\gamma$  was defined as 0.05 km. For Profile 3, as the difference between the true and a priori profiles is quite large, we set  $\beta = 0.4$  and  $\gamma = 0.1$  km, so that the constrain from the a priori profile is weaker. The measurement uncertainty covariance matrix ( $\mathbf{S}_e$ ) was also defined as in most of the other MAX-DOAS studies that  $\mathbf{S}_e$  is a diagonal matrix with variances equal to the square of the DOAS fitting error ( $\epsilon_{\text{fit}}^2$ ). We defined  $\epsilon_{\text{fit}}$  the same as in the LUT-based retrieval, but the other six error sources were not included. The retrieval parameters related to the radiative transfer simulation followed the settings of our LUT-based retrieval.

The results retrieved from the data with and without noise are shown in Figure 5.33 as solid and dashed red curves, respectively. In all of the 12 retrieval cases, the  $\text{O}_4$  DSCDs simulated with the retrieved profiles are well correlated to the input values (the relative RMS error varies between 0.7% and 4.7%). However, as the retrieval is ill-posed, the retrieved profiles cannot reproduce the true profile well. Especially at high altitudes (above 1 km), the retrieved profiles are mostly dominated by the a priori profile. In addition, the OEM-based retrieval is sensitive to measurement noise, which can be seen from the large variations in the profile shape and aerosol extinction. The results indicate that our LUT-based algorithm is much more suitable for the measurements at the UFS.

#### 5.11.4 Comparison to sun photometer measurements

Figure 5.34 shows the comparison of the AODs measured by MAX-DOAS and sun photometer during the entire study period. The seasonally averaged AODs measured by both instruments are listed in Table 5.7. As the AODs measured by the MAX-DOAS refer to the AODs between 0 and 2 km while the AODs measured

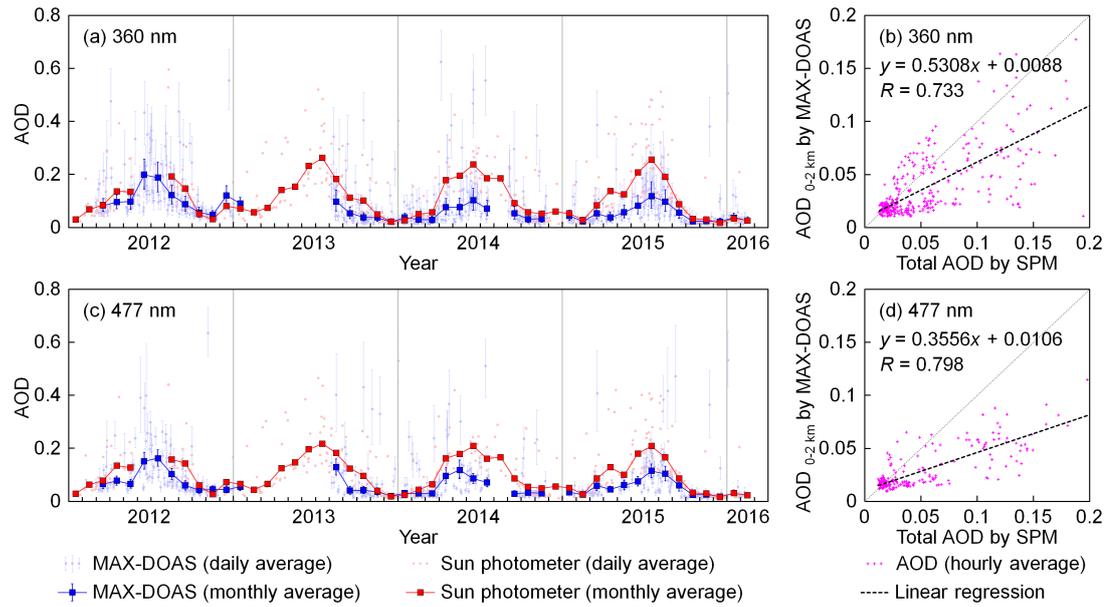


Figure 5.34: Comparison of AODs at (a and b) 360 nm and (c and d) 477 nm measured by the MAX-DOAS and sun photometer at the UFS. The charts on the left side (a and c) show the daily and monthly averaged time series, whereas the scatter plots on the right side (b and d) show the hourly averaged results. The AODs measured by MAX-DOAS refer to the vertical range between 0 and 2 km above the instrument (i.e.,  $\tau_{0-2\text{km}}(\hat{\mathbf{x}}) = 0.5\sigma_1(\hat{\mathbf{x}}) + 0.5\sigma_2(\hat{\mathbf{x}}) + \sigma_3(\hat{\mathbf{x}})$ ). The measurements were available during daytime with  $\text{SZA} < 85^\circ$  and cloud-free conditions. The AODs measured by the sun photometer refer to the total AODs, and only the measurements during 10:00–14:00 UTC were used due to their accuracy. The daily and monthly averaged results were calculated from all available hourly averaged AODs. The error bars of the MAX-DOAS data refer to the averages of the uncertainties calculated by Eq. (5.23) and (5.24). A few data points are outside the scatter plots.

by the sun photometer refer to the total AODs, the sun photometer results are expected to be larger. Despite the difference, the time series (Panels (a) and (c) of Figure 5.34) show that the AODs measured by both instruments have a similar seasonal variation with the highest AOD in summer and the lowest in winter. The monthly averaged data show that the difference between the AODs measured by MAX-DOAS and sun photometer is much larger in summer, this coincides with the ceilometer profiles shown in Figure 3.15 which indicate much higher aerosol extinction coefficients above 2 km (4,650 m a.s.l.) in summer.

The correlation between hourly averaged AODs measured by MAX-DOAS and sun photometer is shown in Figure 5.34 (b, d). AODs show a general agree-

Table 5.7: Seasonal average AODs measured by the MAX-DOAS and sun photometer at the UFS. The AODs measured by MAX-DOAS refer to the AODs between 0 and 2 km above instrument (i.e., 2,650–4,650 m a.s.l.), and the measurements were available during the daytime with  $SZA < 85^\circ$  and no cloud; the AODs measured by sun photometer refer to the total AOD, and the measurements were only available during 10:00–14:00 UTC. The results listed in the table were calculated from all available hourly averaged AODs.

Season	AOD (0–2 km) measured by MAX-DOAS		Total AOD measured by sun photometer	
	360 nm	477 nm	360 nm	477 nm
Spring (MAM)	0.064	0.065	0.106	0.101
Summer (JJA)	0.121	0.114	0.214	0.184
Autumn (SON)	0.048	0.040	0.070	0.068
Winter (DJF)	0.028	0.024	0.037	0.033

ment at the UV and the VIS bands with correlation coefficients of  $R = 0.733$  and  $0.798$ , respectively. However, AODs from MAX-DOAS are lower, consequently the slopes of the regression lines are  $0.5308$  and  $0.3556$  for UV and VIS bands, respectively. This is within expectation due to the different definitions of AODs. It is in particular true in cases of large AODs due to very strong convection of polluted air masses from the valley and/or the presence of Saharan dust layers. Then, particles are often transported beyond the range of the MAX-DOAS measurements and the disagreement is largest. This feature might be strengthened by the decreased sensitivity of the MAX-DOAS measurements at higher altitudes, so that the upper part of an aerosol layer is missed. In addition, a few data points lie above the 1:1 reference lines. This might be explained by the inhomogeneous distribution of aerosols in horizontal direction, and the light paths of the MAX-DOAS and the sun photometer are different. MAX-DOAS measures scattered sunlight while sun photometer derives the AOD from direct sun measurements. Therefore, when the aerosol load along the light path of MAX-DOAS is higher than that of the direct sun measurement, the AOD measured by the MAX-DOAS may exceed the one measured by the sun photometer. For most of these points, the difference between the results of the two instruments is within their uncertainty range, and the disagreement is probably due to the measurement and retrieval errors.

