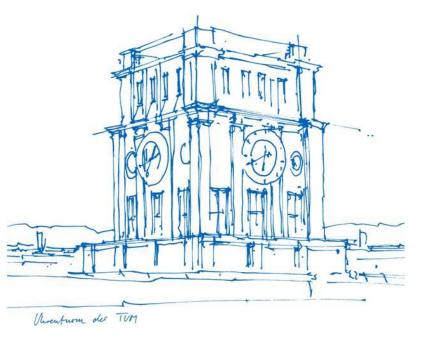


# First Evaluation of Swedish & Finnish Corner Reflectors

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# 1. Short Introduction

(1) Point Target Analysis

(I) Downloading the radar products needed for the calculation

(II) Performing a subpixel analysis (2) Corrections Processor

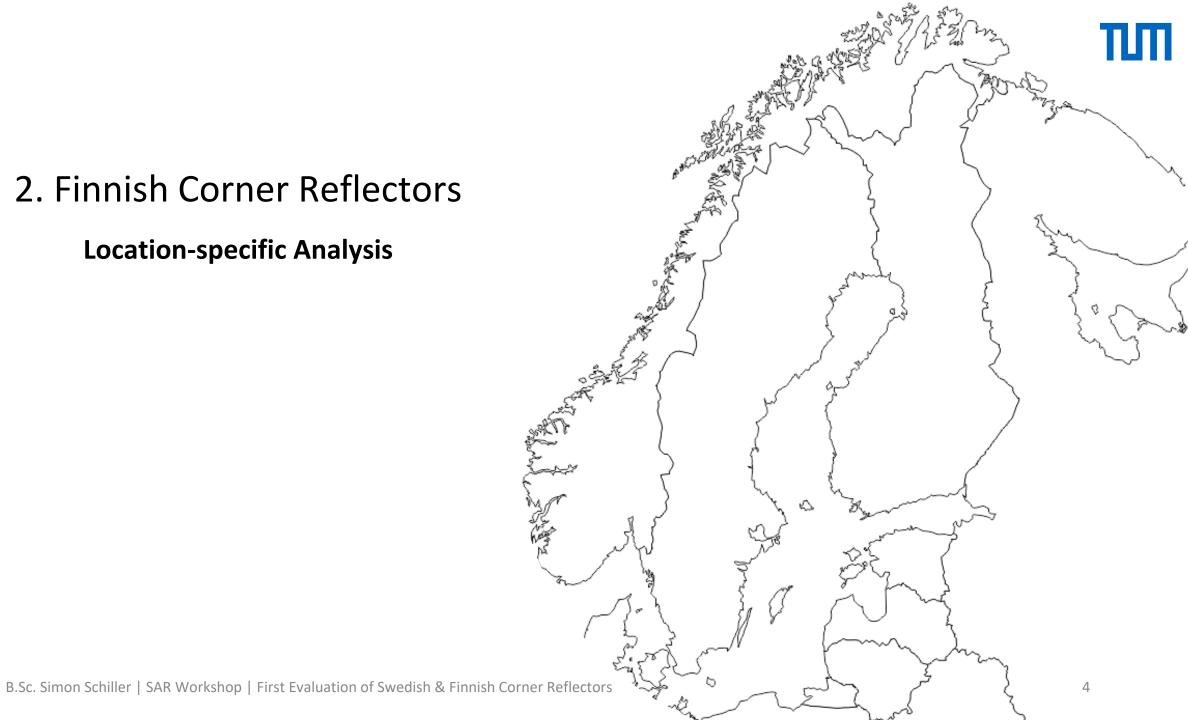
(I) Formulation of the Doppler range equation

