

# Novel Sensor Networks and Methods for Urban Greenhouse Gas Monitoring

Jia Chen  
TU Munich  
*Environmental  
Sensing & Modeling*  
[jia.chen@tum.de](mailto:jia.chen@tum.de)

**Jia Chen**<sup>1</sup>, Adrian Wenzel<sup>1</sup>, Andreas Luther<sup>1</sup>, Andreas Forstmaier<sup>1</sup>, Patrick Aigner<sup>1</sup>, Vigneshkumar Balamurugan<sup>1</sup>, Florian Dietrich<sup>1</sup>, Daniel Kühbacher<sup>1</sup>, Moritz Makowski<sup>1</sup>, Haoyue Tang<sup>1</sup>, Xinxu Zhao<sup>1</sup>, Friedrich Klappenbach<sup>1</sup>, Hossein Maazallahi<sup>2</sup>, Thomas Roeckmann<sup>2</sup>, Hugo Denier van der Gon<sup>3</sup>, Taylor Jones<sup>4</sup>, and Bradley Matthews<sup>5</sup>

<sup>1</sup>Environmental Sensing and Modelling, Technical University of Munich, Munich, Germany

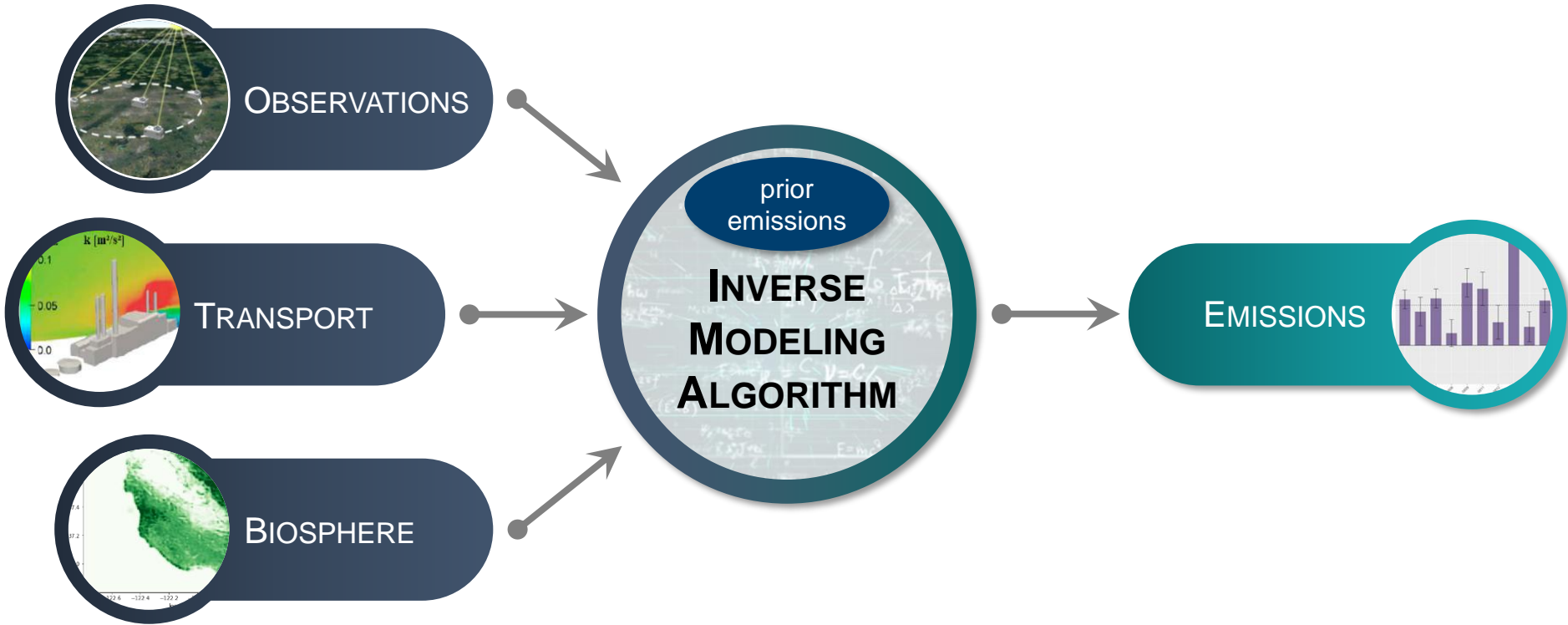
<sup>2</sup>Institute for Marine and Atmospheric research Utrecht (IMAU), Utrecht University (UU), Utrecht, the Netherlands

<sup>3</sup>Netherlands Organisation for Applied Scientific Research (TNO), Utrecht, the Netherlands

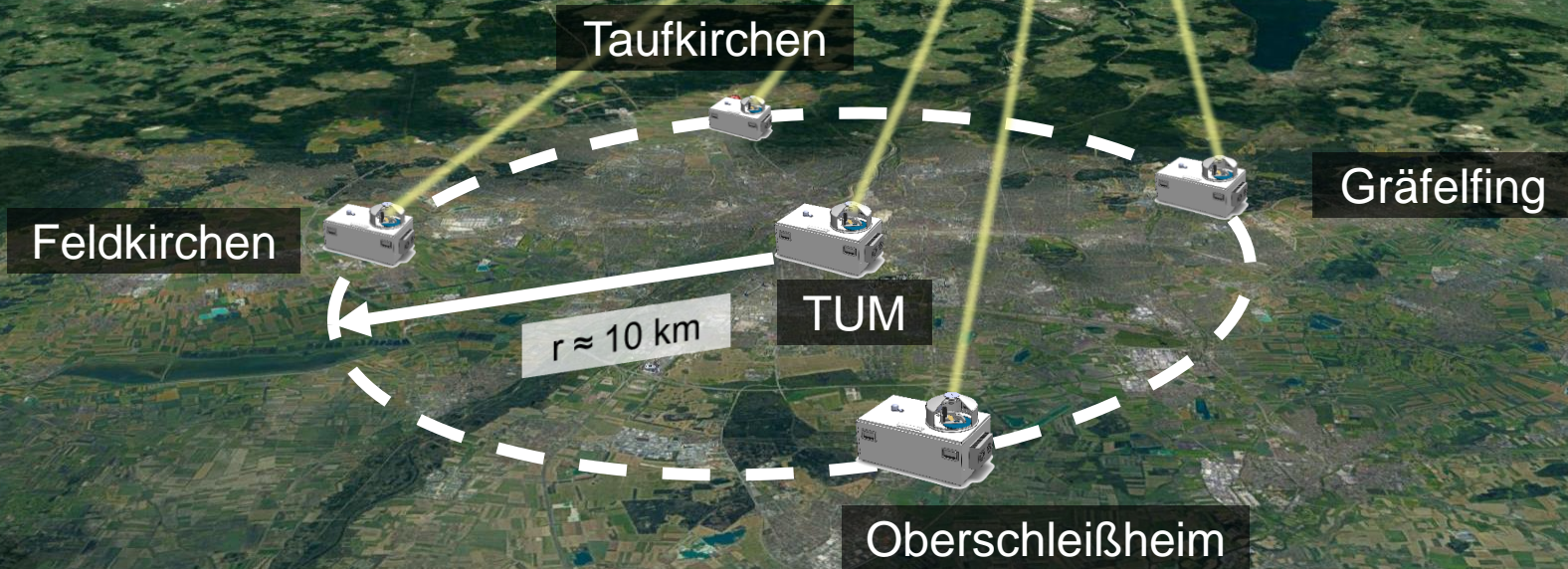
<sup>4</sup>Earth and Environment, Boston University, Boston, United States

<sup>5</sup>University of Natural Resources and Life Sciences Vienna, Institute of Forest Ecology, Vienna, Austria

# Emission Monitoring



# MUCCnet – Munich Urban Carbon Column network



*Dietrich, Chen et al.: MUCCnet: Munich Urban Carbon Column network. Atmos. Meas. Tech., 2021, <https://doi.org/10.5194/amt-14-1111-2021>*

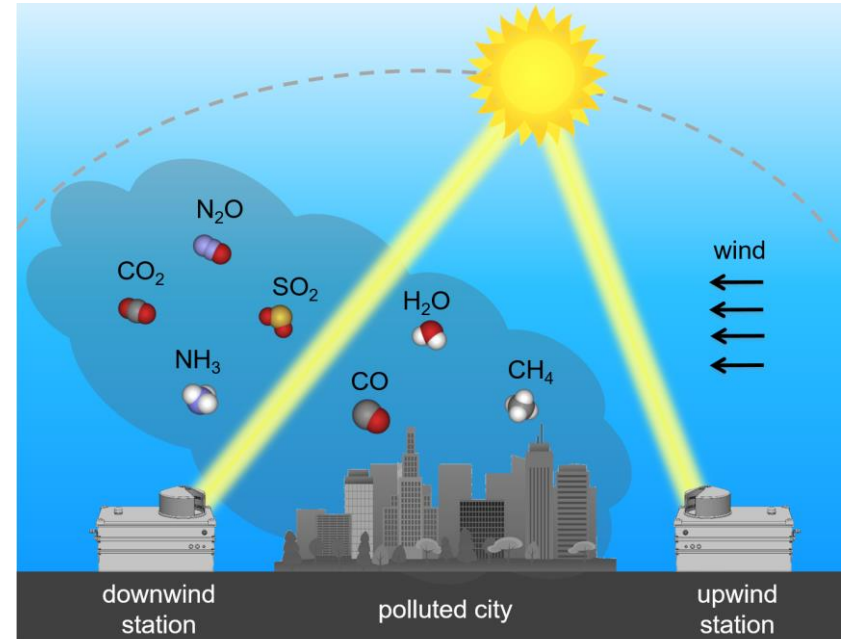
Google Earth

Image Landsat / Copernicus  
Data SIO, NOAA, U.S. Navy, NGA, GEBCO

# Differential Column Measurements

(Chen et al., 2016, Dietrich et al. 2021)

- **Approach:**  $Emission \propto C_{downwind} - C_{upwind}$
- **Species:** CO<sub>2</sub>, CH<sub>4</sub> and CO
- **Advantages:**
  - Insensitive to boundary layer height dynamics
  - Representative for regional emissions
- **Precision:** 0.01% @ 10 min integration time
- **Application:**
  - Monitoring urban GHG emissions over long-term
  - Validating satellites
- Included the **WMO IG3IS** Guideline for Urban GHG Emission Monitoring



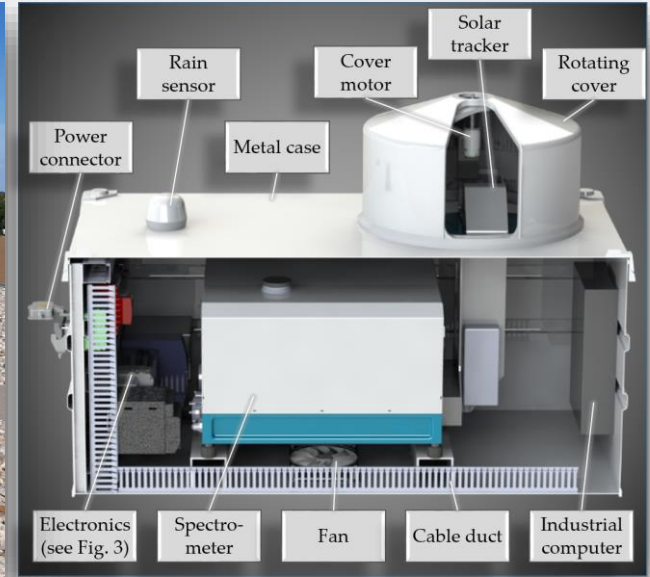
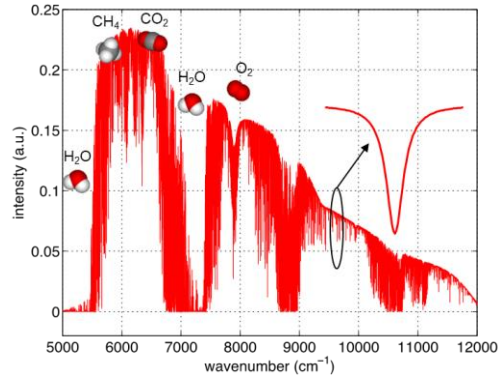
**Fig. 1:** Principle of the differential column measurements

# MUCCnet Sensor System

(Heinle and Chen, 2018; Dietrich, Chen et al. 2021)

➤ Fully-automated sensor systems:

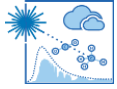
- Solar-tracking Fourier transform spectrometer (Bruker EM27/SUN)
- Patented enclosure system



➔ Our system reduces the personnel costs to a minimum and increases the amount of measurement data to a maximum

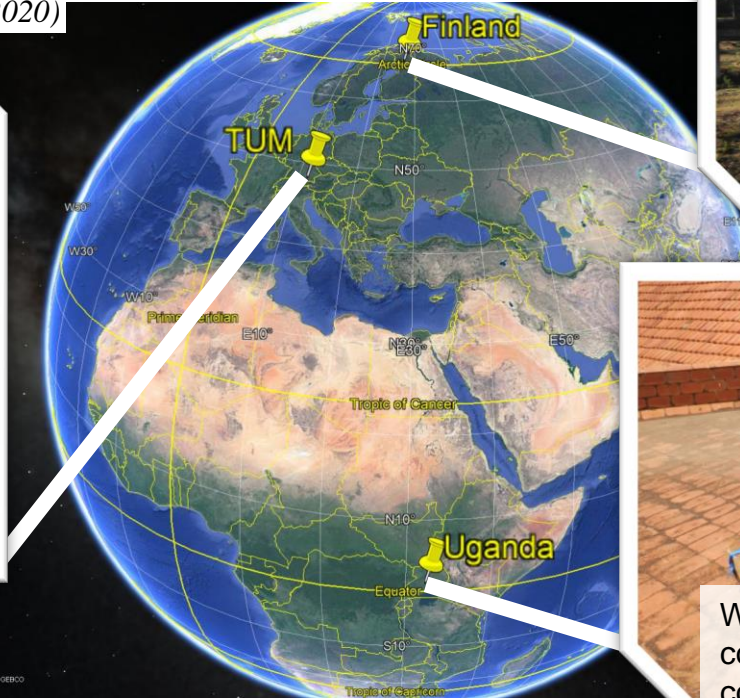
Heinle and Chen: Automated Enclosure and Protection System for Compact Solar-Tracking Spectrometers. *Atmos. Meas. Tech.*, 2018, <https://doi.org/10.5194/amt-11-2173-2018>