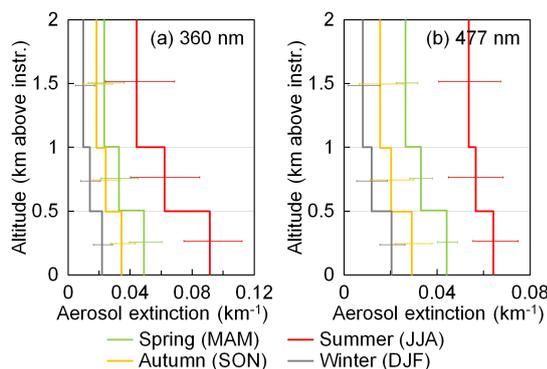


Figure 5.35: Seasonal average aerosol extinction profiles at (a) 360 and (b) 477 nm derived from the long-term measurement results of the MAX-DOAS at the UFS. The error bars represent the average uncertainties calculated by Eq. (5.23) and (5.24).

### 5.11.5 Temporal variation of aerosol characteristics

The seasonally averaged aerosol extinction profiles derived from the long-term measurements of the MAX-DOAS at the UFS are shown in Figure 5.35. The results indicate that the aerosol load at the UFS is highest in summer and lowest in winter, which coincides with the ceilometer results shown in Figure 3.15. The seasonal pattern can be explained by the higher biogenic emissions from vegetation in summer. Moreover, the mixing layer is higher in summer, thus anthropogenic aerosols are more likely dispersed to upper altitudes. The shape of the profiles also agree with the ceilometer results that the averaged aerosol extinction decreases with increasing altitude in all seasons — taking into account the coarse vertical resolution of the MAX-DOAS. In addition, Figure 5.35 shows a larger vertical gradient at 360 nm in summer. This might be explained by the lower sensitivity of the UV measurement for high altitudes due to the more decreased visibility at shorter wavelengths.

We compared the seasonally averaged aerosol extinction coefficients at 360 and 477 nm in the bottom layer (0–0.5 km above the instrument,  $\sigma_1$ ), see Figure 5.36. The averaged aerosol extinction coefficients are shown as bar charts. The ratios between the aerosol extinction coefficients at 360 and 477 nm are indicated by the gray curve. The results show that the aerosol extinction coefficient ratio between 360 and 477 nm is significantly higher in summer than in the other seasons.

The Ångström exponents (AEs) can be calculated from the ratios. The results are listed in Table 5.8. The seasonally averaged AEs of 380–500 nm from

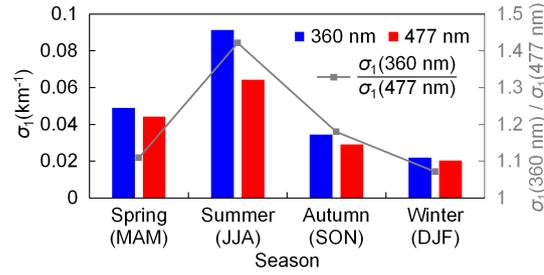


Figure 5.36: Comparison of seasonal average aerosol extinction coefficients at 360 and 477 nm in the bottom layer (0–0.5 km above instrument,  $\sigma_1$ ). The colored bars show the average aerosol extinction coefficients of the four seasons (equal to the bottom values shown in Figure 5.35). The gray square markers indicate the ratios between the aerosol extinction coefficients at 360 and 477 nm.

Table 5.8: Seasonal average Ångström exponents (AEs) obtained from MAX-DOAS near-surface measurements (0–0.5 km above instrument) and from AERONET measurements at Hohenpeißenberg. The results of MAX-DOAS were calculated from the ratios between the seasonal average aerosol extinction coefficients at 360 and 477 nm (i.e., the ratios shown in Figure 5.36). The results of AERONET are the seasonally averaged values of AEs (380–500 nm) at Hohenpeißenberg from Apr 2013 to Feb 2016.

Season	AE from UFS MAX-DOAS	AE from AERONET at Hohenpeißenberg
Spring (MAM)	0.37	1.26
Summer (JJA)	1.25	1.38
Autumn (SON)	0.59	1.05
Winter (DJF)	0.24	0.47

the AERONET measurements at Hohenpeißenberg from April 2013 to February 2016 are also listed for comparison. The result shows that both the UFS and Hohenpeißenberg measured the highest AE in summer and the lowest in winter. The AE at the UFS is in general lower than that measured at Hohenpeißenberg with a smaller difference in summer. This can be explained by the different altitude of the two sites. As the AERONET station at Hohenpeißenberg is located at  $\sim 950$  m a.s.l., larger contribution of anthropogenic aerosols is expected. The extremely low AE at the UFS in spring, autumn and winter agrees with the result measured at a plateau site (Lhasa, China, 3,688 m a.s.l.) reported in Xin et al. (2007). The annual mean AE at that site is reported to be  $0.06 \pm 0.31$ , which is significantly lower than those measured at low-altitude sites, in particular urban and forest sites. In general, a smaller AE implies larger aerosol particle

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sizes (Dubovik et al., 2002). The increased AE at the UFS in summer indicates a larger contribution of fine particles. The result is consistent with the fact that the particle size of biogenic secondary aerosols transported from the lower altitudes to upper altitudes in summer is in general smaller than ice particles.

# Chapter 6

## Retrieval of total VCDs of $\text{O}_3$ and $\text{NO}_2$

In this chapter, we present the retrieval of the total VCDs of  $\text{O}_3$  and  $\text{NO}_2$  from MAX-DOAS zenith measurements. Since off-zenith spectra were not used in such retrieval, the MAX-DOAS was virtually used as a ZSL-DOAS.

### 6.1 Basic principle

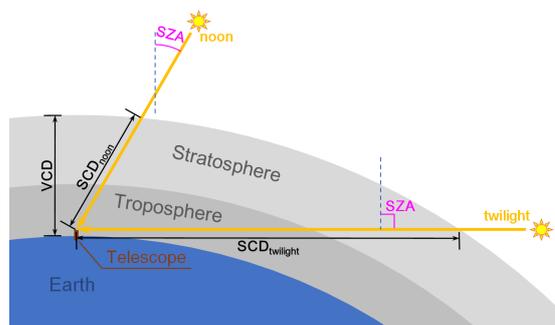


Figure 6.1: Light paths of scattered sunlight at noon and during twilight periods.

The vertical column density (VCD,  $V$ ) of a certain kind of atmospheric gas refers to the vertically integrated number density:

$$V = \int n(z)dz, \quad (6.1)$$

where  $z$  is the altitude, and  $n(z)$  is the number density at altitude  $z$ . In this study,

the total VCDs (the VCDs integrated from the ground surface to the top of the atmosphere) of O<sub>3</sub> and NO<sub>2</sub> were retrieved from the zenith spectra measured during twilight periods, i.e. the sunrise and sunset periods, when the SZA is close to 90°. In the retrieval, a fixed zenith spectrum measured at noon was used as the reference spectrum for the DSCD calculation. As illustrated in Figure 6.1, the light path at noon (especially in summer) is much shorter than the one during twilight periods. The air mass factor (AMF,  $A$ ), which means the ratio between the SCD and the VCD of trace gas, can be calculated by RTM.

For the measurements during a single twilight period (usually about 0.5 h, when  $86^\circ < \text{SZA} < 90^\circ$ ), based on the definitions of AMF, SCD, DSCD, and VCD, as well as the assumption that the total VCDs of O<sub>3</sub> and NO<sub>2</sub> are stable within such a short time span, we can derive that

$$\Delta S_i = S_i - S_{\text{ref}} = V \cdot A_i - S_{\text{ref}}, \quad (6.2)$$

where  $\Delta S_i$  is the  $i^{\text{th}}$  DSCD measurement during the twilight period, which is the difference between the total SCDs of the  $i^{\text{th}}$  twilight measurement ( $S_i$ ) and the reference measurement ( $S_{\text{ref}}$ ).  $A_i$  is the AMF corresponding to the  $i^{\text{th}}$  measurement. As the reference spectrum is fixed and the total VCD ( $V$ ) is assumed to be constant, the DSCD ( $\Delta S$ ) would be a linear function of the AMF ( $A$ ). Since we have a number of DSCD measurements during each twilight period and their corresponding AMFs are also available,  $V$  and  $S_{\text{ref}}$  can be derived by applying a linear regression between  $\Delta S_i$  and  $A_i$ . The mean total VCD during the period is then given by the slope of the fitted trend line, and  $S_{\text{ref}}$  can be derived from the intercept of the linear fit (multiplied by  $-1$ ). This method is called Langley plot.

