

Subjective Evaluation of a Semi-Automatic Optical See-Through Head-Mounted Display Calibration Technique

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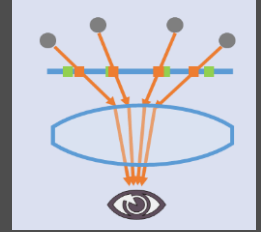
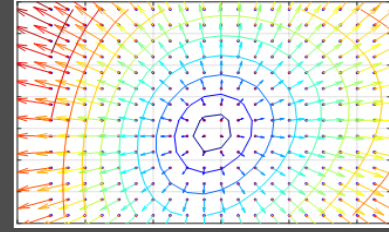
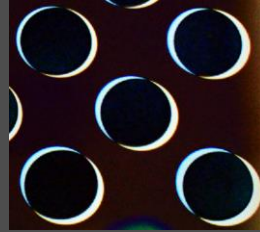
Nara Institute of Science & Technology



Summary of our 3 talks



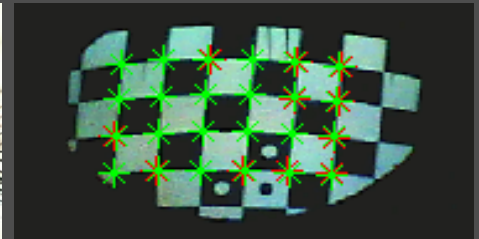
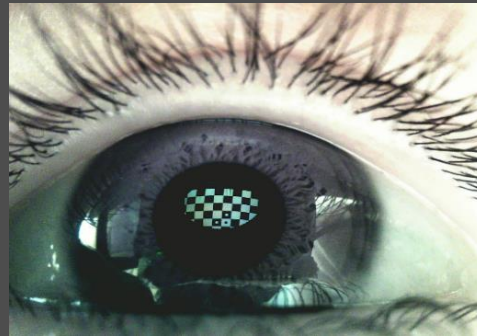
1. Better HMD model



By Yuta



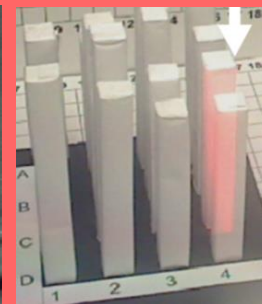
2. Better Eye localization



By Alex

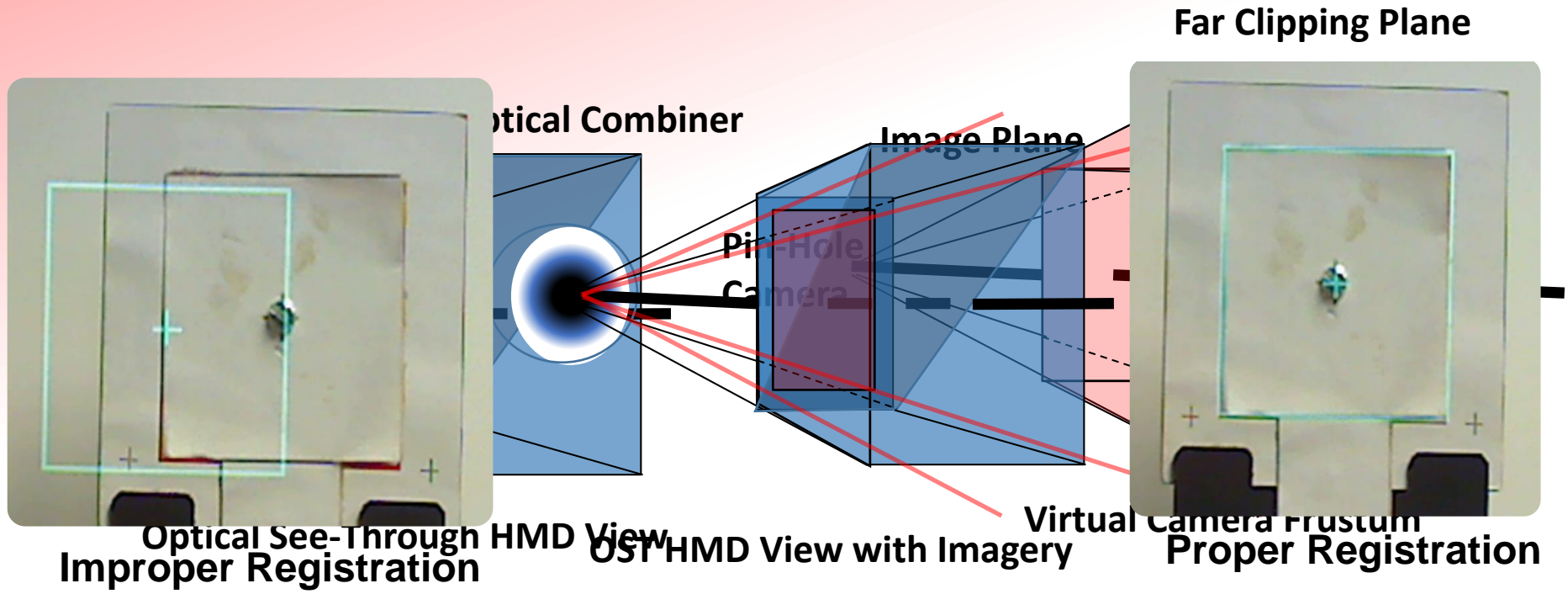


3. Formal User study



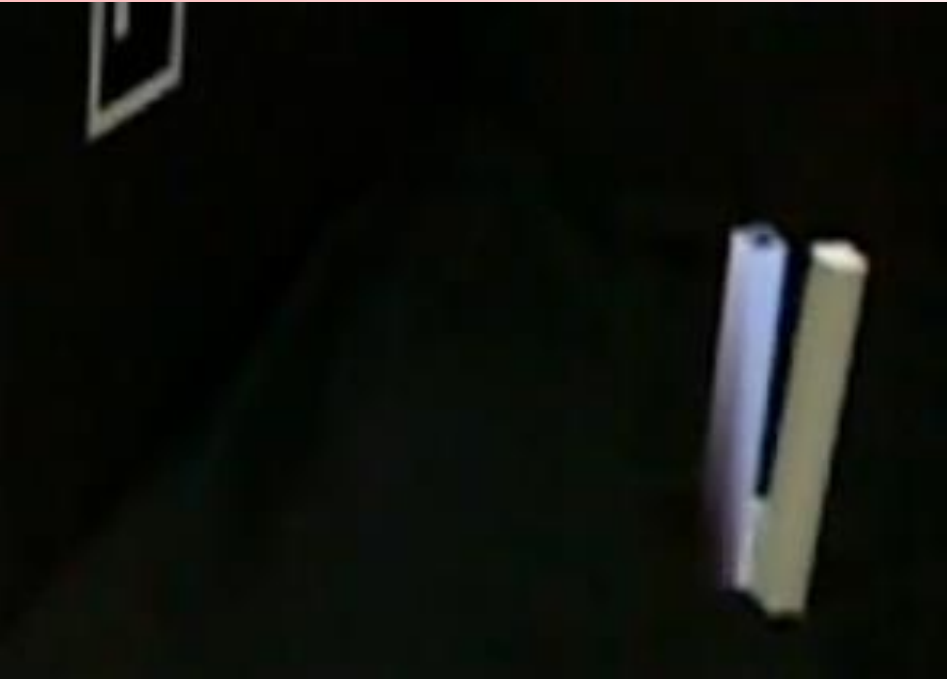
By Kenny

OST-HMD Calibration



OST-HMD Calibration

Video Taken Through Camera Set Within The Display



Less Accurate Registration

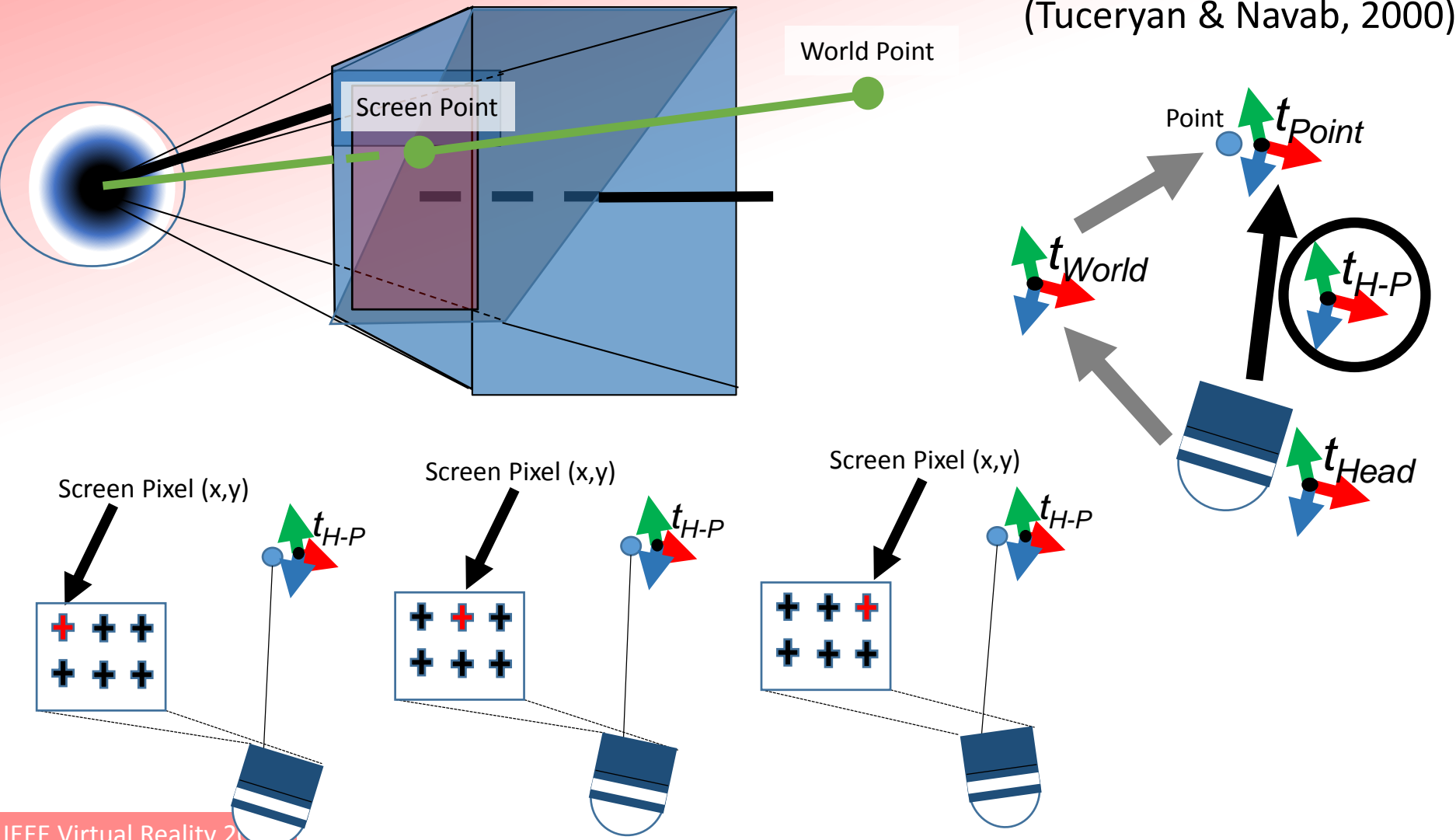


More Accurate Registration

Calibration Methods

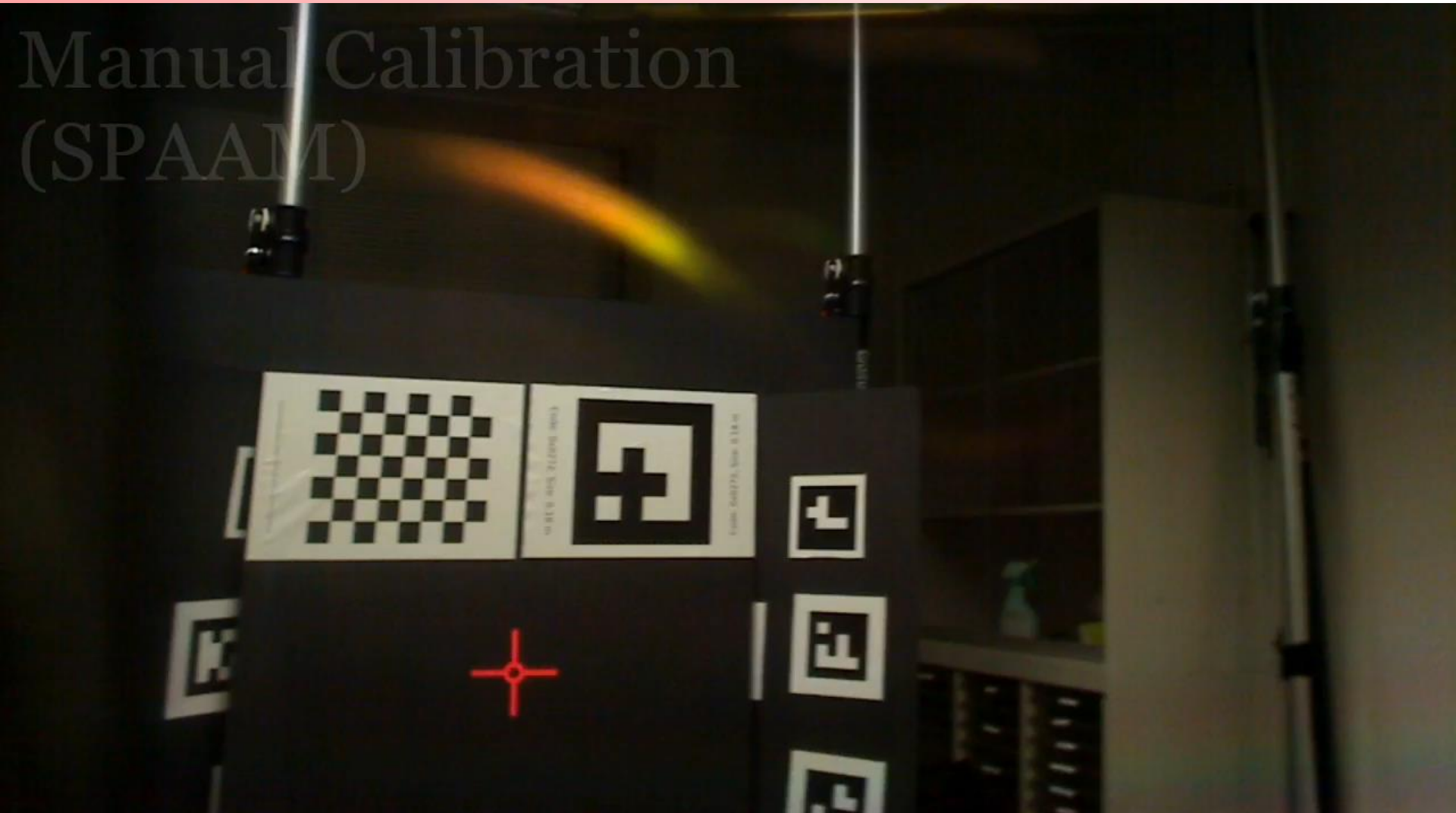
Single Point Active Alignment Method (SPAAM)

