



## Outline



**Cyber Physical Production systems / Industry 4.0- challenges in research and industrial application)**

1. **CPPS and Industrie 4.0 in Germany**
2. Agent technology to enable CPPS
3. Myjoghurt
  - Production changes due to malfunctions
  - New products
  - Maintenance support
4. xPick & Place unit plus COCOME an open I 4.0 demonstrator (PP 1593)
5. Metrics for CPPS and Industrie 4.0
6. Open Research issues

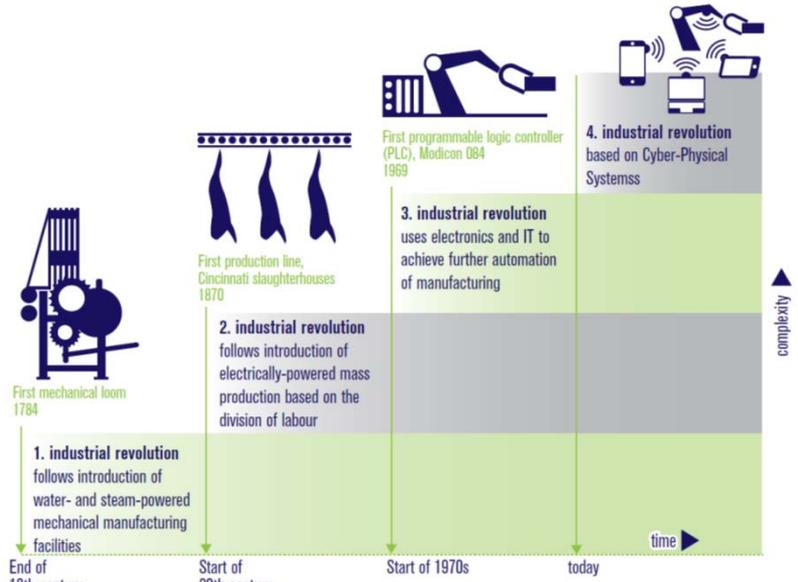
**Univ.-Prof. Dr.-Ing. Birgit Vogel-Heuser**  
 Full professor and head of Chair Automation and Information systems (AIS)  
 Faculty of mechanical engineering, Technische Universität München  
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## Four stages of industrial revolution



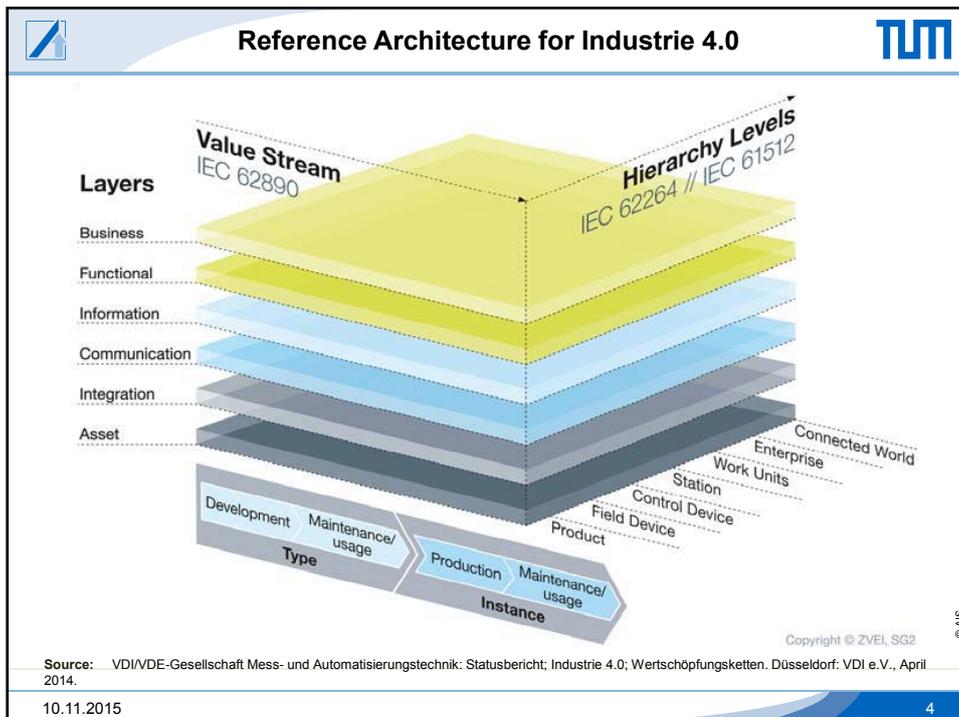
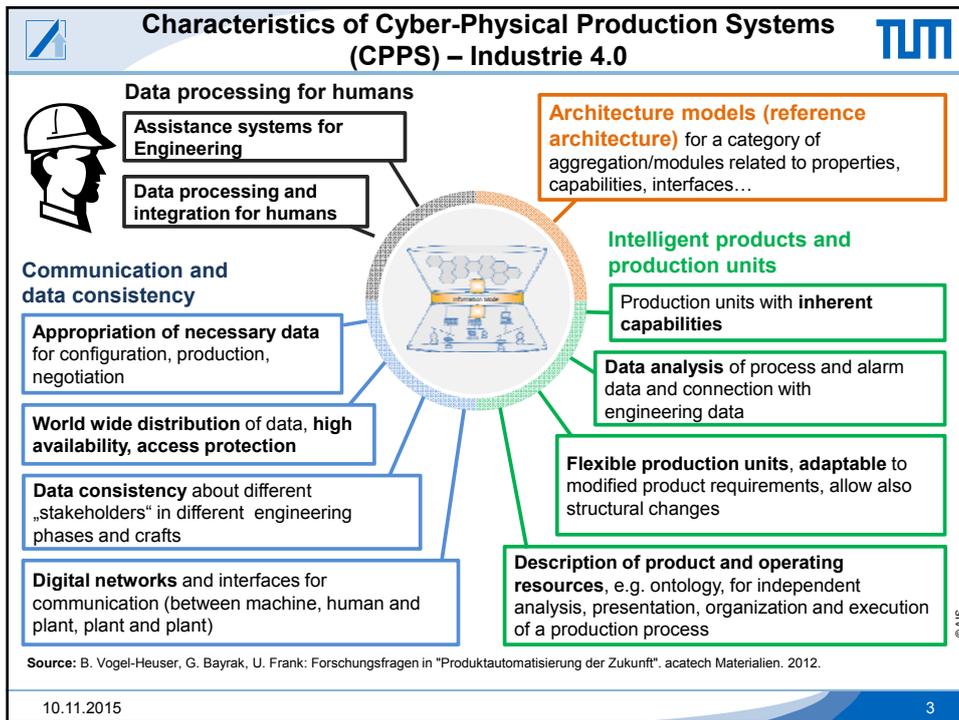


The diagram illustrates the four stages of industrial revolution, showing increasing complexity over time. The stages are represented by a grid with a vertical axis for 'complexity' and a horizontal axis for 'time'.