Once  $S_{\text{ref}}$  is known, the VCD of each measurement ( $V_i$ ) can be calculated:

$$V_i = \frac{\Delta S_i + S_{\text{ref}}}{A_i}, \quad (6.3)$$

and the mean total VCD during the twilight period ( $\bar{V}$ ) can be calculated in a simpler way:

$$\bar{V} = \frac{\sum_{i=1}^n V_i}{n}, \quad (6.4)$$

where  $n$  is the number of measurements in the period.

The Langley plot method has some limitations. First, the assumption that the total VCD is stable over the twilight period must be fulfilled, however, even if the

plot shows a straight line, this assumption is not necessarily correct (Marenco, 2007). Second, the AMFs must be accurately calculated, however, the actual AMFs can be influenced by clouds and aerosols, as well as the actual profile of the trace gas. In addition, errors exist in the measured DSCDs, especially due to the varying temperature. Therefore, in most other studies (e.g., Vaughan et al., 1997; Chen, 2008), the Langley plot method was only used to derive  $S_{\text{ref}}$ , while the total VCDs were calculated using Eq. (6.3) and (6.4), as this method is more robust than the Langley plot method (Bassford et al., 2001).

## 6.2 DSCD calculation

For the retrieval of the total VCDs of O<sub>3</sub> and NO<sub>2</sub>, the DSCDs were both calculated from VIS spectra using DOAS method. The fit settings are summarized in Table 6.1. We followed the settings recommended by the NDACC (Network for the Detection of Atmospheric Composition Change), except for a slight change of the fitting window of NO<sub>2</sub> due to the spectral range of our VIS spectrometer (fitting window starts from 428 nm instead of 425 nm). The DSCDs of O<sub>3</sub> were calculated using the 450–550 nm spectral interval, which is called the Chappuis band (Chappuis, 1880; Grebenshchikov et al., 2007). The DSCDs of NO<sub>2</sub> were calculated using the fitting window of 428–490 nm. A fixed spectrum measured on the noon of 28 Jun 2012 was used as the reference spectrum, because this spectrum has the lowest O<sub>3</sub> absorption over the measurement period. As in the DOAS evaluation in Chapter 5, DSCDs with the RMS of fitting residual larger than  $1 \times 10^{-3}$  were filtered out.

## 6.3 AMF look-up tables

The AMFs of O<sub>3</sub> and NO<sub>2</sub> were obtained from the corresponding LUTs developed at BIRA-IASB in support of the NDACC UV-visible WG (Hendrick et al., 2011).

The O<sub>3</sub> and NO<sub>2</sub> AMF LUTs were both calculated using the UVSPEC/DISORT RTM (Mayer and Kylling, 2005) which is based on the Discrete Ordinate Method and includes a treatment of the multiple scattering in a pseudo-spherical geometry. The AMFs were computed at a single wavelength (500 and 465 nm for O<sub>3</sub> and NO<sub>2</sub>, respectively). An aerosol extinction profile corresponding to background conditions was used for the AMF calculation. It was constructed from

Table 6.1: The DOAS fit settings for O<sub>3</sub> and NO<sub>2</sub> for the retrieval of total VCDs.

Species	Evaluation species		Reference
	O <sub>3</sub>	NO <sub>2</sub>	
Fitting window	450–500 nm	428–490 nm	
O <sub>3</sub> <sup>(a)</sup> (223 K)	✓	✓	Bogumil et al. (2003)
NO <sub>2</sub> <sup>(b)</sup> (220 K)	✓	✓	Vandaele et al. (1998)
H <sub>2</sub> O	✓	✓	Hitran 2004
O <sub>4</sub>	✓	✓	Hermans et al. (2003)
Ring	✓	✓	Chance and Spurr (1997)
Polynomial	5 <sup>th</sup> order	5 <sup>th</sup> order	
Intensity offset	linear	linear	

<sup>(a)</sup> I<sub>0</sub> correction is applied with SCD of 10<sup>19</sup> molec/cm<sup>2</sup> (Aliwell et al., 2002).

<sup>(b)</sup> I<sub>0</sub> correction is applied with SCD of 2 × 10<sup>16</sup> molec/cm<sup>2</sup> (Aliwell et al., 2002).

the aerosol model of Shettle (1989) included in UVSPEC/DISORT. The temperature profile was from the TOMS (Total Ozone Mapping Spectrometer) version 8 (TV8) climatology (McPeters et al., 2007). A global monthly climatology of the surface albedo was coupled to the interpolation routines so that realistic albedo values could be obtained in a transparent way. This albedo climatology was extracted from the GOME surface albedo database developed by Koelemeijer et al. (2003).

The database of O<sub>3</sub> AMFs is based on the TV8 ozone and temperature profile climatology (Bhartia et al., 2004). The TV8 is a monthly-zonal climatology sorted according to the ozone column. It has been widely used for the retrieval of global total ozone fields from recent US and European UV-VIS nadir sounders (e.g., Bhartia et al., 2004; Coldewey-Egbers et al., 2005; Van Roozendaal et al., 2006; Eskes et al., 2005). The parameters considered in building the LUT are wavelength, ground albedo, altitude and SZA.

The database of NO<sub>2</sub> AMFs is based on the harmonic climatology of stratospheric NO<sub>2</sub> profile developed by Lambert et al. (1999, 2000). This climatology consists of a Fourier harmonic decomposition of UARS HALOE v19 and SPOT-4 POAM-III v2 NO<sub>2</sub> profile data records. It has been used for the retrieval of global total ozone fields from recent European UV-VIS nadir sounders (GOME and SCIAMACHY). For the NO<sub>2</sub> AMF calculation, the NO<sub>2</sub> concentration between 20 and 60 km altitude was taken from the climatology of Lambert et al. (1999, 2000). Between 12 and 17 km, the NO<sub>2</sub> profiles were complemented by a climatology derived from SAOZ balloon observations. The NO<sub>2</sub> concentration

was set to zero below 12 km altitude.

## 6.4 Results and discussions

### 6.4.1 Langley plots of O<sub>3</sub>

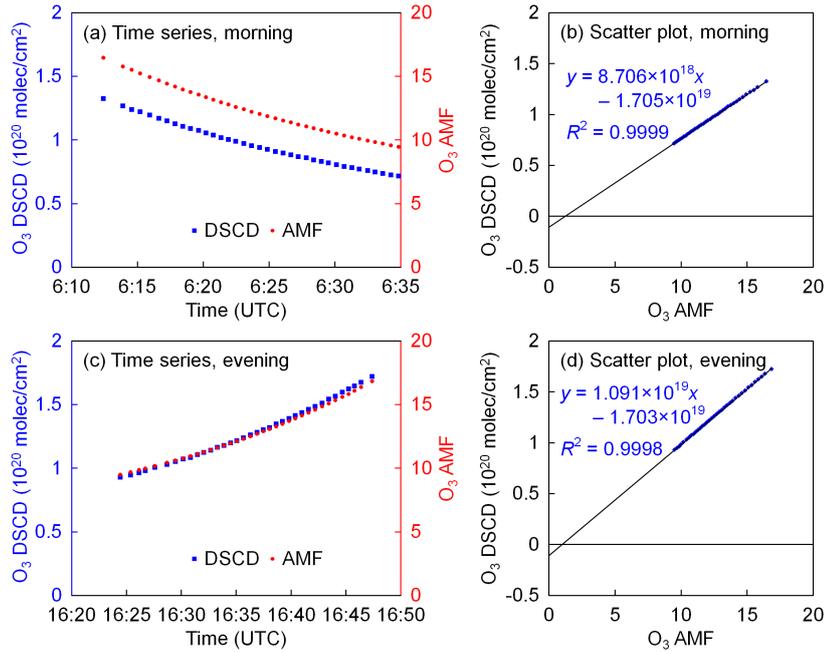


Figure 6.2: Time series of O<sub>3</sub> DSCDs and AMFs (a and c) during the twilight periods of 24 Feb 2014 and the corresponding Langley plots (b and d). The reference spectrum was taken on 28 Jun 2012 at 11:37 UTC.