Dietrich, Chen et al.: MUCCnet: Munich Urban Carbon Column network. *Atmos. Meas. Tech.*, 2021, <https://doi.org/10.5194/amt-14-1111-2021>



# International Sites of Our Automated System

(Dietrich, Chen et al. 2021; Tu et al. 2020)



Google Earth

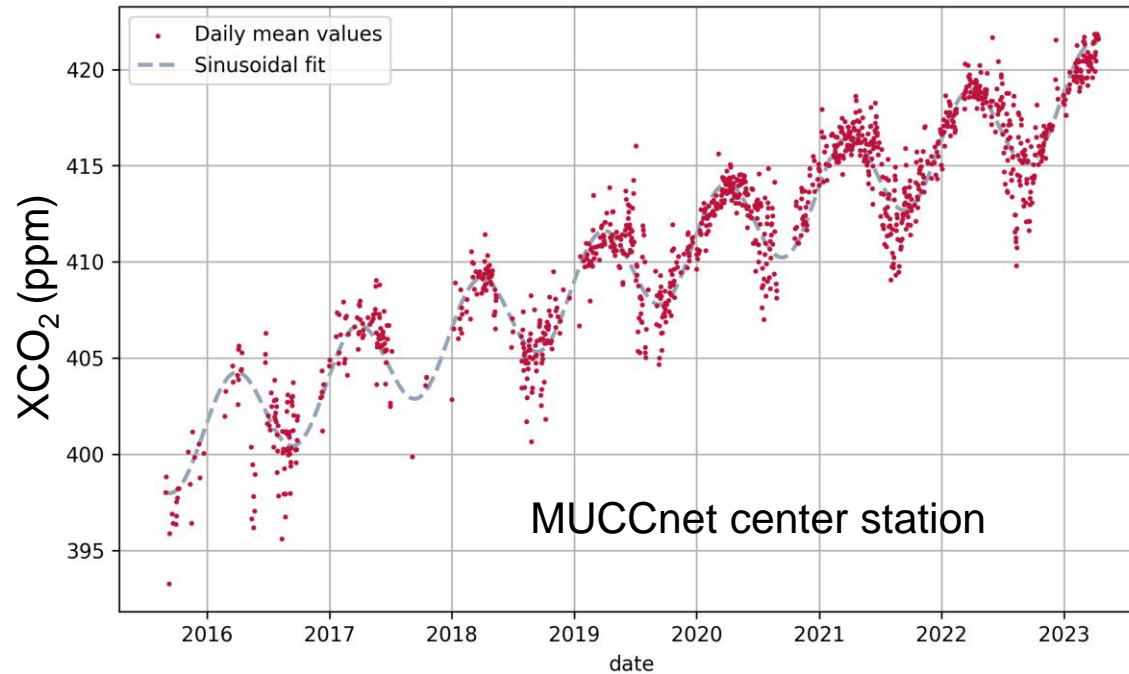
Image Licensed / Copernicus  
©2019 Google

Satellite validation north of the polar circle (in collaboration with team **Frank Hase**)



Wetland CH<sub>4</sub> emissions. **First** column measurement in East-Africa (In collaboration with team **Hartmut Bösch**)

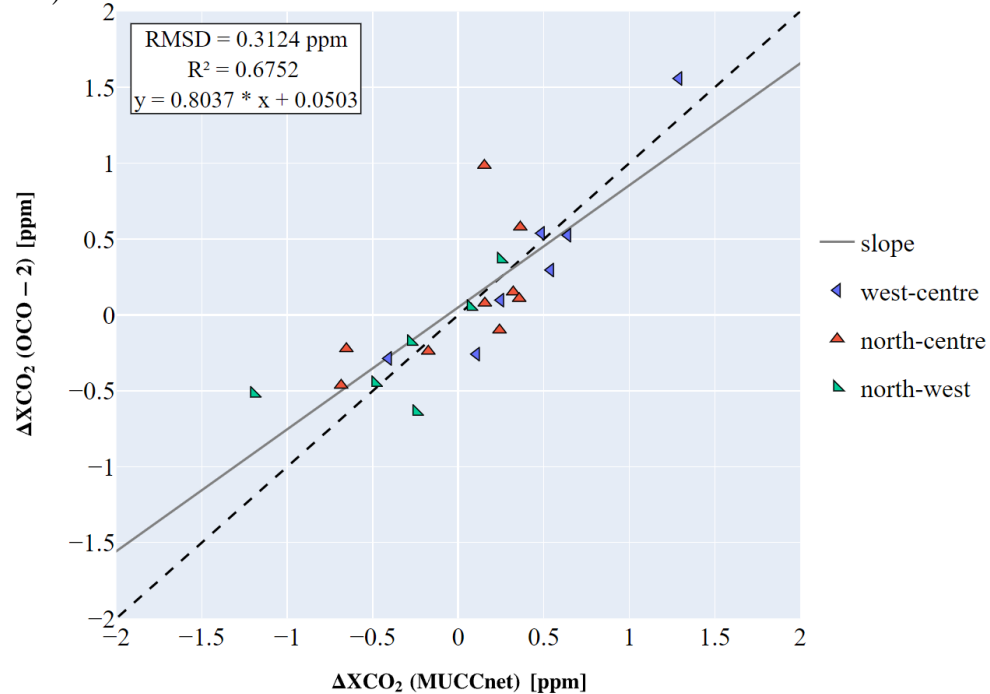
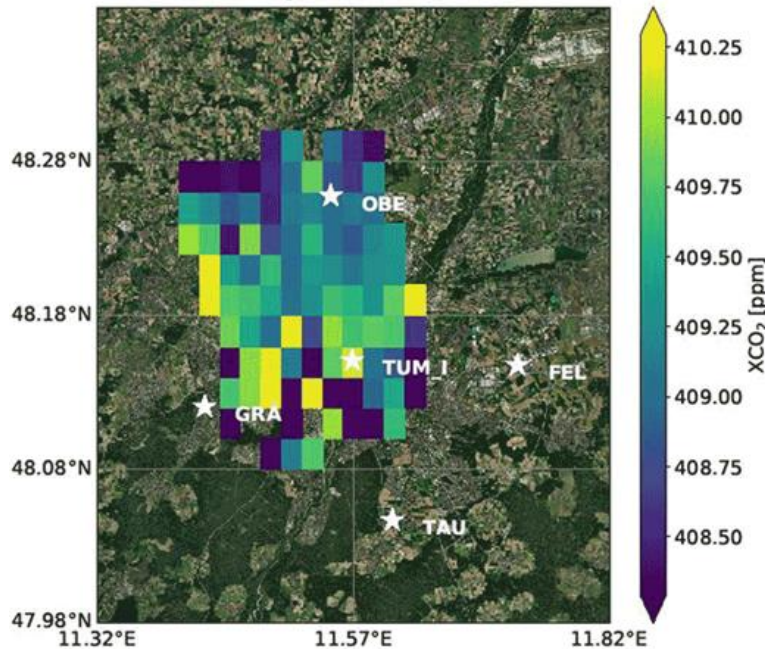
## Measurements (2015 – now)



# Satellite Gradient Validation using MUCCnet

(Rißmann et al. 2022 - in collaboration with M. Kiel and G. Osterman)

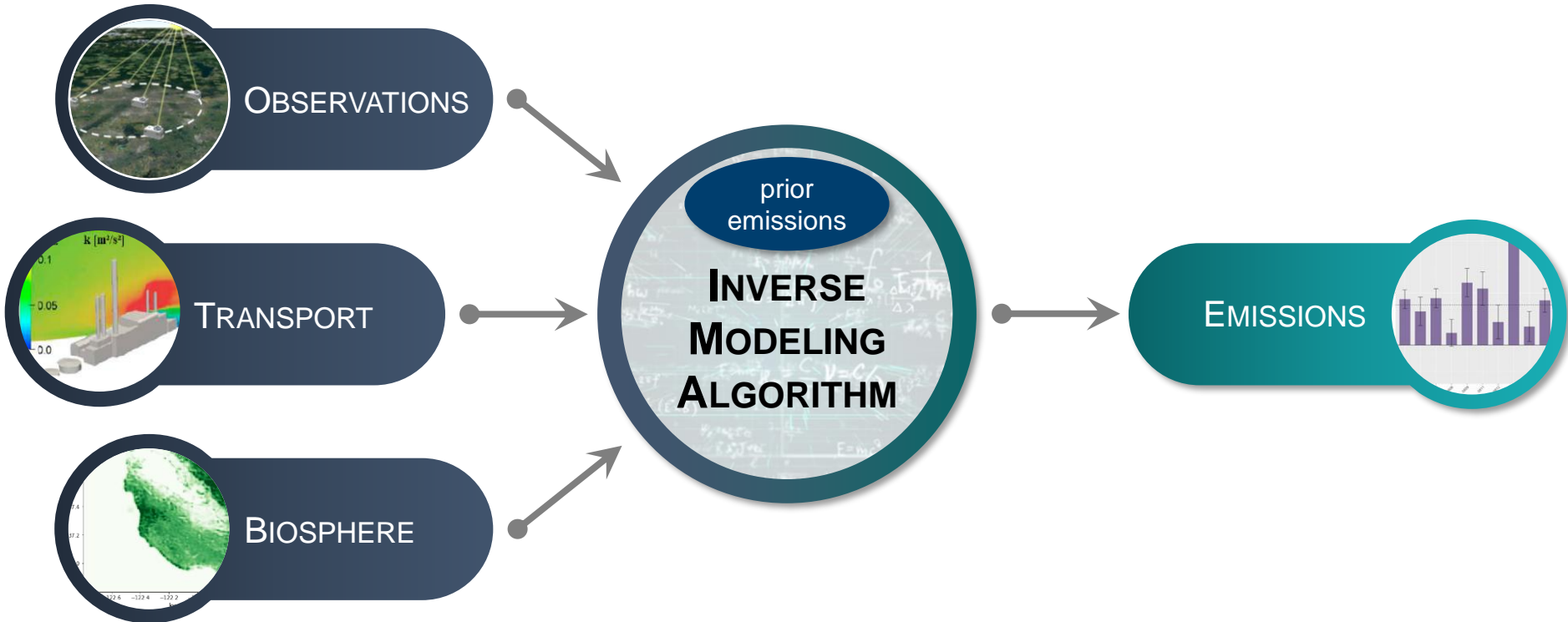
OCO-2 Target Munich - 2020-08-12

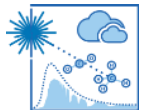


→ Strong correlation between gradient measured by MUCCnet and by satellite



# Emission Monitoring

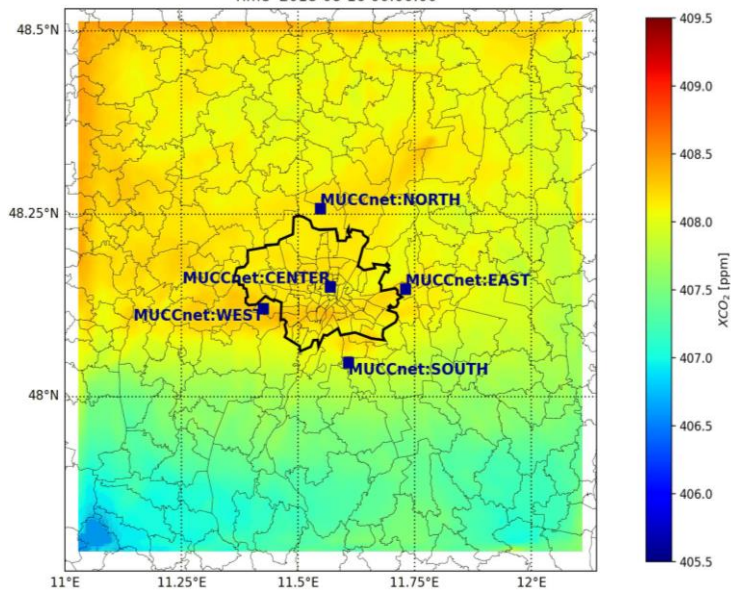




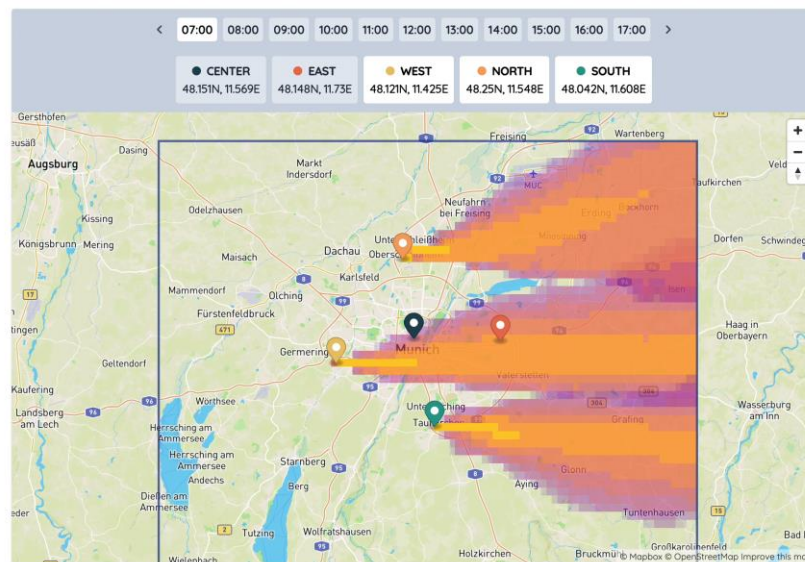
# Automated Transport Modeling

(WRF-GHG, 400m)