(Tuceryan & Navab, 2000)



Calibration Methods

Manual Calibration (SPAAM)

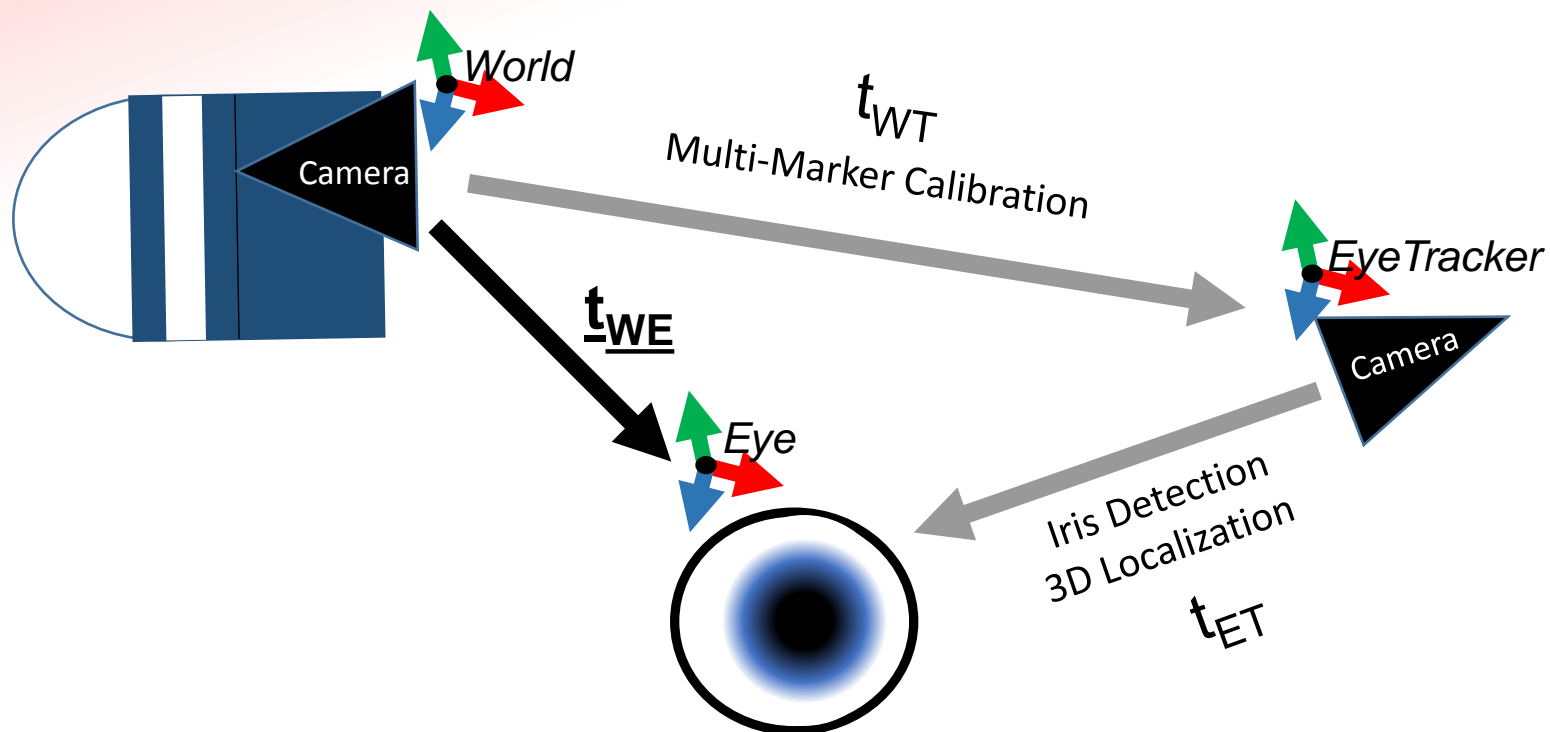


Calibration Methods

Interaction Free Display Calibration (INDICA)

(Itoh & Klinker, 2014)

Recycled INDICA: Updates Calibration Matrix With Eye Location

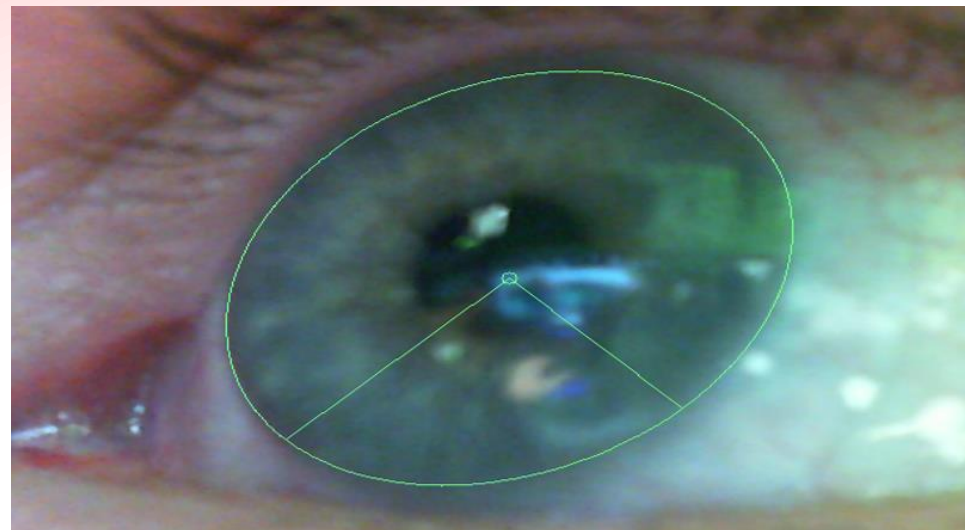


Calibration Methods

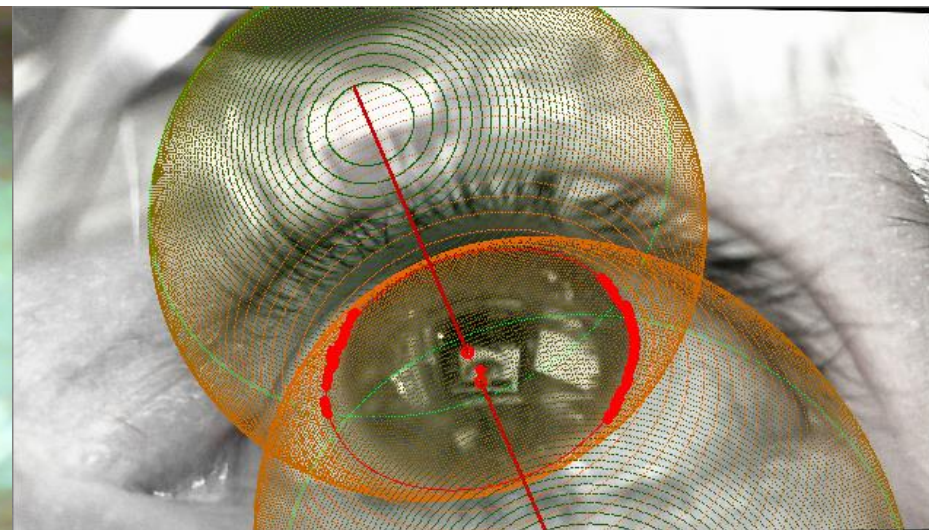
Interaction Free Display Calibration (INDICA)

(Itoh & Klinker, 2014)

Eye Center Locations Determined Through Limbus Detection



Swirski, 2012



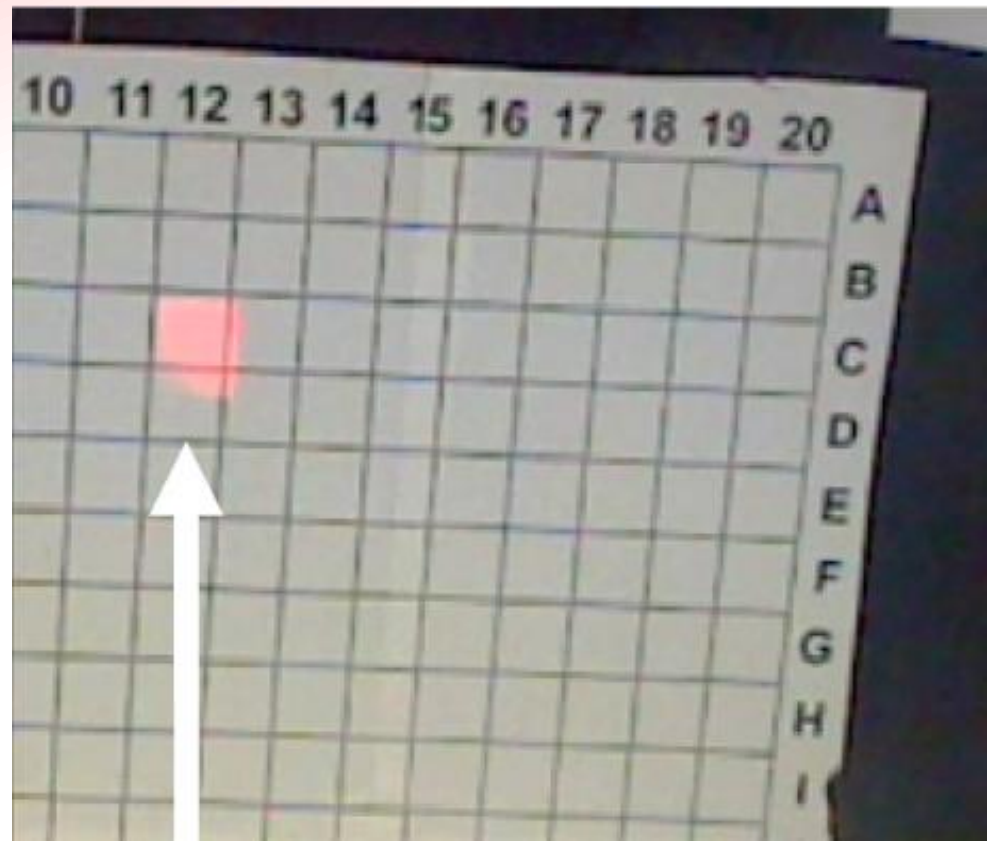
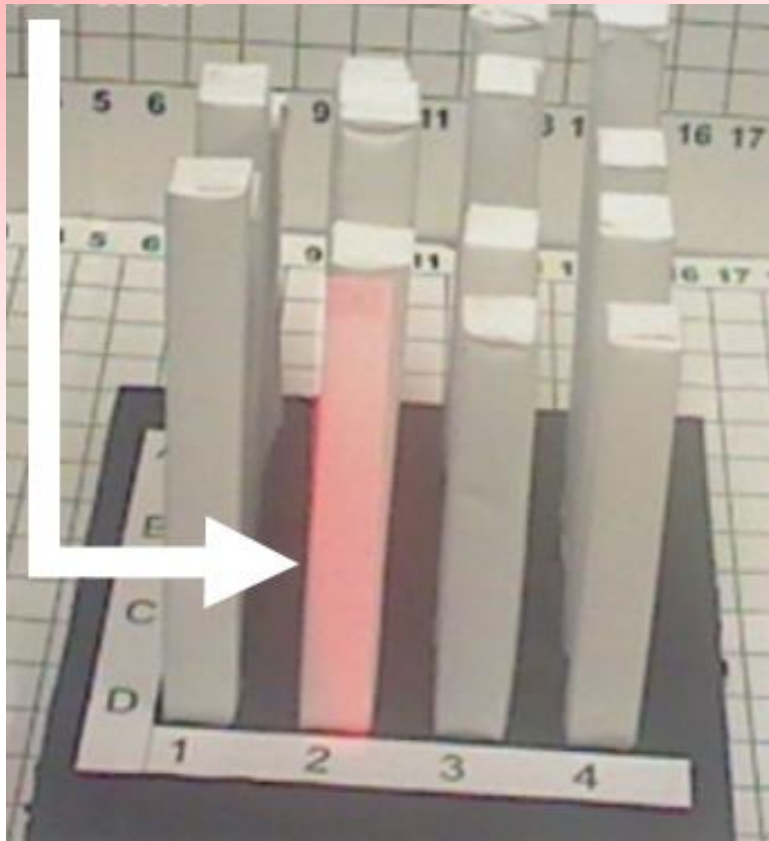
Nitschke, 2013

Calibration Methods Evaluated

- SPAAM:
 - 20 screen - world alignments
 - taken over 1.5m – 3.0m distance to world point
- Degraded SPAAM:
 - reuse of SPAAM result
 - HMD removed and replaced
- Recycled INDICA:
 - Reuse intrinsic values from SPAAM calibration
 - Combine updated Eye Position for final result