Stage	Time Period	Key Event	Description
1. industrial revolution	End of 18th century	First mechanical loom 1784	follows introduction of water- and steam-powered mechanical manufacturing facilities
2. industrial revolution	Start of 20th century	First production line, Cincinnati slaughterhouses 1870	follows introduction of electrically-powered mass production based on the division of labour
3. industrial revolution	Start of 1970s	First programmable logic controller (PLC), Modicon 084 1969	uses electronics and IT to achieve further automation of manufacturing
4. industrial revolution	today		based on Cyber-Physical Systems

Source: DFKI 2011

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Outline

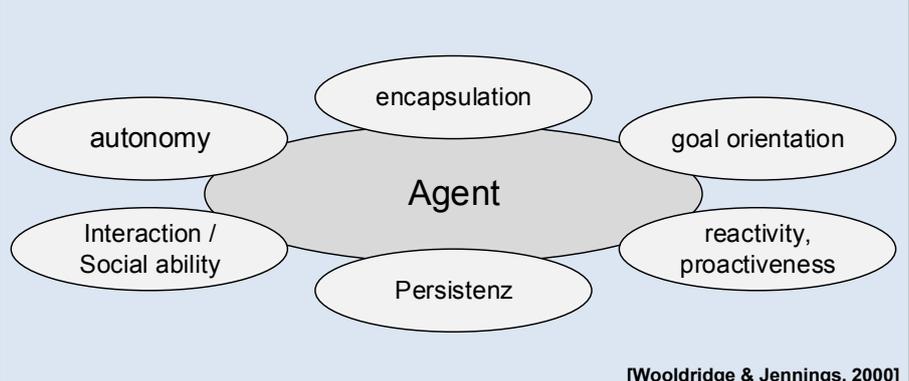

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Properties of software agents

[Wooldridge & Jennings, 2000]

A **technical agent** is an **encapsulated** (hardware/software) entity with **specified objectives**. An agent endeavors to reach these objectives through its **autonomous behavior**, in **interacting** with its **environment** and with **other agents**.

Source: VDI-Standard 2653 Sheet 1, 2010

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## Technical Constraints of the Automation System

- Real-time requirements of aPS → hard real-time for the platform (PLC)
- Cyclic behavior of the platform (1µs – 1s)
- Classical PLC as well as Soft-PLC (PC-based) programmed in IEC 61131-3 Languages
- Increasing amount of IPC and C, C-derivatives
- Online change is mandatory**

### IEC 61131-3 Languages

<p><i>Sequential Function Chart</i></p>	<p><i>Ladder Diagram</i></p> <p><i>Structured Text</i></p> <pre>OUT = (Var1 &amp; Var2 &amp; Var3) OR (Var4 &amp; Var5)</pre>	<p><i>Function Block Diagram</i></p> <p><i>Instruction List</i></p> <pre>LDN Var1 ANDN Var2 ANDN Var3 ST OUT</pre>
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### IEC 61131-3 Programming Languages

- Proprietary programming languages: Structured Text (ST), Ladder Diagram (LD), Instruction List (IL), Sequential Function Chart (SFC), Function Block Diagram (FBD)
- Upcoming: C**

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## Fields of application

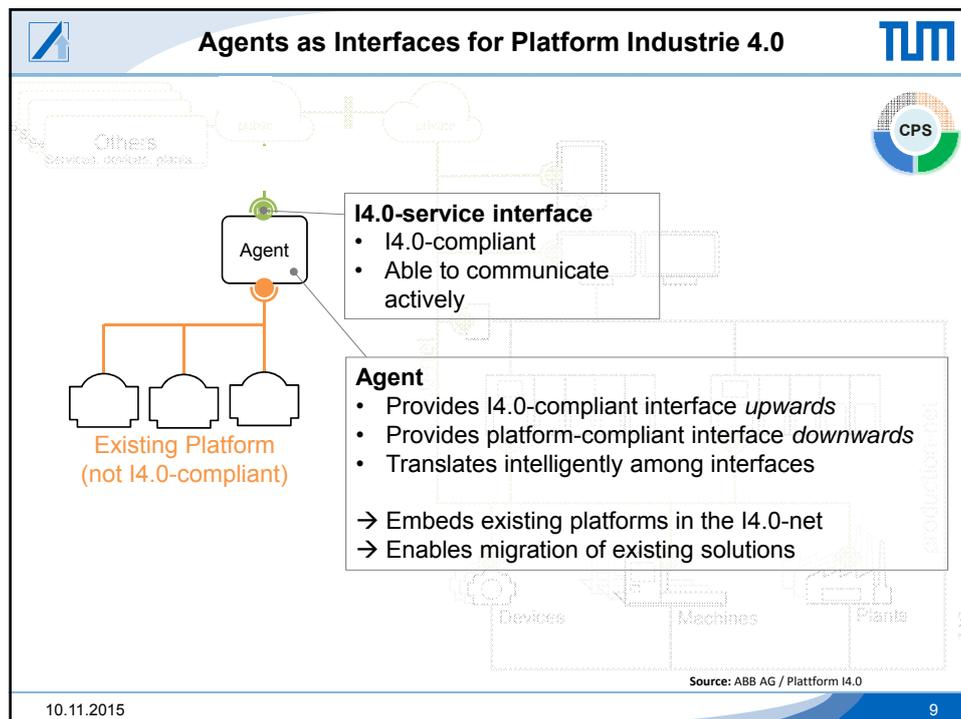
Increasing realtime requirements

Increasing amount of data

<p style="text-align: center;"><b>Extended Enterprise</b></p> <p>Reaction time: 8 hours &lt; x &lt; 1 week</p> <p>Synchronized frequency: 1 hour &lt; x &lt; 1 day</p> <p>Any agent systems are applicable</p> <p>Programming languages: C++, C#, Java, ...</p>
<p style="text-align: center;"><b>Merchandise management system</b></p> <p>Reaction time: 1 hour &lt; x &lt; 1 day</p> <p>Synchronized frequency: 60 seconds &lt; x &lt; 1 day</p> <p>Any agent systems are applicable</p> <p>Programming languages: C++, C#, Java, ...</p>
<p style="text-align: center;"><b>Production planning and controlling systems</b></p> <p>Reaction time: 1s &lt; x &lt; 60s</p> <p>Synchronized frequency: 1s &lt; x &lt; 60s</p> <p>Need for multi-agent systems</p> <p>IEC 61131, C++, C#, Java</p>
<p style="text-align: center;"><b>Field control system</b></p> <p style="text-align: center;">Control of the production processes</p> <p>Reaction time: 10ms &lt; x &lt; 1s</p> <p>Synchronized frequency: 100 µs &lt; x &lt; 100ms</p> <p>Realtime Agents on RT-Java</p> <p>Mostly IEC 61131 and C</p>
<p style="text-align: center;"><b>Field control system</b></p> <p style="text-align: center;">Control of the machine physics</p> <p>Reaction time: partly &lt; 1ms</p> <p>Synchronized frequency: partly &lt; 1µs</p> <p>Need for multi-agent systems</p>

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### Characteristics of Cyber-Physical Production Systems (CPPS) – Industrie 4.0



**Data processing for humans**

- Assistance systems for Engineering
- Data processing and integration for humans

**Communication and data consistency**

- Appropriation of necessary data for configuration, production, negotiation
- World wide distribution of data, high availability, access protection
- Data consistency about different „stakeholders“ in different engineering phases and crafts
- Digital networks and interfaces for communication (between machine, human and plant, plant and plant)

**Architecture models (reference architecture)** for a category of aggregation/modules related to properties, capabilities, interfaces...

