



# Improved Intercalibration of Multimission Altimeter Significant Wave Heights for Climate Data Record

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The Sea State Climate Change Initiative	1991 1992 1993 1994 1995 1996 1997 1998 1999 2000 2001 2002 2003 2004 2005 2006 2007 2008 2009 2010 2011 2012 2013 2014 2015 20	16 2017 2018 2019 2020 2021 2022 2023 2024
sea state cci	ERS-1 (35-day / 98.5°)         TOPEX/Poseidon (9.91-day / 66°)         ERS-2 (35-day / 98.5°)	<ul> <li>Ku-band LRM</li> <li>Ku-band DD</li> <li>Ka-band LRM</li> </ul>
Consistent continuous long-term sea state observations are necessary to assess and measure climate variability and clarify underlying trends. The ESA Sea State Climate Change Initiative (CCI) aims at producing sea state	GFO (17-day / 108°)  GFO (17-day / 108°)  Jason-1 (9.91-day / 66°)  ENVISAT (35-day / 98.5°)  Jason-2 (9.91-day / 66°)	

climate data records by developing state-of-the-art data analysis methods and implementing them to historical global satellite data. To date, the most widely used satellite sensors to measure significant wave height (SWH) and spectral wave properties are radar altimeters and SAR imagers, respectively. A key requirement to produce a robust multi-sensor multi-mission product is the **intercalibration process**, which ensures that every mission provides measurements consistent with each other. In this poster, we present the method developed for calibrating the altimeter missions of the Sea State CCI product.

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Missions in operation									(	CRYO	SAT-2	(369-	day wit	:h 30-da	ay subc	ycle / 9	2°)						
												SA	ARAL (	35-day	/ 98.5°	)							
Historical missions available in CCI V1.1															Jaso	on-3 (9	).91-da	y / 66°)					
Reprocessed missions available in CCI V3	Ir	nterc	alib	rate	d m	niss	ions	s in	Se	a St	tate	CC	CI V.	3	Sentinel-3A (27-day / 98.6°)				İ				
Overlapping period with reference mission	ו																Se	entinel-C	3B (27	-day / 98.6	°)		
Missions to be included in future versions																		CFOS	AT (13	3 <mark>-day / 9</mark> 7.	5°)		
																				Sentinel-	6A (9.9	1 / 66°	
1991 1992 1993 1994 1995 1996 1997 1998 1999 2000	2001 20	002 2003	3 2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014	2015	2016	2017	2018	2019	2020	2021 20	)22 2	023 2	2024

Recent radar altimeter sensors use Delay-Doppler (DD) processing to increase along-track resolution. In the latest release of the Sea State CCI dataset (v3), 6 conventional and 1 DD altimeter mission have been reprocessed (+ Sentinel-1A&B SAR missions).

#### **Absolute calibration of Jason-2 mission**

Jason-2 SWH records are calibrated against in situ data to provide an absolute reference for calibrating all other missions. Only offshore (>100km from the coast) in situ buoys are used. Matchups between altimeter and in situ records are computed within 100-km distance and 1-h time window.





#### Calibration Look-Up Tables (LUT)

- Residuals between altimeter and in situ computed versus SWH (grey dots)
- Median and std of the residuals computed for every 20-cm bins, containing at least 100 values (blue error bars)
- Linear regression fitted through the median over the range 2.5-6 m (green line) • Correction LUT combines binned median values for SWH<2.5 m and linearly interpolated values for SWH>=2.5 m

# Key features of the Sea State CCI v3 dataset :

### Check it on :

- novel waveform retracking algorithms for conventional (WHALES) and SAR altimetry missions (LR-RMC)
- total SWH from S1A&B SAR missions using neural net. approach
- wave directions and wavelengths from ENVISAT, S1A&B (SAR) • consistent data editing and intercalibration across all missions
- EMD-based denoising of 1Hz along-track SWH

#### Inter-mission calibration at crossover

All missions are inter-calibrated against the corrected Jason-2 mission, using crossover measurements during overlapping time periods ( $\Delta X < 100$  km,  $\Delta T < 1$ -hr). Altimeter SWH are filtered using 50-km along-track average.



(magenta dots)

• 5-point moving average applied to the 0.05-m spaced LUT to reduce noise in the correction

## Validation against buoys

The methodology is validated by comparing uncalibrated and calibrated measurements against in situ data. Systematic and random error metrics show improvements in the calibrated data. In particular the bias is reduced from 0.09 m to 0.02 m on average.

Mission	<b>#values</b>	Bias (m)	Bias <sub>cal</sub> (m)	NRMSE (%)	NRMSE <sub>cal</sub> (%)	SI (%)	SI <sub>cal</sub> (%)	R <sup>2</sup>	R <sup>2</sup> cal
Jason-1	11433	0.05	-0.01	9.72	8.88	9.55	8.87	0.96	0.97
ENVISAT	14131	0.07	-0.01	9.17	8.48	8.8	8.47	0.97	0.97
Jason-2	17146	0.07	0	9.56	8.34	9.24	8.34	0.97	0.97
CRYOSAT-2	795	-0.09	0.02	8.2	7.23	7.29	7.18	0.97	0.97
SARAL	10909	0.24	0.02	12.37	7.98	8.35	7.94	0.97	0.97
Jason-3	7043	0.07	0.02	9.33	8.13	8.98	8.11	0.97	0.98
Sentinel-3A	12718	0.09	0.01	10.1	9.23	9.38	9.21	0.97	0.97
AVERAGE	10727	0.09	0.02	9.96	8.56	9.1	8.54	0.97	0.97





This figure shows the corrections (magenta dots) obtained for each mission and highlights the different behaviors of each sensor at low and high sea states. The non linear relationship between sensors, in particular at low sea states, clearly prevents from applying linear calibration.

#### Impact on trends

Linear trends of the winter (JFM) mean SWH are computed with the version 1 and version 3 of the Sea State CCI products, which use different processing techniques (waveform retracking, intercalibration). Differences between these products are mostly found in enclosed seas, where low sea states are more frequent and where LUT corrections differ the most from linear corrections. CCI v1 [JFM 2003-2019] CCI v3 [JFM 2003-2019]







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Information on the Sea State CCI project (publication, data, user consultation meetings...) can be found at : https://climate.esa.int/en/projects/sea-state/