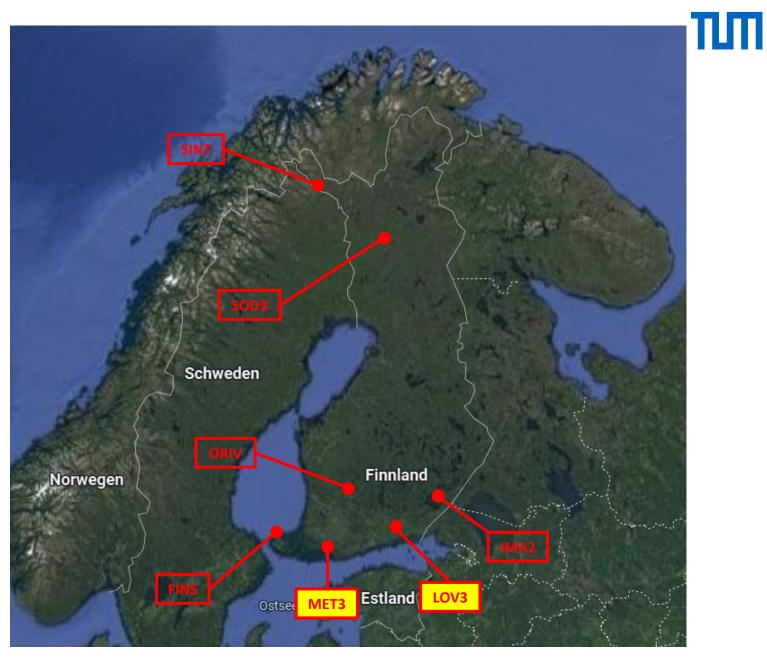
(II) Applying the necessary corrections (3) Absolute Positioning

(I) Choice of a suitable mathematical model

(II) Principle of fitting conditions with additional unknown parameters (I) Coordinate triple: [X, Y, Z]

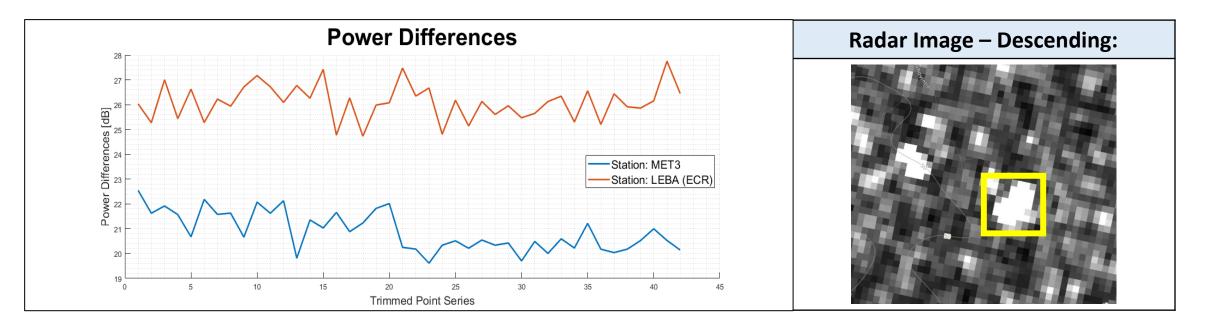
(II) Standard deviations:  $[S_X, S_Y, S_Z]$ 





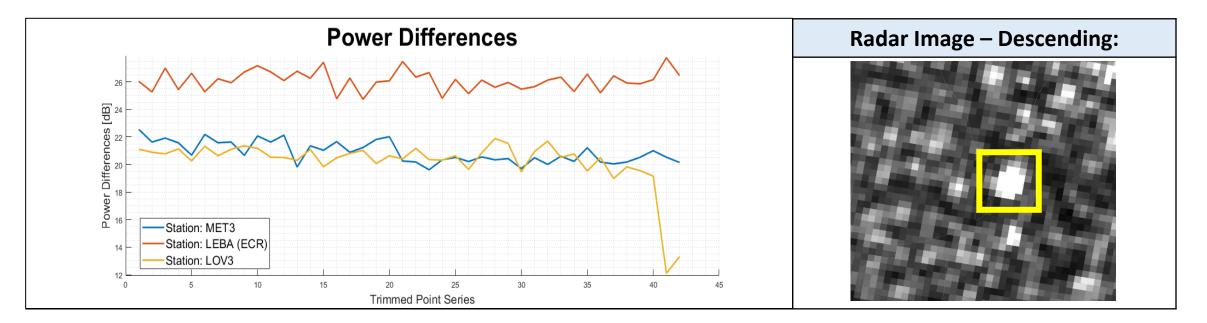


- 2.1 Location-specific Analysis MET3
- Location: Metsähovintie
- Corner Direction: Descending
- Date of Installation: Januar 2020





