



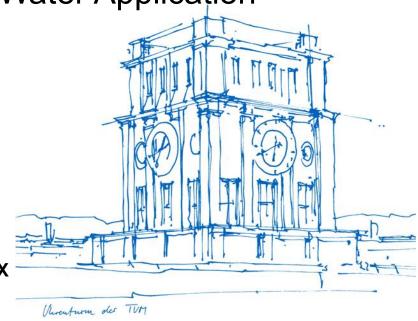
A UPC++ Actor Library and its Evaluation on a Shallow Water Application

Alexander Pöppl¹, Scott Baden², Michael Bader¹

¹Department of Informatics Technical University of Munich

²Computational Research Division Lawrence Berkeley National Laboratory Department of Computer Science and Engineering University of California, San Diego

Parallel Applications Workshop, Alternatives To MPI+X November 18th 2019 Denver, Colorado



Motivation



Invasive Computing:

- Dynamic resource allocation
- Predictability through exclusive resource usage
- Heterogeneous compute tiles

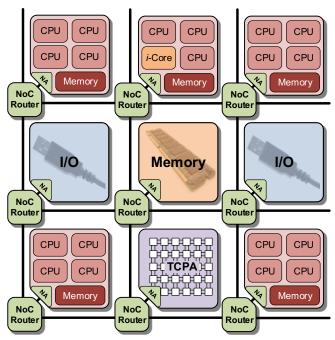
Actor-based Modelling

- Good fit for architecture, enables exploration of different mappings of actors to compute tiles
- SWE-X10 as sample application

Transfer to larger-scale applications

Is it feasible to program an actor library using standard languages and frameworks? If so, how does performance compare, both to our X10-based library, and BSP?

✓ Tools: C++, OpenMP, UPC++



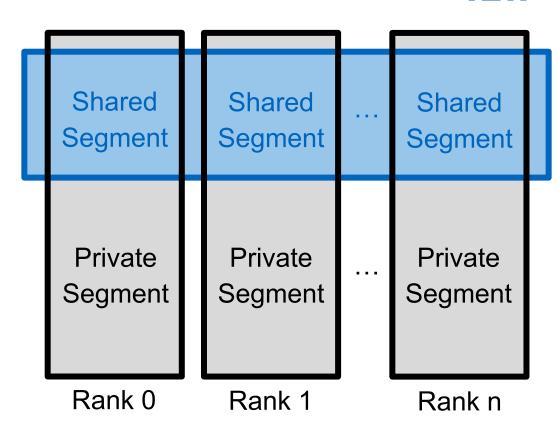


Asynchronous Partitioned Global Address Space (APGAS) Model

Reliance on one-sided communication

Asynchronous, continuation-based API

Based on GASNet-EX, makes direct use of InfiniBand and (some) Cray interconnects

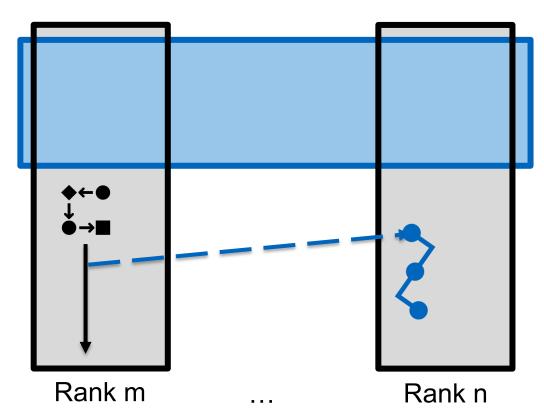


Adapted from: UPC++ Specification v1.0 Draft 10, available at https://upcxx.lbl.gov



RPCs

- Executed asynchronously
- Serialization and transfer of parameters, return value
- Completion events available after the local part (or overall RPC execution) is finished