Modelled XCO<sub>2</sub> for Munich (D03):  
Time 2018-08-16 00:00:00

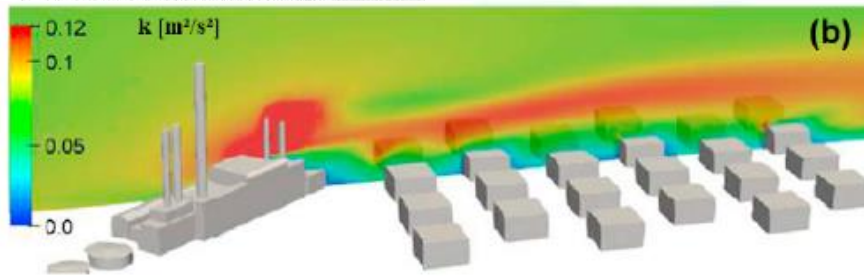
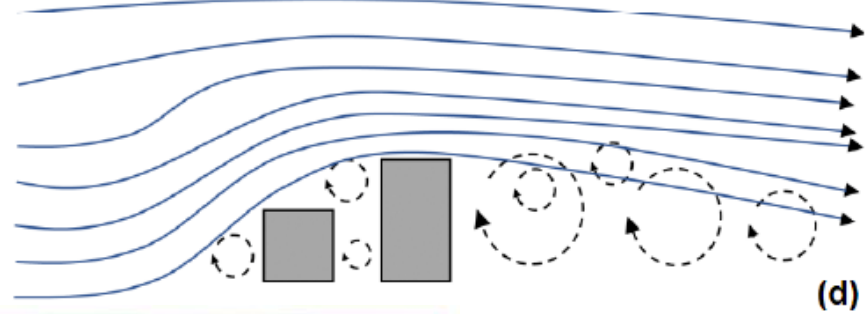
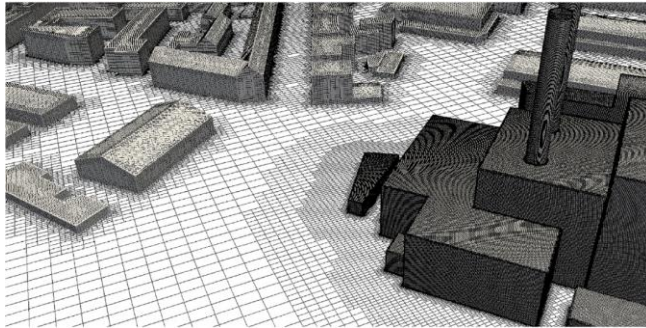


Footprint simulation



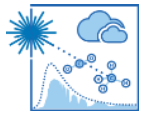
# Computational Fluid Dynamics and Urban Geometry Generalization

*Toja-Silva et al. (2017, 2018)*

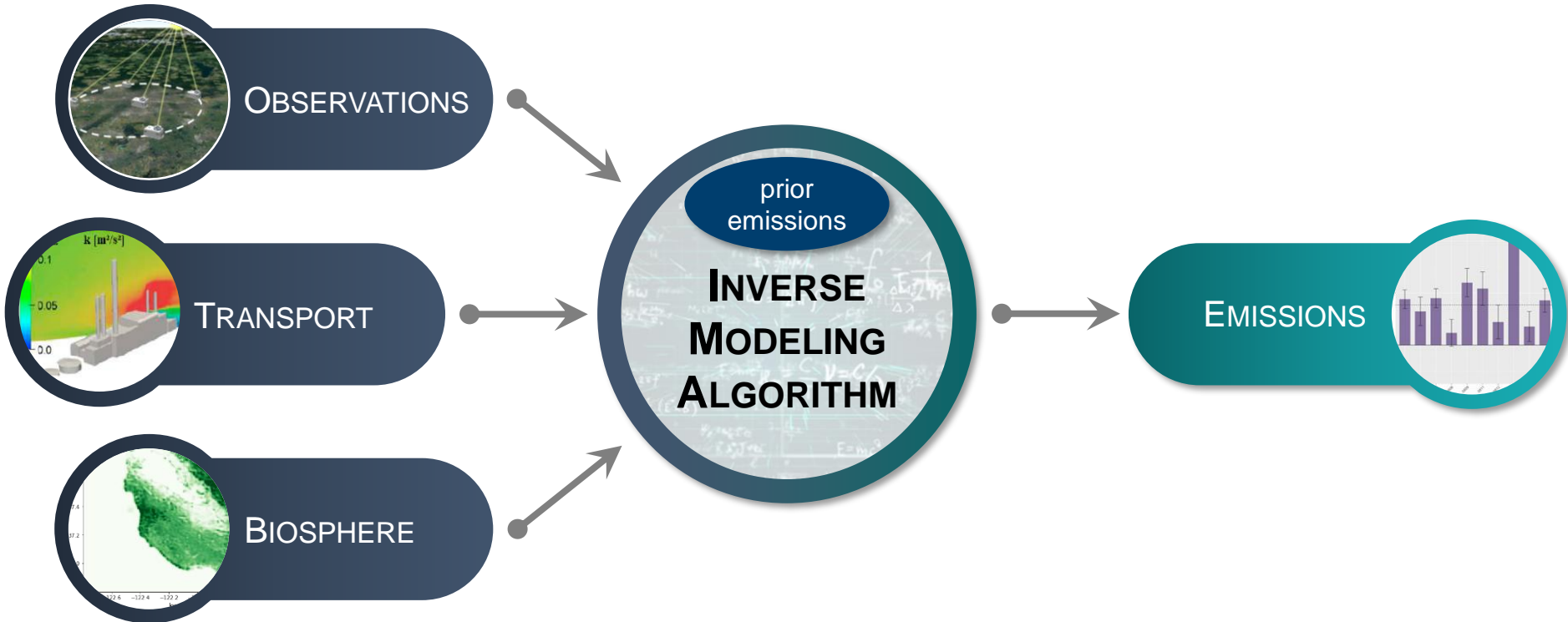


**Optimizing:**  
Building density  
Distribution  
Height

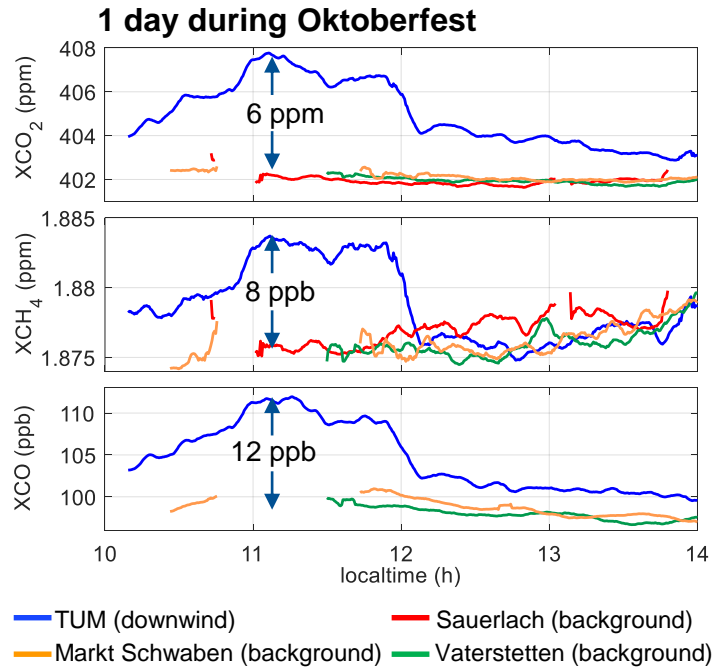
→ Smart geometry building generalization to decrease computational costs while preserving accuracy



# Emission Monitoring

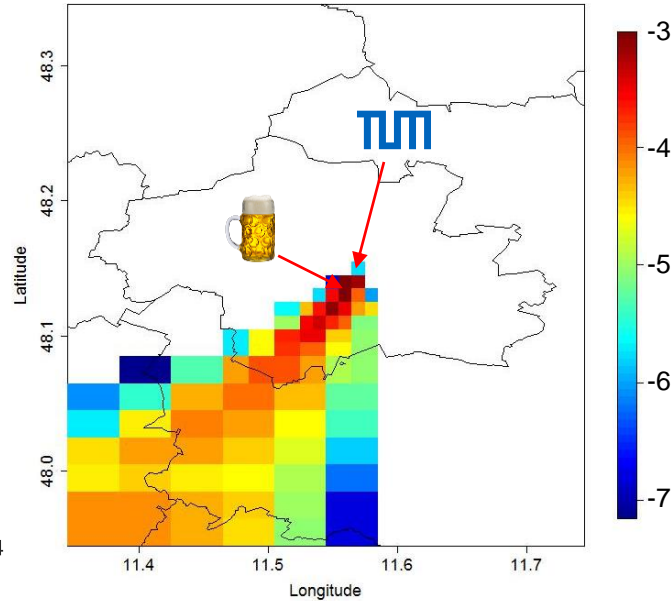
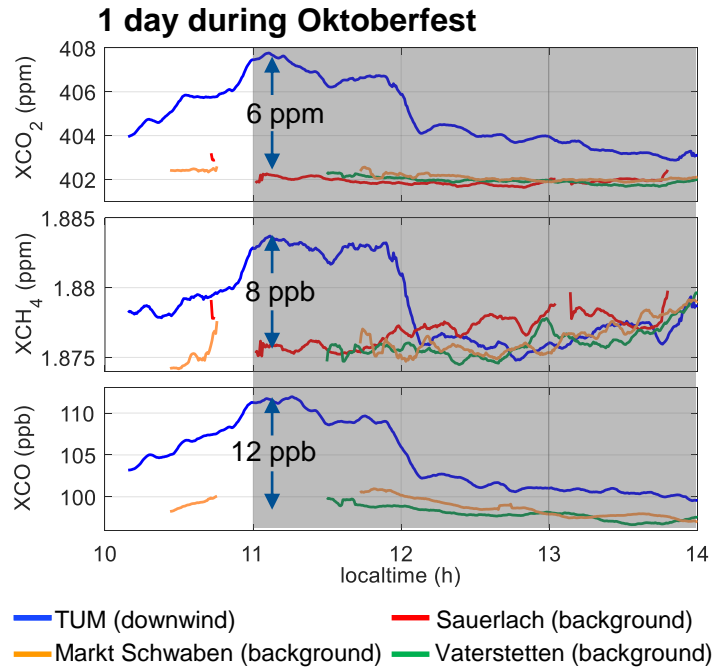


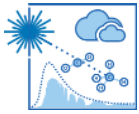
# Unknown Emission Sources



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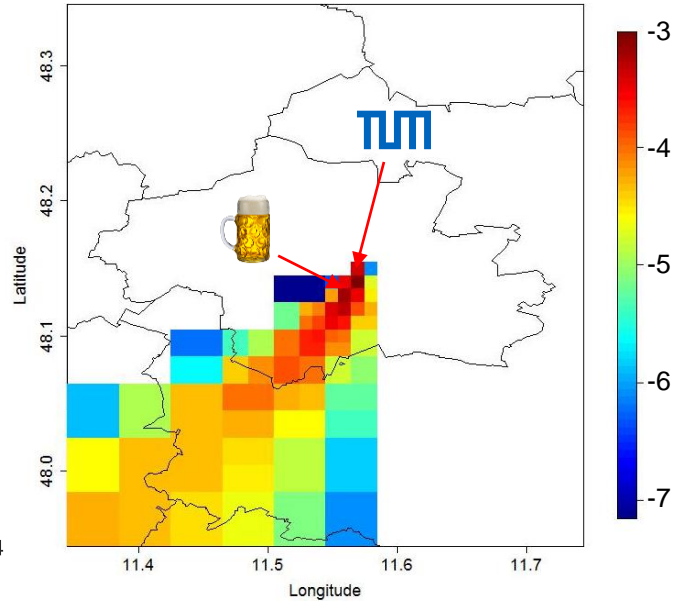
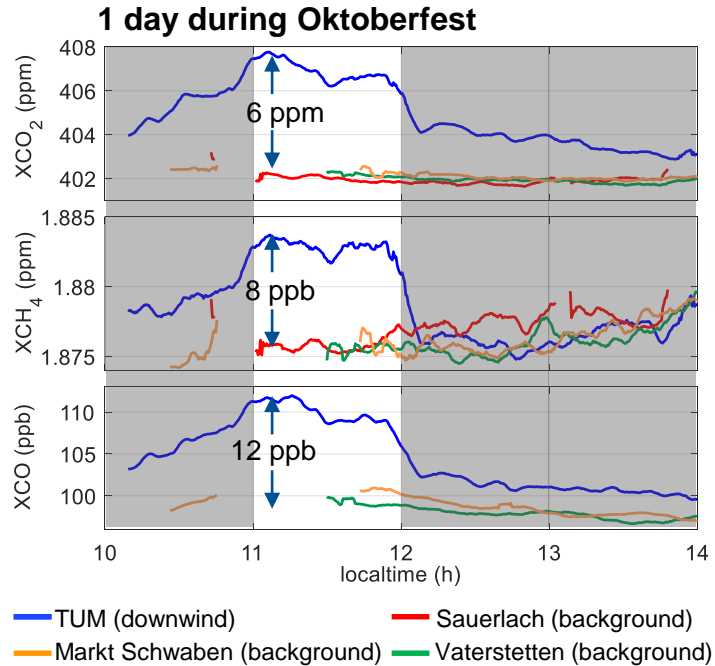
$$\log \left( \text{footprint} / \frac{\text{ppm}}{\frac{\mu\text{mol}}{\text{m}^2 \cdot \text{s}}} \right)$$