**Intelligent products and production units**

- Production units with inherent capabilities
- Data analysis of process and alarm data and connection with engineering data
- Flexible production units, adaptable to modified product requirements, allow also structural changes
- Description of product and operating resources, e.g. ontology, for independent analysis, presentation, organization and execution of a production process

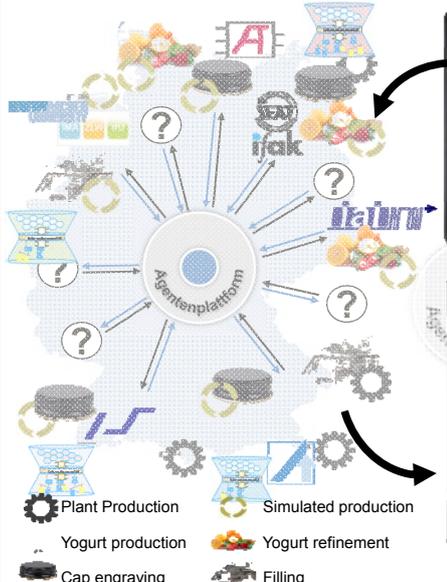
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Source: B. Vogel-Heuser, G. Bayrak, U. Frank: Forschungsfragen in "Produktautomatisierung der Zukunft", acatech Materialien, 2012.

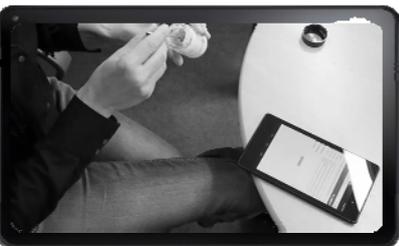
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### Intelligent networked production systems – myJogurt how it all began





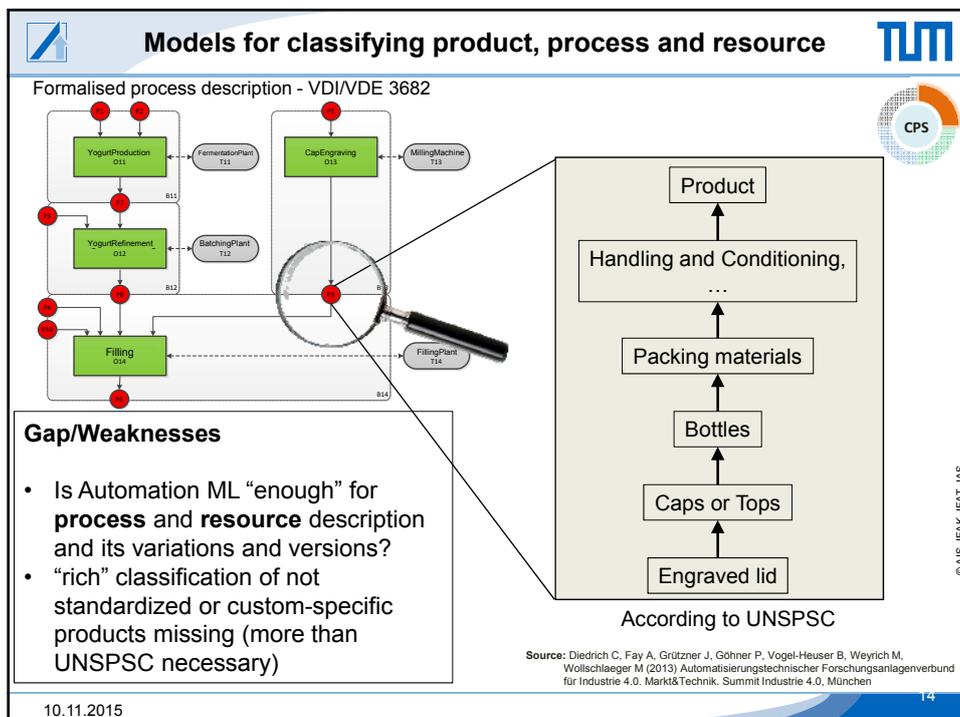
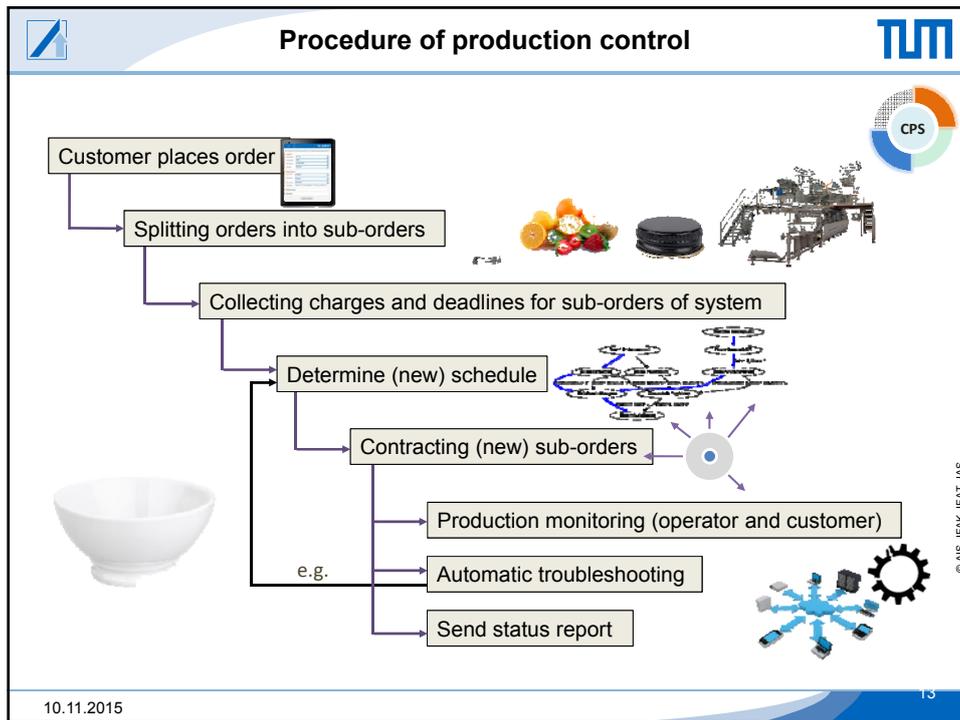
Plant Production      Simulated production  
 Yogurt production      Yogurt refinement  
 Cap engraving      Filling