Figure 6.2 shows the Langley plots of O<sub>3</sub> for the morning and evening twilight periods of 24 February 2014. It can be seen that the AMFs obtained from the LUT are highly correlated with the DSCDs of O<sub>3</sub> during both of the two periods.

Figure 6.3 shows the Langley plot results from February 2012 to February 2016, including O<sub>3</sub> VCDs, correlation coefficients ( $R^2$ ) and O<sub>3</sub> SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from Langley plot. (Note that the results of the twilight periods with less than 10 data were filtered out; for Panels (a) and (c), the results with the correlation coefficient  $R^2 < 0.99$  were also filtered out.) The results show that for most of the measurements, the AMFs are highly correlated with the O<sub>3</sub> DSCDs, as the correlation coefficient ( $R^2$ ) typically varies between 0.99 and 0.9999.

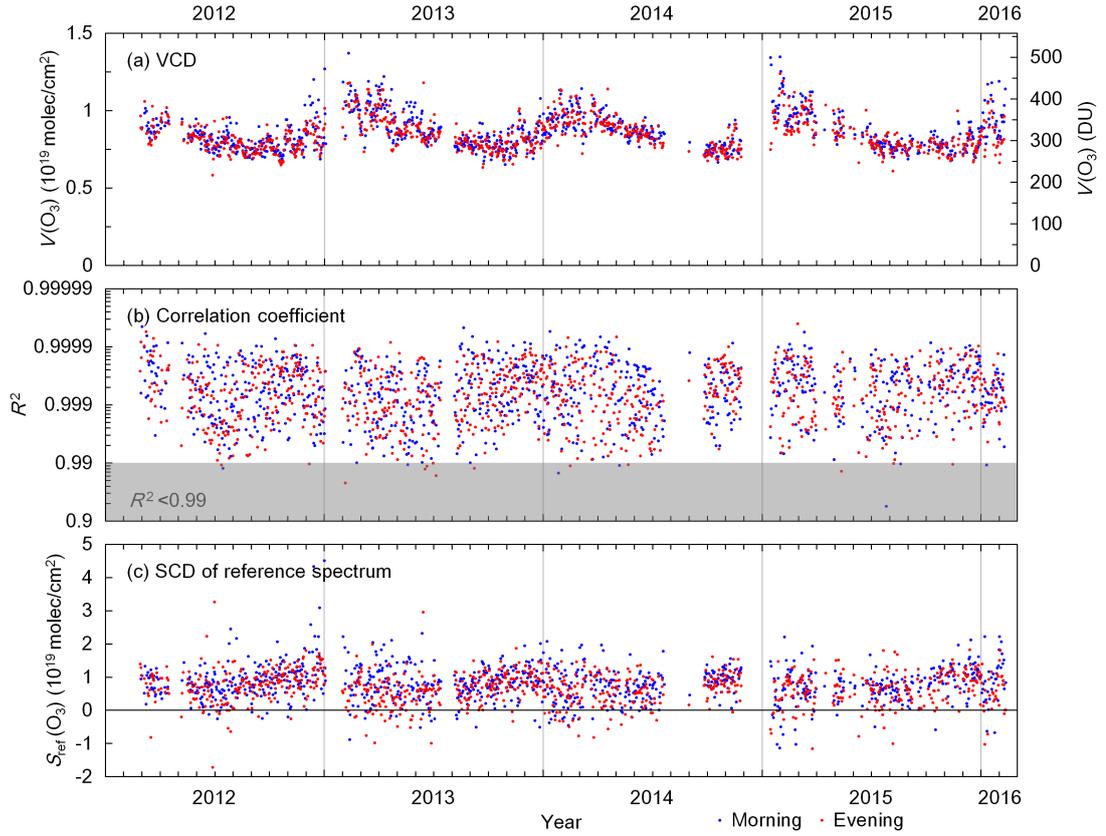


Figure 6.3: Time series of the results of  $\text{O}_3$  Langley plots from Feb 2012 to Feb 2016. (a)  $\text{O}_3$  VCDs. (b) Correlation coefficients. Note that the y-axis is not linear. (c)  $\text{O}_3$  SCDs of the reference spectrum. Note that the twilight periods with less than 10 data were filtered out. In Panels (a) and (c), the data with  $R^2 < 0.99$  (shaded area in Panel (b)) were also filtered out.

However, the  $\text{O}_3$  SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from the Langley plots vary in a large range, for most measurements they vary from  $-1 \times 10^{19}$  to  $2 \times 10^{19}$  molec/cm<sup>2</sup>. This can be explained by the existence of clouds or fog. Clouds or fog can affect the effective light path of the photons received by the telescope due to the multiple scattering process, but the AMF LUT cannot predict such changes, and the data are not cloud screened. Therefore, it is difficult to derive the accurate value of  $S_{\text{ref}}$  from the measurements of a single twilight period. Yet, we can estimate  $S_{\text{ref}}$  according to the statistical analysis of the long-term results. Figure 6.4 shows the frequency distribution of  $S_{\text{ref}}$  derived from the long-term Langley plot results. It can be seen that the derived  $S_{\text{ref}}$  values mostly follow the normal distribution. By fitting the frequency distribution to a Gaussian function, we estimate that  $\langle S_{\text{ref}}(\text{O}_3) \rangle \approx 7.73 \times 10^{18}$  molec/cm<sup>2</sup> (or

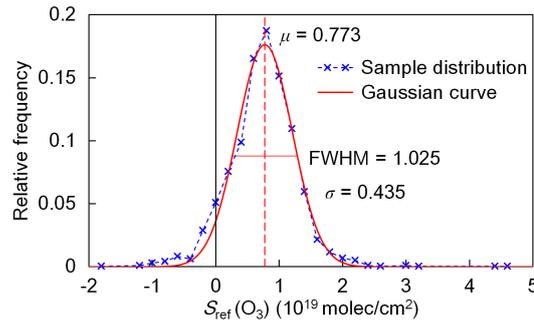


Figure 6.4: Frequency distribution of O<sub>3</sub> SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from Langley plots of data from Feb 2012 to Feb 2016 (for bins of  $2 \times 10^{18}$  molec/cm<sup>2</sup>) and the Gaussian fit. The results of the twilight periods with less than 10 data and the results with the correlation coefficient  $R^2 < 0.99$  were filtered out. The morning and evening results were counted together.

288 DU).

As the reference spectrum has the lowermost O<sub>3</sub> absorption over the years, its AMF should be close to the lower limit of AMF, which equals to  $1/\cos(\text{SZA})$ . The reference spectrum was measured under an SZA of  $24.03^\circ$ , therefore its AMF should be only slightly larger than  $1/\cos(24.03^\circ) = 1.095$ . Then we can estimate that the VCD of the reference measurement is about  $7.06 \times 10^{18}$  molec/cm<sup>2</sup> (or 263 DU). This value is reasonable for the O<sub>3</sub> measurement at the UFS.

In addition, as  $S_{\text{ref}}$  is much smaller than the DSCDs measured during twilight periods (typically varies between  $6 \times 10^{19}$  and  $1.6 \times 10^{20}$  molec/cm<sup>2</sup>) and it is to be divided by the AMF (varies between 9 and 18), the error in  $S_{\text{ref}}$  does not play an important role in calculating the VCDs using Eq (6.3) and (6.4).