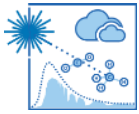




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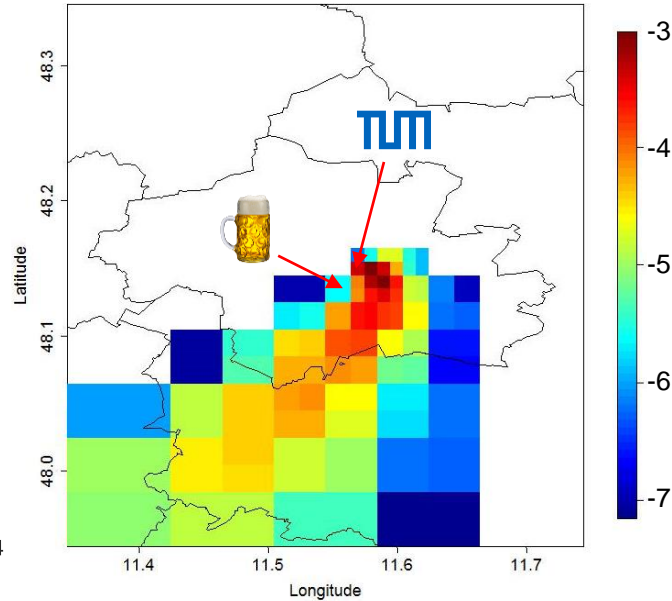
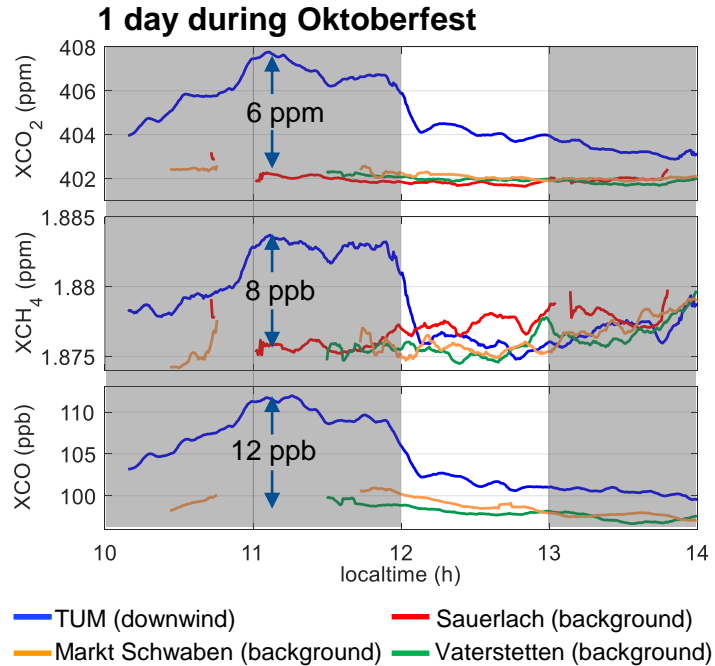
$$\log \left( \text{footprint} / \frac{\text{ppm}}{\frac{\mu\text{mol}}{\text{m}^2 \cdot \text{s}}} \right)$$



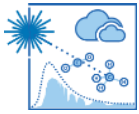


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$$\log \left( \text{footprint} / \frac{\text{ppm}}{\frac{\mu\text{mol}}{\text{m}^2 \cdot \text{s}}} \right)$$

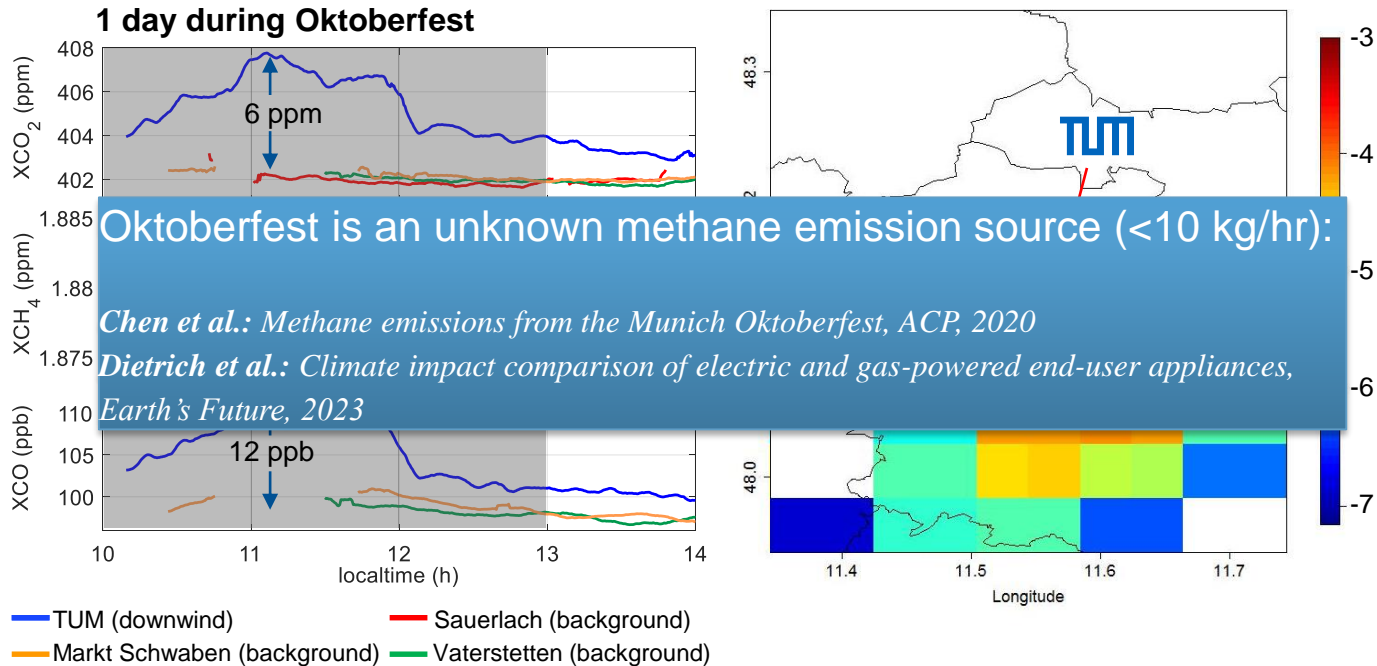




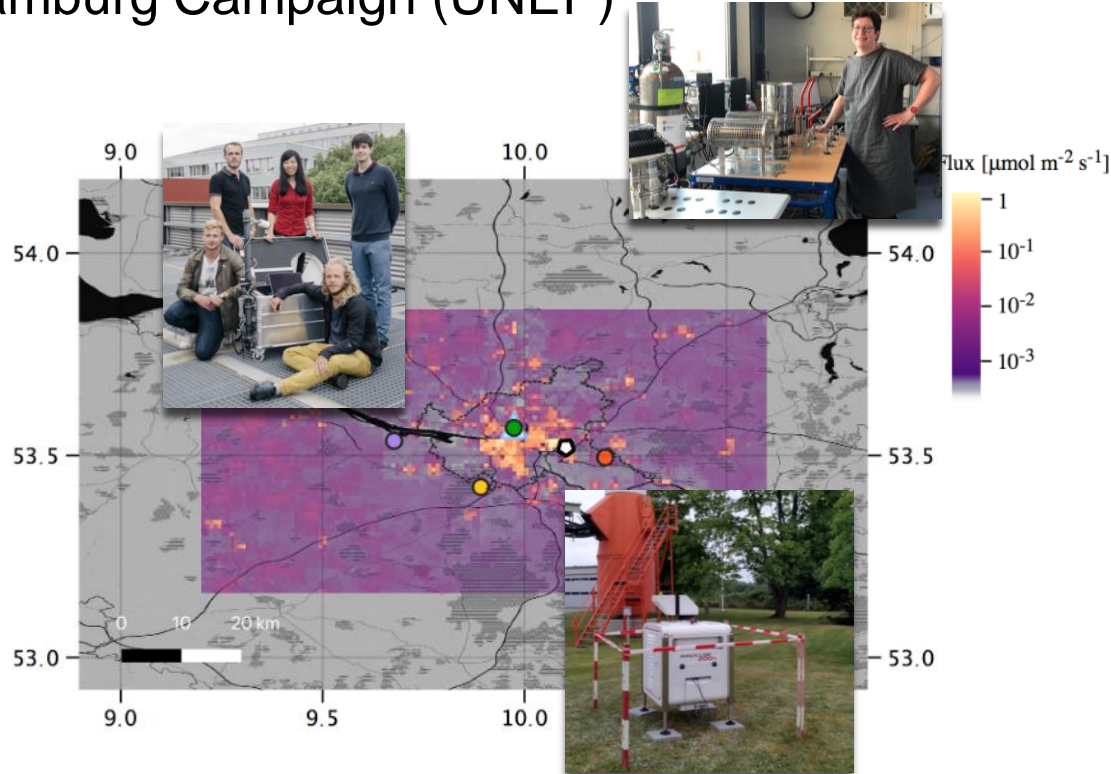


# Unknown Emission Sources

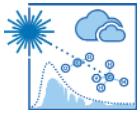
$$\log \left( \text{footprint} / \frac{\text{ppm}}{\frac{\mu\text{mol}}{\text{m}^2 \cdot \text{s}}} \right)$$



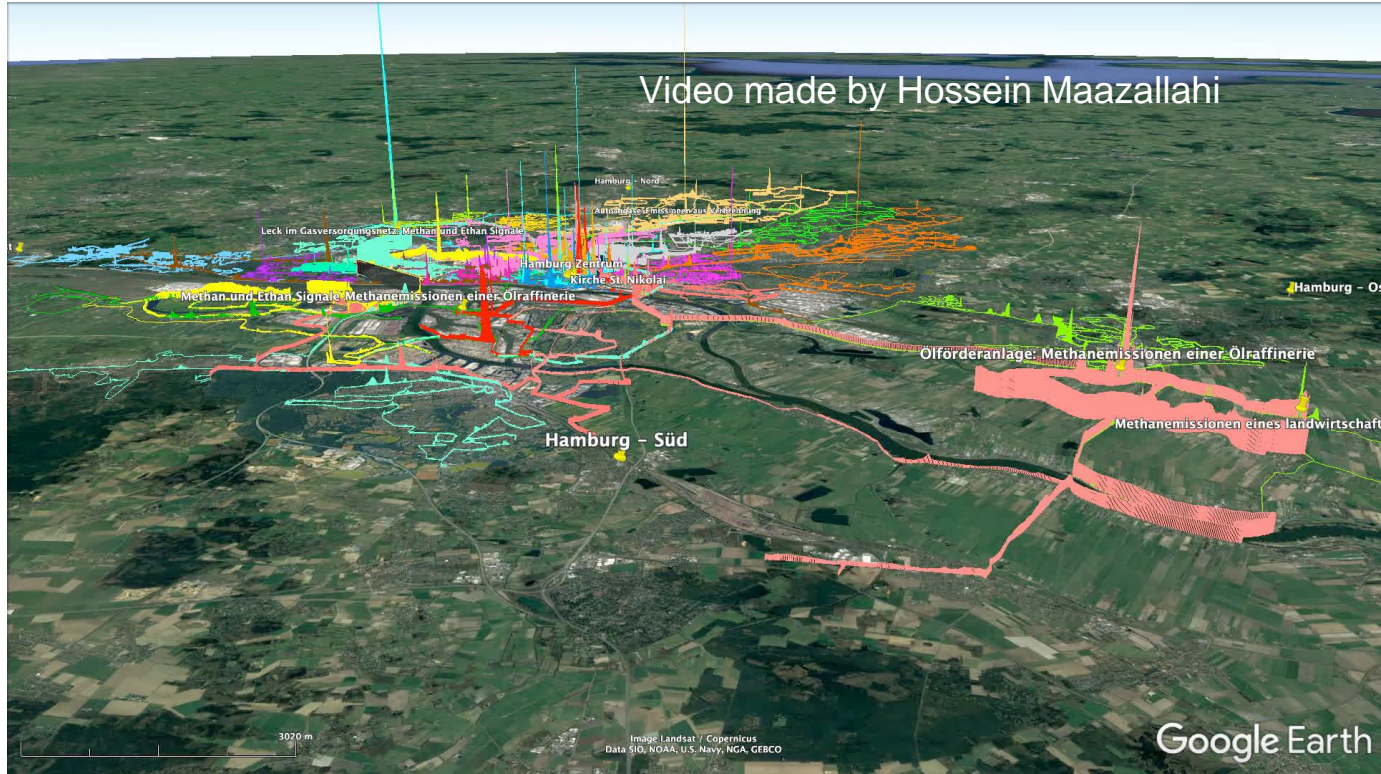
## Hamburg Campaign (UNEP)