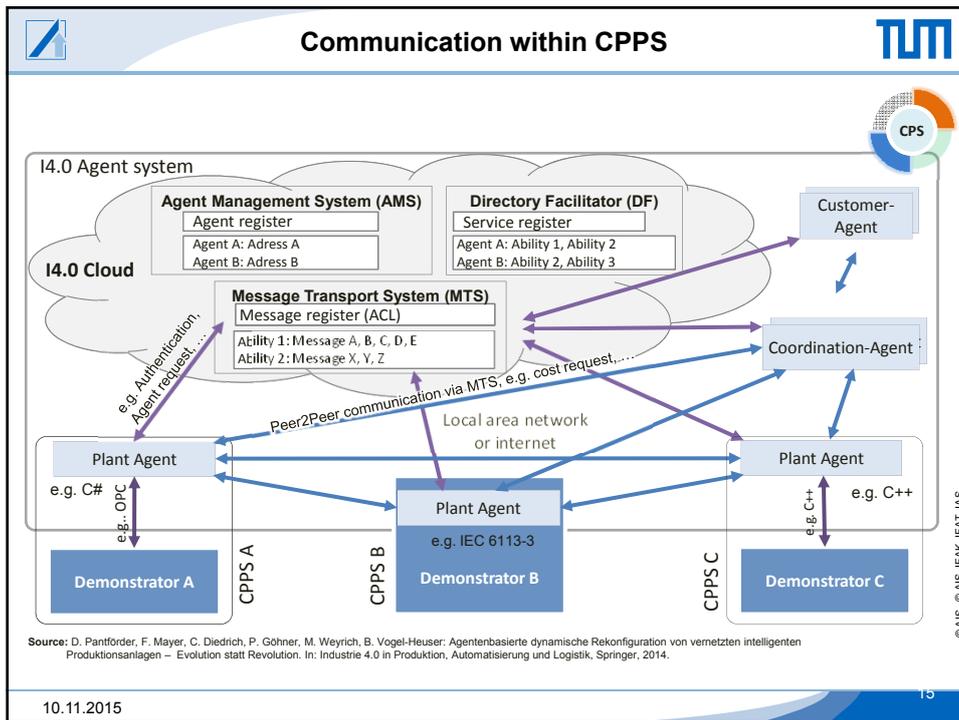



Website: <http://www.ais.mw.tum.de/myjoghurt/>

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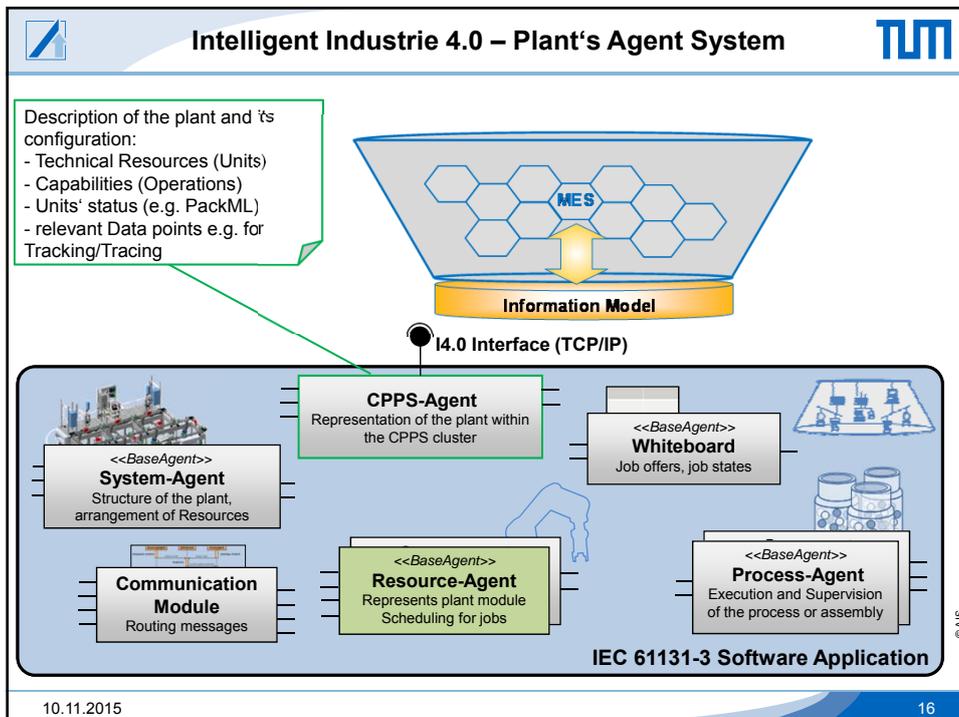
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**Description of the Technical System using MES-ML**

The screenshot displays the MES-ML software interface for describing a technical system. On the left, a tree view shows the 'Hierarchic plant structure' with a 'CPPS Module' highlighted. The main area shows a 'Properties' window for a 'Machine' (Name: WT021) and a 'Library Window' showing a 'Technical System' (Name: Wärmetauscher). A 'Data point management' dialog is open, showing a table of data points and their classes.

Klassifizierung	Datenpunkt	Datenpunkt-Klasse	Beschreibung
AutMES	00002 - AM_Cur_Batch_ID	AM_Process	Chargenbezeichnung Schwert
AutMES	00004 - WS_Cur_Order_ID	WS_Tracing	Auftragsnummer Schwert
AutMES	00005 - AM_Cur_Process	AM_Process	This data point gives the information of the current process on the machine
AutMES	00002 - AM_Cur_Sub_Process	AM_Process	<input type="checkbox"/> Datenpunkt bearbeiten
AutMES	00003 - AM_Cur_Prc_Operation	AM_Process	Klassifizierung
AutMES	00001 - AM_Machine_ID	AM_Mach_ID	Datenpunkt
AutMES	00001 - AM_Cur_Prc	AM_Mach_Value	Datenpunkt-Klasse
AutMES	00001 - AM_Cur_Prc	AM_Mach_Value	WS_Tracing
AutMES	40010 - AM_Cur_Temp	AM_Measure_Value	Zugriffsmodus
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	Read/Write
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	ist virtuell?
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	<input type="checkbox"/>
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	Beschreibung
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	Chargenbezeichnung Schwert
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	OK
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	Abbrechen
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	Wasserverbrauch
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	Heißwasserverbrauch
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	Stromverbrauch
AutMES	40011 - AM_Cur_Sumature	AM_Measure_Value	This data point gives the current heat flow during heating up