Subjective Evaluation Metrics

perceived location error



Virtual Objects in RED

Subjective Evaluation Metrics

quality of registration with perceived location

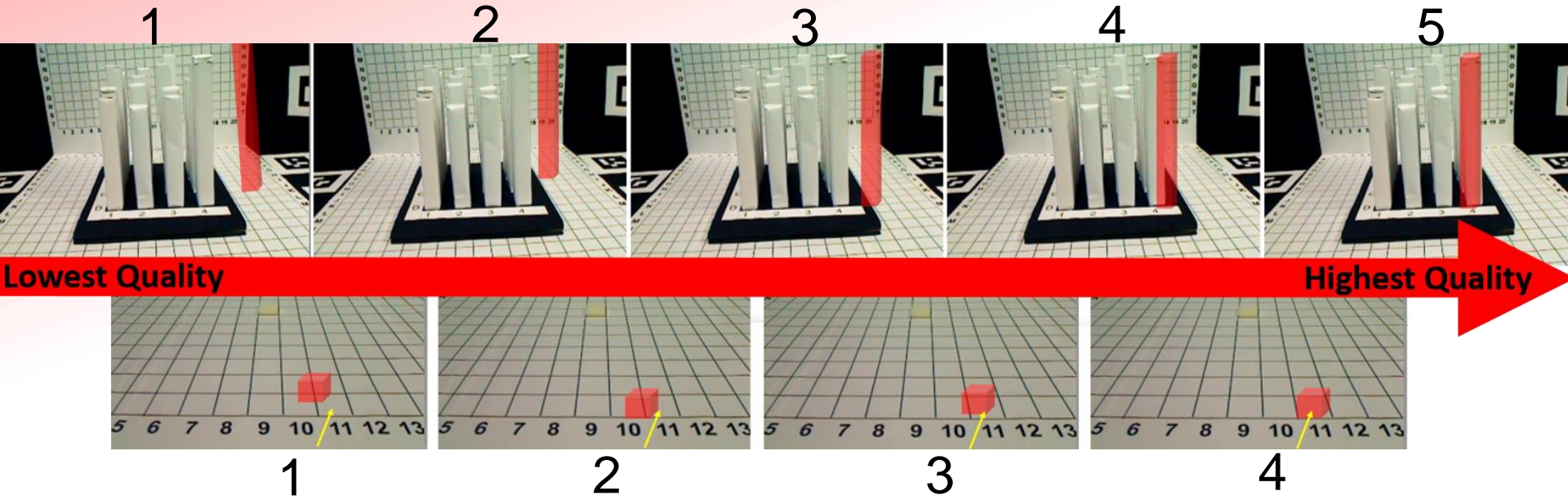
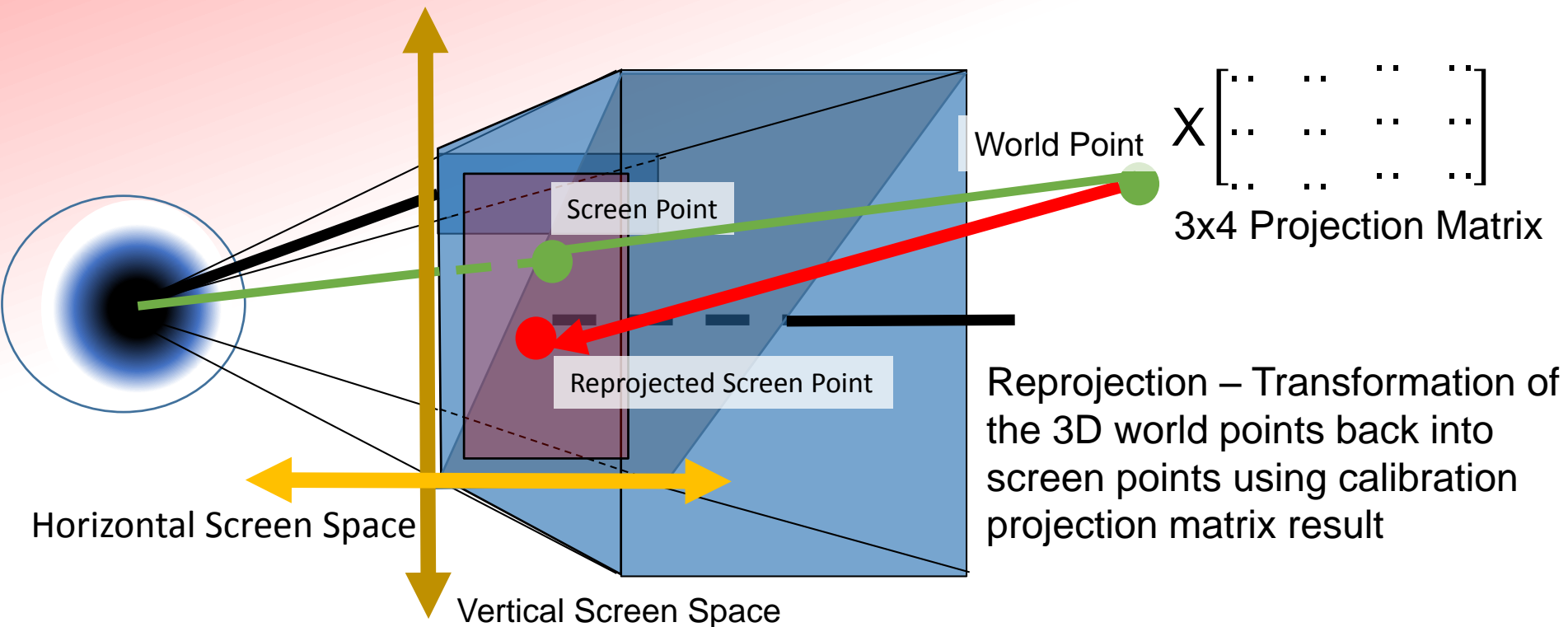


diagram provided to subject before start of each trial set

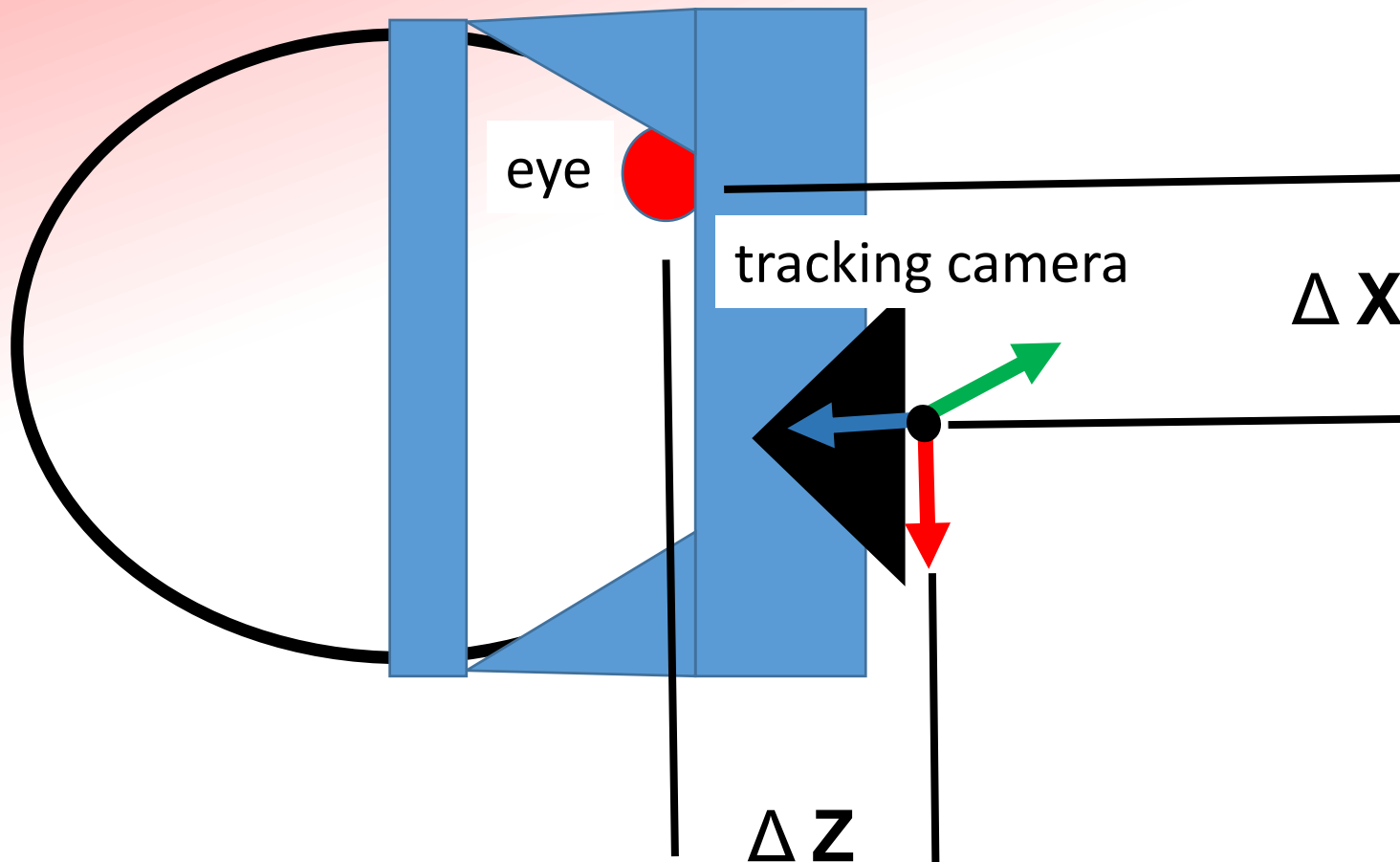
Quantitative Evaluation Metrics

variance of SPAAM alignment point reprojection



Quantitative Evaluation Metrics

variance in eye location estimates



System Hardware



NVIS ST50

1280 x 1024 per eye

HFOV 40° / VFOV 32°

Left Eye (Monocular)



Right Eye Piece (Covered)

System Hardware



Logitech QuickCam Pro
USB 2.0 Interface
Auto-Focus Disabled

World Tracking (head)
640 x 360 30fps

Eye Localization (left eye)
1280 x 720 (still images)



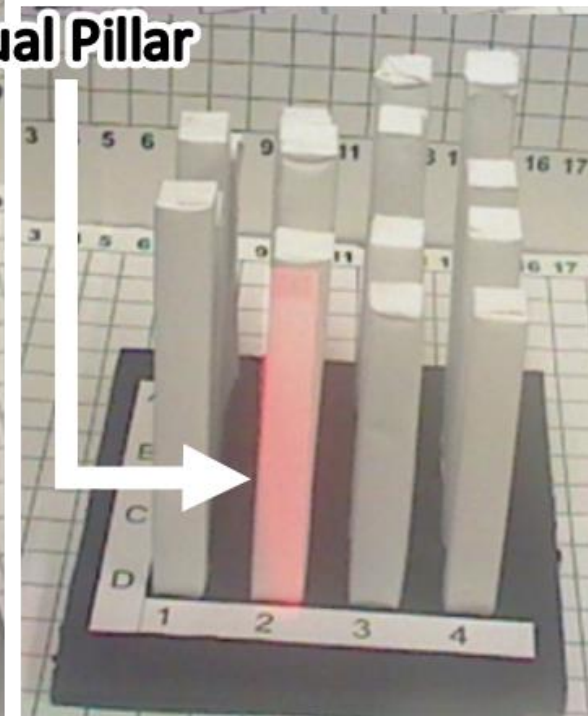
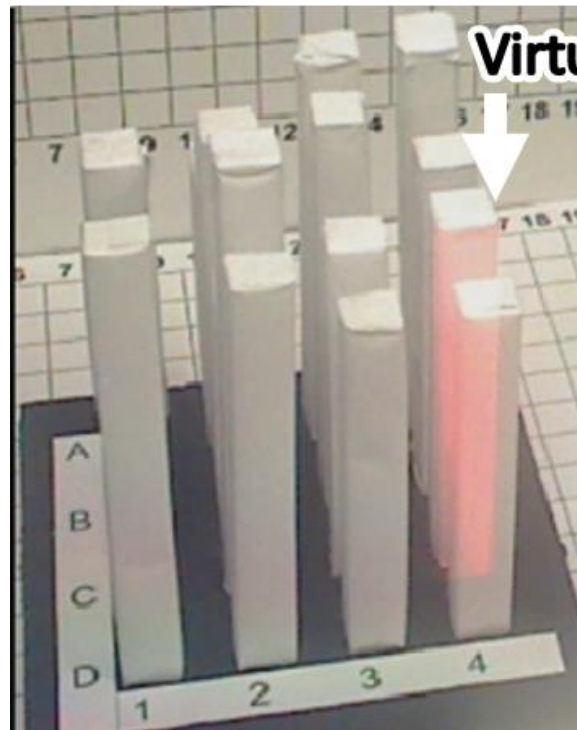
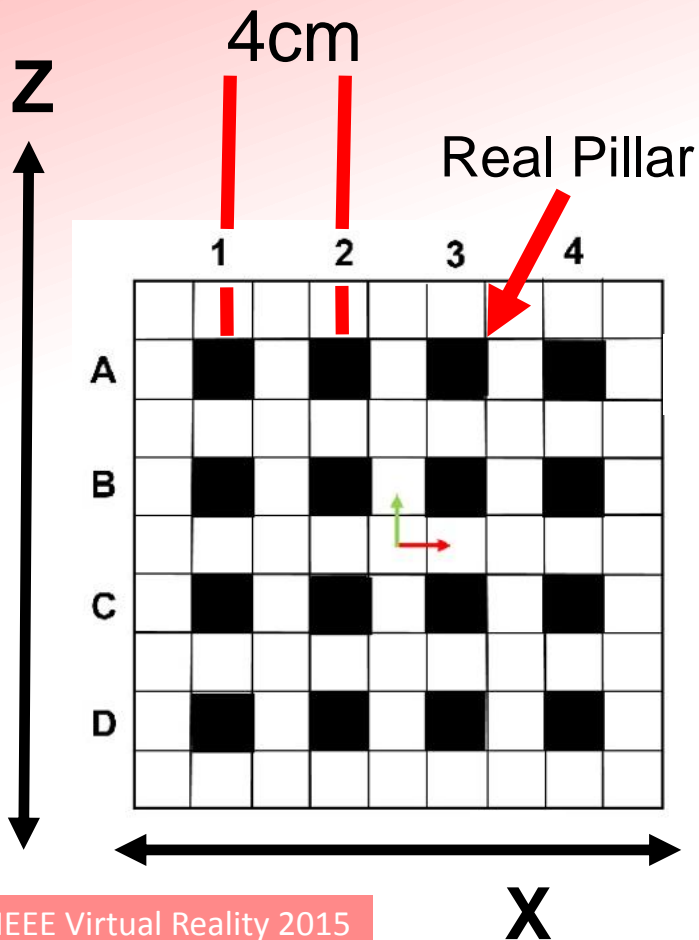
Pillar Evaluation Tasks