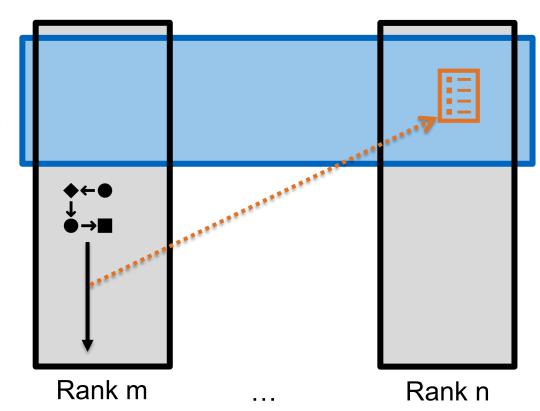


RPCs

- Executed asynchronously
- Serialization and transfer of parameters, return value
- Completion events available after the local part (or overall RPC execution) is finished

Global Pointers

- Point to data in Shared segment
- May be used as target for RMA operations





RPCs

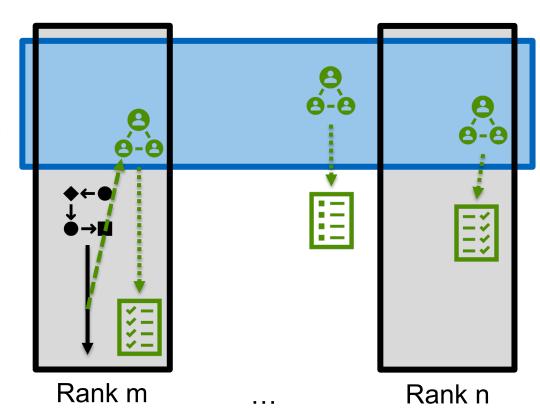
- Executed asynchronously
- Serialization and transfer of parameters, return value
- Completion events available after the local part (or overall RPC execution) is finished

Global Pointers

- Point to data in Shared segment
- May be used as target for RMA operations

Distributed Objects

- Created collectively
- Same handle points to different objects on each rank



UPC++ Actor Library

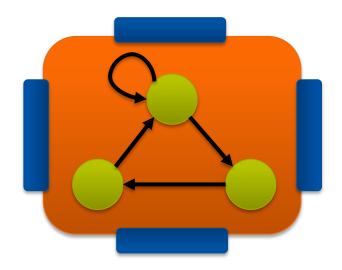


Actors

- Encapsulate specific functionality, data and behavior
- Behavior defined through finite state machines
- No data sharing between actors
- Defined communication endpoints (Ports)
- Have the ability compute whenever data in their ports (InPorts or OutPorts) changes
 - > Actors are being triggered

Application Developers...

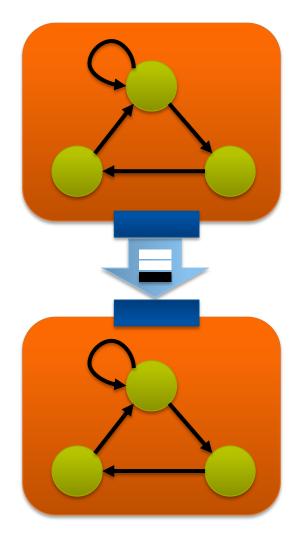
- ...subclass and implement act() method (actor FSM)
- ...use ports as communication endpoints
- ...specify which ports are connected