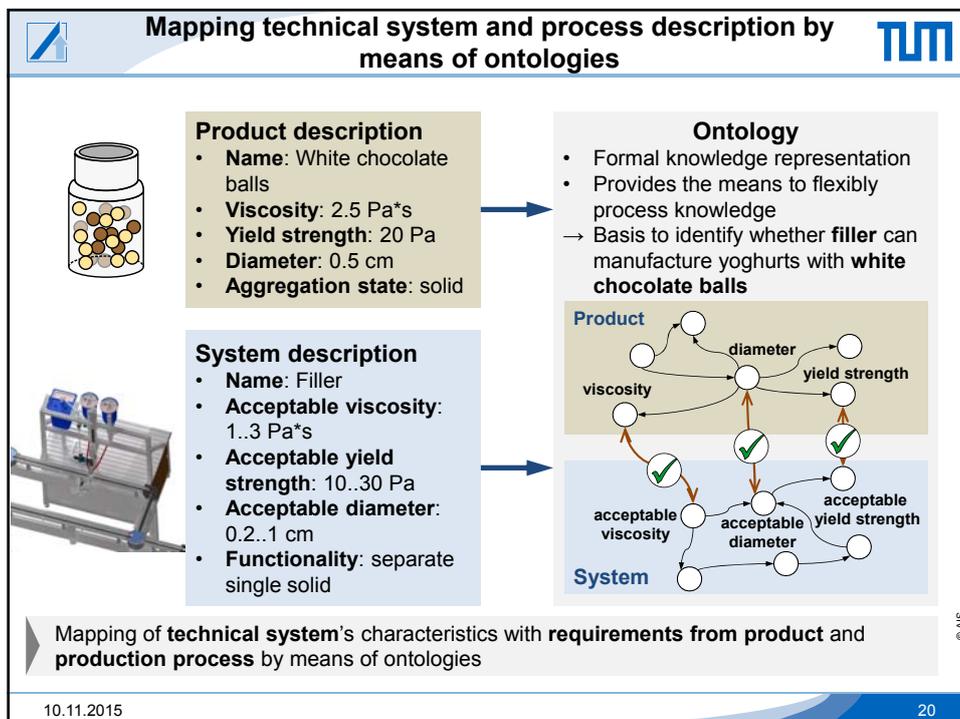
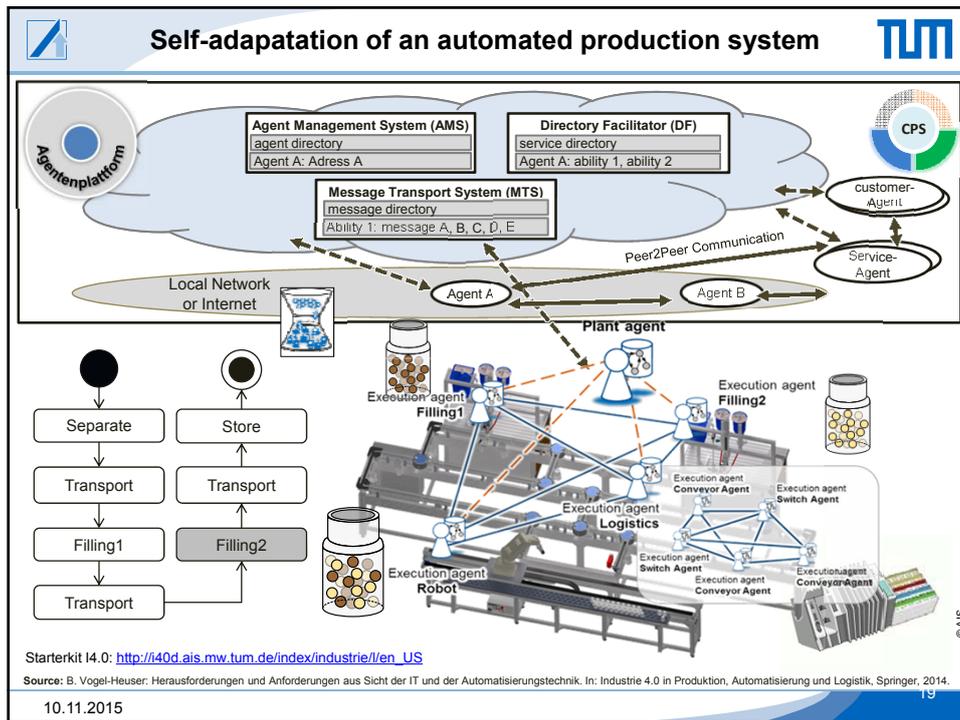
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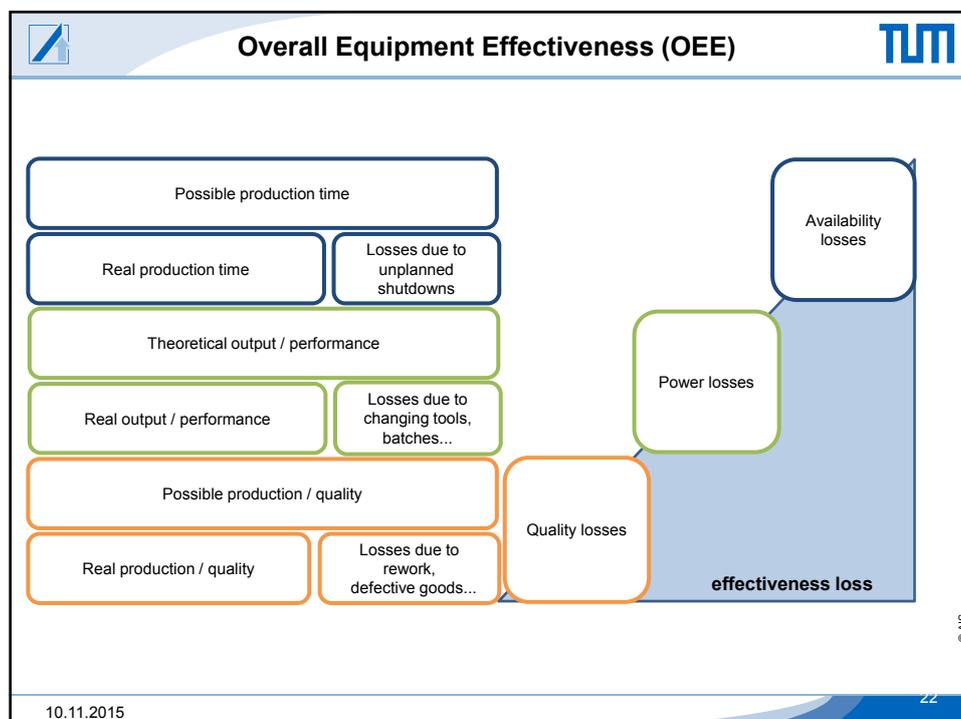


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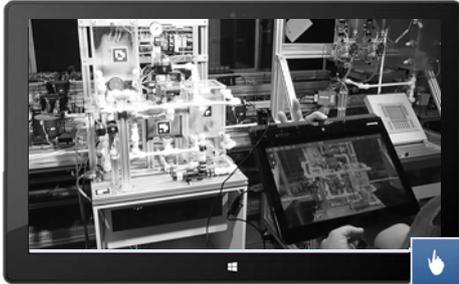
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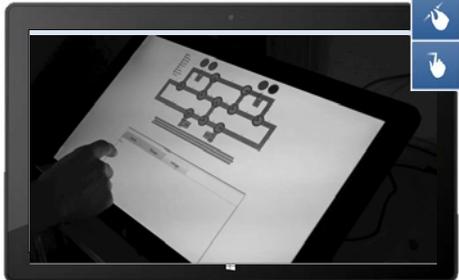
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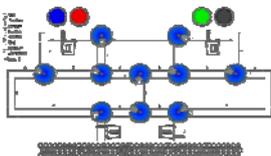
**Scenario: Information aggregation for maintenance HMI with AR and touchscreen**





