

Quantum Process Tomography from Time-Delayed Measurements

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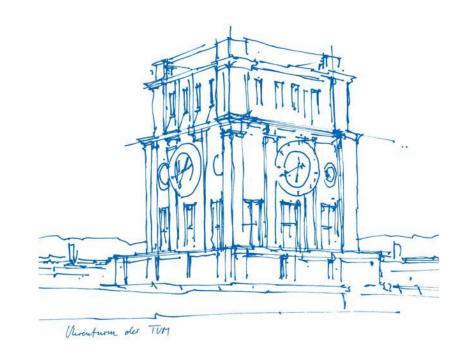
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Dr. Felix Dietrich



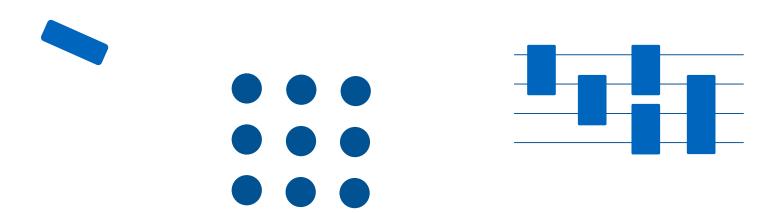
Prof. Christian Mendl





Quantum Process Tomography

Goal: Learn unitary (or Kraus operators) describing time evolution.





Mathematical Framework: Takens Theorem

Let \mathcal{M} be a *d*-dimensional manifold.

Commun. Math. Phys. 20, 167 (1971)

Generic delay embeddings: For pairs (ϕ, y) , $\phi: \mathcal{M} \to \mathcal{M}$ a smooth diffeomorphism and $y: \mathcal{M} \to \mathbb{R}$ a smooth function, it is a generic property that the map $\Phi_{(\phi, y)}: \mathcal{M} \to \mathbb{R}^{2d+1}$, defined by

$$\Phi_{(\phi,y)}(x) = \Big(y(x), y(\phi(x)), \dots, y(\phi \circ \phi \dots \circ \phi(x))\Big)$$

is an embedding of \mathcal{M} .

i.e. given 2d + 1 measurements throughout the time-evolution we can uniquely identify the process



Mathematical Framework: Applied to Quantum Unitaries

Generic delay embeddings: For pairs (ϕ, y) , $\phi: \mathcal{M} \to \mathcal{M}$ a smooth diffeomorphism and $y: \mathcal{M} \to \mathbb{R}$ a smooth function, it is a generic property that the map $\Phi_{(\phi, y)}: \mathcal{M} \to \mathbb{R}^{2d+1}$, defined by

$$\Phi_{(\phi,y)}(x) = \Big(y(x), y(\phi(x)), \dots, y(\phi \circ \phi \dots \circ \phi(x))\Big)$$

is an embedding of M.

$$x = U = e^{-iH}$$

$$\phi(U) = e^{-i\gamma H} = U^{\gamma}$$

$$y(U) = \langle \psi | U^{\dagger} A U | \psi \rangle$$

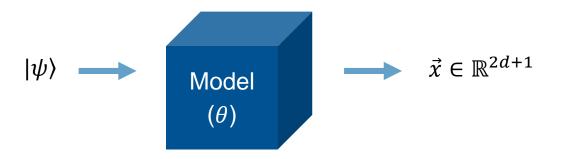
$$\Phi_{(\phi,y)}(\psi) = \left(\left\langle \psi \middle| U^{\dagger} A U \middle| \psi \right\rangle, \cdots, \left\langle \psi \middle| \left(U^{\gamma^{(2d+1)}} \right)^{\dagger} A U^{\gamma^{(2d+1)}} \middle| \psi \right\rangle \right)$$

