

# Present-day surface deformation of the Alpine Region inferred from geodetic techniques

Laura Sánchez<sup>1</sup>, Christof Völksen<sup>2</sup>, Alexandr Sokolov<sup>1,2</sup>, Herbert Arenz<sup>1</sup>, Florian Seitz<sup>1</sup>

<sup>1</sup>Technische Universität München, Deutsches Geodätisches Forschungsinstitut (DGFI-TUM), Germany <sup>2</sup>Bayerische Akademie der Wissenschaften, Erdmessung und Glaziologie, Germany

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# (Simplified) Tectonic framework in the Alps







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### **Motivation**

- The EU INTERREG III-B Alpine Space Programme established in 2004 the project ALPS GPSQUAKENET with the objective of installing the GPS array GAIN (Geodetic Alpine Integrated Network): duration Jan 2004 to Mar 2007, budget 2,424,638 €.
- ALPS GPSQUAKENET was supported by partners from
  - France (2): Institut Physique du Globe de Strasbourg and Laboratoire de Géophysique Interne et Tectonophysique (Grenoble)
  - Italy (7): Regional Authorities from Piedmont, Veneto, Bolzano, Liguria, Lombardy, Trento, and the Fondazione Montagna Sicura, Dipartimento di Scienze della Terra (UniversityTrieste)
  - Germany (2): Deutsches Geodätisches Forschungsinstitut (DGFI-TUM) and Bayerische Akademie der Wissenschaften (BAdW)
  - Slovenia (1): Environmental Agency of the Republic of Slovenia
  - Switzerland and Austria did not participate in the project.







### **GPS array GAIN: Geodetic Alpine Integrated Network**



- Supervised and the second seco
- About 30 continuously operating GNSS stations were installed between 2004 and 2006.
- The data collection still continues.
- Since 2007, DGFI-TUM and BAdW regularly computed positions and velocities of some stations of this network.
- The uncertainty of the results was larger than the deformation signals to be detected.
- Solution: A longer period of observations to become uncertainty values very much less that deformation signals.
- In 2016, it was possible to obtain a first suitable solution.

## **Geodetic surface deformation modelling**

- High-level data processing of GNSS observations collected over 12 years along the Alpine Region → Precise station positions and velocities
- 2) Removal of the Eurasia plate motion from the (observed) station velocities → Deformation vectors
- Interpolation of the deformation vectors to a regular grid using a geodetic Least Squares Collocation approach (LSC) → Deformation model
- 4) Estimation of deformation gradients and computation of strain components → Strain field (Horizontal projection of the surface deformation)







# GNSS stations processed for the estimation of the surface deformation in the Alps



#### GAIN stations plus stations provided by

- International GNSS Service IGS
- Reference Frame Sub-Commission for Europe of the International Association of Geodesy – EUREF
- Federal Agency for Cartography and Geodesy of Germany (BKG) – Germany
- Space Research Institute of the Austrian Academy of Sciences – Austria
- Centro Ricerche Sismologiche (CRS) of the Istituto Nazionale di Oceanografia e di
- Geofisica Sperimentale (OGS) Italy
- Réseau National GPS France
- Orpheon network France
- Automated GNSS Network for Switzerland AGNES (coordinate solution from swisstopo)



### **Station positions and velocities**





- Time span: 2004-01-01 to 2016-05-30
- Bernese GNSS Software V.5.2 (Dach et al. 2015)
- GPS + GLONASS
- Reference frame IGS08/IGb08
- Reference epoch 2010.0
- 306 occupations



Mean precision of station positions at the reference epoch

 $N - E = \pm 1.1 \text{ mm}$ ;  $h = \pm 2.3 \text{ mm}$ 

Mean precision of the station velocities  $V_N - V_E = \pm 0.2 \text{ mm/a}$ ;  $V_h = \pm 0.4 \text{ mm/a}$ 

### **Horizontal deformation vectors**

after removing the Eurasian plate motion from the station velocities







# Modelling of deformations based on the geodetic Least Squares Collocation approach (LSC)

**Vector prediction:** 

$$\mathbf{v}_{pred} = \mathbf{C}_{new}^{T} \left( \mathbf{C}_{obs} + \mathbf{C}_{nn} \right)^{-1} \mathbf{v}_{obs}$$

 $\mathbf{v}_{pred}$  = predicted velocities in a regular grid

 $\mathbf{v}_{obs}$  = (observed) velocities in geodetic stations

 $C_{new}$ = correlation matrix between predicted and observed vectors

 $C_{obs}$ = correlation matrix between observed vectors

 $C_{nn}$  = noise covariance matrix (uncertainty of the station velocities)

 $C_{\rm obs}$  and  $C_{\rm new}$  are built from empirical isotropic, stationary covariance functions

- d = maximum correlation distance:
  - $d \leq 100 \ \text{km}$  for the horizontal deformation model
  - $d \leq 300$  km for the vertical deformation model

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 $c = E(\underline{x}_i \cdot \underline{x}_i)$ 

 $\mathbf{c} = \mathbf{c}_0 \cdot e^{-\mathbf{b} \cdot \mathbf{d}^2}$ 

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after predicting the point-wise deformation vectors into a regular grid (25 km x 25 km)



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### Strain field

### inferred from the horizontal deformation model



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### **Strain field**



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### Strain field





# Strain field

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### Vertical deformation model (Uplift model)







### Vertical deformation model (Uplift model)







### Vertical deformation model (Uplift model)







### Vertical deformation model (subsidence regimes)





### **Closing remarks**

- Computations were performed in the IGS08/IGb08 reference frame. To extend the time span of the GNSS station position time series, a reprocessing based on the IGS14 reference frame is necessary.
- A larger number of GNSS stations along the Po Basin should be considered to improve the resolution of the deformation model in the southern margin of the Alps.
- Methods and results are published in Earth System Science Data ESSD:

Sánchez, L., Völksen, C., Sokolov, A., Arenz, H., and Seitz, F.: Present-day surface deformation of the Alpine region inferred from geodetic techniques, Earth Syst. Sci. Data, 10, 1503-1526, https://doi.org/10.5194/essd-10-1503-2018, 2018

 Station coordinates, deformation models, and strain rate field are available at the long-term data repository Pangaea

https://doi.pangaea.de/10.1594/PANGAEA.886889