- Mobile devices with touchscreen
- Augmented Reality supports optimization and maintenance of industrial plants



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**Information aggregation for maintenance (1)**





role  
shift supervisor

shift supervisor undertakes  
role of mechanic

shift supervisor undertakes  
role of operator

**shift supervisor**

- Red-green color blindness
- Preferred voice control

**role**

- shift supervisor
- mechanic
- operator

**Context**





Source: Lehrstuhl für Automatisierung und Informationssysteme, TU München

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### Information aggregation for maintenance (2)

**role**  
shift supervisor

**shift supervisor undertakes**  
role of mechanic

**shift supervisor undertakes**  
role of operator

**shift supervisor**

- Red-green color blindness
- Preferred voice control

**role**

- shift supervisor
- mechanic
- operator**

**challenge**

- Prediction of critical situations based on analysis of process data and alarm sequences
- recommendations for operator

**Context**

**approach**

- Pattern analysis, statistical approaches and Clustering

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### Project: #SmartData2015 / Data Mining in process industry

- Bundle detailed knowledge of processes and plants and include in analysis
- Data logistics
  - Secure provision and transport
  - Secure storage
- Aggregation and analysis of data
  - Aggregation of data specific to processes and plants with historical data
  - Identification of unknown correlations in data → make implicit knowledge explicit
  - Integration of field device manufacturers for improving field devices
- Data use
  - Application of the analytical findings to plant families throughout the company
  - Supporting the operating personnel in engineering, process management, servicing and maintenance

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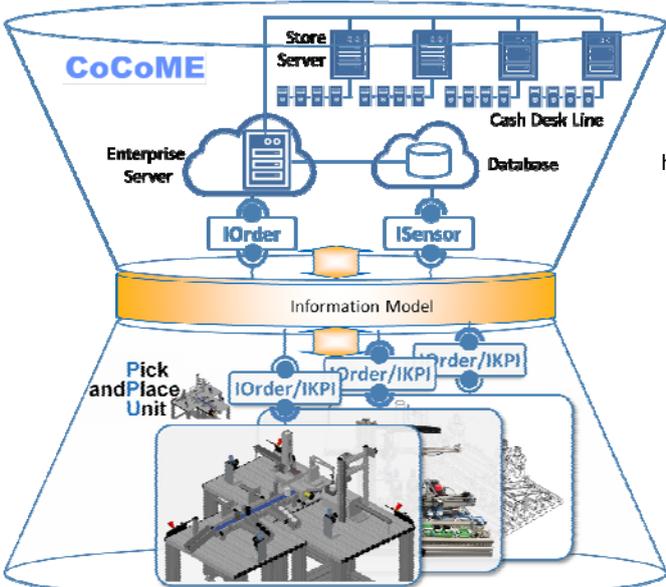

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Joined Industrie 4.0 Demonstrator DFG - PP 1593 phase II

The diagram illustrates the CoCoME architecture within a funnel shape. At the top, a 'Store Server' is connected to a 'Cash Desk Line'. Below this, an 'Enterprise Server' and a 'Database' are connected to 'IOrder' and 'ISensor' components respectively. These components interface with an 'Information Model' layer. Below the information model, 'Pick and Place Unit' components are connected to 'IOrder/IKPI' and 'Order/IKPI' components. At the bottom, a photograph shows the physical 'Pick and Place Unit' hardware.

**Design For FUTURE**

DFG Priority Programme 1593  
Design For Future - Managed Software Evolution

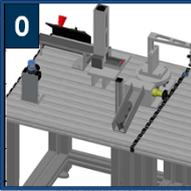
<http://www.dfg-spp1593.de>

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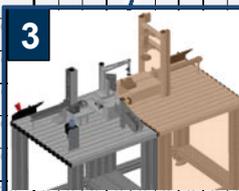
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### Sequential evolution scenarios

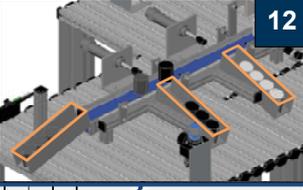
Cause	Scenario	Stack			Crane			Stamp			Ramp			Conveyor			Enabler
		C	P	S	C	P	S	C	P	S	C	P	S	C	P	S	
increasing transportation throughput of work pieces	Sc0	A	A	A	A	A	A	-	-	-	A	A	A	-	-	-	green field, pick and place unit
increasing capacity of output storage	Sc1	o	o	o	o	o	o	o	o	o	M	o	o	o	o	o	1-shaped ramp
two different products are processed	Sc2	A	A	A	o	o	o	-	-	-	o	o	o	-	-	-	inductive sensor for metal detection
one product has to be labeled	Sc3	o	o	o	M	M	M	A	A	A	o	o	o	-	-	-	stamp unit added
decreasing failure due to sensor pollution	Sc4	o	o	o	o	o	o	o	o	o	o	o	o	o	o	o	special crane screws
reliability, redundancy for positioning	Sc4b	o	o	o	o	o	M	o	o	o	o	o	o	o	o	o	
different logistical locations	Sc11	o	o	o	o	o	o	o	o	o	o	o	o	o	o	o	one ramp addition
special sorting that every sorting location has the same WP order	Sc12	o	o	o	o	o	o	o	o	o	o	o	o	o	o	M	adding ramps step by step
increasing the precision of the crane	Sc13	o	o	o	M	A	M	o	o	o	o	o	o	o	o	o	defined sorting of work pieces for (similar for each ramp)
EMC resistance due to electro-magnetic influences	Sc14	o	o	o	M	A	M	o	o	o	o	o	o	o	o	o	analog sensor for crane positioning
											M	M	M				incremental encoder for crane positioning



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**Legend:** A: Added; M: Modified; -: not available at this evolution time; o: no Changes; C: Context; P: Platform; S: Software

**Sources:** Legat, Christoph; Folmer, Jens; Vogel-Heuser, Birgit. *Evolution in Industrial Plant Automation: A Case Study*. 39th Annual Conference of the IEEE Industrial Electronics Society (IECON 2013), 2013, 4386-4391.  
 Vogel-Heuser, B.; Folmer, J.; Legat, C.: Anforderungen an die Softwareevolution in der Automatisierung des Maschinen- und Anlagenbaus. In: *Automatisierungstechnik (at)*, Vol. 62, No. 3, 2014, S. 163-174.