### 6.4.2 Langley plots of NO<sub>2</sub>

Figure 6.5 shows the Langley plots of NO<sub>2</sub> for the morning and evening twilight periods of 24 February 2014. Figure 6.6 shows the Langley plot results from February 2012 to February 2016, including NO<sub>2</sub> VCDs, correlation coefficients ( $R^2$ ) and NO<sub>2</sub> SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from Langley plots. (Note that the results of the twilight periods with less than 10 data were filtered out; For Panels (a) and (c), the data with  $R^2 < 0.99$  were also filtered out.) The results show that the correlation between the DSCDs and AMFs of NO<sub>2</sub> is not as good as that of O<sub>3</sub>. In most cases, the correlation coefficient ( $R^2$ ) varies between 0.9 and 0.999; occasionally, the correlation is poor. In addition,

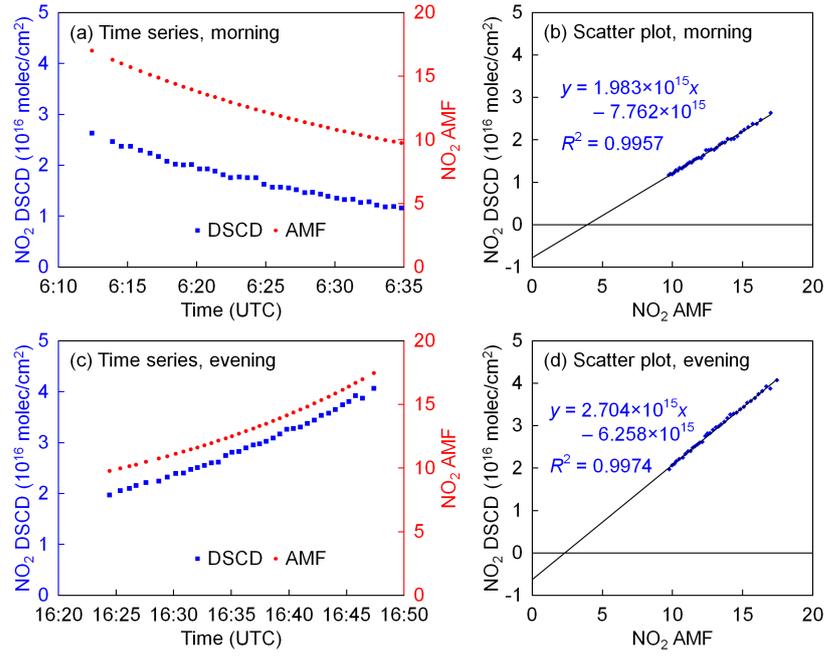


Figure 6.5: Time series of  $\text{NO}_2$  DSCDs and AMFs (a and c) measured during the twilight periods of 24 Feb 2014 and the corresponding Langley plots (b and d). The reference spectrum was taken on 28 Jun 2012 at 11:37 UTC.

the correlation in the evening is better than in the morning on average. This is because the tropospheric  $\text{NO}_2$  plays an important role in the total column, and the concentration of tropospheric  $\text{NO}_2$  is unstable. The variation is especially strong in the morning due to the increasing sunshine. Moreover, such variation cannot be predicted by the AMF LUT.

The frequency distribution of the  $\text{NO}_2$  SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from the long-term Langley plot results is shown in Figure 6.7. The derived  $S_{\text{ref}}$  values typically vary from 0 to  $1.5 \times 10^{16}$  molec/cm<sup>2</sup>, and the values follow the normal distribution as well. Therefore, we estimate the  $\langle S_{\text{ref}} \rangle$  of  $\text{NO}_2$  in the same way as the  $\langle S_{\text{ref}} \rangle$  of  $\text{O}_3$ . By fitting the frequency distribution to a Gaussian function, we estimate that  $\langle S_{\text{ref}}(\text{NO}_2) \rangle \approx 7.72 \times 10^{15}$  molec/cm<sup>2</sup>. Consequently, the VCD of the reference measurement is about  $7.05 \times 10^{15}$  molec/cm<sup>2</sup>. This value is normal for a summer noon.

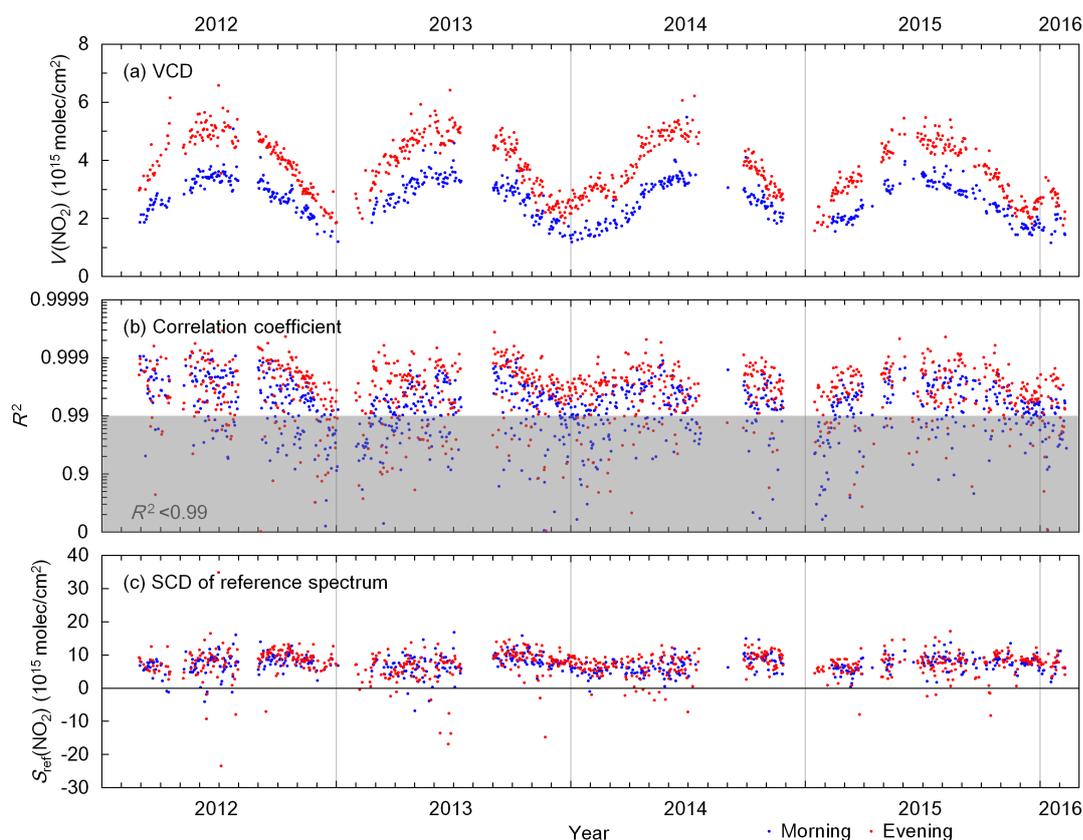


Figure 6.6: Time series of the results of NO<sub>2</sub> Langley plots from Feb 2012 to Feb 2016. (a) NO<sub>2</sub> VCDs. (b) Correlation coefficients. Note that the y-axis is not linear. (c) NO<sub>2</sub> SCDs of the reference spectrum. Note that the twilight periods with less than 10 data were filtered out. In Panels (a) and (c), the data with  $R^2 < 0.99$  (shaded area in Panel (b)) were also filtered out.

### 6.4.3 Satellite validation

Figure 6.8 shows the time series of the VCDs of O<sub>3</sub> and NO<sub>2</sub> measured by the UFS MAX-DOAS and calculated using Eq. (6.3) and (6.4) (blue and red dots), as well as the O<sub>3</sub> and NO<sub>2</sub> VCDs measured by the GOME-2 instrument on the MetOp-A satellite (green triangles). The satellite data are available from February 2012 to December 2014. The satellite data are the averages of all the original VCD data within 150 km from the UFS. The MetOp-A satellite was in a sun-synchronous orbit, and all of its data points were measured at 9:30 local time. Figure 6.9 shows the comparison between the MAX-DOAS and satellite results. The MAX-DOAS results derived by Langley plots and by Eq. (6.3) and (6.4) are both compared.

The results show that the VCDs of O<sub>3</sub> measured by MAX-DOAS in both

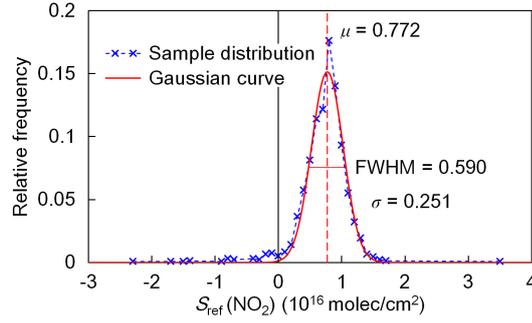


Figure 6.7: Frequency distribution of  $\text{NO}_2$  SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from Langley plots of data from Feb 2012 to Feb 2016 (for bins of  $1 \times 10^{15}$  molec/cm<sup>2</sup>) and the Gaussian fit. The results of the twilight periods with less than 10 data and the results with the correlation coefficient  $R^2 < 0.99$  were filtered out. The morning and evening results were counted together.