verbally state location and registration quality

4 x 4 Grid of Pillars – 4cm spacing

Real Heights: 13.5 – 19.5cm

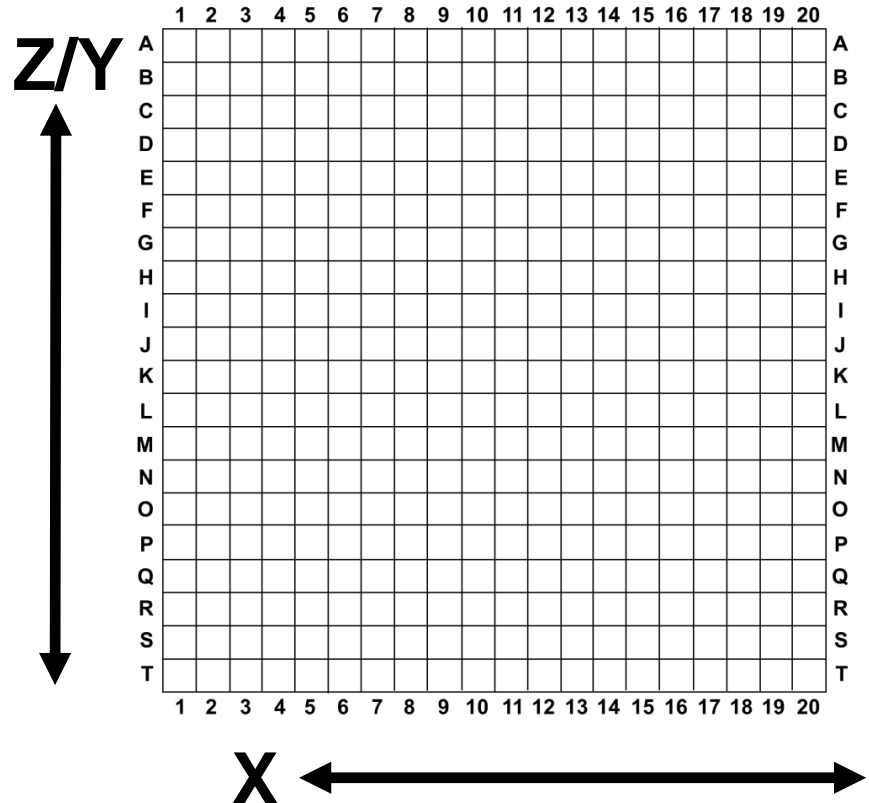
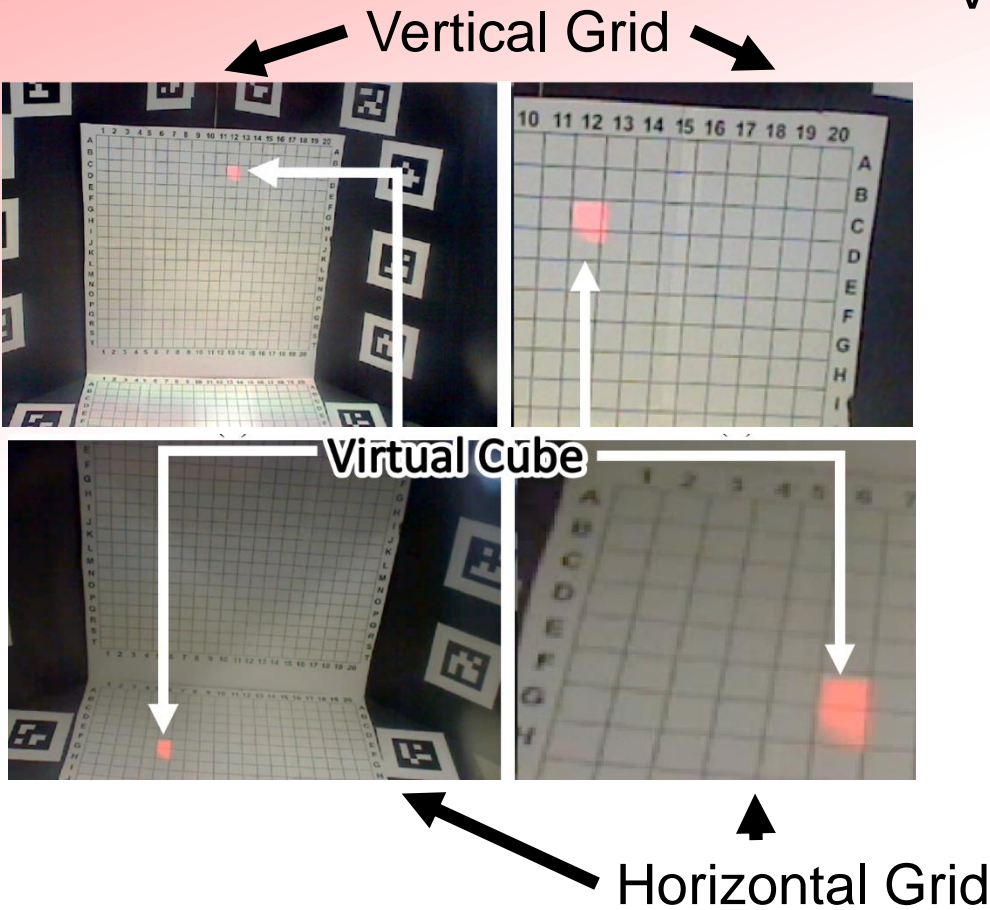
Virtual Height: 15.5cm



Cube Evaluation Tasks

verbally state location and registration quality

Virtual Cube: 2cm x 2cm x 2cm
20 x 20 Grids of Squares



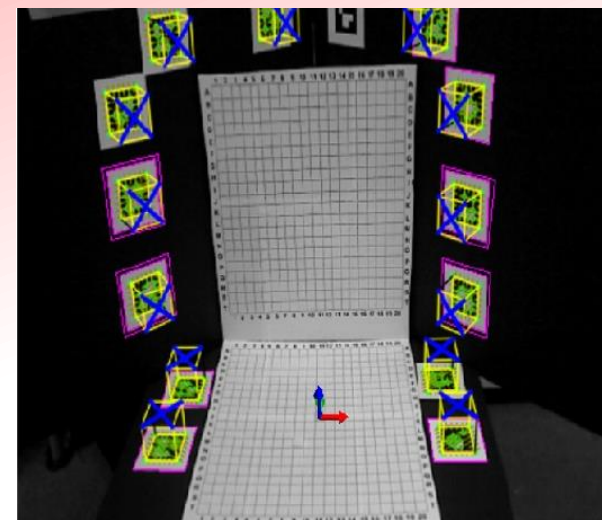
System Hardware

Within-Subjects Design

13 Subjects (6 male / 7 female)

22 – 26 years of age

No prior experience with HMD's



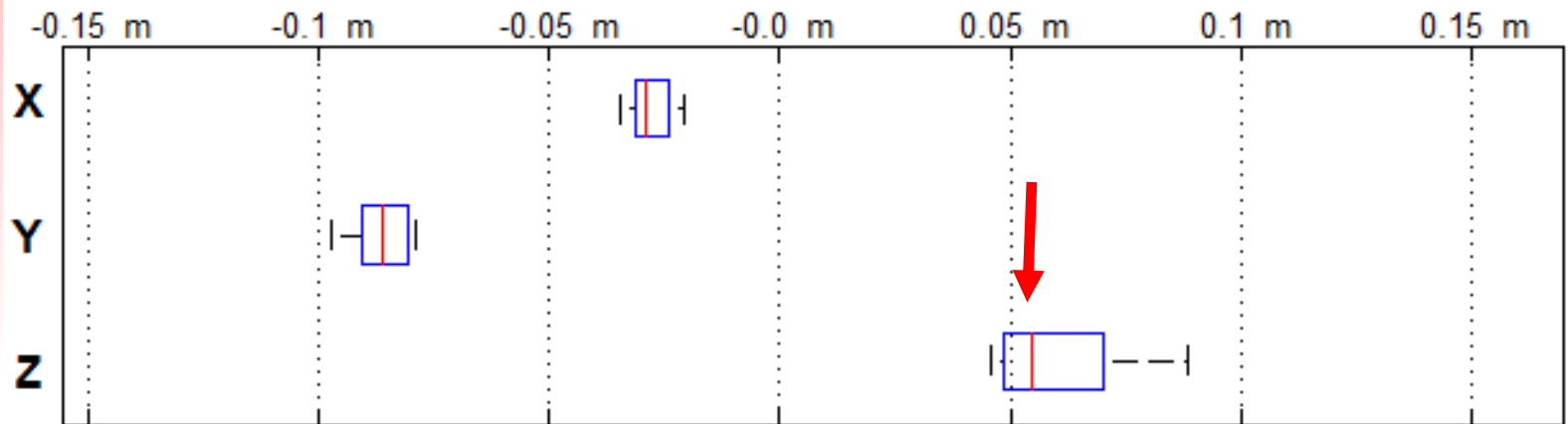
Tracking Performed by Ubitrack
Huber et al., 2007



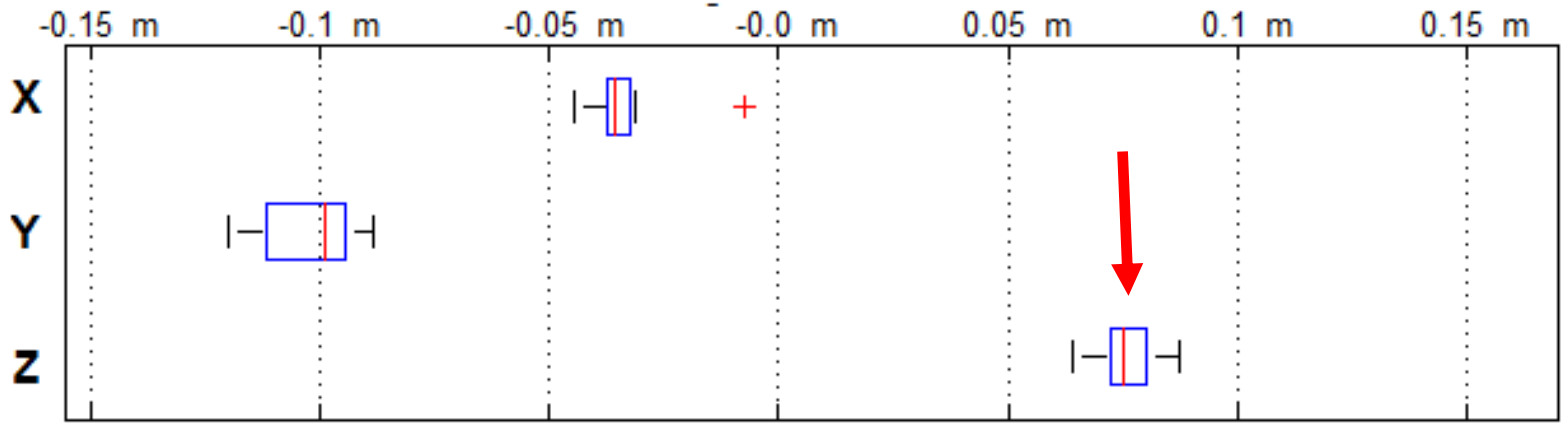
Quantitative Result – Eye Location Estimation

SPAAM Extrinsic Parameters derived through QR Decomposition

SPAAM - Extrinsic Eye Pose Estimates (All Subjects)

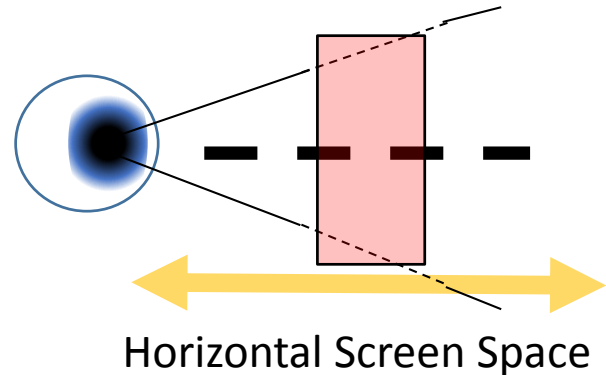
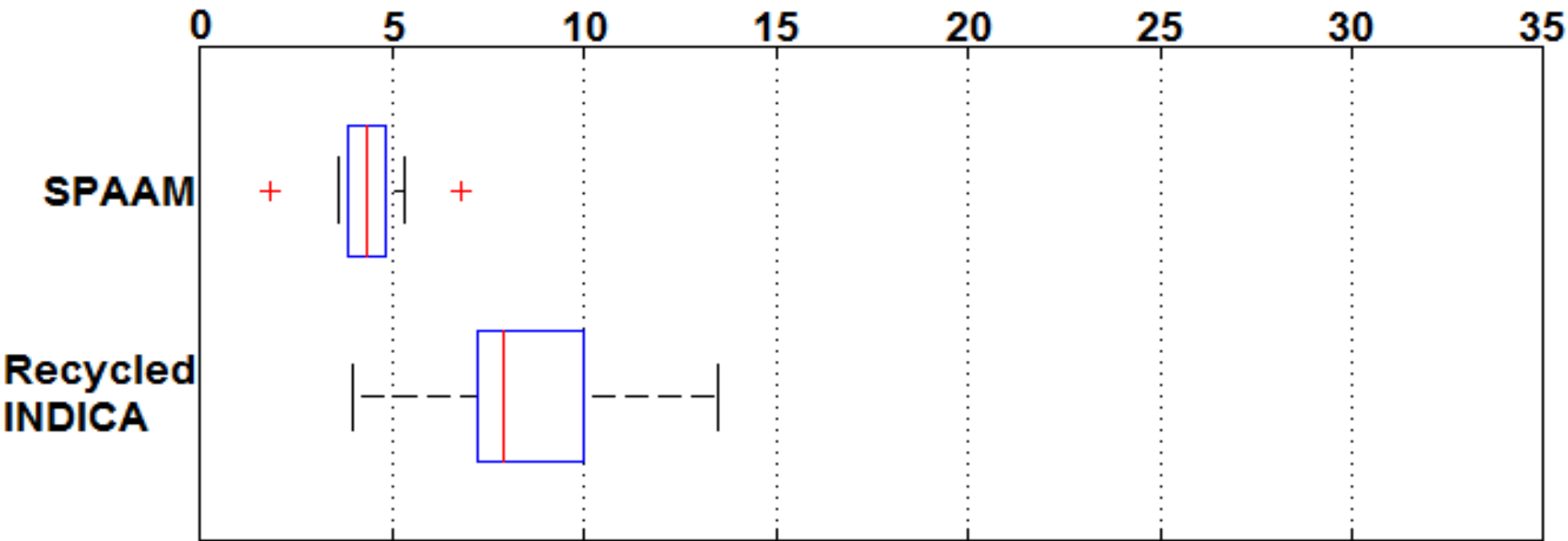


Recycled INDICA - Eye Pose Estimates (All Subjects)