- 2.1 Location-specific Analysis LOV3
- Location: Loviisa
- Corner Direction: Descending
- Date of Installation: December 2021

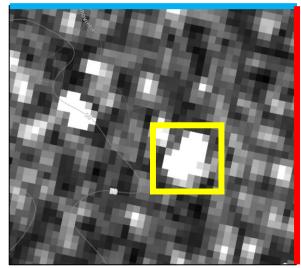




2.2 Visualization of the Results – MET3

	Coordinates [m]	Standard Deviation [ $\pm$ m]
x	2892592.3127	0.0284
Y	1311868.2060	0.0327
z	5512593.1975	0.0326

Range Observations: 201

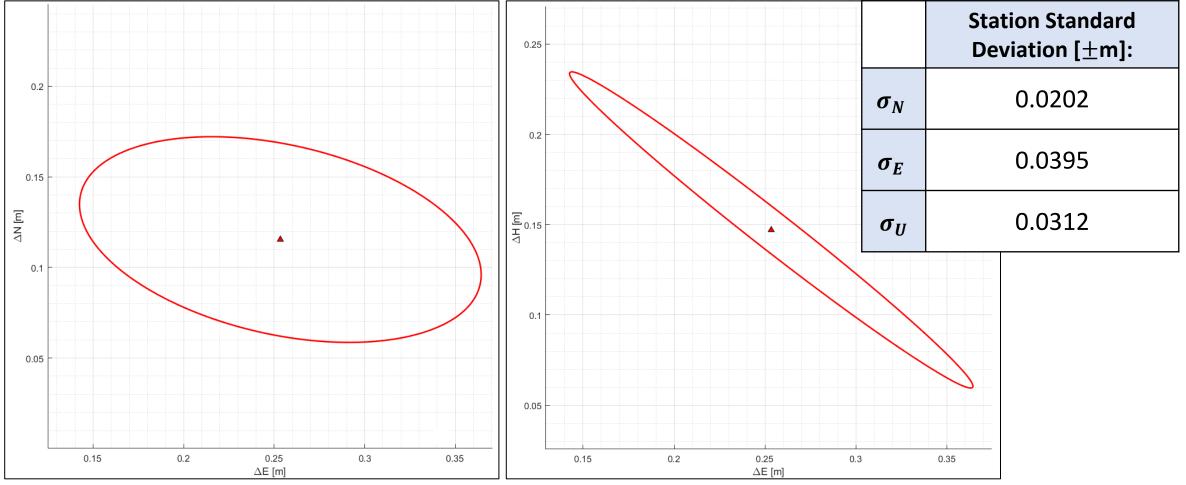


Azimuth Observations: 203

**2.2**Visualization of the Results – MET3

#### Range Observations: 201

#### Azimuth Observations: 203



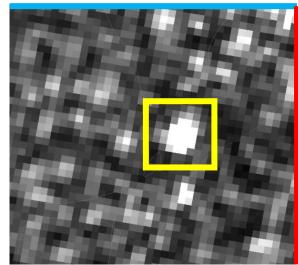
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2.2 Visualization of the Results – LOV3

	Coordinates [m]	Standard Deviation [ $\pm$ m]
x	2828356.1916	0.0507
Y	1396893.3833	0.0568
z	5524907.3823	0.0560