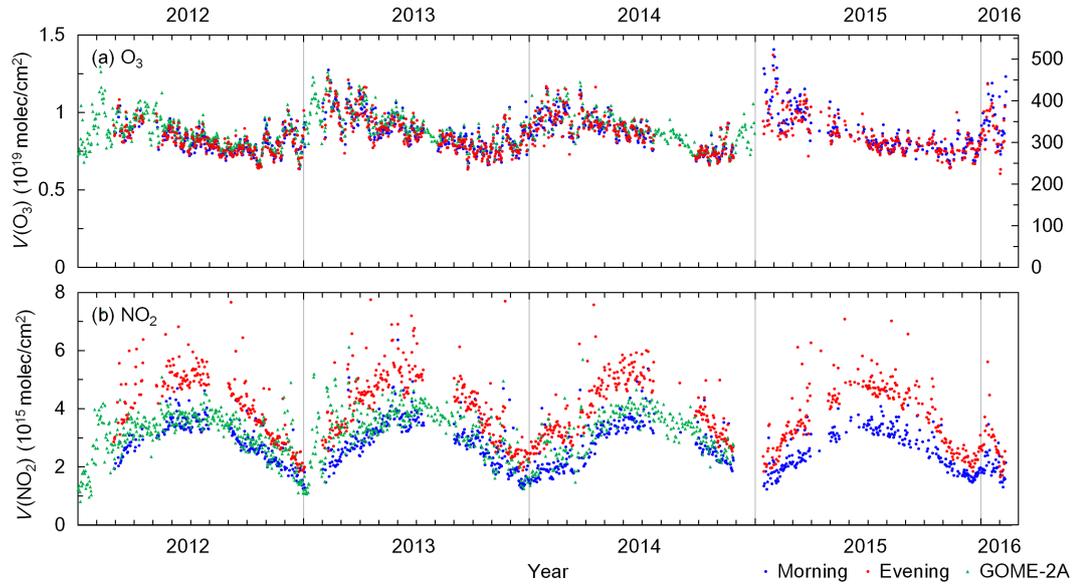


Figure 6.8: Time series of the VCDs of (a)  $\text{O}_3$  and (b)  $\text{NO}_2$  measured by MAX-DOAS and calculated using Eq. (6.3) and (6.4) (blue and red dots represent morning and evening data, respectively), as well as the  $\text{O}_3$  and  $\text{NO}_2$  VCDs measured by the GOME-2 instrument on the MetOp-A satellite (green triangles).

mornings and evenings agree well with the satellite results. In addition, the results calculated using Eq. (6.3) and (6.4) agree with the satellite data better than the results derived by Langley plots. This implies that the former method is more robust than the latter. This conclusion coincides with other studies. The  $\text{O}_3$  VCDs measured by the MAX-DOAS at the UFS are on average slightly smaller

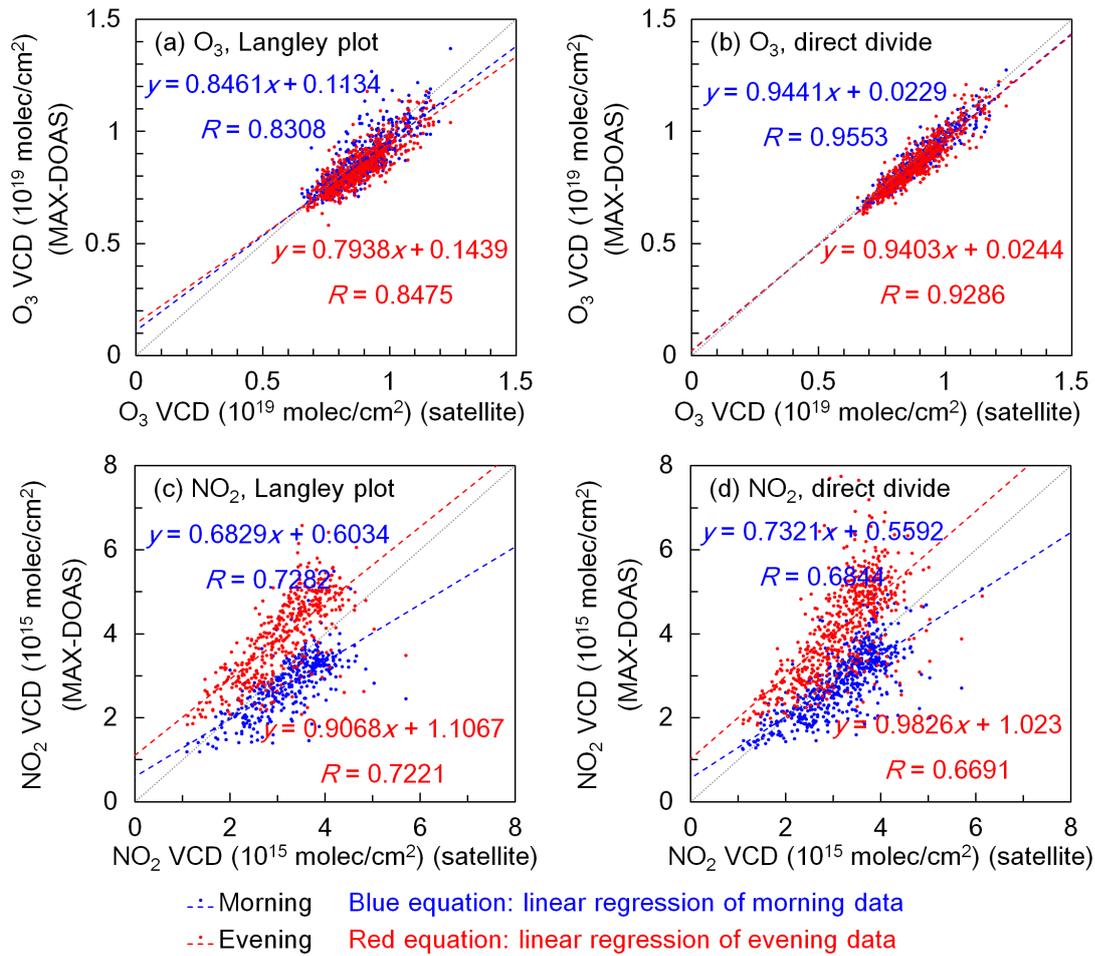


Figure 6.9: Comparison of the total VCDs of O<sub>3</sub> (a and b) and NO<sub>2</sub> (c and d) measured by the UFS MAX-DOAS and the GOME-2 instrument on the MetOp-A satellite. In Panels (a) and (c), the MAX-DOAS data were derived by Langley plots; in Panels (b) and (d), the MAX-DOAS data were calculated using Eq. (6.3) and (6.4).

than the satellite results, this is because the UFS is located at a high altitude, while the satellite measurements include many low-altitude measurements which have stronger O<sub>3</sub> absorption due to the longer light path in the troposphere.

For the VCDs of NO<sub>2</sub>, the agreement between the MAX-DOAS and satellite results is weaker comparing to O<sub>3</sub>, regardless of the calculation method. This can be explained from two aspects. First, unlike O<sub>3</sub>, the concentration of NO<sub>2</sub> has a strong diurnal cycle (it can be seen that the morning and evening MAX-DOAS results differ a lot), and the MAX-DOAS and satellite results were not measured at the same time. Second, the satellite results cover some polluted

areas like Munich and Innsbruck, while the MAX-DOAS only measures at the UFS. For both mornings and evenings, the Langley plot results agree with the satellite results slightly better than the results calculated using Eq. (6.3) and (6.4). However, it should be noted that they are not fully comparable, because for Langley plot results, 37% of the morning data and 22% of the evening data were filtered out due to their low correlation coefficients ( $R^2 < 0.99$ ).

