# Non-Orthogonal Multiple Access for Diffusion-Based Molecular Communication Networks

Alexander Wietfeld TU Munich, Germany alexander.wietfeld@tum.de Sebastian Schmidt TU Munich, Germany sebastian.a.schmidt@tum.de Wolfgang Kellerer TU Munich, Germany wolfgang.kellerer@tum.de

## ABSTRACT

This paper proposes a concept of non-orthogonal multiple access (NOMA) for diffusion-based molecular communication (DBMC) networks. The method relies on the difference in received signal levels for multiple access and uses successive interference cancellation. We analytically investigate the bit error probability (BEP) of a communication system using NOMA with two transmitters (TXs) and a central receiver. Initial results show that the BEP can be minimized by balancing a high received signal level from each TX with the separation in received signal level between the TXs. The identification of this trade-off is a first step towards the further analysis of NOMA for single-molecule-type multiple access in future DBMC networks.

### **KEYWORDS**

molecular communication, non-orthogonal multiple access, NOMA

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#### **1 INTRODUCTION AND PHYSICAL SCENARIO**

In future biomedical applications, molecular communication is expected to provide connectivity between multiple bio-nano sensors and a bio-cyber interface for distributed data gathering [5]. In order to distinguish between different data sources, this many-to-one scenario necessitates controlled multiple access (MA).

For diffusion-based molecular communication (DBMC), different MA schemes have been proposed and investigated, such as time-division MA (TDMA) [5] or molecular-division MA (MDMA) [1]. TDMA enables single-molecule MA while MDMA allows for simultaneous transmission. However, both properties are desirable for low complexity and high capacity DBMC systems [3]. This work investigates non-orthogonal MA (NOMA) based on successive interference cancellation (SIC) [4] applied to DBMC networks. The proposed method provides single-molecule MA as well as simultaneous transmission. For an initial analysis of NOMA in DBMC

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Figure 1: DBMC scenario with two point transmitters at distances  $d_1$  and  $d_2$  from a spherical receiver.

networks, the bit error probability (BEP) is derived for a simplified data gathering system, consisting of two TXs and one RX.

Figure 1 depicts the considered communication scenario with the TXs at distances  $d_1$  and  $d_2$  ( $d_1 \le d_2$ ) from the spherical RX with radius *r*. The TXs are modeled as point sources with instantaneous molecule release. All TXs emit the same type of molecule, which is affected by Brownian motion with diffusion coefficient *D*. The RX is assumed to be passive and the time-varying number of molecules within its bounds is the received signal,  $n_{RX}(t)$ .

For emission of a single molecule at t = 0, the probability of observing it at time t in a RX with volume  $V_{\text{RX}}$  at distance d is derived in [2] as

$$P(t,d) = \frac{V_{\rm RX}}{(4\pi Dt)^{\frac{3}{2}}} \exp\left(-\frac{d^2}{4Dt}\right).$$
 (1)

For pulse-like emission of  $N_{\text{TX}}$  molecules from a single TX,  $n_{\text{RX}}(t)$  can be modeled as a Poisson-distributed random variable with mean  $\lambda(t, d) = N_{\text{TX}}P(t, d)$  [6].

#### 2 SYSTEM DESIGN AND BEP DERIVATION

To transmit information to the RX, both TX<sub>i</sub> in Figure 1 send symbols  $s_i \in \{0, 1\}$  with equal probability using pulse-based on-off-keying. We assume the symbol period to be sufficiently long such that inter-symbol interference (ISI) is negligible allowing us to focus on the interference between the TXs within a single symbol period.

For simultaneously transmitting TXs,  $n_{RX}(t)$  is a sum of Poissondistributed variables  $n_{RX,i}(t)$  with means  $s_i\lambda_i(t) = s_i\lambda(t, d_i)$ . Thus, in the considered scenario  $n_{RX}(t) \sim \mathcal{P}(s_1\lambda_1(t) + s_2\lambda_2(t))$ . A SIC technique, similar to the one proposed for NOMA in [4], is used to separate the signals at the RX. In the first step, the message from TX<sub>1</sub> is detected from  $n_{RX}(t)$  with  $n_{RX,2}(t)$  considered as added interference. In the second step, the RX uses knowledge of the channel to subtract the estimated component of TX<sub>1</sub> from the received signal. The resulting signal is used for the detection of  $s_2$ .

We assume perfect synchronization and distance estimation at the RX. Therefore, the RX can sample  $n_{\text{RX}}(t)$  at the time of the expected peaks for each component  $n_{\text{RX},i}(t)$ , given by  $t_{\text{p,i}} = d_i^2/6D$ .

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Figure 2: Bit error probabilities  $P_{e,i}$  over the detection thresholds  $\tau_i$ . For  $P_{e,2}$ , we assume  $\tau_1 = \tau_1^*$  ( $d_1 = 10 \,\mu\text{m}, d_2 = 12 \,\mu\text{m}, N_{\text{TX}} = 10^6, D = 10^{-9} \,\frac{\text{m}^2}{\text{s}}, r = 1 \,\mu\text{m}$ ).