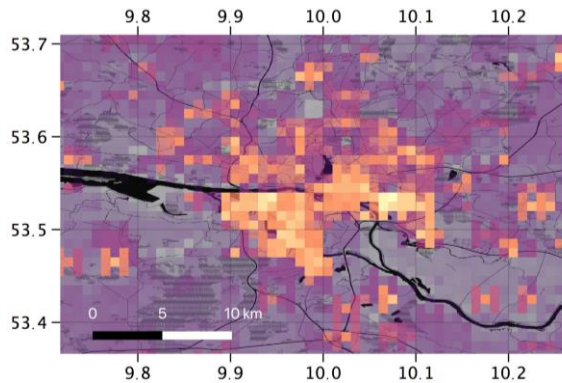
- **4 FTIR systems** around high emission zones in Hamburg
- **1 LiDAR system** in city center captures 3D wind information → improving **transport modeling**
- **Isotope measurement** → **source attribution**
- **Mobile Measurements** → refining the **prior emission inventory**



# Hamburg Campaign: Methane Sources



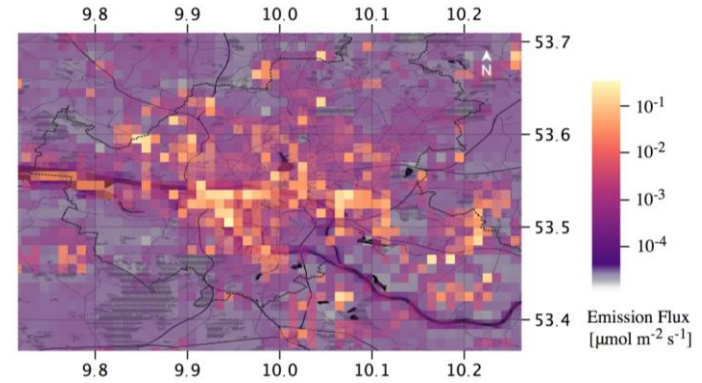
# Improving an A-Priori Emission Inventory



**Original emission inventory**  
(e.g. TNO GHGco)



**Measurements**  
(e.g. using Picarro instruments)



**Corrected emission inventory  
for inversion**

- Correcting spatial distribution of emission inventory
- Adding the Elbe river and the associated wetlands

# Bayesian Inversion

(Jones et al. 2021)

$$\min_{x, b} [(Hx + Bb - y)^T S_\epsilon^{-1} (Hx + Bb - y) + (x_a - x)^T S_a^{-1} (x_a - x)]$$

$y$ : observations

$H$ : footprint matrix

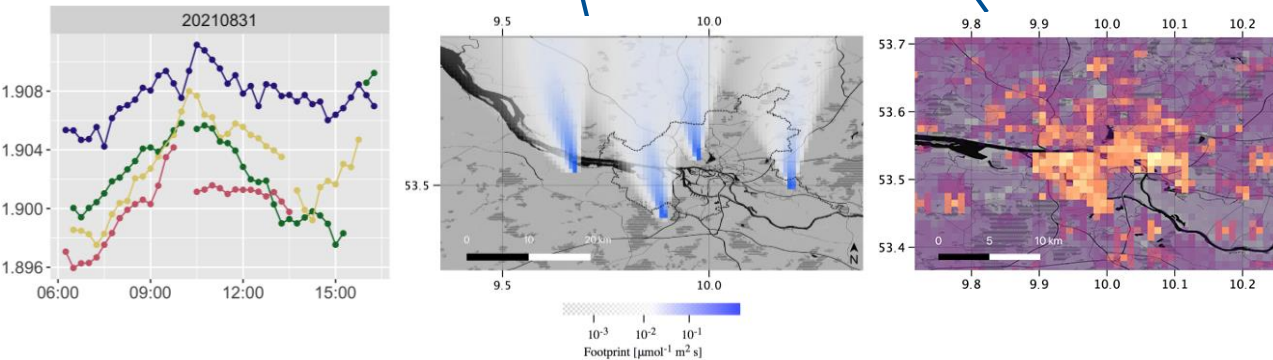
$x$ : emissions

$x_a$ : prior emissions

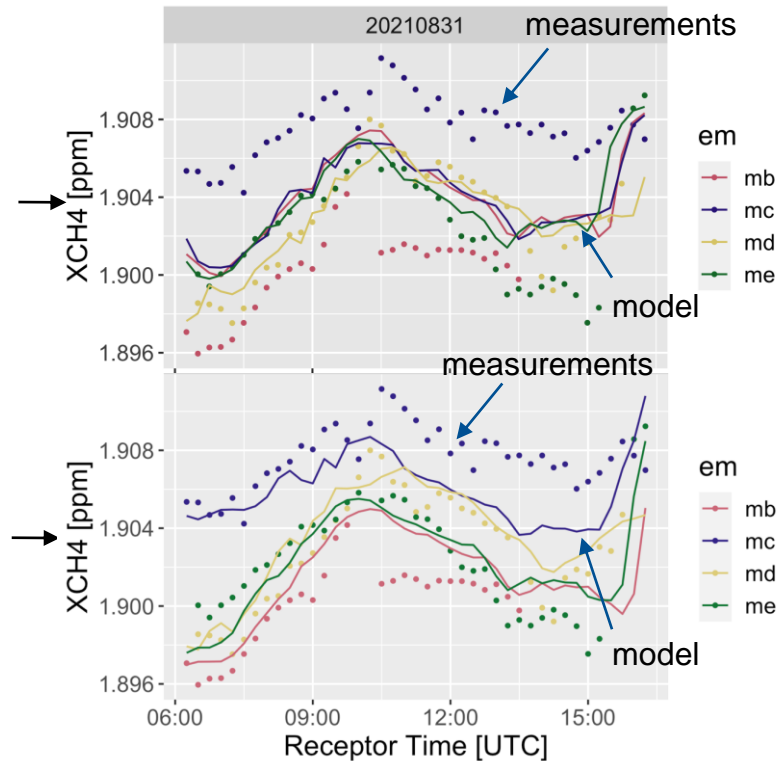
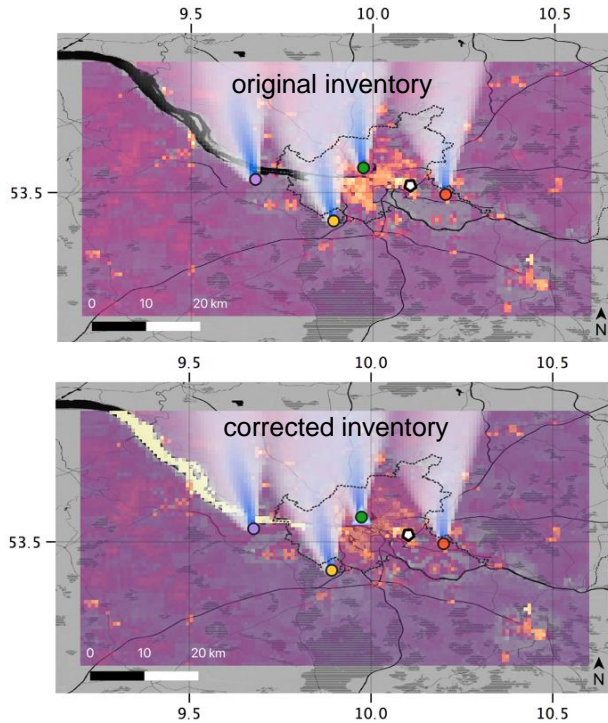
$B$ : background influence matrix

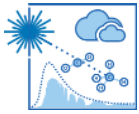
$b$ : background concentration

$S$ : error covariance matrix



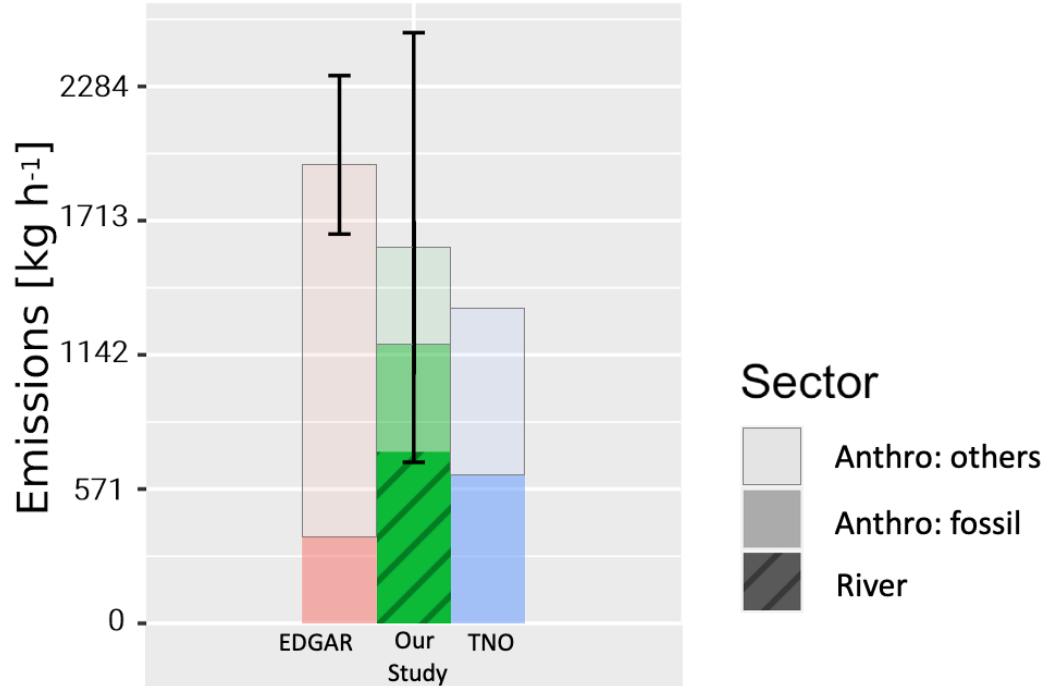
# Updated Emission Inventory → Improved Inverse Modeling Results

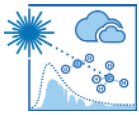




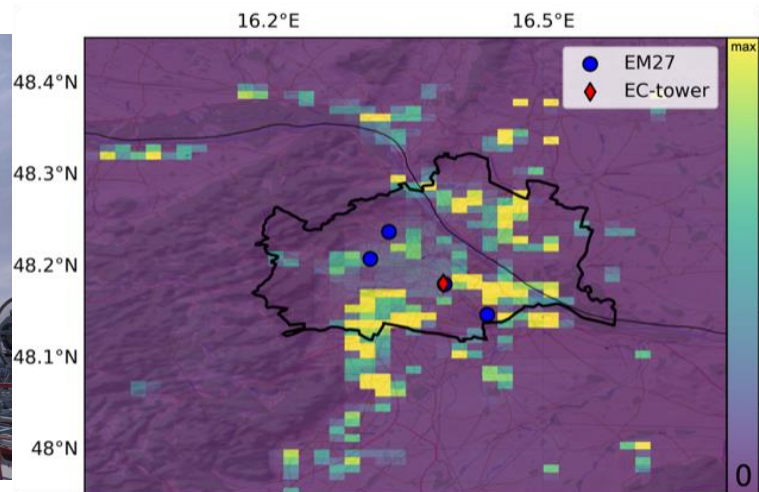
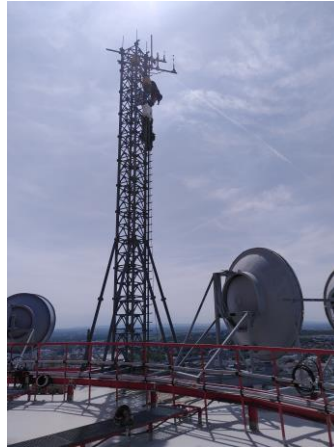
# Hamburg Campaign – Results

(Forstmaier et al. 2023)





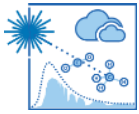
## Vienna Campaign (colab. with Vienna Urban Carbon Laboratory)



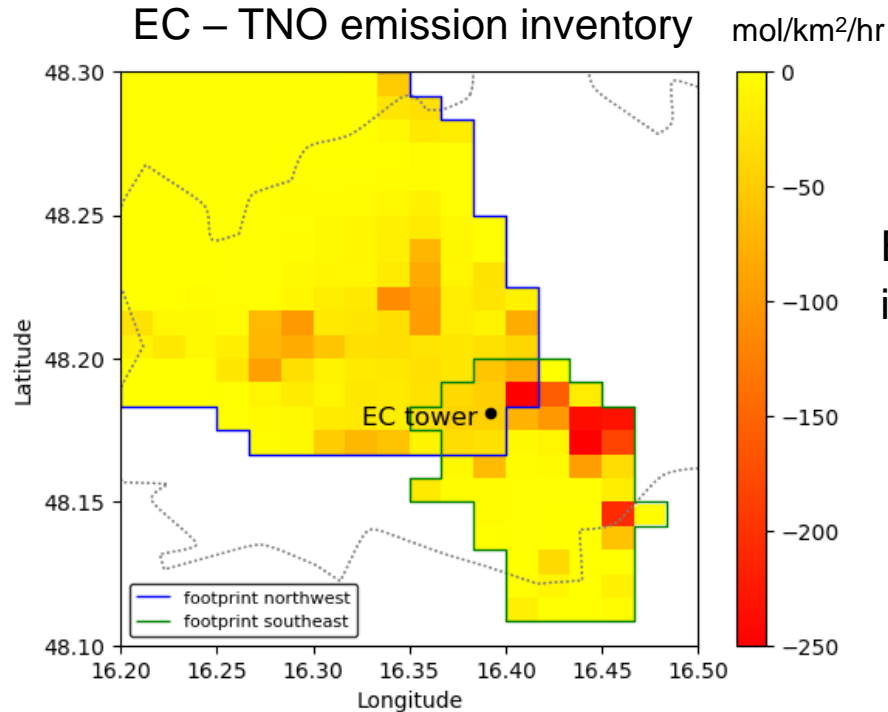
Combining total column and EC-tower measurements