UPC++ Actor Library

Channels

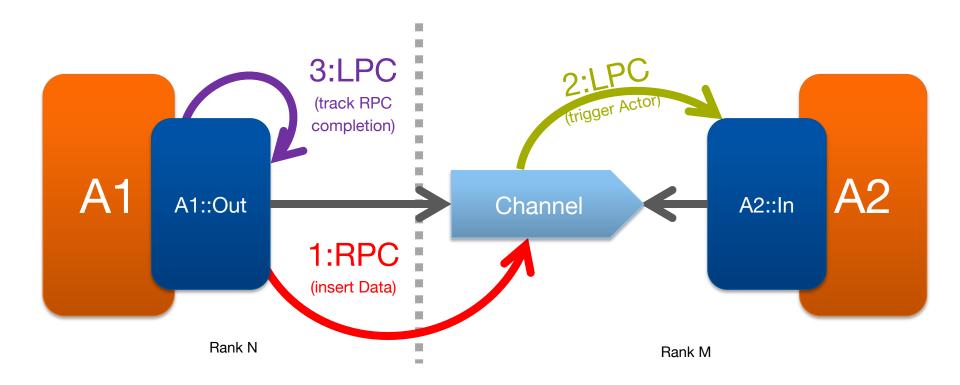
- Unidirectional connection between two ports
- FiFo semantics
- Operations: read(), write(T), peek()
- Guards: available(), freeCapacity()





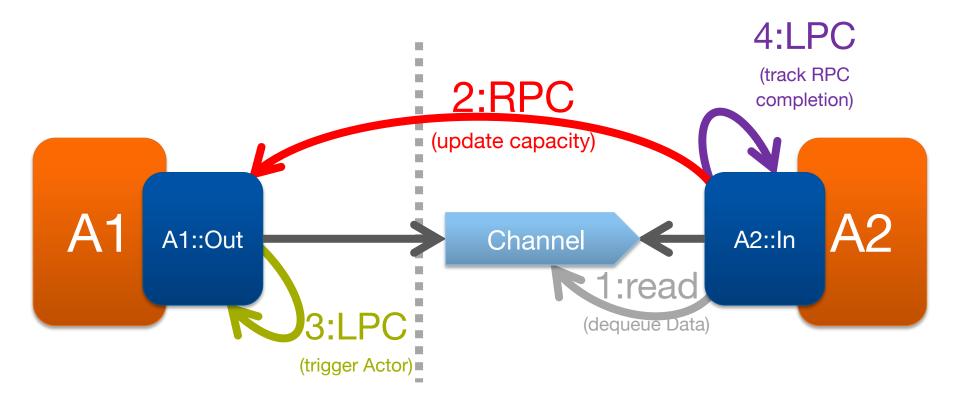
UPC++ Actor Library – Write





UPC++ Actor Library – Read





UPC++ Actor Library – Actor Execution Strategies



Rank-based Execution Strategy

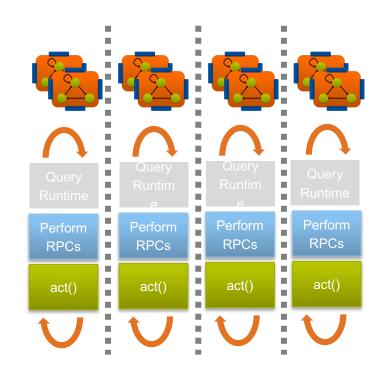
One thread per UPC++ rank, one rank per (logical) core

One event loop:

- Query runtime for progress
- Execute RPCs, mark affected actors
- Execute act() on affected actors

May use sequential UPC++ code mode

Low number of actors per rank



UPC++ Actor Library – Actor Execution Strategies



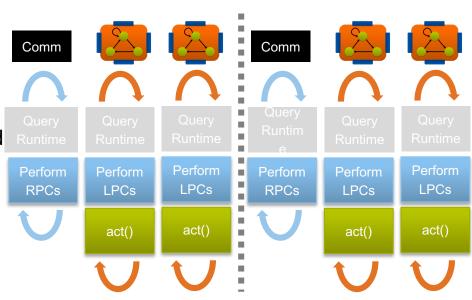
Thread-based Execution Strategy

One thread per actor, and one communication thread, low number of ranks per node

Two event loops:

- Communication thread queries runtime and executes RPCs
- Actor threads query runtime for progress and execute LPCs, execute act