#### Range Observations: 53

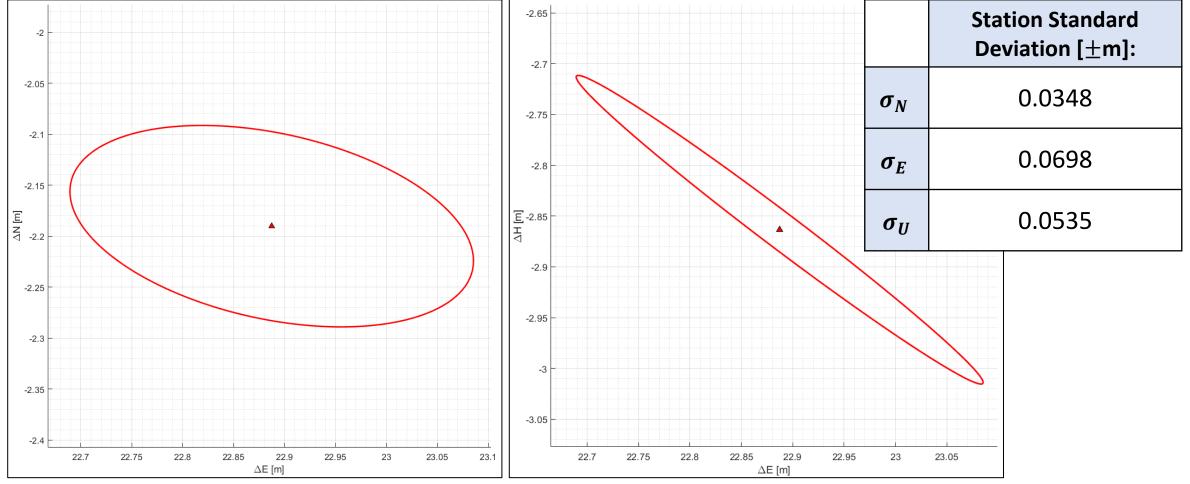


Azimuth Observations: 51

#### 2.2 Visualization of the Results – LOV3

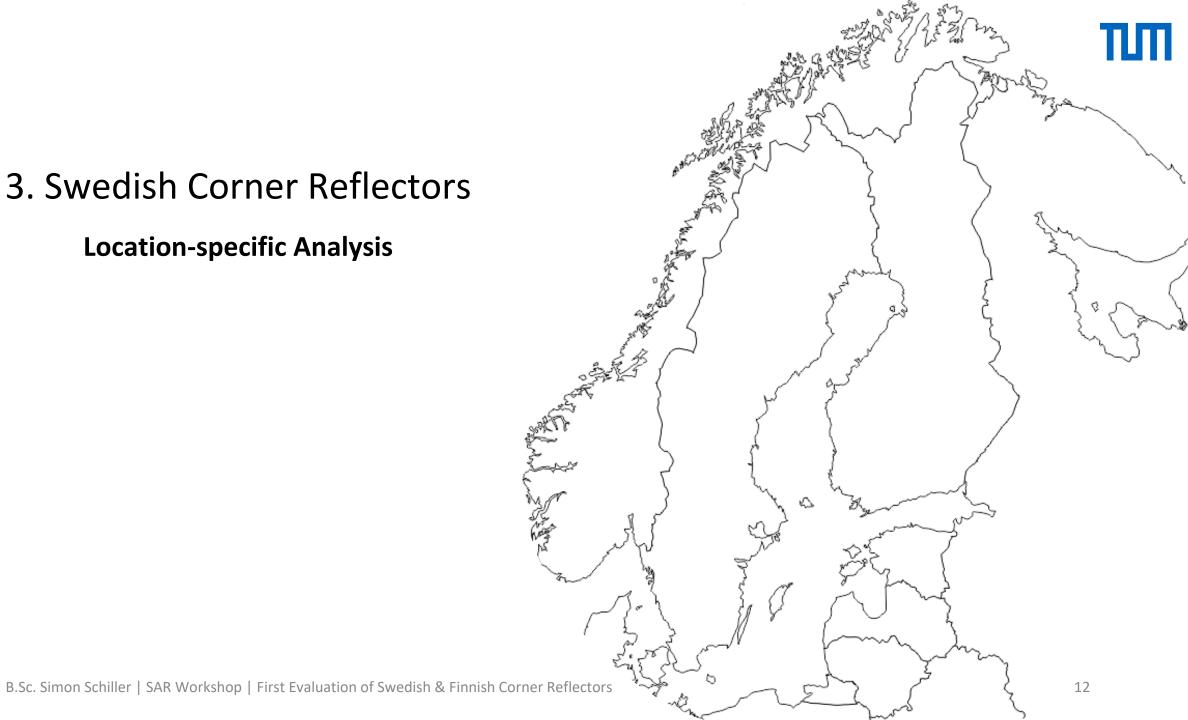
#### Range Observations: 53

#### Azimuth Observations: 51



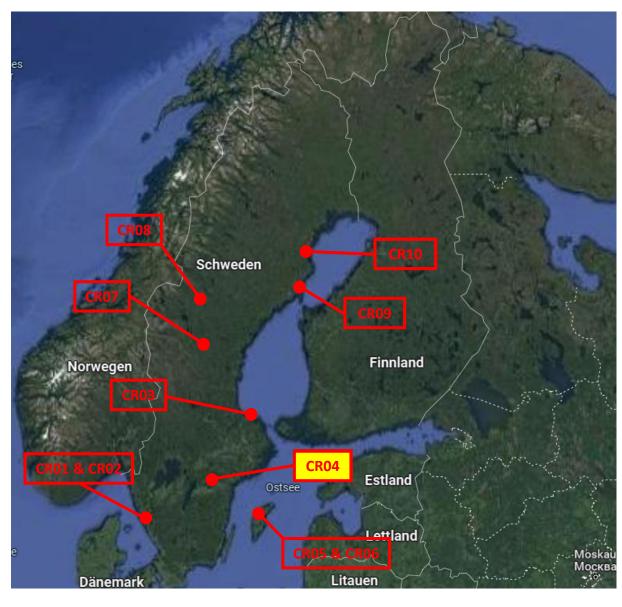
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### 3. Swedish Corner Reflectors



## ТЛП

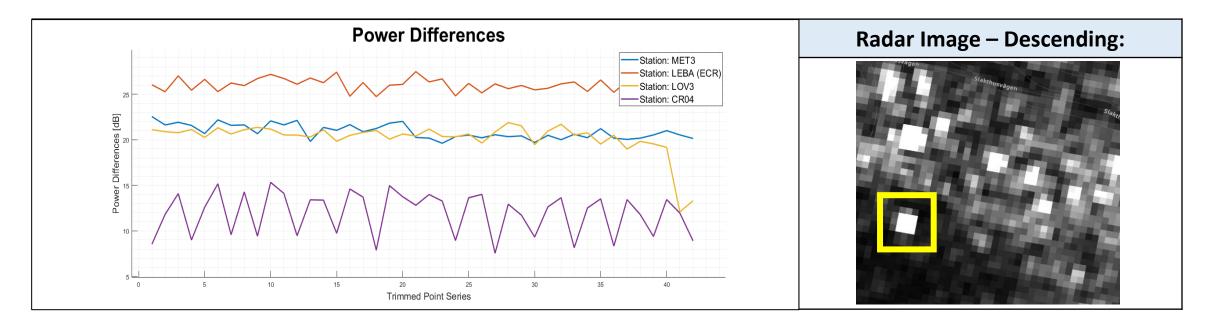
## 3. Swedish Corner Reflectors





### 3. Swedish Corner Reflectors

- 3.1 Location-specific Analysis CR04
- Location: Norrköping
- Corner Direction: Descending and Ascending (Double Back Flipped Square)
- Date of Installation: November 2021

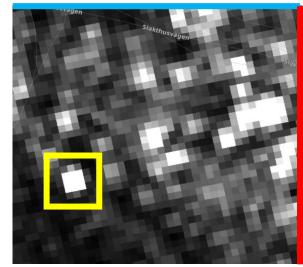




**3.2 Visualization of the Results – CR04** 

	Coordinates [m]	Standard Deviation [ $\pm$ m]
x	3199127.4033	0.0311
Y	932167.2413	0.0128
z	5420307.6903	0.0267

