

Towards geometric multi-scale coupling in preCICE

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Pictures by GRS, available on http://grs.de/. OpenFOAM logo of OpenCFD, www.openfoam.com. G. Chourdakis | Towards geometric multi-scale coupling in preCICE | YIC 2021















Geometric multi-scale coupling





Geometric multi-scale coupling



Mapping types:

- axial -vs- radial
- collect -vs- spread



Geometric multi-scale coupling



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Research questions:

- How to generate missing information? (e.g. velocity components)
- How to reduce information?
- How to convert information? (e.g. velocity vs mass flux)
- How to implement this in a general way in preCICE?
 → What are common use cases?

G. Chourdakis, B. Uekermann, G. van Zwieten, H. van Brummelen (2019). Coupling OpenFOAM to different solvers, physics, models, and dimensions using preCICE. 14th OpenFOAM Workshop, Duisburg.



Prototype: water hammer (1D-3D fluid-fluid coupling)



1D single-phase flow in a pipe, opening-closing valve, axial mapping



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Proof-of-concept:

feasibility, workbench for developing methods.
OpenFOAM + Nutils (www.nutils.org, Python),
mapping directly in preCICE



Prototype: nuclear reactor cooling (1D-3D FF, CHT)



1D two-phase flow in pipes

- + 3D flow in critical regions \rightarrow axial 1D-3D mapping
- + 3D heat transfer in solids \rightarrow radial 1D-3D mapping

Long-term goal:

replace several existing coupling systems with a sustainable approach.

J. Herb (2014). *Coupling OpenFOAM with thermo-hydraulic simulation code ATHLET*. 9th OpenFOAM Workshop, Zagreb.



Prototype: tsunami near coast (2D-3D FF)



2D-3D two-phase flow

- 2D flow in large regions, shallow-water equations
- 3D flow in critical regions, Navier-Stokes equations

 \rightarrow axial 2D-3D mapping



Idea:

the same approach should work for more than 1D-3D (see also 2D-3D in fractures, 5D-6D in plasma fusion)

F.J. Espinosa Pelaez (2020). A flexible approach to 2D-3D coupling of a Shallow-Water Equation solver to OpenFOAM. Master's Thesis. Technical University of Munich.



Prototype: helicopter blades (1D-3D FSI)





1D-3D FSI

- 1D helicopter blade shape (CAMRAD II)
- 3D flow around the blade (DLR TAU)
- \rightarrow radial 1D-3D mapping



Q. Huang, A. Abdelmoula, G. Chourdakis, J. Rauleder, B. Uekermann (2021). *CFD/CSD Coupling for an Isolated Rotor using preCICE*. Proceedings of the ECCOMAS WCCM 2020.



People

Core team:

- Technical University of Munich, SCCS (since < 2008)
 - Gerasimos Chourdakis \rightarrow this talk
 - Benjamin Rüth
 - Frédéric Simonis
- University of Stuttgart, SGS (since 2013)
 - Miriam Schulte (head)
 - $-\,$ Kyle Davis \rightarrow see talk here at 18:30 $\,$
 - Amin Totounferoush
- University of Stuttgart, US3 (since 2021)
 - Benjamin Uekermann (head)
 - Ishaan Desai
 - David Schneider
- + student assistants
- + external contributors on GitHub
- + alumni







Funding preCICE



Summary

Ongoing work: Currently prototypes for fluid-fluid coupling (1D-3D, 2D-3D) and FSI Challenges: How to generate / reduce / convert information Goal: General implementation in preCICE Contact me: I am looking for use cases for geometric multiscale coupling gerasimos.chourdakis@tum.de

- 🥹 precice.org
- github.com/precice
- ♥ @preCICE_org
- precice.discourse.group
 gitter.im/precice

Give me feedback:



go.tum.de/820189



See also poster: Gerasimos Chourdakis, Qunsheng Huang, Francisco Javier Espinosa Pelaez, Fabian Weyermann, Benjamin Uekermann: *Geometric multi-scale coupling prototypes with preCICE*. SIAM CSE21, SIAM, 2021