4 FTIR @ 4 locations  
and one tower at Arsenal





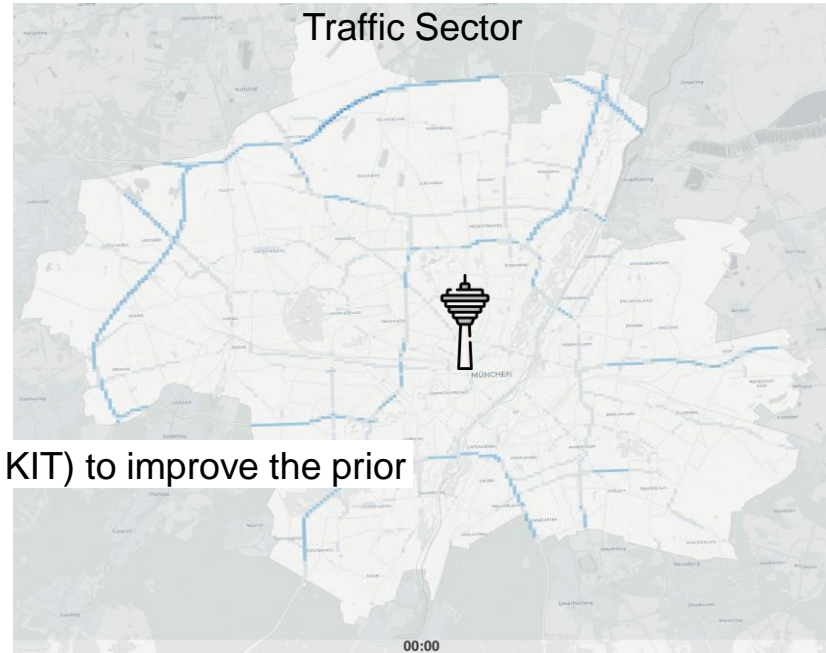
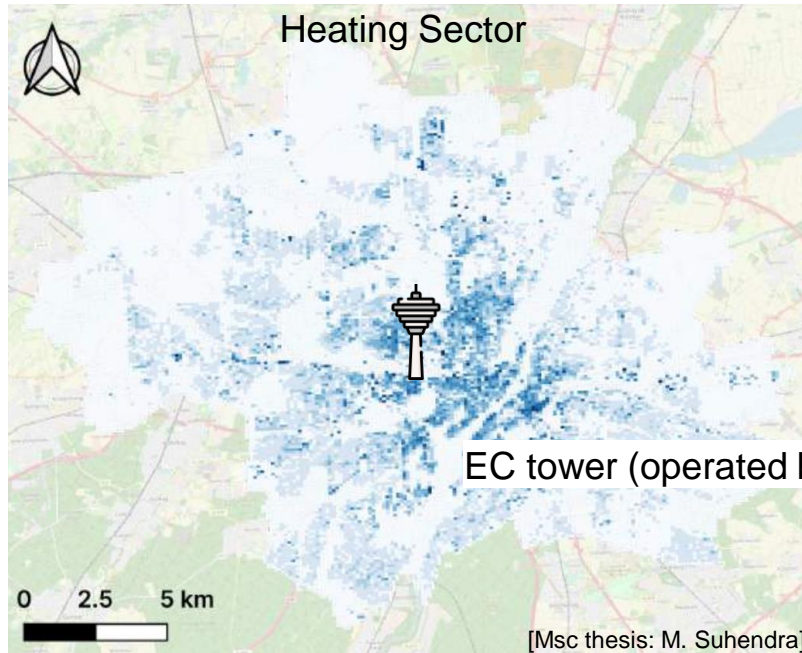
## EC Measurements for Prior Correction

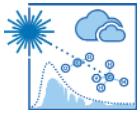


EC sees much less emission  
in southeast

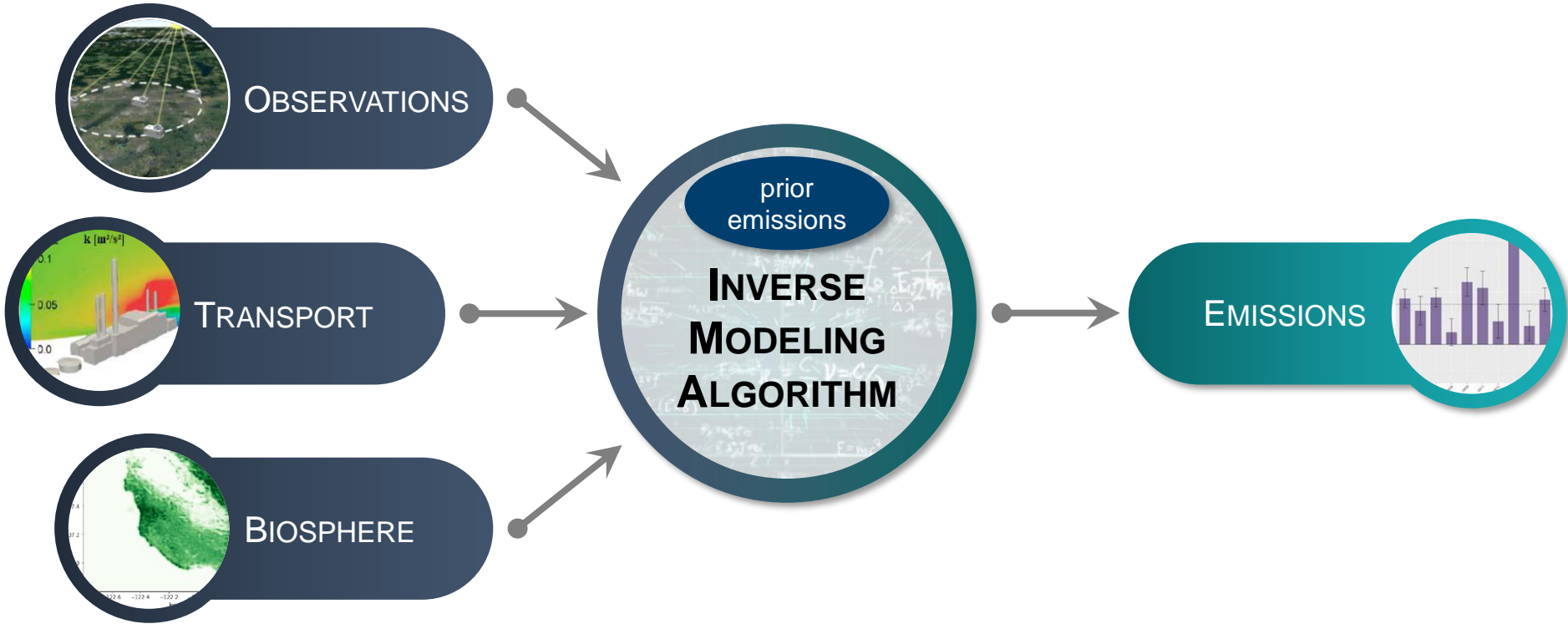
# Munich High Resolution Bottom-up Emission Inventory (100m, 1hr)

(In collaboration with TNO)