### Self healing PPU - fault handling @ belt pushers

Scenario	Customer	Additional functionality self-healing machine and diagnosis	x	0	x	Additional sensors and software required, automatic mode enlarged
Sc12f						

#### Sc12f: Additional Sensor for Fault Detection, Isolation and Handling




- Binary Sensors** for discrete front and back position detection
- Additional analogue sensor** to detect exact position of pusher and redundancy for binary sensors
- Result: work piece jam → self healing mode



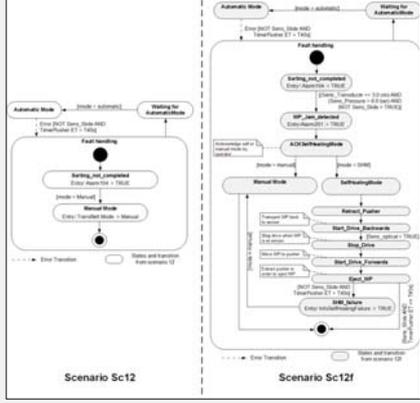
### fault handling @ belt pushers



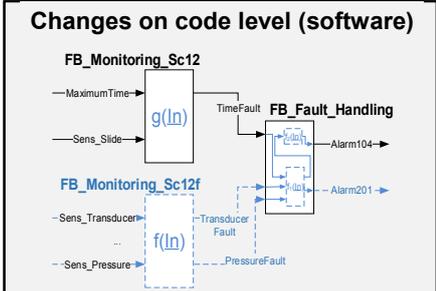
#### Changes on component list/ sensor level (context)

Group	Device	Function	Location	Device/Signal type	P. supply [V]	Remarks
310	B.1.1	pusher is extended	pusher	reed switch DI	24V	mand.
310	B.1.4	position of pusher	pusher	distance sensor AI	24V	SHM
300	B.1	pressure sensor	valve node	pneum. meas AI	0-24V	SHM

#### Changes on model level (software)



#### Changes on code level (software)



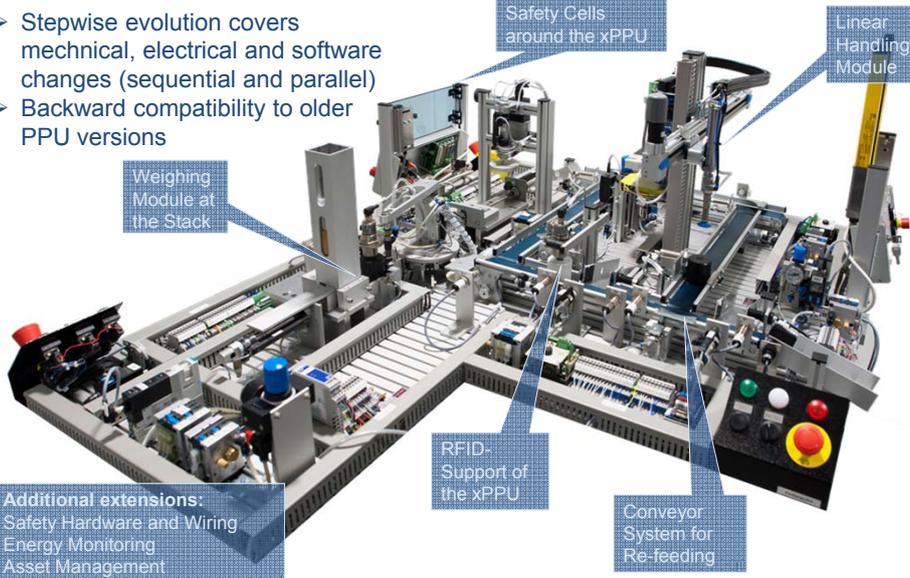
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### Overview of the xPPU (Pick and Place Unit)



- Stepwise evolution covers mechanical, electrical and software changes (sequential and parallel)
- Backward compatibility to older PPU versions



**Additional extensions:**  
Safety Hardware and Wiring  
Energy Monitoring  
Asset Management

Safety Cells around the xPPU

Linear Handling Module

Conveyor System for Re-feeding

RFID-Support of the xPPU

Weighing Module at the Stack

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Deliverables from PPU – for each evolution step

### 16 SysML models with evolutionary changes

#### Behavior

#### Structure

### Technical Documentations

Position	Device	Manufacturer	Order No.	Part No.	Quantity	Unit
1	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
2	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
3	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
4	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
5	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
6	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
7	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
8	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
9	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
10	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
11	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
12	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
13	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
14	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
15	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU
16	PS 307 5A	Siemens	6ES7 307-1EA00-0AA0	307 1EA00	1	PSU

### PLC implementations

Especially for project *Pythia*:

- 45 different IEC 61131-3 Projects
- graphical and textual programming languages

### 16 PLC implementations each

#### Based on plcUML

#### Classical IEC61131

<https://mediatum.ub.tum.de/node?id=1208973>

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### Proposed metrics – adaptivity coverage and realization effort

**BECAI:** Basic Event Coverage Adaptivity Index  
**BENCAI:** Basic Event Not Coverage Adaptivity Index  
**FLCAI<sub>j</sub>:** Fault Level Coverage Adaptivity Index

**plcDFAI:** PLC-cycles to detect faults  
**plcIFAI:** PLC-cycles to isolate faults  
**plcSTSAI:** PLC-cycles to switch to soft sensor  
**plcFCLAI:** PLC fault compensation latency

**Sc12f: Additional Sensor for Fault Detection, Isolation and Handling**

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### Fault Coverage – Basic Event Coverage (level 1)