Here, d is the number of free parameters in U



Numerical Approach: general idea

Choose Ansatz to represent Φ

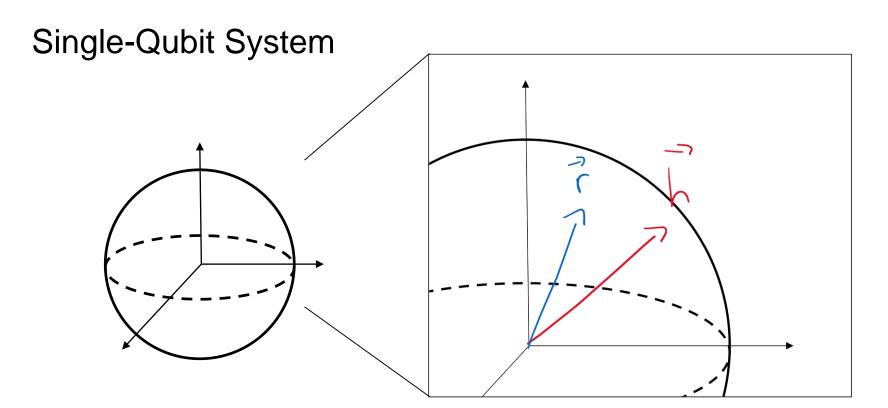


Optimize by:

 $\arg\min_{\theta} C(\vec{y}, \vec{x}(\theta))$

e.g.
$$\|\vec{y} - \vec{x}(\theta)\|^2$$







Single-Qubit System

- Rewrite Hamiltonian vector: $\vec{h} = \frac{1}{2}\omega\vec{v}$
- Evolution described by Rodrigues' rotation formula:

$$U_{\omega,t,\vec{v}}\vec{r} = \cos(\omega t)\vec{r} + \sin(\omega t)(\vec{v} \times \vec{r}) + (1 - \cos(\omega t))(\vec{v} \cdot \vec{r}) \cdot \vec{v}$$

• Measurements are: $y_t = \langle \overrightarrow{m}, U_{\omega,t,\overrightarrow{v}} \overrightarrow{r} \rangle$

First find ω

$$\operatorname{argmin}_{\omega} \min_{a,b,c} \sum_{n=0}^{2d} |y_n - a\cos(\omega t_n - b) - c|^2$$



Single-Qubit System

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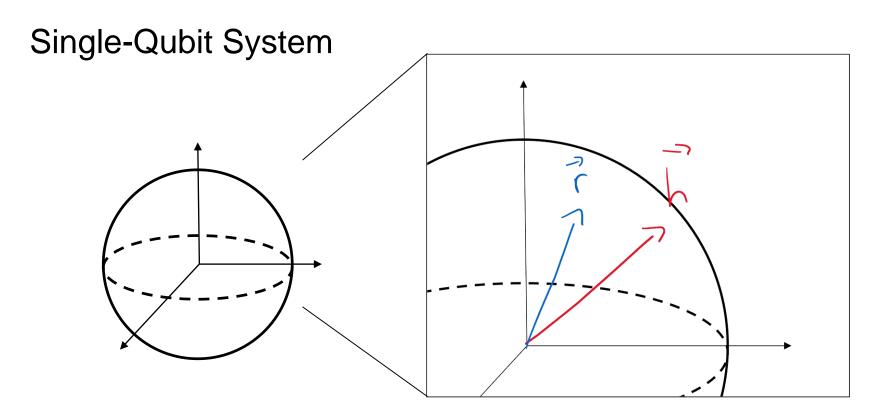
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• Measurements are: $y_t = \langle \overrightarrow{m}, U_{\omega,t,\overrightarrow{v}} \overrightarrow{r} \rangle$

Next find
$$\alpha = \vec{m} \cdot (\vec{v} \times \vec{r})$$
 and $\kappa = (\vec{v} \cdot \vec{r}) \cdot (\vec{m} \cdot \vec{v})$

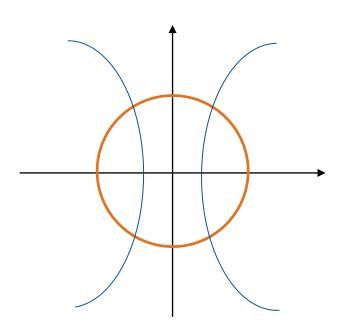
$$\arg\min_{\alpha,\kappa} \sum_{n=0}^{2d} |\tilde{y}_n - \sin(\omega t_n)\alpha - (1 - \cos(\omega t_n))\kappa|^2$$







Single-Qubit System



- 4 solutions
- Optimization let's us find one of them
- Then, decide between 4 with one extra measurement in different basis



Single-Qubit System with Noise

Recall: $y(U) = \langle \psi | U^{\dagger} A U | \psi \rangle$

Not fully known?