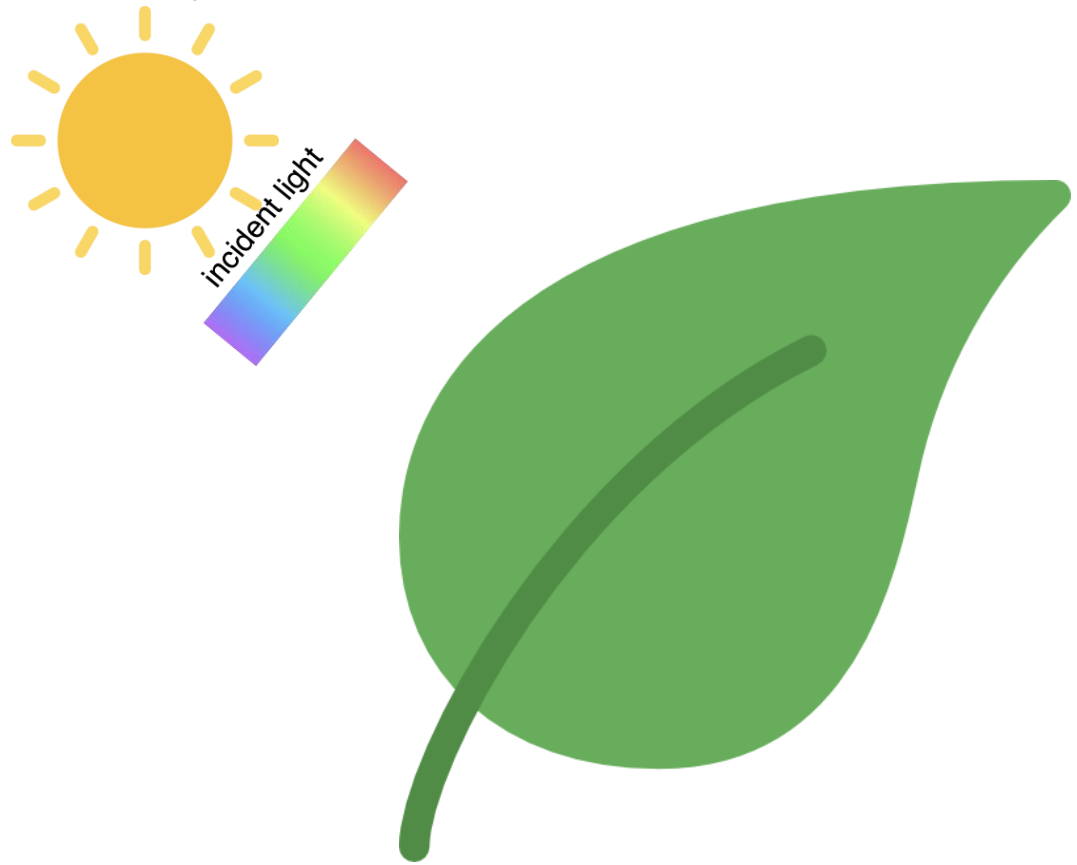




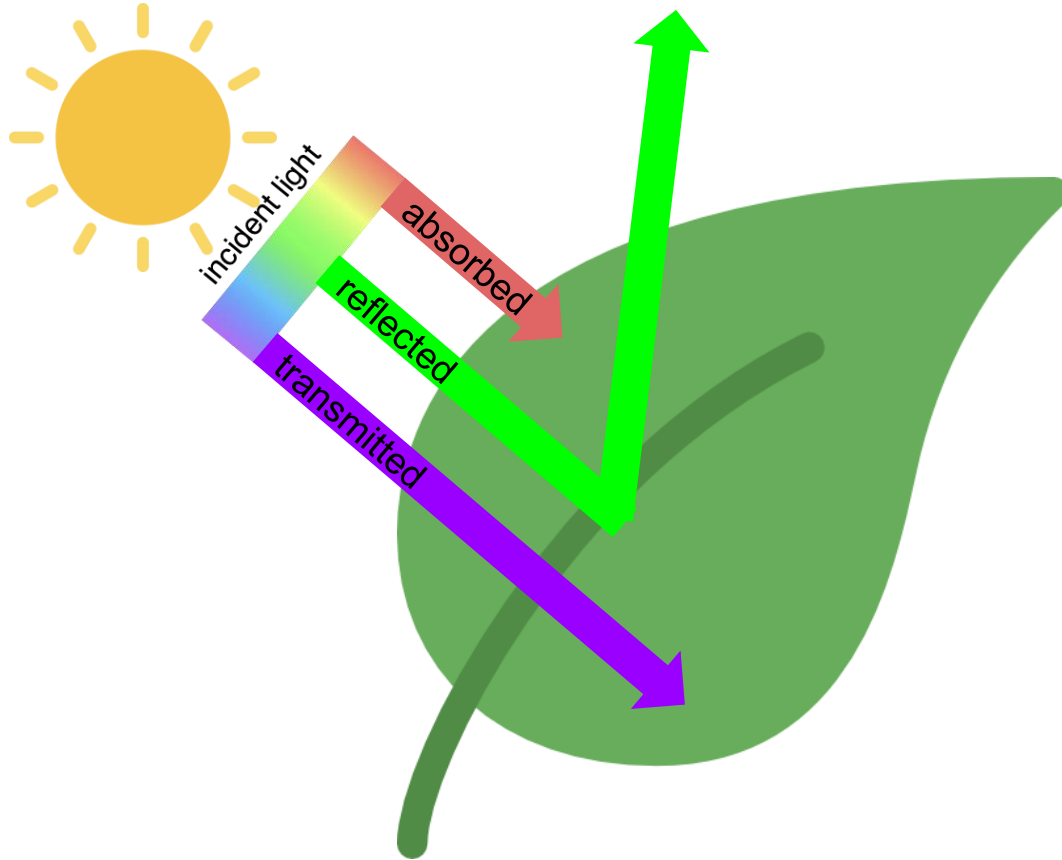
# Emission Monitoring

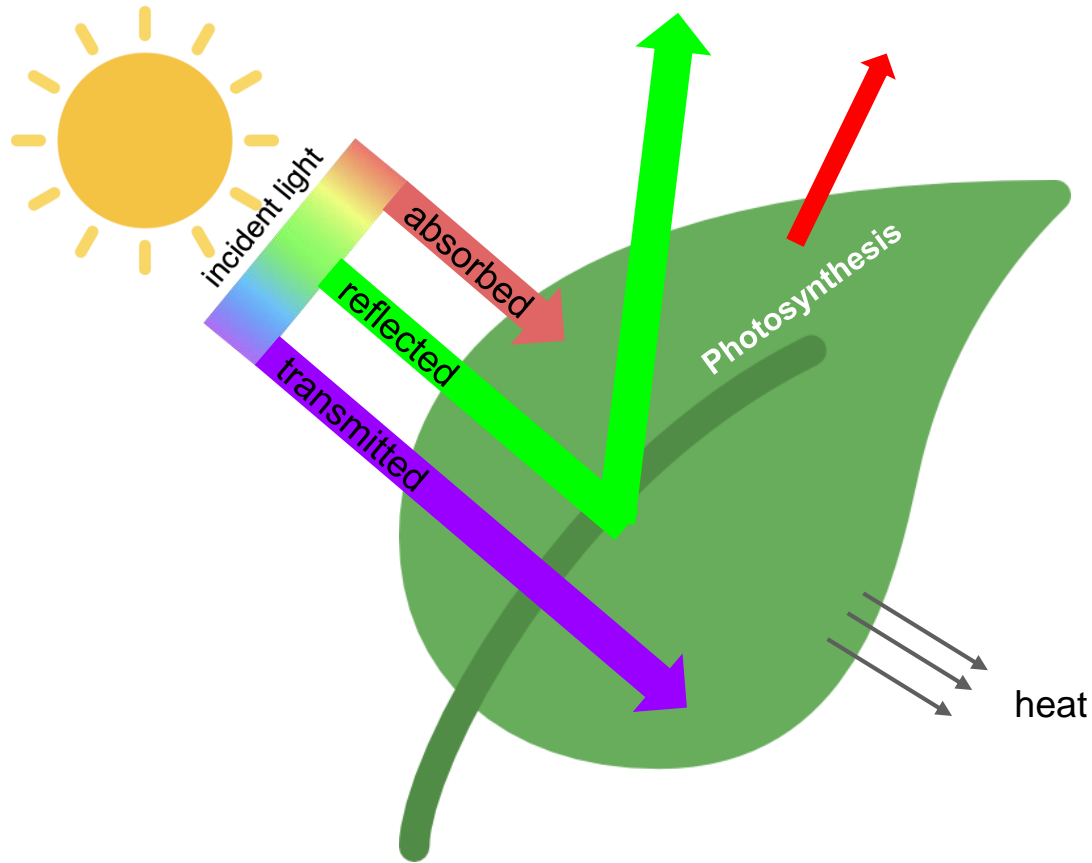


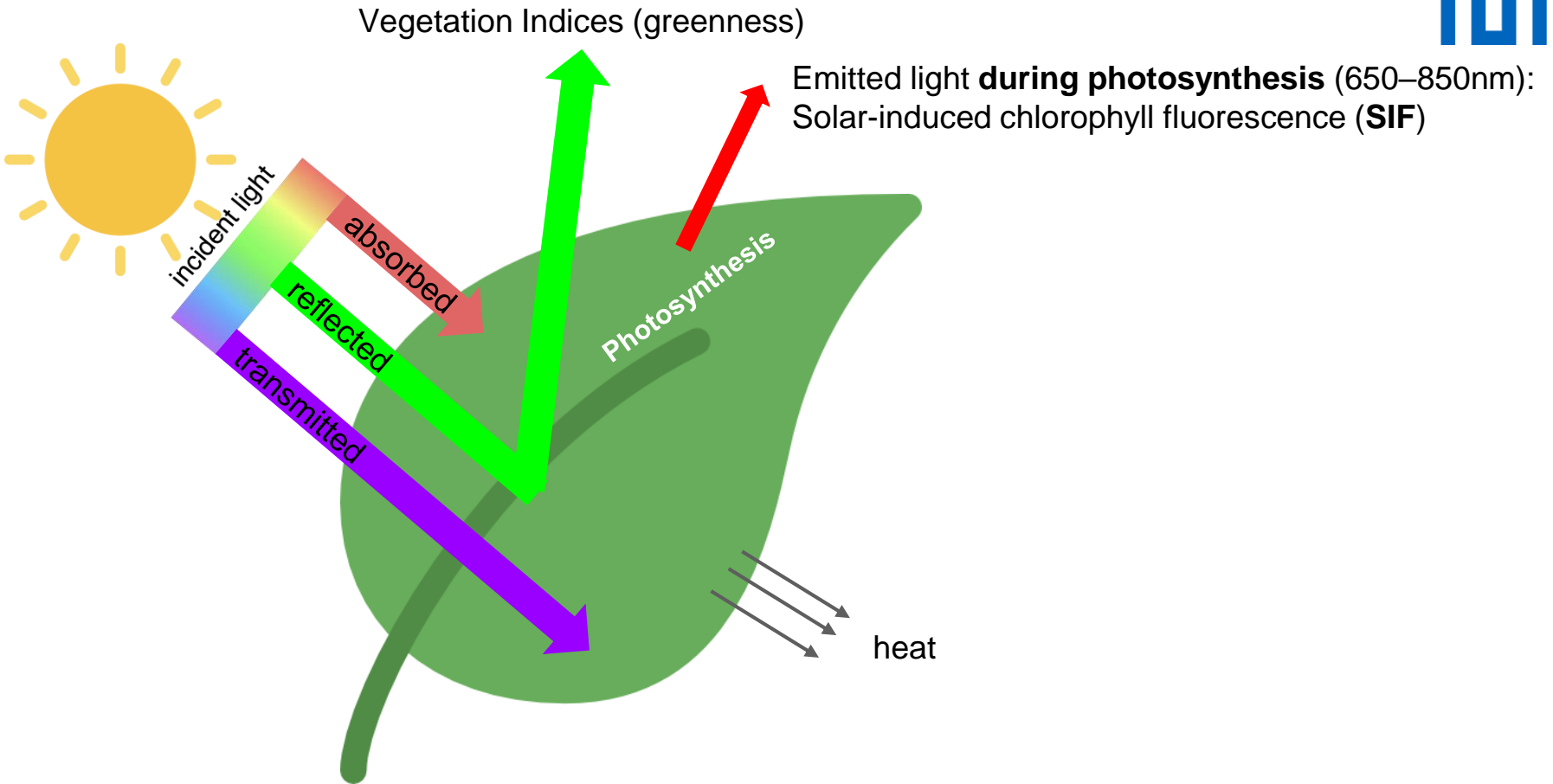
# Photosynthesis



# Photosynthesis

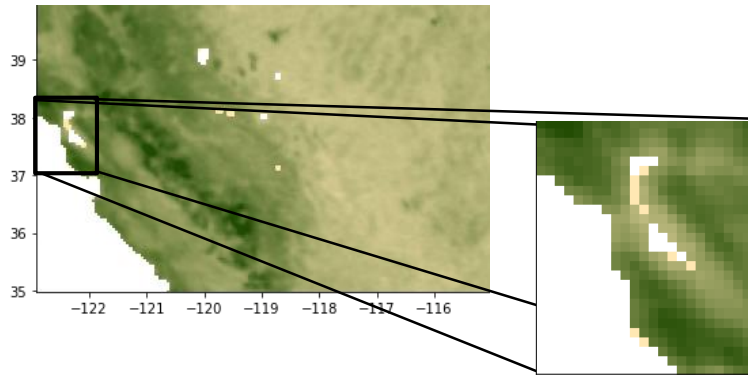






## TROPOMI SIF measurements

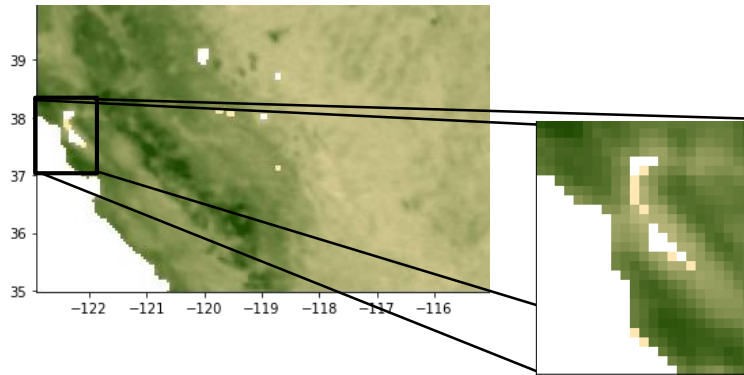
SIF@0.05°





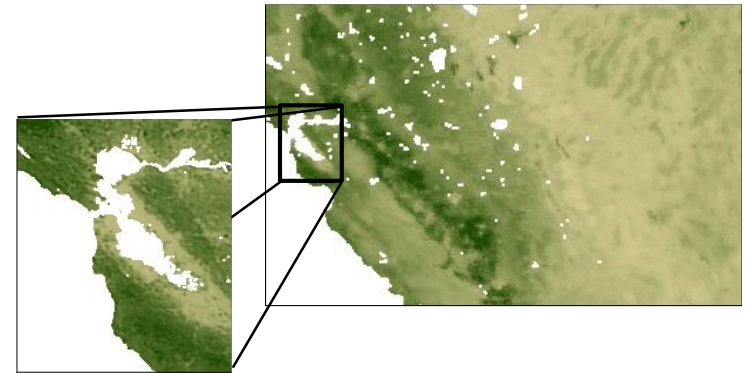
## TROPOMI SIF measurements

SIF@0.05°

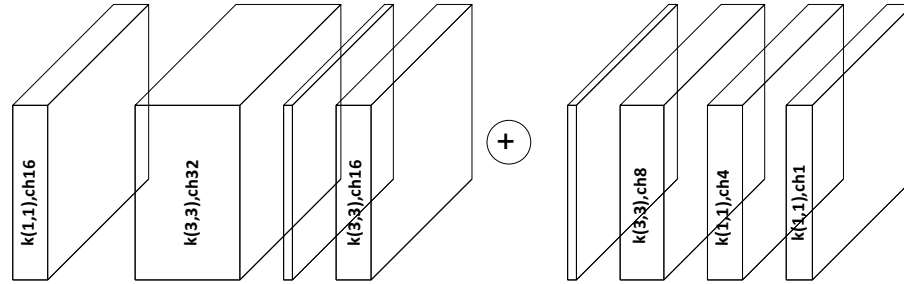


Goal: Estimate SIF at 0.005° resolution (10 times finer)

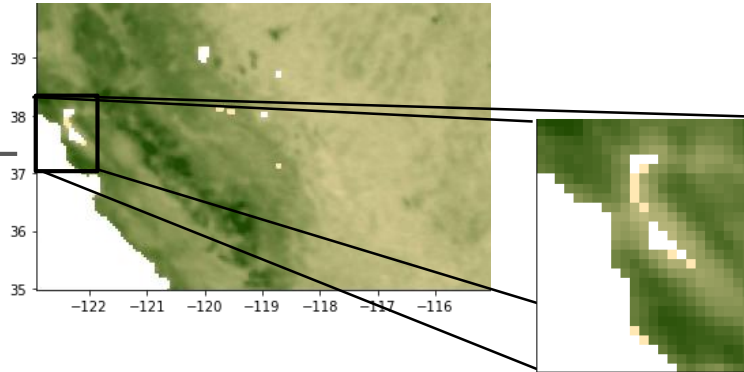
SIF@0.005°



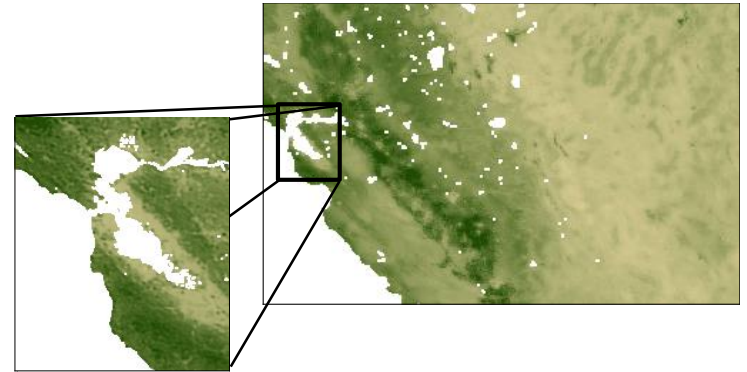
# Convolutional Neural Network



SIF@0.05°

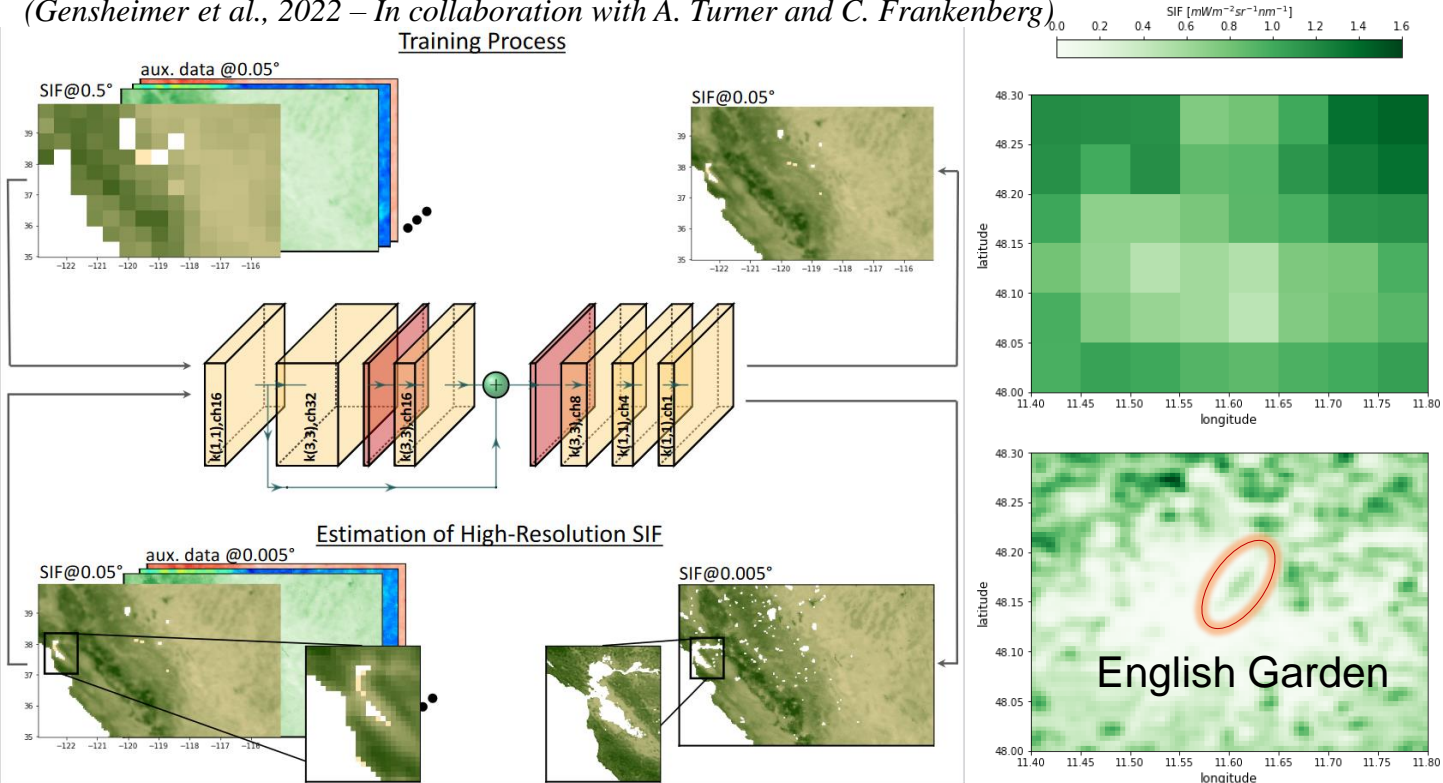


SIF@0.005°



# SIFnet: Super-Resolution Convolutional Neural Network for SIF

(Gensheimer et al., 2022 – In collaboration with A. Turner and C. Frankenberg)





