## Splinter Meeting of the IGS Antenna Working Group

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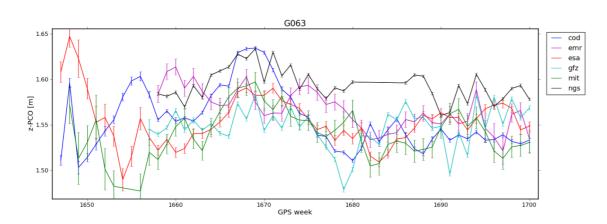




## 1. Satellite antenna issues

#### 1.1 repro2/ITRF2013 implications

- reestimate z-offsets of latest satellites: G064, G065, G066, (G067), R743, R747, (R754)
- keep terrestrial IGS08 scale or reestimate all z-offsets in case ITRF2013 scale differs significantly from ITRF2008 scale?
- update of receiver antenna calibrations when switching to ITRF2013/IGS13? (e.g.: ASH701073.1 calibrations provided by the University of Hannover)







## 1. Satellite antenna issues

## **1.2 Combined processing of terrestrial and LEO data**

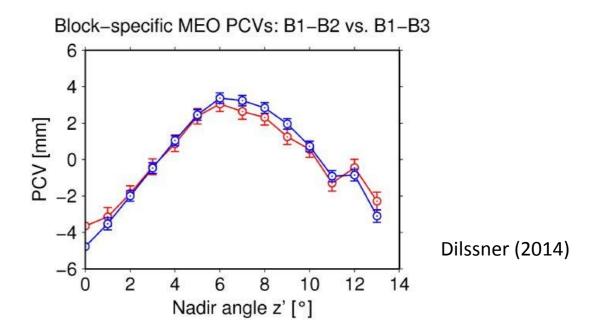
- goals: IGS to provide independent terrestrial scale; consideration of azimuth-dependent PCVs
- requirements: reanalyzing the full history of IGS/LEO data to derive new satellite antenna PCVs by at least two ACs considering:
  - igs08.atx/igs13.atx receiver antenna calibrations
  - multiple GNSS (at least GPS and GLONASS)
  - nadir angles up to 17 deg
  - azimuth-dependence
- date: new set of satellite antenna corrections should be available before the start of repro3



## 1. Satellite antenna issues

## **1.3 Estimation of phase center corrections for new GNSS**

- conventional phase center offset values available on the MGEX website
- cf. poster presentation by Dilssner et al.: *Estimation of satellite antenna phase center corrections for BeiDou*
- other initiatives?





## 2.1 Status of new calibration institutions

#### National Geodetic Survey (NGS):

- L2 tracking issue solved?
- status of the GLONASS calibration?

#### Geoscience Australia (GA):

- comparisons needed in order to be accepted as an IGS calibration institution
- any experience with robot calibrations for the BeiDou frequencies?







#### 2.2 Chamber calibrations from Bonn for MGEX purposes

- University of Bonn provided chamber calibration sets for 15 different antenna/radome combinations including 18 frequencies
- W. Aerts and M. Moore provided comparison with igs08.atx for GPS and GLONASS frequencies of 13 antenna types: good agreement for 5, "fair" agreement for 6 and poor agreement for 2 antenna types
- in accordance with ANTEX 1.4, all 18 frequencies can only be added separately, even though some of them are identical (update of the ANTEX format needed)
- as existing igs08.atx calibrations cannot be changed, only shortterm possibility is to merge chamber (new frequencies) with robot calibrations (GPS/GLONASS)
- possible inconsistency could be removed with igs13.atx?



## 2.3 Strategies to compare phase center calibrations

- two common strategies to define the "datum" of phase center corrections (PCC) resulting in different comparison residuals:
  - PCC(zenith direction) == 0
  - mean(PCC) == 0
- unclear to which strategy the thresholds for "acceptable" PCC differences agreed upon in Newcastle refer
- datum-independent quality measures focusing on the shape of the PCC could be helpful
- status of the toolbox?



#### 2.4 Campaign to compare calibrations with "ground truth"?

- several institutions generally interested to do comparisons: Royal Observatory of Belgium, Finnish Geodetic Institute, University of Luxembourg, others?
- organized comparison campaign desired?
- any antenna samples available that were already calibrated by multiple calibration institutions?
- besides coordinates also troposphere and clock parameters should be analyzed

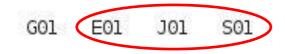


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#### **3.1 MGEX-related issues**

#### **Identical frequencies for different GNSS**

- e.g.: G01 = E01 = J01 = S01
- currently, calibration values have to be duplicated
- solution: allow further entries in START OF FREQUENCY section



START OF FREQUENCY



#### 3.1 MGEX-related issues

#### Manufacturer-defined spacecraft body frames and attitude modes

• necessary to consider conventional phase center offsets etc.

Constellation		Attitude Mode	Compatibility with IGS Attitude Model
GLONASS-M/K		yaw-steering	Requires mapping (+x <sub>GLO</sub> = -z <sub>IGS</sub> , +y <sub>GLO</sub> = +x <sub>IGS</sub> , +z <sub>GLO</sub> = -y <sub>IGS</sub> )
GIOVE-A/B		yaw-steering	Requires mapping (+x <sub>GIO</sub> = -x <sub>IGS</sub> )
Galileo IOV		yaw-steering	Requires mapping (+x <sub>GAL</sub> = -x <sub>IGS</sub> )
QZSS		yaw-steering	Requires mapping (+x <sub>QZSS</sub> = -x <sub>IGS</sub> )
		orbit-normal	NO
BeiDou	MEO	yaw-steering	Yes*)
BeiDou	IGSO	?	?
BeiDou	GEO	orbit-normal (?)	NO
SBAS		orbit-normal (?)	NO



Montenbruck (2012)

## 3.2 RMS section

• ANTEX format description **not practicable** 

Record indicating the start of an rms   value section related to the specified	3X, A1, I2, 54X *
frequency. The section includes the rms values of the phase center eccentricities and of	
	value section related to the specified   frequency.   The section includes the rms values of

- as PCO and PCVs are intimately connected, separate RMS values make no sense
- only PCV RMS should be provided
- should it be allowed to provide RMS values for a subset of frequencies only? (Geo++ can currently provide GPS RMS, but no GLONASS RMS)
- reasonable to include RMS sections into the official IGS model?



#### 3.3 Various issues (what is necessary and practicable?)

- consideration of individual GLONASS frequencies
- code calibrations for satellite and receiver antennas
- (receiver-dependent) carrier-to-noise patterns CN0
- near- and/or far-field effects?
- station-specific empirical biases?



## 4. CB antenna file issues

## 4.1 rcvr\_ant.tab

- accepted as a standard by manufacturers; maintenance gets more and more time-consuming
- could data flow between calibration institutions and the CB be optimized?

## 4.2 antenna.gra

- definition of the north reference point (NRP) ready to be published
- compromise for JAVGRANT antennas necessary
- "call for photos" to replace NRP=UNK after publication
- antennas at IGS stations should **not** be touched in case the orientation was not in accordance with antenna.gra! (comment in the station log might be helpful)



## 5. Any other business



# Further questions or comments?