The sample is decoded as  $\hat{s}_i = 0$  if it is smaller than a threshold  $\tau_i \in \mathbb{N}$  and as  $\hat{s}_i = 1$  otherwise. The expected number of molecules from TX<sub>i</sub> at a sampling point is denoted as  $s_i\lambda_{i,j} = s_i\lambda_i(t_{p,j})$ .

For TX<sub>1</sub>, the probability of the sample  $n_{\text{RX}}(t_{\text{p},1})$  being below  $\tau_1$  for any symbol combination is defined as

$$P_1^{s_1,s_2} = \mathbb{P}(n_{\text{RX}}(t_{p,1}) < \tau_1 | s_1, s_2)$$
  
=  $\mathcal{P}_{\text{CDF}}(\tau_1 - 1; s_1\lambda_{1,1} + s_2\lambda_{2,1}),$  (2)

where  $\mathcal{P}_{\text{CDF}}(m; \lambda) = \sum_{k=0}^{k=m} \lambda^k \frac{e^{-\lambda}}{k!}$ . By taking into account all symbol combinations, we can write the BEP of TX<sub>1</sub> as

$$P_{e,1} = \frac{1}{4} \left( (1 - P_1^{0,0}) + (1 - P_1^{0,1}) + P_1^{1,0} + P_1^{1,1} \right).$$
(3)

For TX<sub>2</sub>, SIC is incorporated by considering a sample, from which  $\hat{s}_1\lambda_{1,2}$ , the estimated component from TX<sub>1</sub>, has been subtracted. Consequently, the BEP for TX<sub>2</sub>,  $P_{e,2}$ , depends on the previous detection step. Considering both possible cases for  $\hat{s}_1$ , we define

$$\begin{aligned} P_{2}^{s_{1},s_{2}} &= \mathbb{P}\left(n_{\mathrm{RX}}(t_{\mathrm{p},2}) - \hat{s}_{1}\lambda_{1,2} < \tau_{2}|s_{1},s_{2}\right) \\ &= \mathbb{P}(\hat{s}_{1}=1|s_{1},s_{2}) \cdot \mathcal{P}_{\mathrm{CDF}}\left(\tau_{2} - 1 + \lambda_{1,2}; s_{1}\lambda_{1,2} + s_{2}\lambda_{2,2}\right) \quad (4) \\ &+ \mathbb{P}(\hat{s}_{1}=0|s_{1},s_{2}) \cdot \mathcal{P}_{\mathrm{CDF}}\left(\tau_{2} - 1; s_{1}\lambda_{1,2} + s_{2}\lambda_{2,2}\right). \end{aligned}$$

Here,  $\mathbb{P}(\hat{s}_1|s_1, s_2)$  represents the detection for TX<sub>1</sub> and can be calculated using Equation 2, e.g.  $\mathbb{P}(\hat{s}_1=1|s_1=1, s_2=1) = (1 - P_1^{1,1})$ . Using Equation 4,  $P_{e,2}$  can be written in analogy to Equation 3 and the BEP for the system can be defined as  $P_{e,sys} = \frac{1}{2} (P_{e,1} + P_{e,2})$ .

### **3 RESULTS AND CONCLUSION**

Figure 2 depicts the value of  $P_{e,i}$  over the respective  $\tau_i$  for one choice of  $d_i$ . The results show that optimal threshold values  $\tau_i^*$ , which minimize  $P_{e,i}$  for both TXs can be found.  $P_{e,2}$  depends on  $\tau_1$ , as shown in Equation 4. Therefore, we assume  $\tau_1 = \tau_1^*$  before plotting  $P_{e,2}$ .

In Figure 3, the minimum achievable  $P_{e,sys}$  found through threshold optimization via exhaustive search is shown on a heatmap as a function of  $d_1$  and  $\Delta d = d_2 - d_1$ . The visible pattern is caused by two counteracting effects that can be analyzed in isolation. Firstly, the further either of the TXs is situated from the RX, the lower





Figure 3: System bit error probability  $P_{e,sys}$  with optimum thresholds for different values of  $d_1$  and  $\Delta d$ . Optimum  $\Delta d^*$ , which minimizes  $P_{e,sys}$  for given  $d_1$ , is highlighted. Parameters used in Figure 2 are given as an example. ( $N_{TX} = 10^6$ ,  $D = 10^{-9} \frac{m^2}{s}$ ,  $r = 1 \mu m$ ).

the received signal level from the TX, which causes a higher  $P_{e,sys}$ . Secondly, the greater  $\Delta d$ , the higher the separation between the two signal levels, which leads to a more effective SIC and therefore lower  $P_{e,sys}$ . For a given  $d_1$ , there is always a  $\Delta d^*$ , which minimizes  $P_{e,sys}$  representing the equilibrium point between the two effects.

The presented results suggest that signal-level-based NOMA with SIC has the potential to be a promising single-molecule MA method for DBMC systems. For a more realistic performance evaluation, we will extend the model to include the effects of ISI. Further, we plan for a generalization towards multiple TXs, performance comparisons with other MA schemes, investigation of adaptive TX signal levels, and simulation studies.

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