#### Range Observations: 125



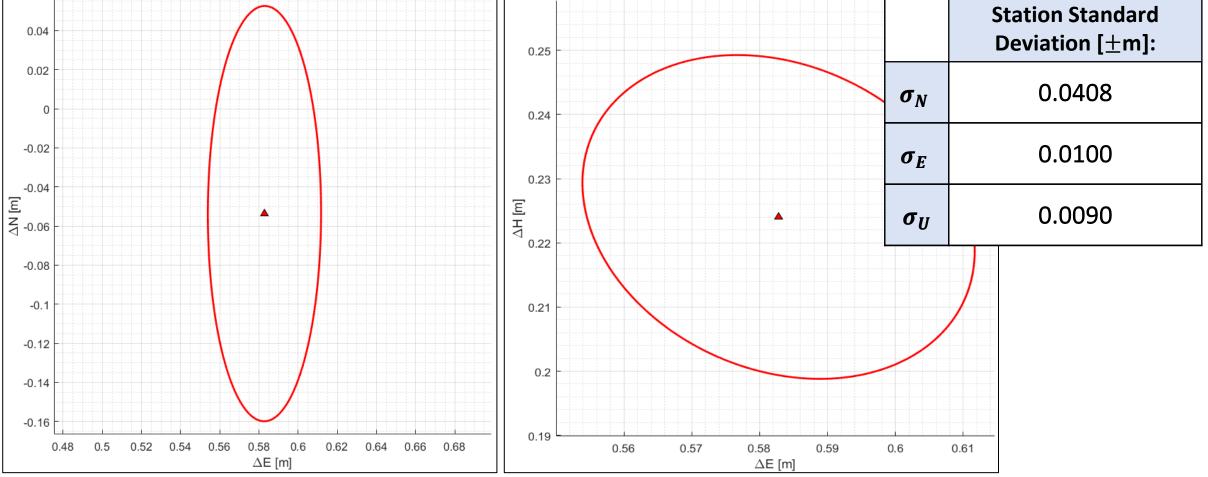
Azimuth Observations: 123



#### **3.2 Visualization of the Results – CR04**

Range Observations: 125

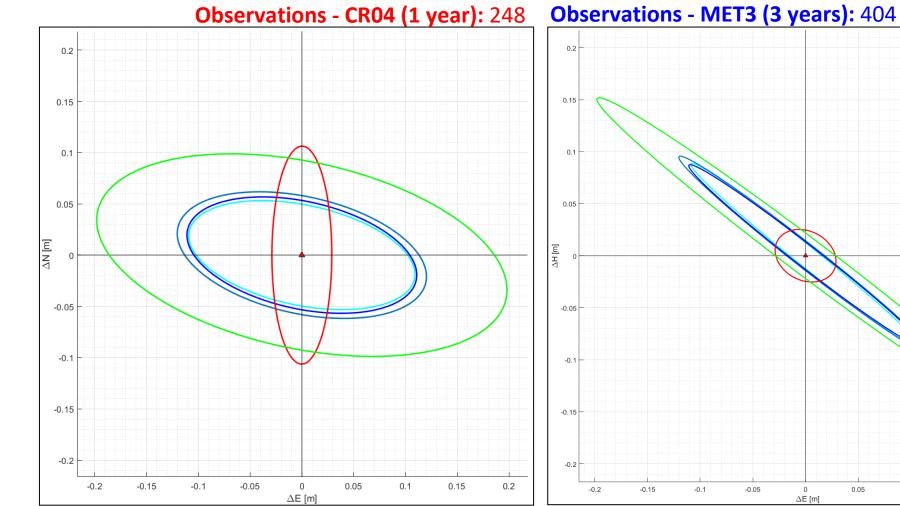




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# 4. Comparison

Observations - LOV3 (1 year): 104 Observations - CR04 (1 year): 248



Observations - MET3 (1 year): 164

Observations - MET3 (2 years): 312

0.1

0.15

0.2

# 5. Conclusion

#### > **Dependency of the signal response** on the used corner reflectors:

- Significant differences between passive and active reflectors
  Nevertheless in all examples: Strong and easily detectable reflection
  Influenced also by the type of passive reflectors
- > Achieving high precisions in the explored time intervals:
  - □ High precision of positioning results: 1-6 cm
  - □ Fluctuations and renewed instabilities detectable over multi-annual observations of MET3 station
- > Strong improvement of precision by using reflectors aligned on both sides:
  - Homogenization of error ellipses due to bilateral geometry (Directional behavior detectable in both DSC stations)
  - $\Box$  Increasing the number of observations in the same time  $\rightarrow$  Faster achievement of the required observations



## 6. Image Sources

#### - Cover Slide Scandinavia:

https://d-maps.com/m/europa/scandinavie/scandinavie06.gif (Last visited: 01.03.2023).

#### - Aerial View Images:

https://www.google.de/maps/preview (Last visited: 01.03.2023).

#### - Radar Images:

https://apps.sentinel-hub.com/sentinel-playground (Last visited: 01.03.2023).