## Munich Greenhouse Gas Observation Landscape in 2015



## Munich Greenhouse Gas and Air Quality Landscape Today



- Multiscale measurements
- Combining greenhouse gas and air pollutant measurements

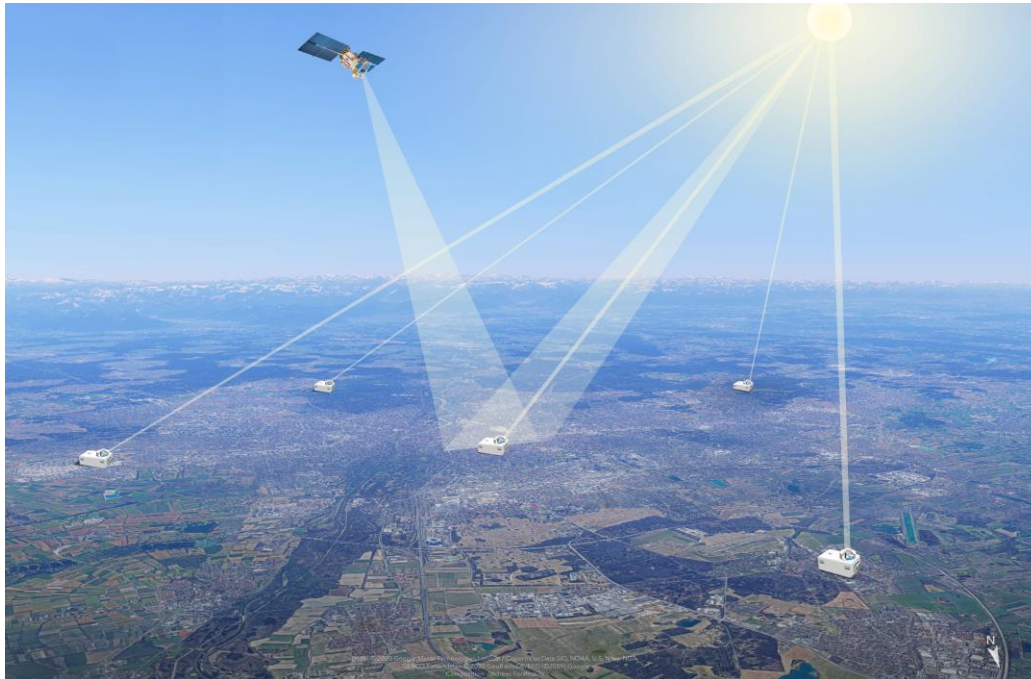


## Munich Greenhouse Gas and Air Quality Landscape 2019



➤ 5 MUCCnet station

## Munich Greenhouse Gas and Air Quality Landscape 2020



- 5 MUCCnet station
- OCO target mode

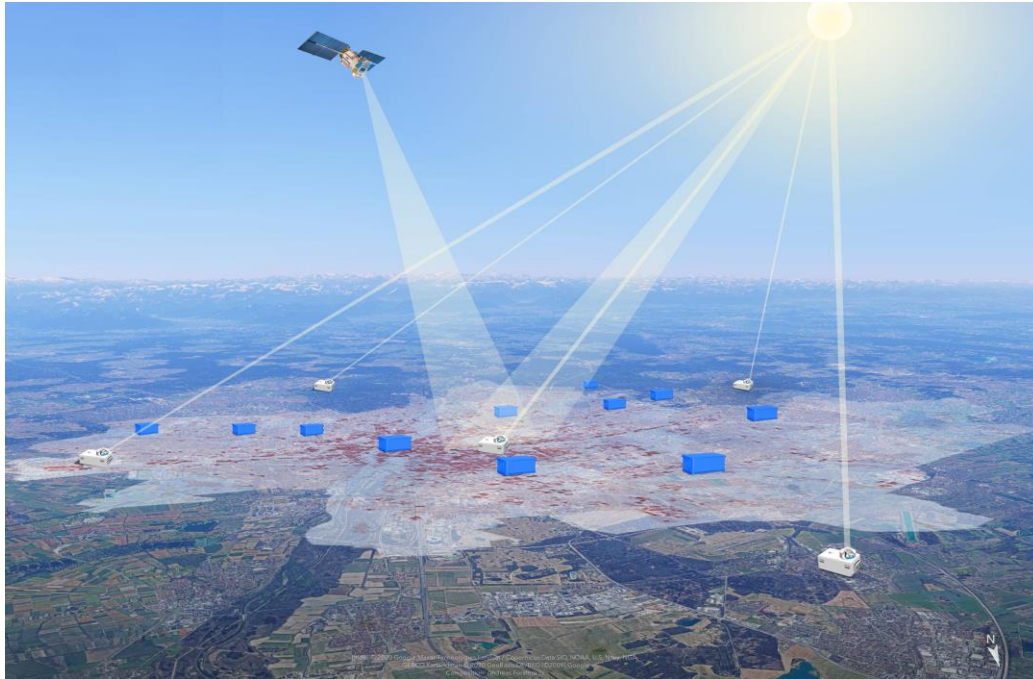
## Munich Greenhouse Gas and Air Quality Landscape 2021



- 5 MUCCnet station
- OCO target mode
- 100m, 1hr emission inventory



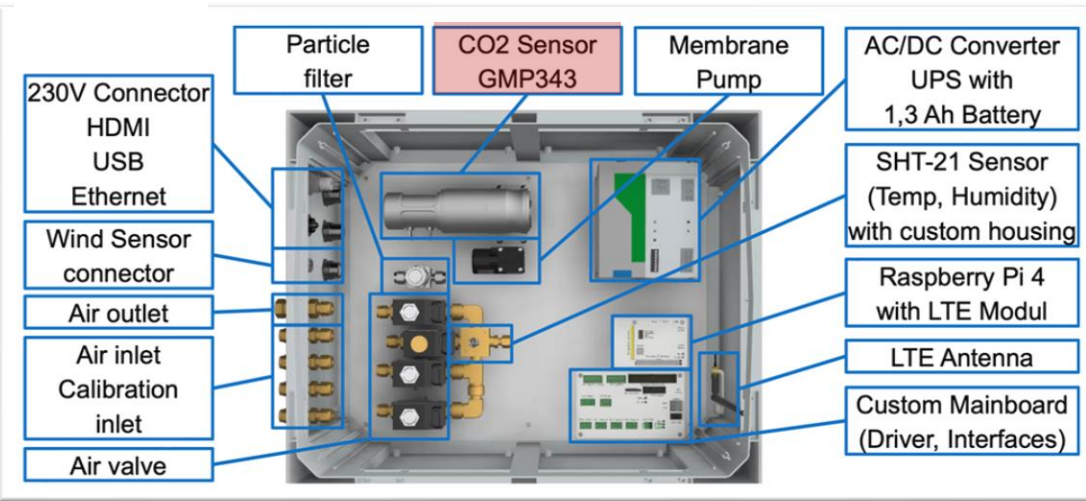
## Munich Greenhouse Gas and Air Quality Landscape Today



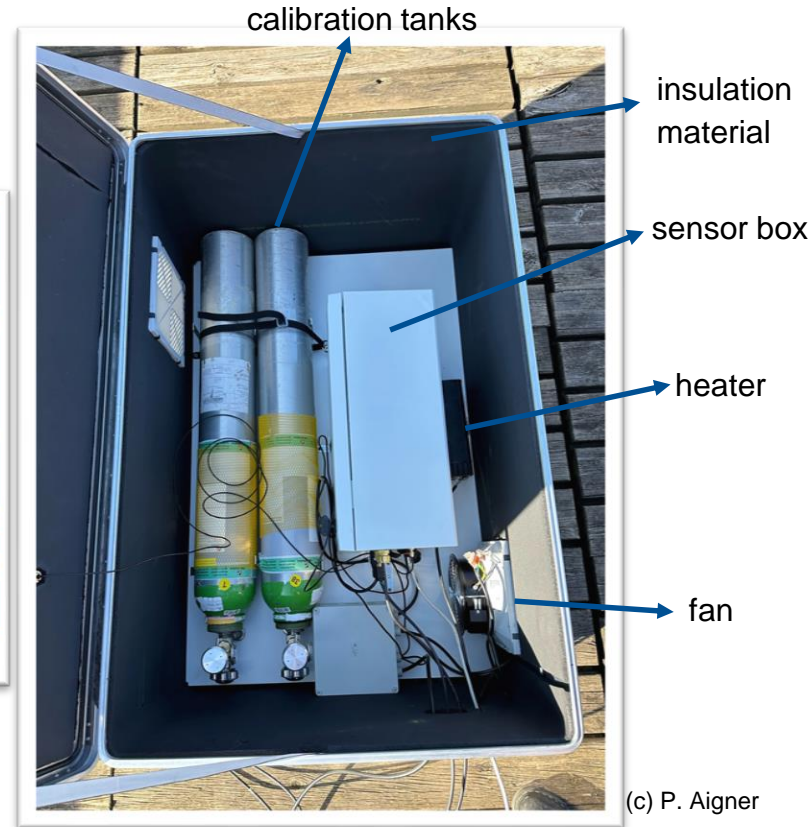
- 5 MUCCnet station
- OCO target mode
- 100m, 1hr emission inventory
- 20 mid-cost CO<sub>2</sub> sensors

# Mid-Cost Sensor System

## NDIR



[Msc thesis: A. Schmitt]



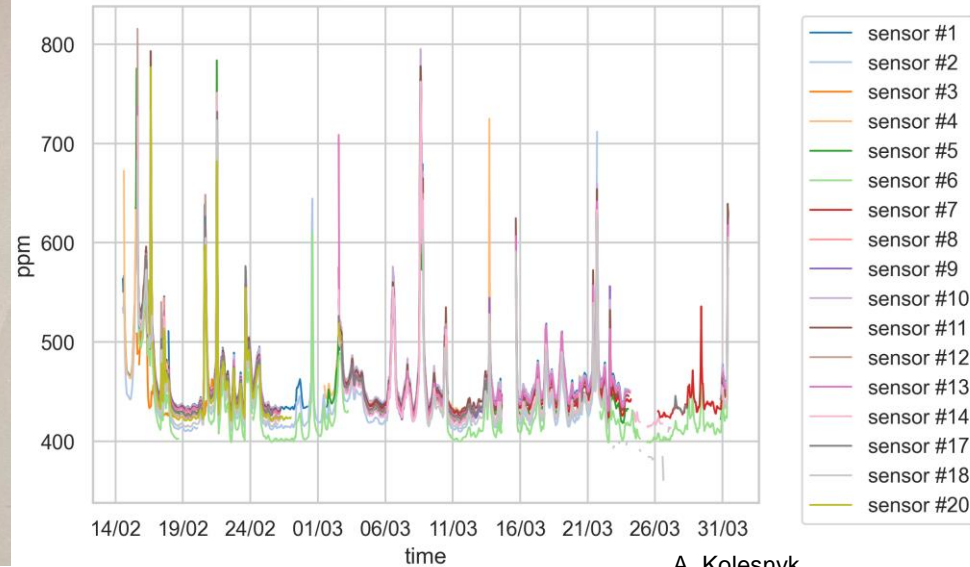
(c) P. Aigner

# Mid-Cost Sensor System



(c) P. Aigner

1.5 months lab test



A. Kolesnyk

## Munich Greenhouse Gas and Air Quality Landscape Today



- 5 MUCCnet station
- OCO target mode
- 100m, 1hr emission inventory
- 20 mid-cost CO<sub>2</sub> sensors
- 100 low-cost CO<sub>2</sub> sensors and 50 low-cost air quality sensors

# Air Quality Sensors

Side-by-side



Measure NO<sub>x</sub>, O<sub>3</sub>, CO and PM

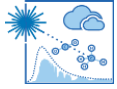


(c) F. Dietrich

Calibration Unit



(c) A. Wenzel



Universiteit Utrecht

**TNO** innovation  
for life



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HEIDELBERG  
ZUKUNFT  
SEIT 1386



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PICARRO