#### 6.4.4 Temporal variation of the VCDs of $O_3$ and $NO_2$

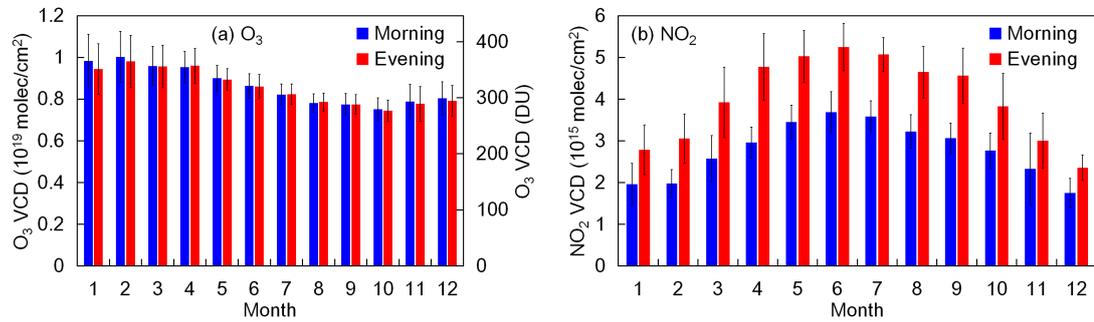


Figure 6.10: Annual variation patterns of the VCDs of (a)  $O_3$  and (b)  $NO_2$ , averaged from the data from Feb 2012 to Feb 2016. The original data were calculated using Eq. (6.3) and (6.4). The error bars indicate the standard deviations.

Table 6.2: Seasonal average VCDs of  $O_3$  and  $NO_2$  measured by the MAX-DOAS and calculated using Eq. (6.3) and (6.4), averaged from the data from Feb 2012 to Feb 2016.

Season	$O_3$ (molec/cm <sup>2</sup> )		$NO_2$ (molec/cm <sup>2</sup> )	
	Morning	Evening	Morning	Evening
Spring (MAM)	$9.37 \times 10^{18}$ (349 DU)	$9.37 \times 10^{18}$ (349 DU)	$2.97 \times 10^{15}$	$4.52 \times 10^{15}$
Summer (JJA)	$8.24 \times 10^{18}$ (307 DU)	$8.25 \times 10^{18}$ (307 DU)	$3.59 \times 10^{15}$	$5.10 \times 10^{15}$
Autumn (SON)	$7.70 \times 10^{18}$ (287 DU)	$7.64 \times 10^{18}$ (284 DU)	$2.69 \times 10^{15}$	$3.73 \times 10^{15}$
Winter (DJF)	$9.26 \times 10^{18}$ (345 DU)	$9.03 \times 10^{18}$ (336 DU)	$1.89 \times 10^{15}$	$2.72 \times 10^{15}$

Figure 6.10 shows the annual variation patterns of the VCDs of  $O_3$  and  $NO_2$ , and Table 6.2 summarizes the seasonally averaged VCDs of  $O_3$  and  $NO_2$ . The

data were averaged from the MAX-DOAS results (calculated using Eq. (6.3) and (6.4)) from February 2012 to February 2016.

The results show that among the four seasons, the VCD of  $O_3$  is highest in spring and lowest in autumn. The spring average is larger than the autumn average by 22% and 23% for morning and evening data, respectively. Although the formation of  $O_3$  requires UV radiation and the solar radiation is strongest in summer, the VCD of  $O_3$  does not peak in summer. This might be caused by the strong exchange of air between the stratosphere and the troposphere in summer, so that more tropospheric air with low  $O_3$  concentration is transported to the ozone layer.

The VCD of  $NO_2$  is highest in summer and lowest in winter. In addition, it has a much larger yearly amplitude comparing to the VCD of  $O_3$ . For both the morning and evening data, the summer average is larger than the winter average by nearly 90%. This can also be explained by the strong vertical exchange of air in summer, so that the pollutants in the PBL are more likely dispersed to the free troposphere and the stratosphere. This result coincides with the annual variation pattern of aerosol load measured at the UFS.

# Chapter 7

## Conclusions and outlook

In this chapter, we summarize the results and findings of this work and provide directions for future research.

### 7.1 Summary and conclusions

In this work, we analyzed the long-term spectra measured by the MAX-DOAS instrument at the high-altitude station UFS. In Chapter 4, we presented the cloud-screening method. In Chapter 5, we presented the retrieval of aerosol extinction profiles. In Chapter 6, we presented the retrieval of the total VCDs of  $O_3$  and  $NO_2$  from the zenith measurements during twilight periods.

#### 7.1.1 Cloud screening method

In Chapter 4, we presented the cloud-screening method for the UFS, which is based on the color index (CI) of the zenith spectra.

The CIs were calculated from the UV spectra, defined as the ratio between the radiative intensities at 330 and 390 nm. In order to make the CIs measured during different periods as well as the simulated CIs comparable, CIs were first calibrated following the method suggested in (Wagner et al., 2016), with which measured CIs under overcast skies were fitted to the simulated minimum CIs.

However, we found the further cloud screening method suggested in (Wagner et al., 2016) infeasible for the measurements at the UFS. Instead, we defined SZA-dependent CI thresholds for cloud screening according to the long-term frequency distribution of calibrated CIs. For each SZA, calibrated CIs show a bimodal frequency distribution, and the two peaks correspond to the measurements under

overcast and clear skies. Therefore, the threshold for each SZA was defined as the calibrated CI with the minimum probability between the two distribution peaks, and a 4<sup>th</sup> order polynomial fitting was applied to smooth the function.

The cloud screening method has been applied to the entire measurement period from February 2012 to February 2016. The percentage of cloudy measurements is highest in summer and lowest in winter. In total, about 60% of the zenith measurements have been identified as cloudy scenes and filtered out for aerosol profile retrieval.

### 7.1.2 Retrieval of aerosol profiles

Chapter 5 is the major part of this work. In this chapter, we first presented the basic principle of MAX-DOAS aerosol profile retrieval. We found that the commonly used OEM-based retrieval algorithms are not suitable for the high-altitude site, hence we developed a new aerosol profile retrieval algorithm based on a parametrized O<sub>4</sub> DSCD LUT.

We investigated the sensitivity of O<sub>4</sub> absorption to several parameters. According to the measurement sensitivity, aerosol profiles were parametrized as the aerosol extinction coefficients of three layers (0–0.5 km, 0.5–1 km, and 1–2 km). We defined a profiles set which is assumed to include all possible aerosol extinction profiles under cloud-free conditions at the UFS. The profile set consists of 7,553 profiles. O<sub>4</sub> DSCDs at 360 and 477 nm were simulated with all the profiles in the profile set and all possible viewing geometries (with a 1° × 1° SZA-RAA grid). The simulated data were stored in a LUT, and the LUT was used as the forward model in the aerosol profile retrieval. UV and VIS measurements were retrieved separately. In the retrieval of each measurement cycle, the simulated O<sub>4</sub> DSCDs corresponding to all of the profiles in the profile set were obtained from the LUT. The cost function ( $\chi^2$ ) of each profile was then calculated according to the simulated and measured O<sub>4</sub> DSCDs as well as the measurement uncertainties. A comprehensive error analysis was performed to estimate the total uncertainty. Valid profiles were selected from the profile set according to the cost functions. The optimal solution was defined as the weighted mean of all the valid profiles.

A key finding of this study is that elevation-dependent O<sub>4</sub> DSCD scaling factors are needed to bring the measured and simulated O<sub>4</sub> DSCDs into agreement. Based on the assumption that the LUT covers all possible aerosol profiles under clear-sky conditions, we determined the scaling factors according to the statistical

analysis of the long-term measurements. The agreement between measured and simulated  $O_4$  DSCDs has been greatly improved by this correction.

In order to test the effectiveness of the algorithm, we retrieved profiles from synthetic data. The results indicate that our algorithm can reproduce the true profile well, and the retrieval is stable to measurement noise.