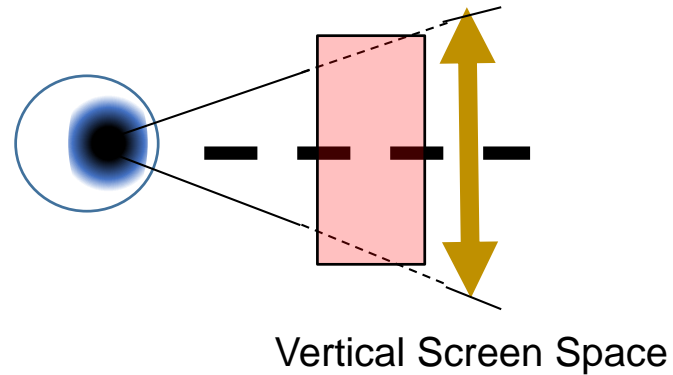
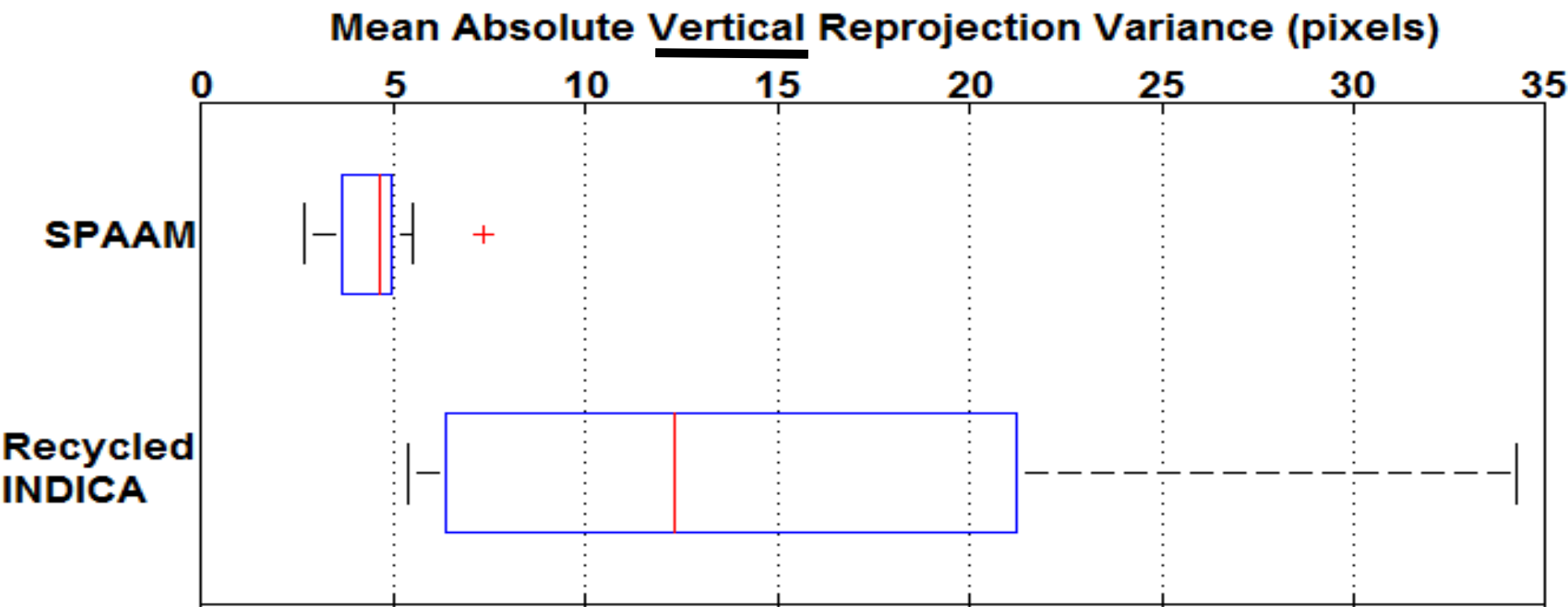


Quantitative Result – Reprojection Variance

Mean Absolute Horizontal Reprojection Variance (pixels)



Quantitative Result – Reprojection Variance



Subjective Result – Location Error

Difference in cm between perceived and actual location

0: No error (perfect registration)

