Hochschulbibliographie

Name: Informatik 6 - Lehrstuhl für Echtzeitsysteme und Robotik (Prof. Knoll)

Occurrences:
   - Hochschulbibliographie > 2016 > Fakultäten > Informatik
entries:


[2/87]: Sunderrajan, Abhinav; Viswanathan, Vaisagh; Cai, Wentong; Knoll, Alois, Traffic State Estimation Using Floating Car Data, Procedia Computer Science, 2016, 80, 2008-2018


[4/87]: Litescu, Sorina Costache; Viswanathan, Vaisagh; Aydt, Heiko; Knoll, Alois, Information Dynamics in Transportation Systems with Traffic Lights Control, Procedia Computer Science, 2016, 80, 2019-2029


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[9/87]: Booklet | Brain-inspired intelligent robotics: The intersection of robotics and neuroscience sciences, Science, 2016, 354, 6318, 1445.2-1445

[10/87]: Richter, Christoph; Jentzsch, Soren; Hostettler, Rafael; Garrido, Jesus A.; Ros, Eduardo; Knoll, Alois; Rohrbain, Florian; van der Smagt, Patrick; Conradt, Jorg, Musculoskeletal Robots: Scalability in Neural Control, IEEE Robotics & Automation Magazine, 2016, 23, 4, 128-137


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[21/87]: Vandesompele, Alexander; Walter, Florian; Rohrbain, Florian, Neuro-evolution of spiking neural networks on SpiNNaker neuromorphic hardware, 2016 IEEE Symposium Series on Computational Intelligence
(SSCI), IEEE, 2016


[24/87]: Brandenbourger, Benjamin and Vathoopan, Milan and Zoitl, Alois, Engineering of Automation Systems using a Metamodel implemented in AutomationML, Industrial Informatics (INDIN), 2016 IEEE 14th International Conference on, 2016

[25/87]: Haage, Mathias; Profanter, Stefan; Kessler, Ingmar; Perzylo, Alexander; Somani, Nikhil; Sörnmo, Olof; Karlsson, Martin; Robertz, Sven Gestegård; Nilsson, Klas; Resch, Ludovic; Marti, Michael, On cognitive robot woodworking in SMeRobotics, International Symposium on Robotics (ISR), 2016


[30/87]: Feihu Zhang and Alois Knoll, Vehicle detection based on probability hypothesis density filter, Sensors, 2016


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