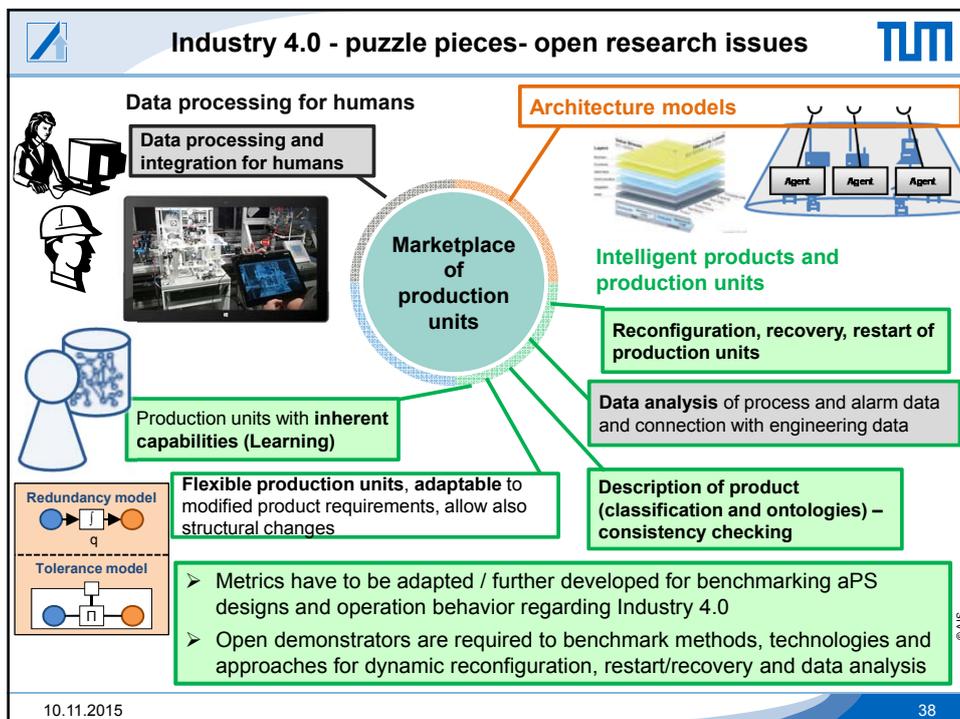
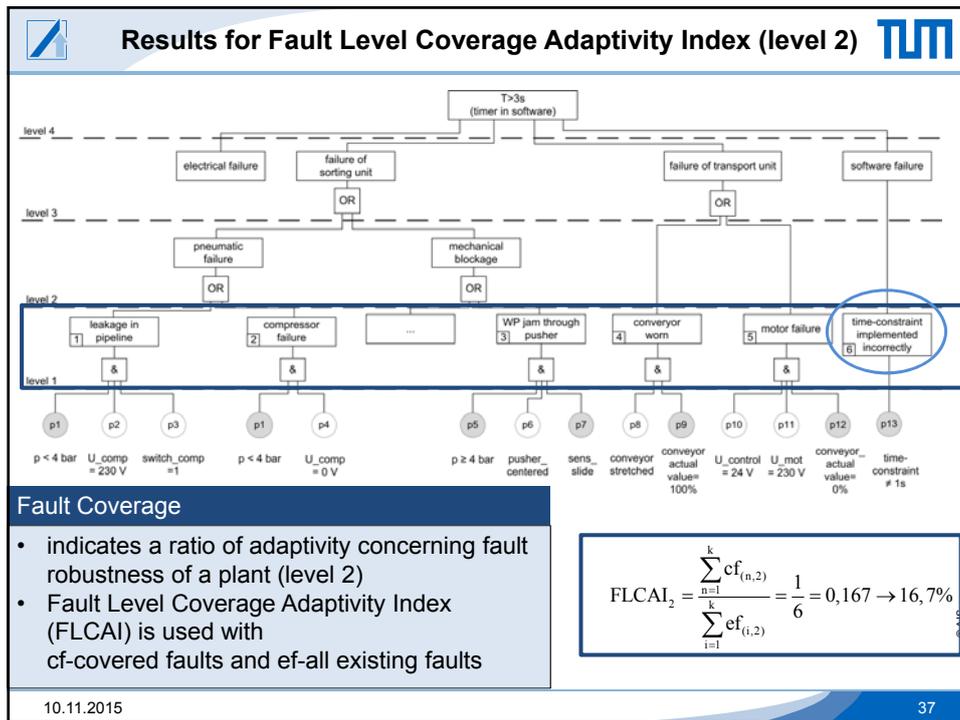
Fault tree based fault detection

**Measured Basic Events** to detect symptoms of a fault

- values that
  - are measured (grey) or
  - need to be measured (white) to detect level 2 fault
- BECAI - coverage of values that are measured (c) related to all basic events (b)

$$BECAI = \frac{\sum_{j=1}^k c_j}{\sum_{i=1}^n b_i} \in [0,1]$$

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## Selected Related Publications



- **U. Frank, J. Papenfort, D. Schütz:** Real-time capable software agents on IEC 61131 systems – Developing a tool supported method. In: Proc. of 18th IFAC World Congress, Mailand, Italien, 2011, S. 9164-9169.
- **C. Legat, B. Vogel-Heuser:** A Multi-agent Architecture for Compensating Unforeseen Failures on Field Control Level. In: International Workshop on Service Orientation in Holonic and Multi-Agent Manufacturing and Robotics (SOHOMA), 2013.
- **F. Li, G. Bayrak, K. Kernschmidt, B. Vogel-Heuser:** Specification of the Requirements to Support Information Technology-Cycles in the Machine and Plant Manufacturing Industry. In: 14th IFAC Symposium on Information Control Problems in Manufacturing, 2012.
- **B. Vogel-Heuser et al.:** Model-driven Engineering of Manufacturing Automation Software Projects – A SysML-based Approach. Mechatronics, vol. 24, pp. 883-897, 2014.
- **D. Schütz et al.:** Development of PLC-based Software for Increasing the Dependability of Production Automation Systems. IEEE Transactions on Industrial Informatics, vol. 9, pp. 2397-2406, 2013.
- **S. Ulewicz et al.:** Flexible Real Time Communication between Distributed Automation Software Agents. 22nd International Conference on Production Research (ICPR 2013), Iguassu Falls, Brazil, 2013.
- **C. Legat, J. Folmer, B. Vogel-Heuser:** Evolution in Industrial Plant Automation: A Case Study. 39th Annual Conference of the IEEE Industrial Electronics Society (2013), Vienna, Austria.
- **B. Vogel-Heuser, C. Legat, Folmer J., and S. Rösch:** Challenges of Parallel Evolution in Production Automation Focusing on Requirements Specification and Fault Handling. at – Automatisierungstechnik, Vol. 62, Nov. 11, 2014.
- **B. Vogel-Heuser, J. Folmer, C. Legat:** Anforderungen an die Softwareevolution in der Automatisierung des Maschinen- und Anlagenbaus. at – Automatisierungstechnik, Vol. 62, No. 3, pp. 163-174.
- **Hackenberger et al.:** Formal Technical Process Specification and Verification for Automated Production Systems. System Analysis and Modeling (SAM) 2014.
- **Legat et al.:** Interface Behavior Modeling for Automatic Verification of Industrial Automation Systems' Functional Conformance. at – Automatisierungstechnik, Vol. 62, 2014.
- **C. Haubeck, J. Ladiges, J. Fuchs, C. Legat, W. Lammersdorf, A. Fay, and B. Vogel-Heuser:** Interaction of model-driven engineering and signal-based online monitoring of production systems. 40th Annual Conference of the IEEE Industrial Electronics Society (IECON 2014), 2014.
- **M. Kowal, C. Legat, D. Lorefica, C. Prehofer, I. Schäfer, and B. Vogel-Heuser:** Delta modeling for variant-rich and evolving manufacturing systems. 36th International Conference on Software Engineering Workshops (ICSE), 2014, pp. 32-41.
- **S. Holthusen, D. Wille, C. Legat, S. Beddig, I. Schäfer, and B. Vogel-Heuser:** Family model mining for function block diagrams in automation software". in 2nd International Workshop on Reverse Variability Engineering (REVE 2014), 2014, pp. 36-43.
- **M. Lochau, J. Bürdek, S. Lity, M. Hagner, C. Legat, U. Golz, and A. Schürr:** Applying Model-based Software Product Line Testing Approaches to the Automation Engineering Domain. at – Automatisierungstechnik, Vol. 62, Nov. 11, 2014.
- **B. Vogel-Heuser, A. Fay, I. Schäfer, M. Tichy:** Evolution of software in automated production systems – Challenges and Research Directions. Journal of Systems and Software, Vol. 110, 2015, pp. 54-84.

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# Thank you for your attention.

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