Requires balancing of communication thread against number of actors



UPC++ Actor Library – Actor Execution Strategies



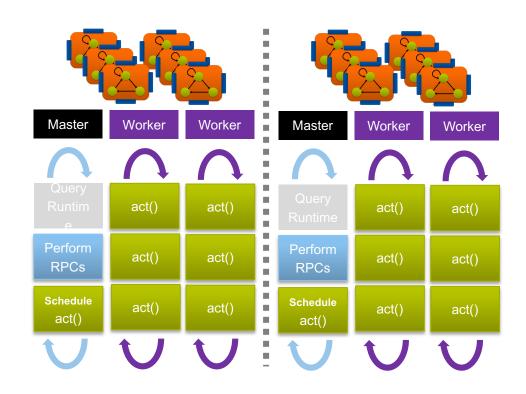
Task-based Execution Strategy

Map act() executions on OpenMP tasks

One event loop:

- Master thread queries Runtime
- Performs any incoming RPCs and triggers affected actors
- Schedules OpenMP task for each invocation of act. Dependencies between act invocations of same actor

Large number of actors per rank possible





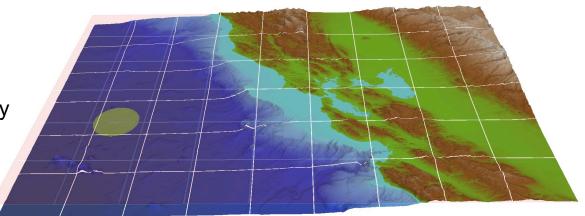
Based on prior applications

 SWE, a BSP-based code written using MPI and OpenMP

SWE-X10, an actor-based X10 application written using the actorX10 library

Parallelized using our actor library

Possible to auto-vectorize with AVX512 with Intel Compiler (v18.0)



http://www5.in.tum.de/wiki/index.php/Tsunami Simulation - Winter 15



$$\begin{bmatrix} h \\ hu \\ hv \end{bmatrix}_{t} + \begin{bmatrix} hu \\ hu^{2} + \frac{1}{2}gh^{2} \\ huv \end{bmatrix}_{x} + \begin{bmatrix} hv \\ huv \\ hv^{2} + \frac{1}{2}gh^{2} \end{bmatrix}_{y} = S(t, x, y)$$

$$hu(x, t)$$

$$b \ge 0$$

$$hu(x, t)$$

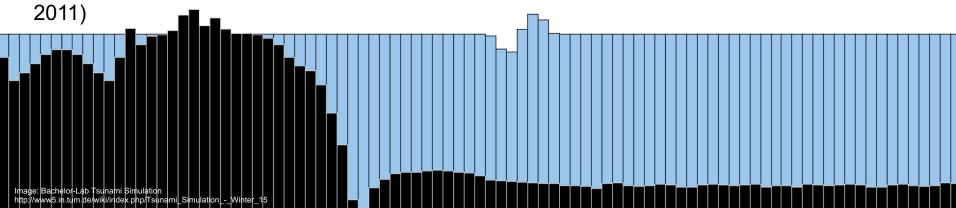


Finite volume scheme on a Cartesian grid with piecewise constant unknown quantities and Euler time step

$$Q_{i,j}^{n+1} = Q_{i,j}^{n} - \frac{\Delta t}{\Delta x} \left(\mathcal{A}^{+} \Delta Q_{i-\frac{1}{2},j} + \mathcal{A}^{-} \Delta Q_{i+\frac{1}{2},j}^{n} \right) - \frac{\Delta t}{\Delta y} \left(\mathcal{B}^{+} \Delta Q_{i,j-\frac{1}{2}} + \mathcal{B}^{-} \Delta Q_{i,j+\frac{1}{2}}^{n} \right)$$

Numerical approach based on LeVeque (R. J. LeVeque, D. L. George, and M. J. Berger.