+Y: Virtual perceived above

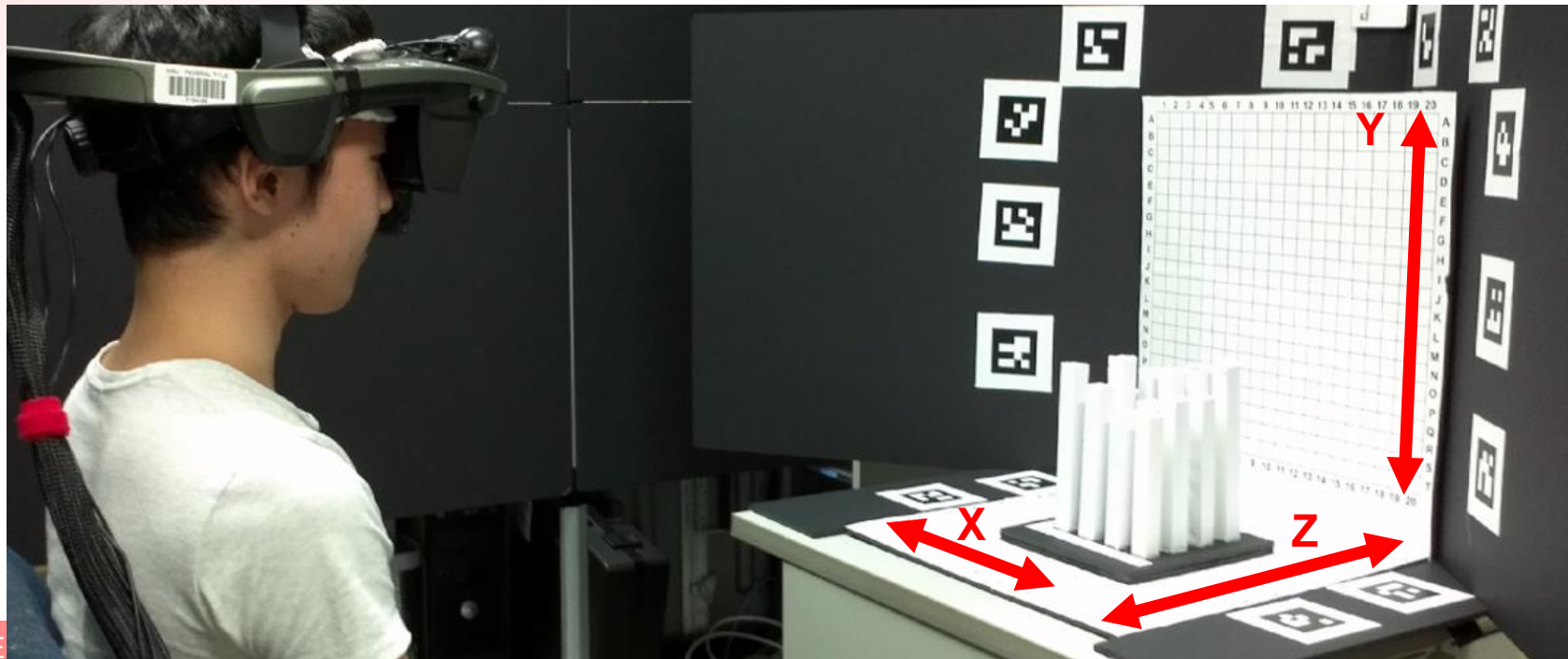
- Y: Virtual perceived below

+X: Virtual perceived to the right

- X: Virtual perceived to the left

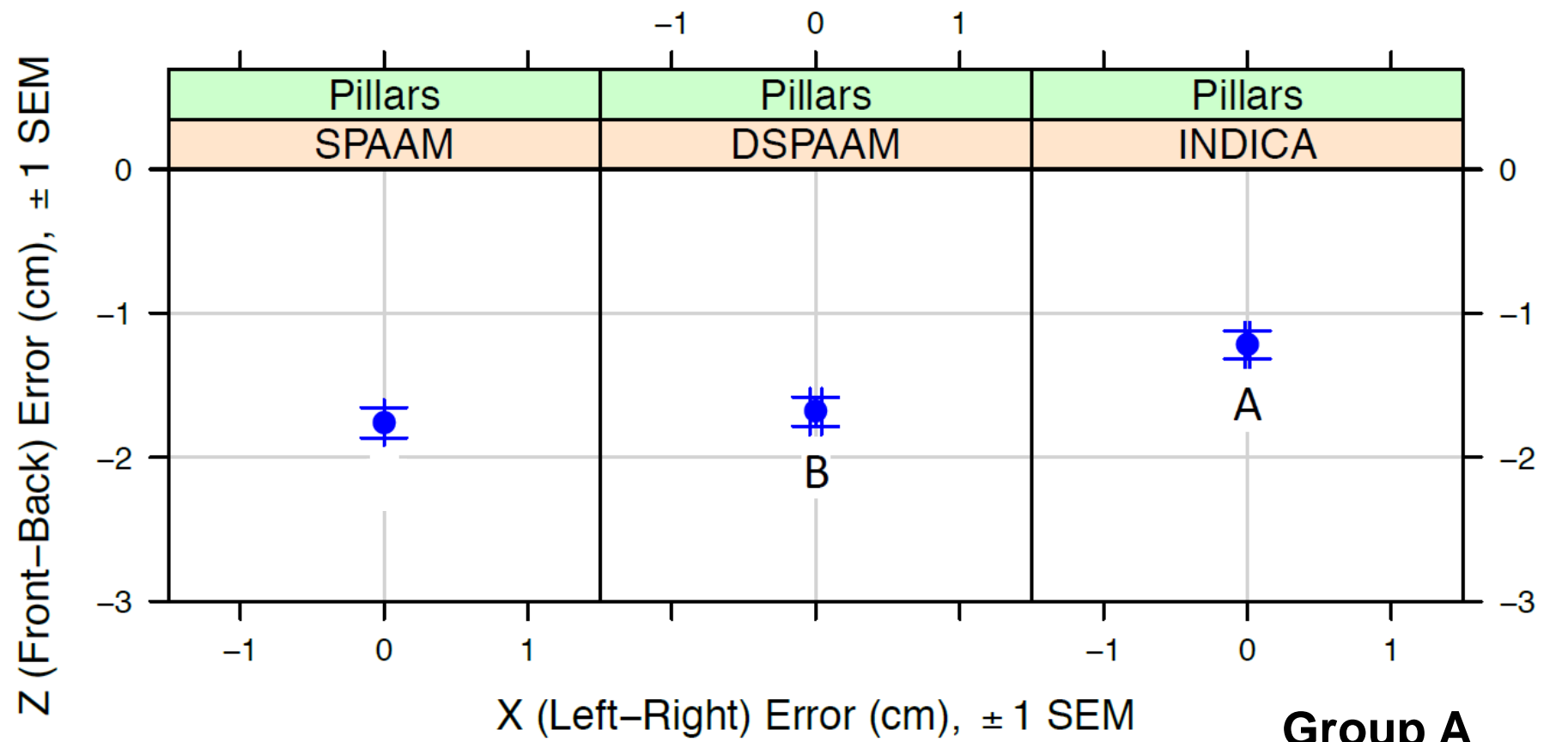
+Z: Virtual perceived further

-Z: Virtual perceived closer



Subjective Result: Location Error – Pillars

Difference Between Perceived & Actual Location



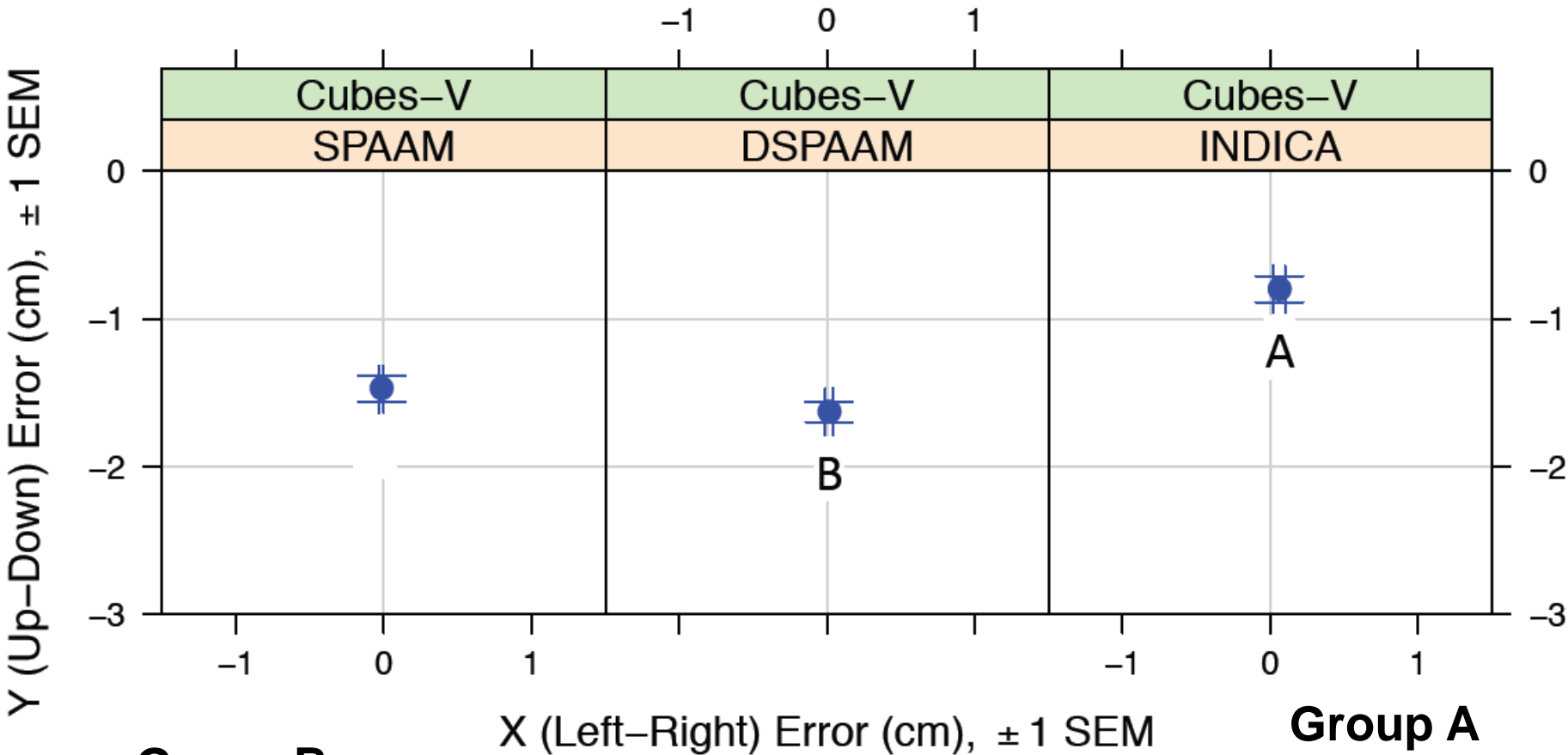
Group B
*No Significance**

Group A
Significance in Z.
 $F(2, 24) = 14.011$
 $p < .001$

* $p \leq 0.05$ Ryan REGWQ post-hoc homogeneous subset test

Subjective Result: Location Error – Cubes Vertical Grid

Difference Between Perceived & Actual Location



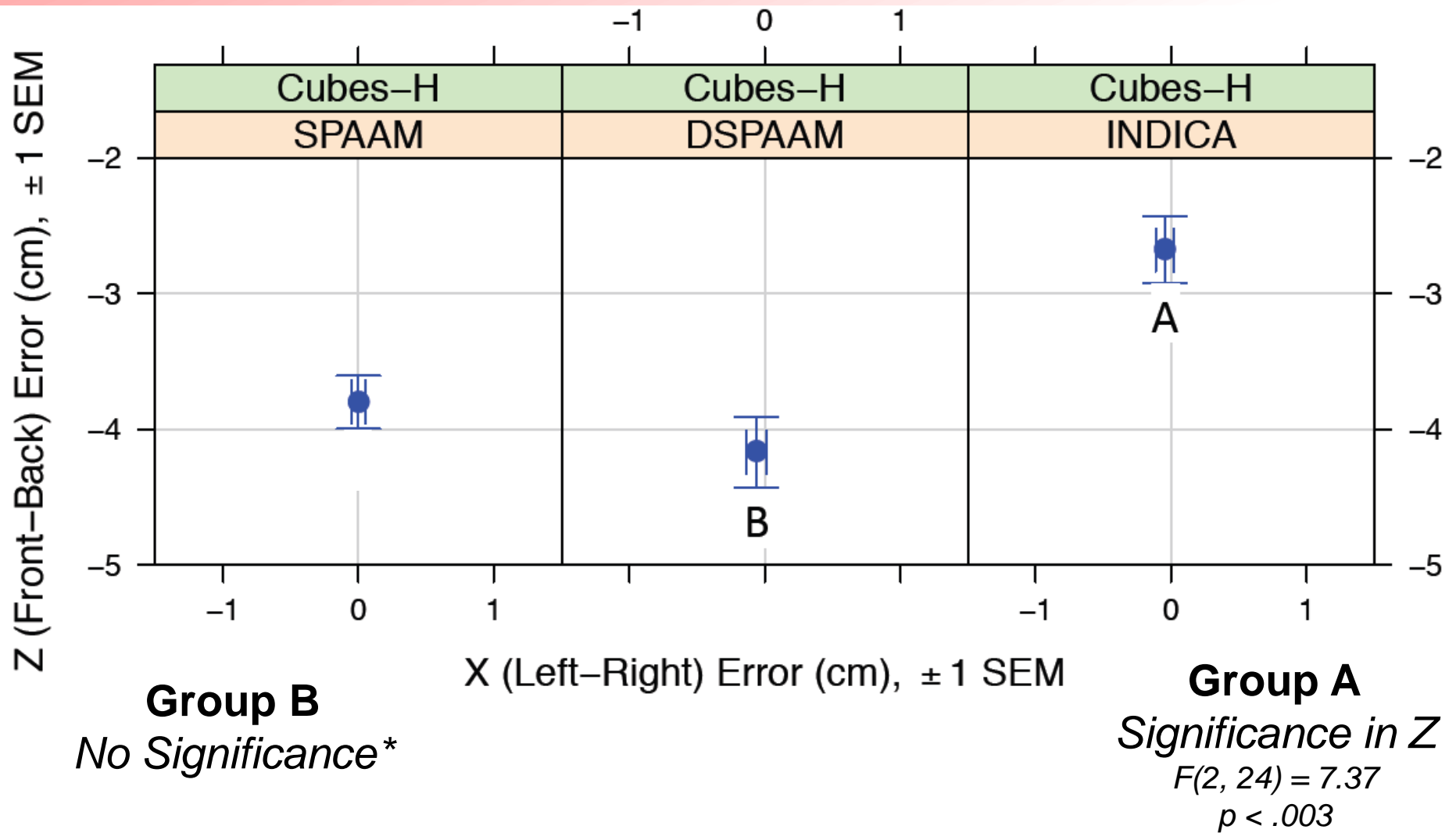
Group B
*No Significance**

Group A
Significance in Y
 $F(2, 24) = 10.96$
 $p < .0016 \epsilon = .75^{**}$

* $p \leq 0.05$ Ryan REGWQ post-hoc homogeneous subset test
**Mauchly's test indicated non-sphericity, p value adjusted by Huynh – Feldt ϵ

Subjective Result: Location Error – Cubes Horizontal Grid

Difference Between Perceived & Actual Location



* $p \leq 0.05$ Ryan REGWQ post-hoc homogeneous subset test

Subjective Result: Location Error

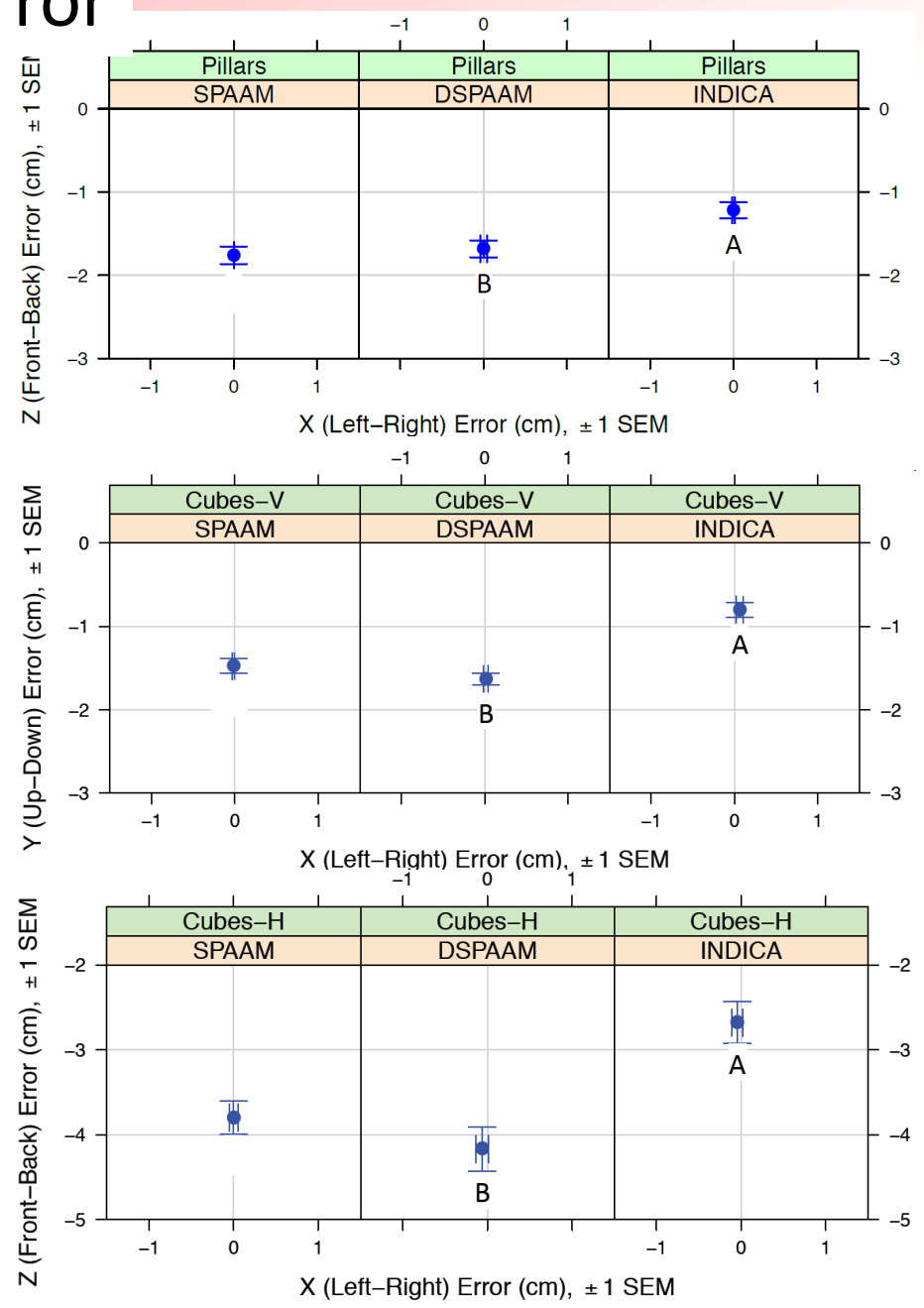
Quantitative Measures Not a Performance Prediction

No Difference SPAAM/DSPAAM

No Difference All Algorithms in X

Highest Overall Error in Z

INDICA Significantly Better Y/Z



Subjective Result: Registration Quality – Pillars

Registration Quality with Chosen Location

Group A

*No Significance**

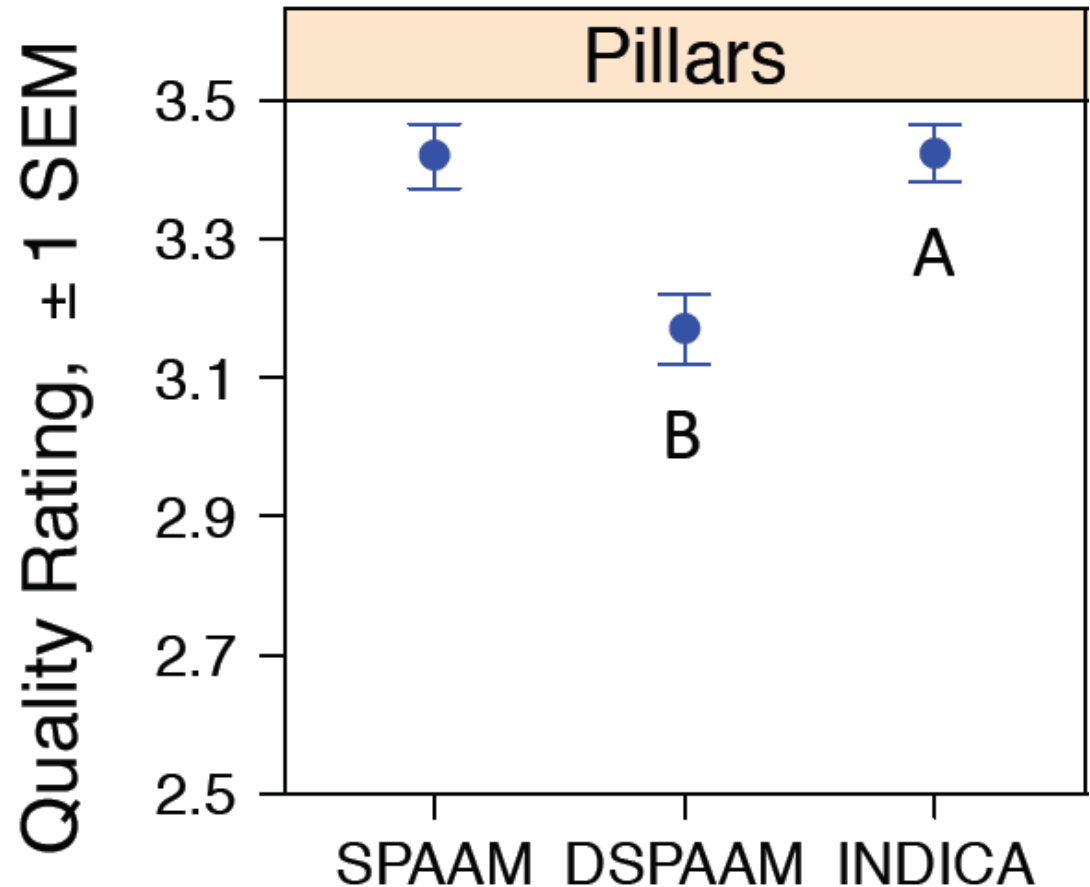
Group B

Significance in Quality

ANOVA: $F(2, 24) = 5.03, p < .015$

Friedman: $\chi^2(2) = 5.45, p < .066$

Kruskal-Wallis: $\chi^2(2) = 18.92, p < .001$



* $p \leq 0.05$ Ryan REGWQ post-hoc homogeneous subset test

Subjective Result: Registration Quality – Cubes Vertical

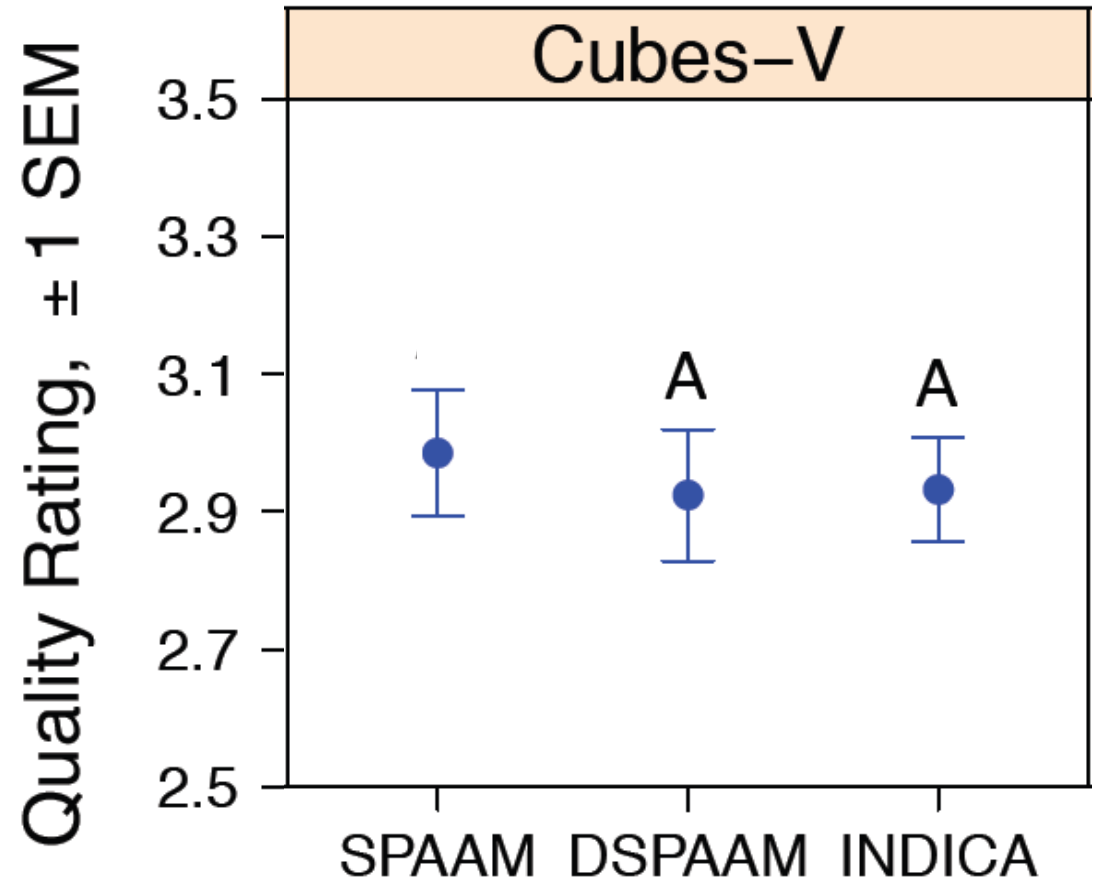
Registration Quality with Chosen Location

