Fakultät für Informatik

Name: 2009

Occurrences:
- Einrichtungen > Fakultäten > Fakultät für Informatik > Lehrstühle der Informatik > Informatik 6 - Lehrstuhl für Echtzeitsysteme und Robotik (Prof. Knoll)
entries:

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[3/100]: Rickert, Markus; Kassecker, Michael; Knoll, Alois, Aufgabenbeschreibung mit verhaltensbasierter Roboterteuerung und natürlicher Kommunikation, Munich, Germany, 2009

[4/100]: Hellerer, Matthias, Potential field based position control for Mitsubishi RV-6S industrial robots, 2009


[8/100]: Althoff, M.; Stursberg, O.; Buss, M., Safety Assessment of Driving Behavior in Multi-Lane Traffic for Autonomous Vehicles, Proc. of the IEEE Intelligent Vehicles Symposium, 2009


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[18/100]: Buckl, Christian; Sommer, Stephan; Scholz, Andreas; Knoll, Alois; Kemper, Alfons; Heuer, Jörg; Schmitt, Anton, Services to the Field: An Approach for Resource Constrained Sensor/Actor Networks, The Fourth Workshop on Service Oriented Architectures in Converging Networked Environments (SOCNE 2009) - extended version, IEEE, 2009

[20/100]: Castellini, Claudio; Smagt, Patrick van der, Surface EMG in Advanced Hand Prosthetics, Biological Cybernetics, 2009, 100, 1, 35--47

[21/100]: Cheng, Chih-Hong; Buckl, Christian; Esparza, Javier; AloisKnoll, Modeling and Verification for Timing Satisfaction of Fault-Tolerant Systems with Finiteness, Proceedings of the 13th IEEE/ACM International Symposium on Distributed Simulation and Real Time Applications (DS-RT'09), IEEE, 2009

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[23/100]: Cheng, Chih-Hong; Knoll, Alois; Esparza, Javier; Buckl, Christian; Chen, Yang, Examining Robotic Systems with Shape-Adjustable Manipulators under Dynamic Environments: From Simulation to Verification, Proceedings of the 8th IEEE International Symposium on Computational Intelligence in Robotics and Automation (CIRA'09), IEEE, 2009

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[29/100]: Flores-Campos, J.A.; Dean-Le'on, E.C.; Palacios-Montufar, C., Robot Motion Planning for Multiple Moving Objects Interception with constant acceleration, VII Congreso Internacional sobre Innovacion y Desarrollo Tecnologico CIINDET, 2009

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