Tsunami modelling with adaptively refined finite volume methods. Acta Numerica, 20:211–289,



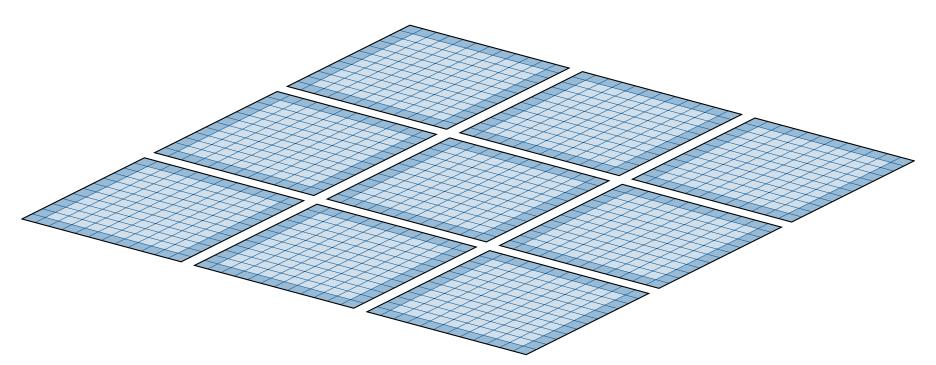


Finite volume scheme on a Cartesian grid with piecewise constant unknown quantities and Euler time step

$$Q_{i,j}^{n+1} = Q_{i,j}^n - \frac{\Delta t}{\Delta x} \left(\mathcal{A}^+ \Delta Q_{i-\frac{1}{2},j} + \mathcal{A}^- \Delta Q_{i+\frac{1}{2},j}^n \right)$$
$$- \frac{\Delta t}{\Delta y} \left(\mathcal{B}^+ \Delta Q_{i,j-\frac{1}{2}} + \mathcal{B}^- \Delta Q_{i,j+\frac{1}{2}}^n \right)$$



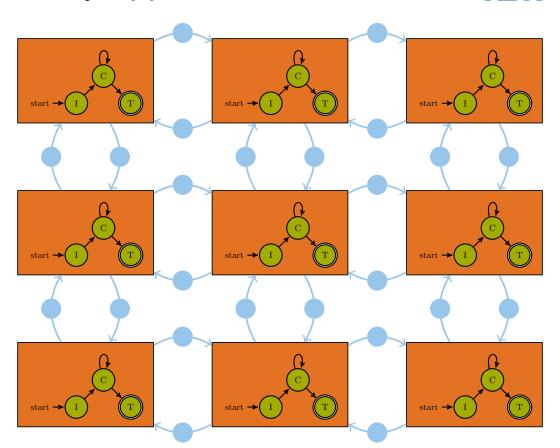
Subdivision into rectangular, equally-sized patches with Halo regions





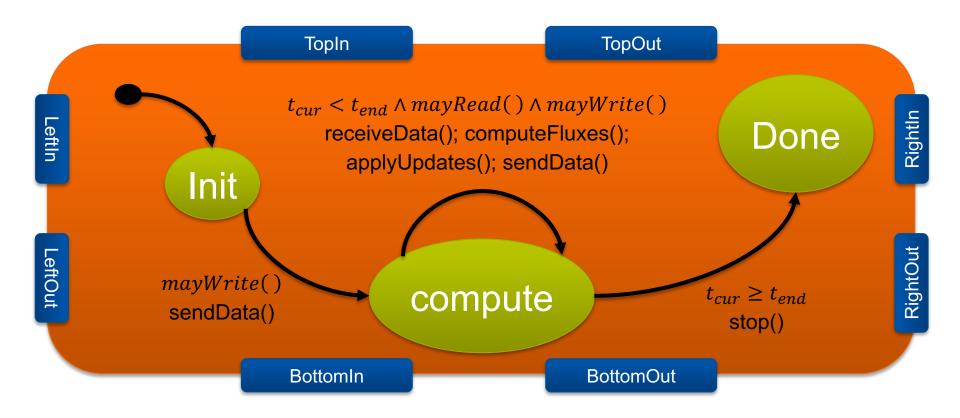
One actor per patch

Actors connected with direct neighbors



Pond – Simulation Actor





Evaluation



Performed on NERSC Cori

- Single socket Intel Xeon Phi (Knights Landing) nodes
- 68 cores (272 hyperthreads) per node
- 16GB MCDRAM
- 6TFlop/s (SP)
- Intel Compiler 18, Vectorization using AVX512