Group A

No Significance*

Friedman: $\chi^2(2) = .15$

Kruskal-Wallis: $\chi^2(2) = .98$



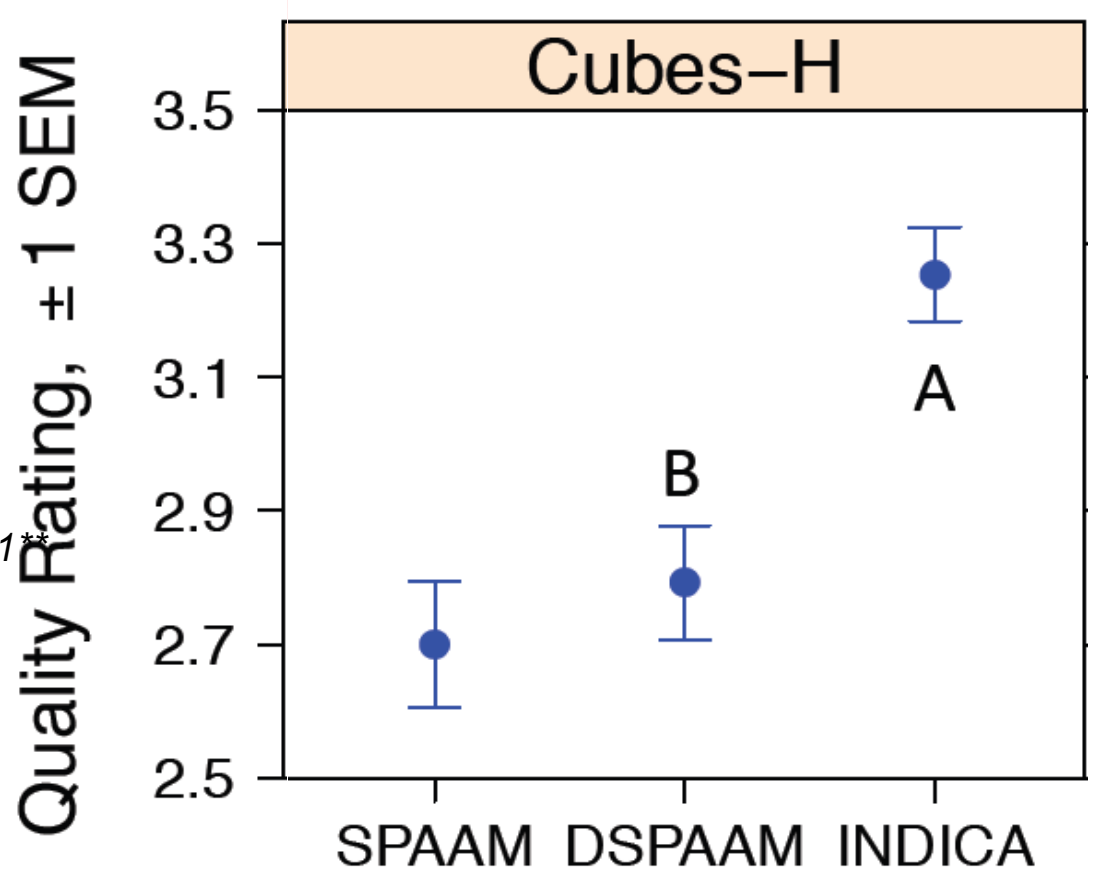
* $p \leq 0.05$ Ryan REGWQ post-hoc homogeneous subset test

Subjective Result: Registration Quality – Cubes Horizontal

Registration Quality with Chosen Location

Group B
*No Significance**

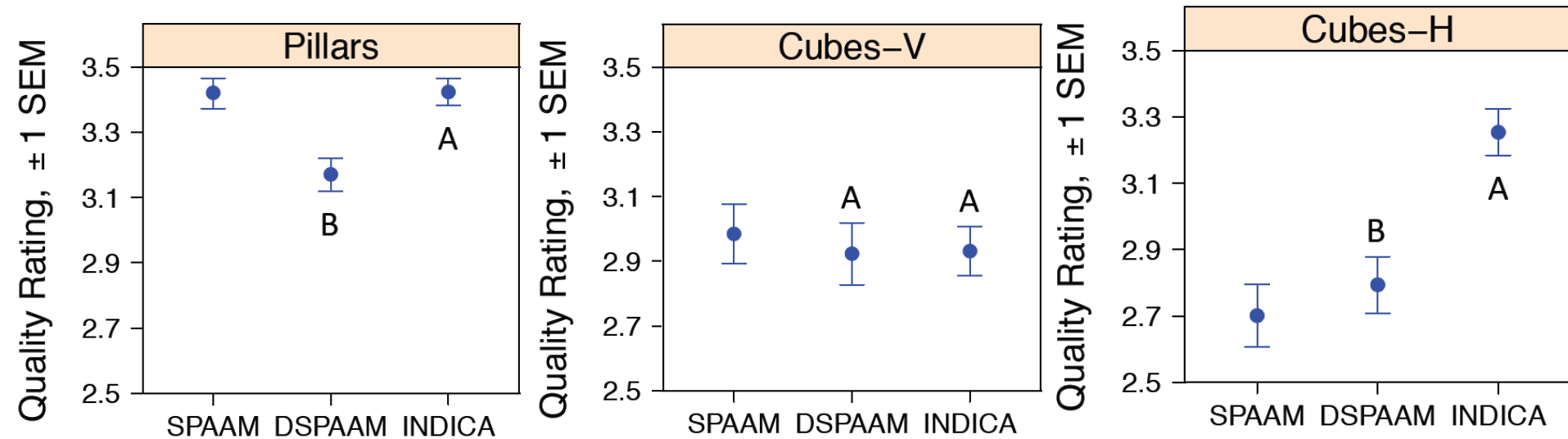
Group A
Significance in Quality
ANOVA: $F(2, 24) = 6.65, p < .013, \epsilon = .71^{**}$
Friedman: $\chi^2(2) = 13.06, p < 0.0015$
Kruskal-Wallis: $\chi^2(2) = 21.21, p < 0.001$



* $p \leq 0.05$ Ryan REGWQ post-hoc homogeneous subset test
**Mauchly's test indicated non-sphericity, p value adjusted by Huynh – Feldt ϵ

Subjective Result: Registration Quality

Registration Quality with Chosen Location



Quality Values Match Performance Measures

INDICA Quality is Equal or Better Than SPAAM

INDICA Quality Significantly Better in Z

Why Apparent Disagreement in Quantitative & Subjective?

~~Poor Eye Localization for INDICA?~~

Eye Location Values for INDICA Show Low Variance

Removal/Replacement of HMD Between Conditions

Reprojection Shows Closer to Actual Pixels Used in Alignment

INDICA Presumes a Simplistic HMD Model

Why No Significant Performance Change in SPAAM/DSPAAM?

HMD Specific Properties

Fit on User's Head

Exit Pupil Location

Resolution of Task Not High Enough to Find Significance

SPAAM / Degraded SPAAM – almost no difference

- Removal/Replacement little effect on accuracy
- Accuracy in X equal to INDICA
- Less favorable method (exit survey)

INDICA – Equal or Superior performance to SPAAM

- Significantly higher performance in Y/Z
- Significantly higher quality in Z
- **Recycled INDICA requires SPAAM intrinsics**
- Minimal requirement from user
- Less time to perform (user preferred)

Future Work

Evaluation of Full INDICA

Remove induced error from SPAAM intrinsics (Full INDICA)

Utilize more robust eye localization (Alex's presentation)

Real time update of calibration (on-line)

Binocular Task

More relevant depth cue

Verification of SPAAM Z error

Best VS Best

Comparison of best possible calibrations SPAAM/INDICA

Removal of HMD distortion (Yuta's presentation)

Improvements to SPAAM to reduce impact of user error

Special Thanks



Dr. Hirokazu Kato

Everyone at the Interactive Media Design Lab

All of the Anonymous Subjects



Dr. Goshiro Yamamoto

Support



NSF Awards: IIA-1414772, IIS-1320909, IIS-1018413



NASA Mississippi Space Grant Consortium Fellowship



European Union Seventh Framework
PITN-GA-2012-316919-EDUSAFE

Take Away

SPAAM / Degraded SPAAM – almost no difference

- Removal/Replacement little effect on accuracy
- Accuracy in X equal to INDICA
- Less favorable method (exit survey)

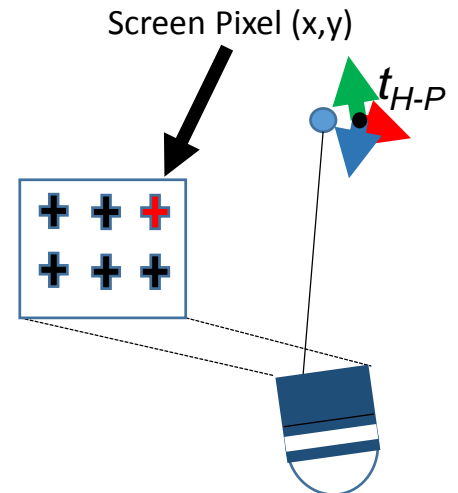
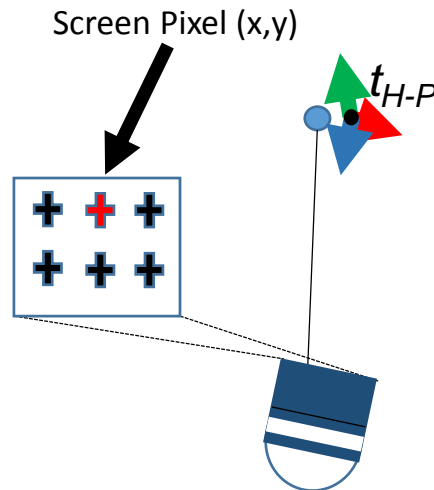
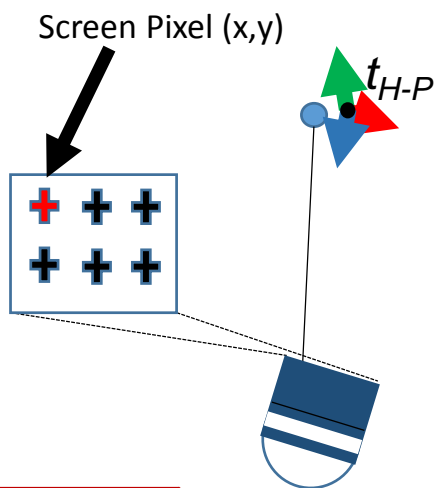
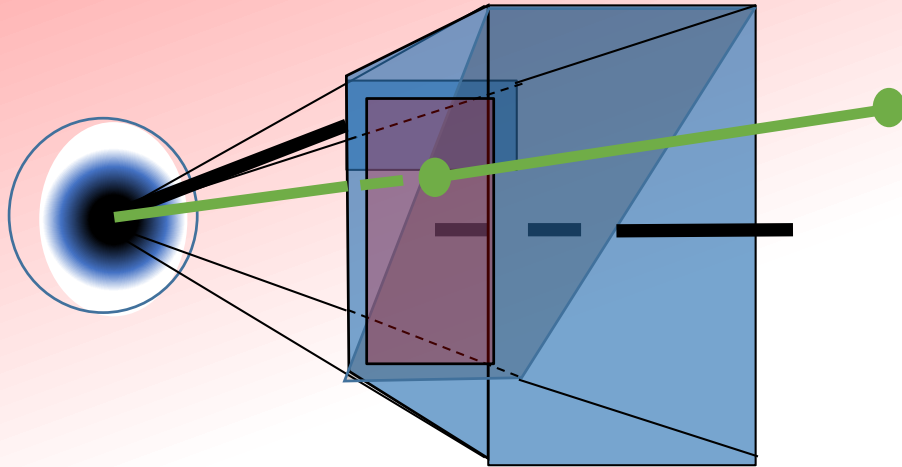
INDICA – Equal or Superior performance to SPAAM

- Significantly higher performance in Y/Z
- Significantly higher quality in Z
- **Recycled INDICA requires SPAAM intrinsics**
- Minimal requirement from user
- Less time to perform (eye measures vs alignment)

Calibration Methods

Single Point Active Alignment Method (SPAAM)

(Tuceryan & Navab, 2000)



Interaction Free Display Calibration (INDICA)

(Itoh & klinker, 2014)

Recycled Setup

Intrinsic Calib. Params.	K_E
Translation World – Eye	t_{WE}
Translation World – Screen	t_{WS}

Full Setup

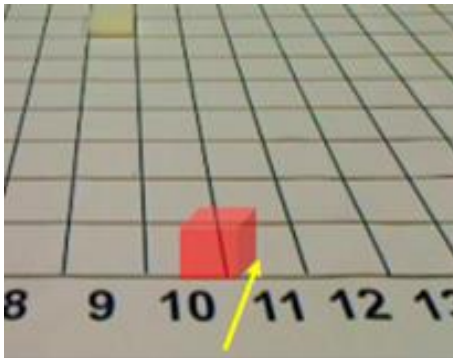
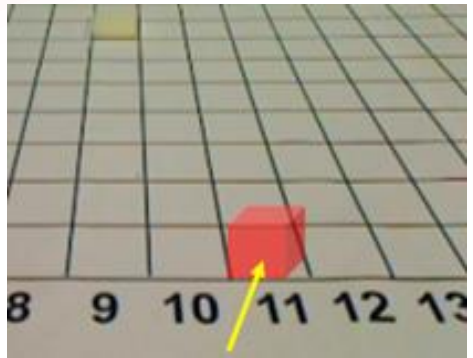
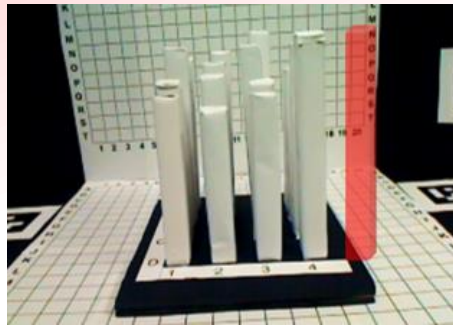
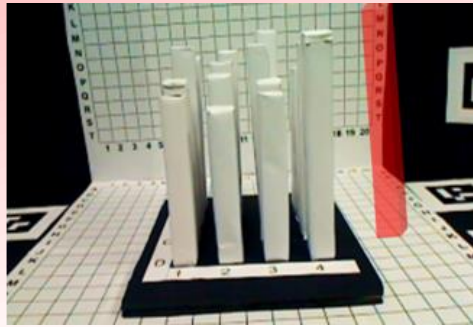
Translation World – Screen	t_{WS}
Pixel Scaling Factor	$\alpha_{(x,y)}$