The AODs retrieved from the long-term MAX-DOAS measurements were compared to the sun photometer observations at the UFS. The results show reasonable agreement with each other. However, especially in summer, the sun photometer results are systematically larger (by about a factor of 2) than the MAX-DOAS results. This discrepancy is mainly due to the different definitions of AOD measured by the MAX-DOAS and sun photometer. The larger difference in summer also coincides with the ceilometer measurements at the UFS which indicate larger aerosol extinctions at high altitudes in summer. The long-term results show that the aerosol load at the UFS is highest in summer and lowest in winter. High AOD in summer is mainly related to a higher frequency of extended mixing layers which allow particles to disperse from lower to upper altitudes. According to the MAX-DOAS measurements, the mean aerosol extinction decreases with increasing altitude in all seasons, which agrees with the ceilometer measurements. The Ångström exponents derived from MAX-DOAS surface measurements are highest in summer and extremely low in winter, which implies a smaller particle size in summer. This might be due to a significant contribution from biogenic sources in summer.

The study demonstrated that our aerosol profile retrieval algorithm is effective for the MAX-DOAS measurements at the UFS. Since the profile set only includes reasonable profiles and the final solution is calculated from the weighted mean of all valid profiles, and because the retrieval does not rely on a priori profiles, many of the limitations of OEM-based retrieval algorithms have been overcome. In addition, as the  $O_4$  DSCDs of all possible profiles were pre-calculated, our method significantly reduces the computational time, so that real-time retrievals should be possible. However, the pre-calculation of the LUT database requires massive computational efforts. Therefore, this method is more suitable for long-term measurements.

### 7.1.3 Retrieval of total VCDs of O<sub>3</sub> and NO<sub>2</sub>

In Chapter 6, we presented the retrieval of the total VCDs of O<sub>3</sub> and NO<sub>2</sub> from the zenith spectra measured during twilight periods.

We first introduced the principle of the retrieval method, including the Langley plot method. Then we introduced the O<sub>3</sub> and NO<sub>2</sub> AMF LUTs developed at BIRA-IASB in support of the NDACC UV-visible WG.

Langley plots of O<sub>3</sub> and NO<sub>2</sub> were applied to the long-term measurements at the UFS. The Langley plots of O<sub>3</sub> show that for most measurements, the AMFs obtained from the LUT are highly correlated with the DSCDs, as the correlation coefficient ( $R^2$ ) typically varies between 0.99 and 0.9999. For the Langley plots of NO<sub>2</sub>, the correlation between DSCDs and AMFs is weaker than O<sub>3</sub>. The correlation coefficient typically varies from 0.9 to 0.999, and occasionally below 0.5. For both O<sub>3</sub> and NO<sub>2</sub>, the SCDs of the reference spectrum ( $S_{\text{ref}}$ ) derived from Langley plots vary in large ranges. However, their long-term distributions both follow the normal distribution. We determined the values of  $\langle S_{\text{ref}} \rangle$  from the long-term distributions using Gaussian fits. Then we calculated the VCDs of O<sub>3</sub> and NO<sub>2</sub> by directly dividing the SCDs (derived by adding  $\langle S_{\text{ref}} \rangle$  to the twilight DSCDs) by the AMFs (Eq. (6.3) and (6.4)).

The long-term VCDs of O<sub>3</sub> and NO<sub>2</sub> derived by both Langley plots and Eq. (6.3) and (6.4) were compared to satellite measurements. The comparisons show that the VCDs of O<sub>3</sub> measured by MAX-DOAS in both mornings and evenings agree well with the satellite results, and the results calculated using Eq. (6.3) and (6.4) agree with the satellite data better than the results derived by Langley plots. For the comparison of NO<sub>2</sub>, the agreement is weaker than that of O<sub>3</sub>, regardless of the calculation method.

The long-term measurements show that the VCD of O<sub>3</sub> is highest in spring and lowest in autumn, while the VCD of NO<sub>2</sub> is highest in summer and lowest in winter. The VCD of NO<sub>2</sub> has a much larger yearly amplitude comparing to the VCD of O<sub>3</sub>. For the VCD of NO<sub>2</sub>, the summer average is larger than the winter average by nearly 90%; while for O<sub>3</sub>, the spring average is larger than the autumn average by  $\sim 22\%$ .

## 7.2 Outlook

The long-term MAX-DOAS measurement at the UFS is a valuable database. Much more information could be retrieved from the spectra. Based on our aerosol profile results, the profiles of trace gases such as  $\text{NO}_2$ , HCHO, HONO, etc. could be further retrieved. In addition, the amount of certain important stratosphere trace gas species other than  $\text{O}_3$  and  $\text{NO}_2$  (e.g., BrO and OCIO) could also be derived from the spectra. As the UFS is a background station with usually clean air, such measurements would provide valuable information on the stratosphere processes in the northern mid-latitudes. Pollution episodes with enhancement of free tropospheric trace gases can be used to investigate the transport of pollutants.

Our cloud screening method and aerosol profile retrieval algorithm (including the  $\text{O}_4$  correction method) can also be adapted to other sites, including low-altitude sites and urban sites (our cloud screening method may only be suitable for unpolluted sites). We hope they can be used in more studies, so that the methods can be further optimized. Further studies may also focus on the combination of the LUT method and machine learning approach.

# List of abbreviations

AAC	Aerodynamic Aerosol Classifier
ABL	Atmospheric Boundary Layer
AE	Ångström Exponent
AERONET	AERosol RObotic NETwork
AMF	Air Mass Factor
AMS	Aerosol Mass Spectrometer
AOD	Aerosol Optical Depth
APS	Aerodynamic Particle Sizer
a.s.l.	Above Sea Level
BIRA-IASB	Belgisch Instituut voor Ruimte-Aeronomie - Institut d'Aéronomie Spatiale de Belgique (Belgian Institute for Space Aeronomy)
CCD	Charge Coupled Device
CE-DOAS	Cavity Enhanced Differential Optical Absorption Spectroscopy
CI	Color Index
CL	ChemiLuminescence
CPC	Condensation Particle Counter
DAMF	Differential Air Mass Factor
DC	Dark Current
DMA	Differential Mobility Analyzer
DOAS	Differential Optical Absorption Spectroscopy
DSCD	Differential Slant Column Density
DWD	Deutscher WetterDienst (German Weather Service)
EAS	Electrical Aerosol Spectrometer
FOV	Field Of View
FTIR	Fourier Transform InfraRed
FWHM	Full Width at Half Maximum

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GOME	Global Ozone Monitoring Experiment
ILAS	Improved Limb Atmospheric Spectrometer
IPCC	Intergovernmental Panel on Climate Change
LIDORT	LInearized Discrete Ordinate Radiative Transfer
LMU	Ludwig-Maximilians-Universität München (Ludwig Maximilian University of Munich)
LP-DOAS	Long Path Differential Optical Absorption Spectroscopy
LUT	Look-Up Table
MAX-DOAS	Multi-AXis Differential Optical Absorption Spectroscopy
MPIC	Max-Planck-Institut für Chemie (Max Planck Institute for Chemistry)
NDACC	Network for the Detection of Atmospheric Composition Change
OEM	Optimal Estimation Method
OMI	Ozone Monitoring Instrument
OSIRIS	Optical Spectrograph and InfraRed Imager System
PBL	Planetary Boundary Layer
PC	Personal Computer
PM	Particulate Matters
ppbv	Part(s) Per Billion by Volume
ppmv	Part(s) Per Million by Volume
pptv	Part(s) Per Trillion by Volume
RAA	Relative solar Azimuth Angle
RRS	Rotational Raman Scattering
RTE	Radiative Transfer Equation
RTM	Radiative Transfer Model
RVRS	Rotational Vibrational Raman Scattering
SAA	Solar Azimuth Angle
SCD	Slant Column Density
SCIAMACHY	SCanning Imaging Absorption spectroMeter for Atmospheric CHartography
SH	Scaling Height
SNR	Signal-to-Noise Ratio
SSA	Single Scattering Albedo
TDLAS	Tunable Diode Laser Absorption Spectroscopy
TOMS	Total Ozone Mapping Spectrometer
TROPOMI	TROPOspheric Monitoring Instrument

TV8	TOMS (Total Ozone Mapping Spectrometer) Version 8
UFS	UmweltForschungsstation Schneefernerhaus (Environment Research Station Schneefernerhaus)
UV	UltraViolet
VCD	Vertical Column Density
VMR	Volume Mixing Ratio
VIS	VISible
WHO	World Health Organization
WPS	Wide-range Particle Spectrometer
ZSL-DOAS	Zenith Scattered Light Differential Optical Absorption Spectroscopy

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