Comparison of

- SWE-X10, prior X10 application, based on actorX10, an X10 actor library
- SWE, prior MPI+OpenMP application, follows the BSP model
- Pond using our actor library (using the three available execution strategies, Rank, Thread and Task)

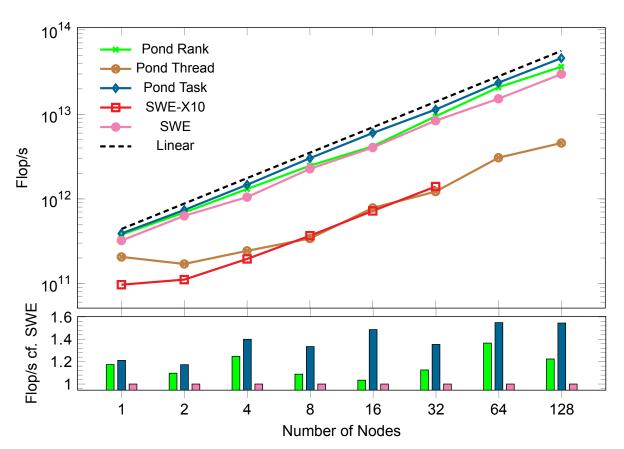
All subjects follow same numerical approach, same Riemann solver used in all cases

Evaluation – Weak Scaling



Radial Dam Break Scenario

4096² grid cells per node



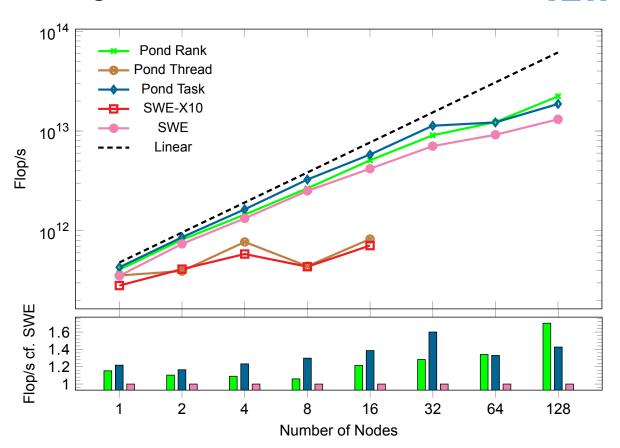
Evaluation – Weak Scaling



Radial Dam Break Scenario

16384² grid cells per node

Patch sizes from 512x512 down to 64x64 grid cells



Conclusion



Competitive with OpenMP and MPI

UPC++ enables overlap of communication and computation

Higher abstraction level for application programmer

Flexibility regarding backend

Questions + Acknowledgements



- This research was funded by the German Research Foundation (DFG, Deutsche Forschungsgemeinschaft) - Project number 14671743 - TRR 89 Invasive Computing.
- This research was supported by the Exascale Computing Project (17-SC- 20-SC), a collaborative effort of the U.S. Department of Energy Office of Science and the National Nuclear Security Administration.
- This research used resources of the National Energy Research Scientific Computing Center, a DOE Office of Science User Facility supported by the Office of Science of the U.S. Department of Energy under Contract No. DE- AC02-05CH11231.
- Scott Baden was supported in part by the Exascale Computing Project (17-SC-20-SC), a collaborative effort of the U.S. Department of Energy Office of Science and the National Nuclear Security Administration.

UPC++ Tutorial at LBL

- December 16th
- At NERSC or Online



More Info at:

https://www.exascaleproject.org/event/upcpp
https://upcxx.lbl.gov ► News