Noisy measurement?



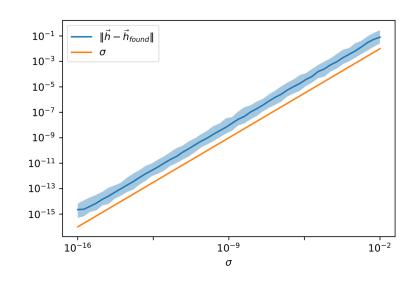
Single-Qubit System with Noise

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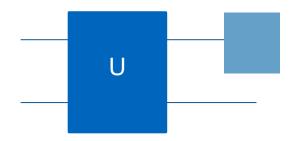
Model as: $y(U) = \langle \psi | U^{\dagger} A U | \psi \rangle + \mathcal{N}(0, \sigma^2)$

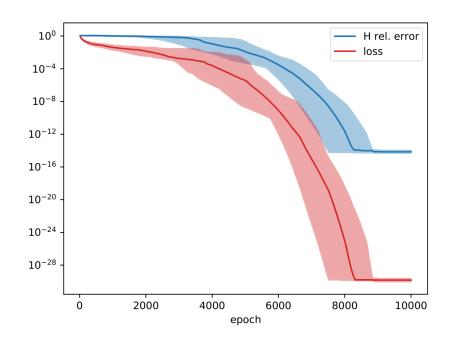




Partial (subsystem) measurements

- No restrictions on measurement
- We can choose: $I \otimes \sigma^j$

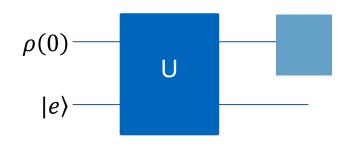






Partial (subsystem) measurements

- No restrictions on measurement
- We can choose: $I \otimes \sigma^j$



Can model a noisy process on a single qubit

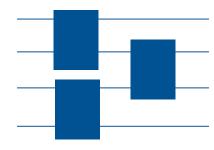
$$\rho(t) = \sum_{k} E_k \ \rho(0) E_k^{\dagger}$$

$$\rho(t) = \operatorname{tr}_{\text{env}} (U(\rho(0) \otimes |e\rangle\langle e|) U^{\dagger})$$



Partial Knowledge of Hamiltonian

- E.g. local interactions
- Model can use less parameters
- And therefore we need less time points

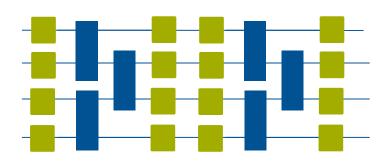


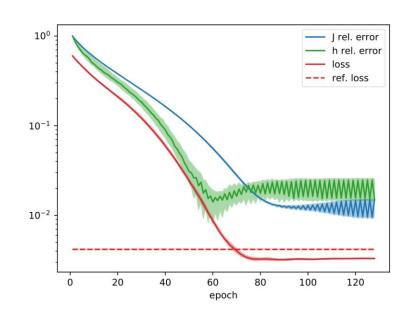


Partial Knowledge of Hamiltonian

Uniform interaction (3 \times 4 lattice)

$$H = -J \sum_{\langle j,k \rangle} \sigma_j^z \sigma_k^z - \sum_j \vec{h} \cdot \vec{\sigma}_j$$







Summary

- Takens' theorem provides a mathematical framework for the reconstruction
- Number of expectation values needed: 2d + 1 (where d is the number of free parameters in U)
- Limited to one or two-qubit systems or systems with some underlying structure
- One must be careful with symmetries

Future work

 Experimental tests in collaboration with Robert Stárek and Michal Micuda from Department of Optics, Palacký University Olomouc (Chzech Republic)