Required for Both

Translation Eye -Tracker	t_{ET}
Rotation World – Screen	R_{WS}
Rotation World – Tracker	R_{WT}
Translation World – Tracker	t_{WT}

Registration Quality Comparison

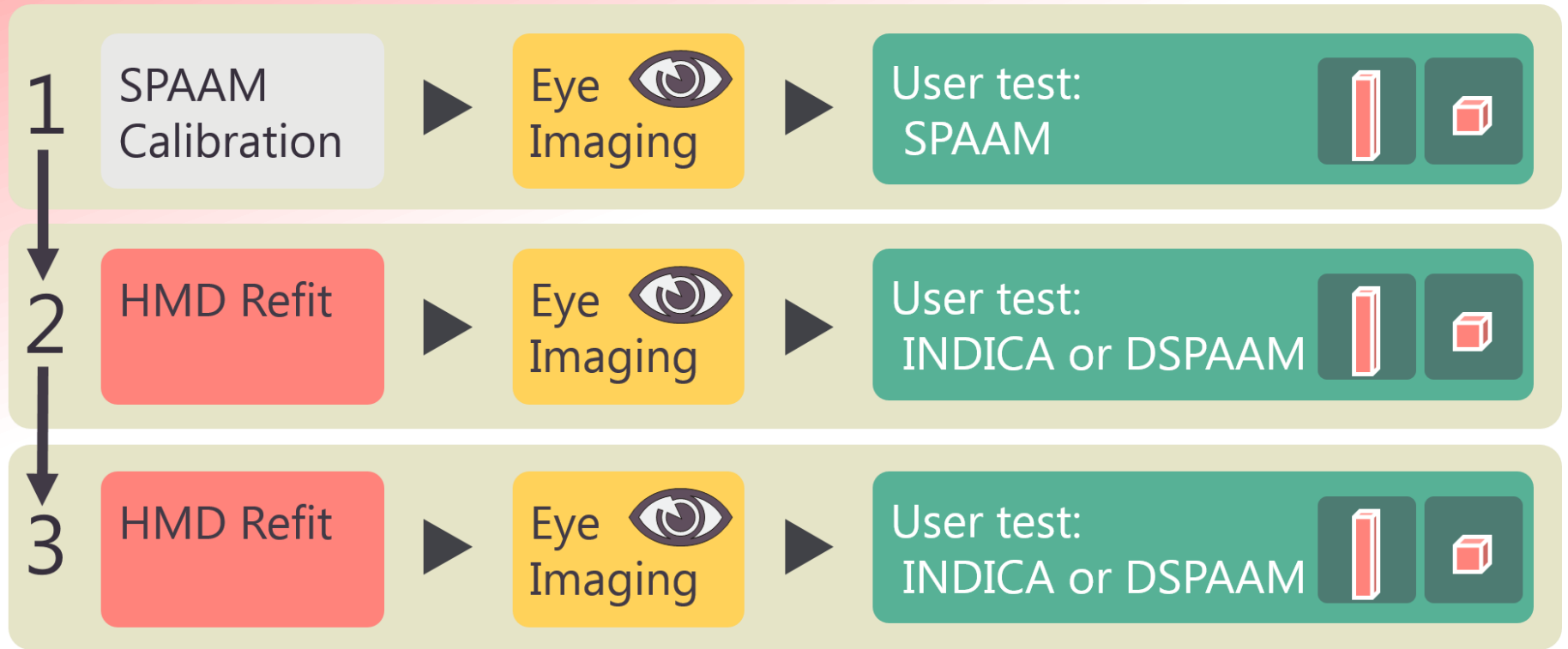
Perceived VS Intended Location



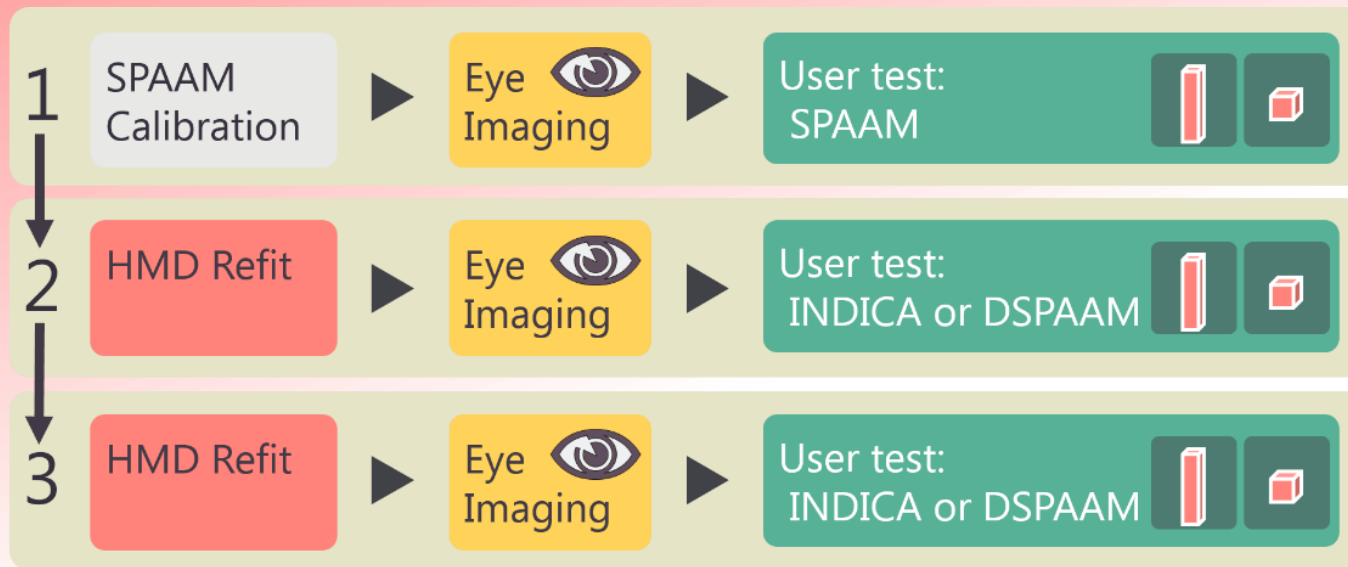
- SPAAM
- Degraded SPAAM:
Reuse of SPAAM result
after HMD replacement
- Recycled INDICA:
Reuse intrinsic values
from SPAAM calibration

Evaluation Study

Degraded SPAAM & Recycled INDICA rely on values from SPAAM calibration



Evaluation Study



Within-Subjects Design

3 Alg. X 2 Tasks = 6 Conditions

16 Pillar Trials/20 Cube Trials per cond.

13 Subjects (6 male / 7 female)

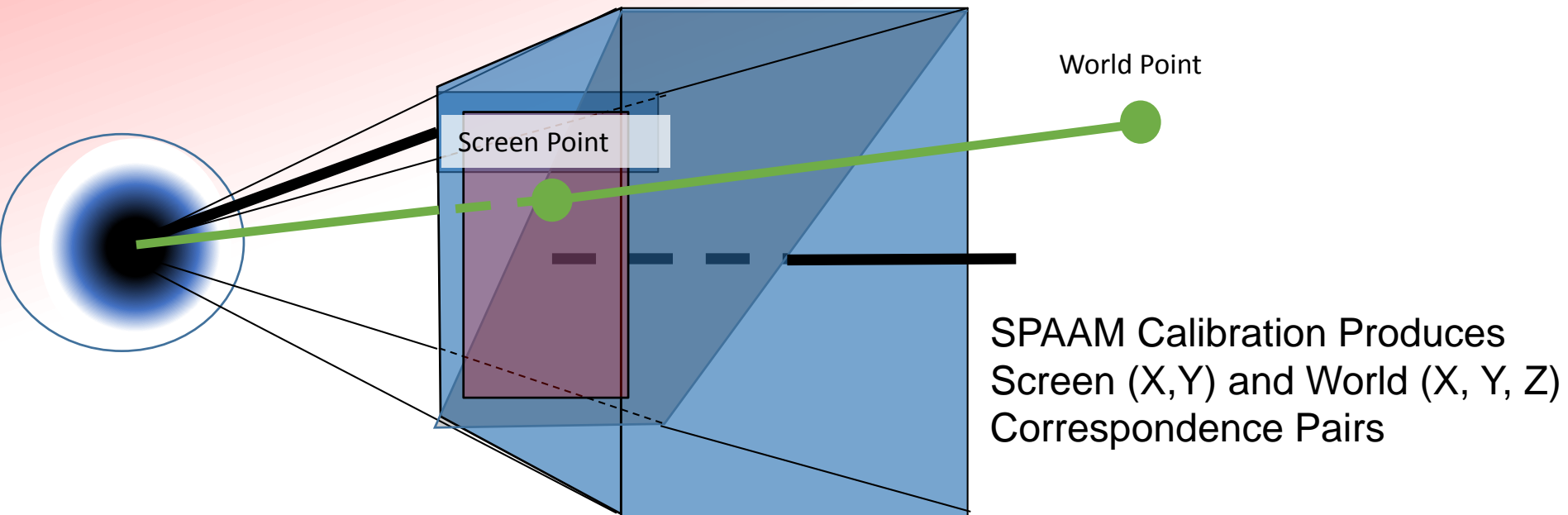
22 – 26 years of age

No prior experience with HMD's

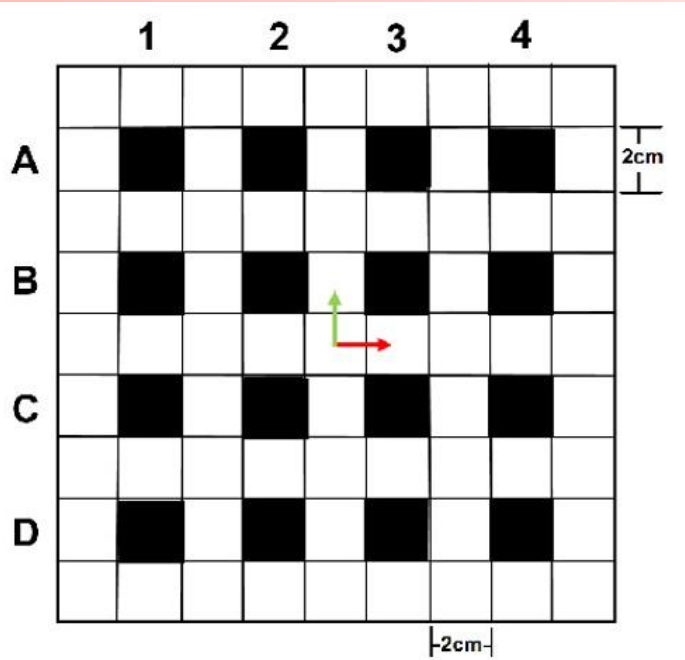
Order of D. SPAAM and R. INDICA, as well as Cube/Pillar task presentation, distributed such that no two subjects experienced the same sequence

Experimental Results & Discussion

Quantitative Measures – Reprojection Estimates



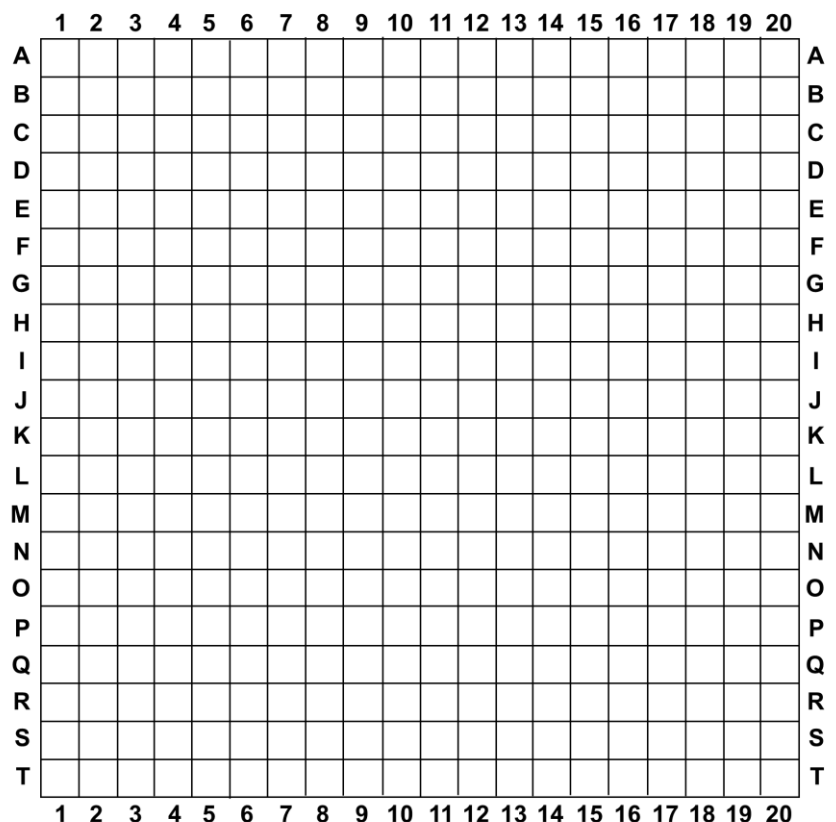
Evaluation Tasks



Vertical Axis: A – Z (A-D)
Horizontal Axis: 1 – 20 (1-4)

Discrete 2Axis Grids

Each Square 2cm x 2cm



Subjective Measures – Registration Quality

Verbal Response from Subject (1-4/5)

Normalized both scales (Pillars/Cubes) into 1-4

Quality values are **not** Likert scale data – provided images create reference for quality range

Statistical Analysis on Quality Data:

- ANOVA
- Friedman
 - Less power compared to ANOVA
 - Reduces number of considered data points
- Kruskal-Wallis
 - More power compared to ANOVA
 - Does not consider within subject design

Performance Summary – Quantitative Measures

SPAAM – Extrinsic/Reprojection Values Match Previous Findings

- Extrinsic show Higher variance along Z axis
- Low reprojection variance

SPAAM result closely reproduces SPAAM alignments

INDICA – Stable Eye Estimates / High Reprojection Variance.

- Manual Limbus Detection Required for best estimates
- Eye position in Z more consistent
- Higher reprojection variance

Reprojection not indication of result quality

INDICA reprojection shows actual pixel used (?)