Fakultät für Informatik

Name:
1996

Occurences:
· Einrichtungen > Fakultäten > Fakultät für Informatik > Lehrstühle der Informatik > Informatik 6 - Lehrstuhl für Echtzeitsysteme und Robotik (Prof. Knoll)
Entries:

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[3/19]: Max, Fischer, Aufgabenpezifikation und Bahnplanung für kooperierende Manipulatoren, 1996, 163 Seiten


[7/19]: Fuchs, Florian, Multi-Agent Collaboration in Competitive Scenarios, Proceedings of the 15th Workshop of the UK Planning and Scheduling Special Interest Group, 1996


[9/19]: Knoll, Alois; Schröder, Ralf; Wolfram, And're, Fusion of Data from Fuzzy Integral-Based Active and Passive Colour Stereo Vision Systems for Correspondence Identification, Proceedings of the VIII European Signal Processing Conference, EUSIPCO-96, 1996


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[16/19]: Zhang, Jianwei; Knoll, Alois, Constructing Fuzzy Controllers with B-Spline Models, Proceedings of the IEEE International Conference on Fuzzy Systems, 1996

[17/19]: Zhang, Jianwei; Wille, Frank; Knoll, Alois, Fuzzy Logic Rules for Mapping Sensor Data to Robot Control, Proc. EUROBOT'96 - 1st Euromicro Workshop on Advanced Mobile Robots, 1996

[18/19]: Zhang, Jianwei; Wille, Frank; Knoll, Alois, Modular Design of Fuzzy Controller Integrating Deliberative and Reactive Strategies, Proceedings of the IEEE International Conference on Robotics and Automation, 1996