# EXISTENCE THEOREMS FOR MULTIDIMENSIONAL GENERALIZED MOMENT REPRESENTATIONS 

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We establish the conditions for the existence of multidimensional generalized moment representations.

In 1981, Dzyadyk [1] proposed a method of generalized moment representations, which later turned into an efficient tool for the construction and investigation of rational approximations of special functions (see [2]).

Definition 1 [1]. A generalized moment representation of the number sequence of complex numbers $\left\{s_{k}\right\}_{k \in \mathbb{Z}_{+}}$ on the product of linear spaces $\mathcal{X} \times \mathcal{Y}$ is defined as a two-parameter collection of equalities

$$
\begin{equation*}
s_{k+j}=\left\langle x_{k}, y_{j}\right\rangle, \quad k, j \in \mathbb{Z}_{+}, \tag{1}
\end{equation*}
$$

where $\left\{x_{k}\right\}_{k \in \mathbb{Z}_{+}} \subset \mathcal{X},\left\{y_{j}\right\}_{j \in \mathbb{Z}_{+}} \subset \mathcal{Y}$, and $\langle.,$.$\rangle is a bilinear form defined on \mathcal{X} \times \mathcal{Y}$.
The following result concerning the conditions of existence of mappings of the form (1) was established in [3]:
Theorem $1[3,4]$. Suppose that $\mathcal{H}$ is an infinite-dimensional separable Hilbert space and $\left\{e_{k}\right\}_{k \in \mathbb{Z}_{+}}$is an orthonormal basis in this space. In order that a sequence $\left\{s_{k}\right\}_{k \in \mathbb{Z}_{+}}$have a generalized moment representation of the form (1), where

$$
\langle x, y\rangle=\sum_{m=0}^{\infty}\left(x, e_{m}\right)\left(y, e_{m}\right)
$$

and the elements $x_{k}, k \in \mathbb{Z}_{+}$, and $y_{j}, j \in \mathbb{Z}_{+}$, have the form

$$
\begin{equation*}
x_{k}=\sum_{m=0}^{k} \alpha_{m}^{(k)} e_{m}, \quad \alpha_{k}^{(k)} \neq 0, \quad k \in \mathbb{Z}_{+} ; \quad y_{j}=\sum_{m=0}^{j} \beta_{m}^{(j)} e_{m}, \quad \beta_{j}^{(j)} \neq 0, \quad j \in \mathbb{Z}_{+}, \tag{2}
\end{equation*}
$$

it is necessary and sufficient that all Hankel determinants of this sequence

$$
H_{N}:=H_{0, N}=\operatorname{det}\left\|s_{k+j}\right\|_{k, j=0}^{N}, \quad N \in \mathbb{Z}_{+},
$$

be nonzero.
Moreover, the relations

$$
\begin{equation*}
\alpha_{p}^{(p)} \beta_{p}^{(p)}=\frac{H_{p}}{H_{p-1}}, \quad p \in \mathbb{Z}_{+}, \quad H_{-1}:=1 \tag{3}
\end{equation*}
$$

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are true and if the sequences of nonzero numbers $\left\{\alpha_{p}^{(p)}\right\}_{p \in \mathbb{Z}_{+}}$and $\left\{\beta_{p}^{(p)}\right\}_{p \in \mathbb{Z}_{+}}$satisfying (3) are fixed, then the remaining coefficients in (2) are uniquely determined by the formulas

$$
\begin{align*}
& \alpha_{p}^{(k)}=\alpha_{k}^{(k)} \frac{S_{k}\left(\begin{array}{ccccc}
0 & 1 & \ldots & p-1 & k \\
0 & 1 & \ldots & p-1 & p
\end{array}\right)}{H_{p}}, \quad p=\overline{0, k}, \quad k \in \mathbb{Z}_{+},  \tag{4}\\
& \beta_{p}^{(j)}=\beta_{j}^{(j)} \frac{S_{j}\left(\begin{array}{lllll}
0 & 1 & \ldots & p-1 & p \\
0 & 1 & \ldots & p-1 & j
\end{array}\right)}{H_{p}}, \quad p=\overline{0, j}, \quad j \in \mathbb{Z}_{+} \tag{5}
\end{align*}
$$

where $S_{N}\left(\begin{array}{cccc}l_{0} & l_{1} & \ldots & l_{r} \\ n_{0} & n_{1} & \ldots & n_{r}\end{array}\right)$ are minors of the matrix

$$
S_{N}=\left\|s_{k+j}\right\|_{k, j=0}^{N}=\left\|\begin{array}{cccc}
s_{0} & s_{1} & \ldots & s_{N} \\
s_{1} & s_{2} & \ldots & s_{N+1} \\
\ldots & \ldots & \ldots & \ldots \\
s_{N} & s_{N+1} & \ldots & s_{2 N}
\end{array}\right\|, \quad N \in \mathbb{Z}_{+}
$$

with the numbers of columns $l_{0}, l_{1}, \ldots, l_{r}$ and the numbers of rows $n_{0}, n_{1}, \ldots, n_{r}$ for $l_{m} \leq N$ and $n_{m} \leq N$, $m=\overline{0, r}$.

Later, the method of generalized moment representations was developed for two- and multidimensional sequences [5,6]. This led to the problem of determination of the conditions of existence of generalized multidimensional moment representations.

Definition 2 [5]. A generalized moment representation of the two-dimensional number sequence

$$
\left\{s_{k, m}\right\}_{k, m \in \mathbb{Z}_{+}}
$$

on the product of linear spaces $\mathcal{X} \times \mathcal{Y}$ is defined as a collection of equalities

$$
s_{k+j, m+n}=\left\langle x_{k, m}, y_{j, n}\right\rangle, \quad k, j, m, n \in \mathbb{Z}_{+},
$$

where $\left\{x_{k, m}\right\}_{k, m \in \mathbb{Z}_{+}} \subset \mathcal{X},\left\{y_{j, n}\right\}_{j, n \in \mathbb{Z}_{+}} \subset \mathcal{Y}$, and $\langle\cdot, \cdot\rangle$ is a bilinear form on $\mathcal{X} \times \mathcal{Y}$.
Prior to formulating the corresponding result, we recall that the Cantor numbering function

$$
c(x, y)=\frac{(x+y)^{2}+x+3 y}{2}
$$

bijectively maps $\mathbb{Z}_{+}^{2}$ onto $\mathbb{Z}_{+}$(see, e.g., [7, p. 13]). Moreover, there exist inverse functions $l, r: \mathbb{Z}_{+} \rightarrow \mathbb{Z}_{+}$, such that

$$
c(l(n), r(n)) \equiv n, \quad l(c(m, n))=m, \quad r(c(m, n))=n \quad \forall m, n \in \mathbb{Z}_{+}
$$

By using the two-dimensional sequence $\left\{s_{k, m}\right\}_{k, m \in \mathbb{Z}_{+}}$, we can define a one-dimensional sequence $\left\{\tilde{s}_{p}\right\}_{p \in \mathbb{Z}_{+}}$ such that

$$
\begin{gather*}
s_{k, m}=\tilde{s}_{c(k, m)}, \quad(k, m) \in \mathbb{Z}_{+}^{2},  \tag{6}\\
\tilde{s}_{p}=s_{l(p), r(p)}, \quad p \in \mathbb{Z}_{+} .
\end{gather*}
$$

We also construct the sequence of matrices

$$
\begin{equation*}
\tilde{S}_{N}=\left\|s_{l(k)+l(j), r(k)+r(j)}\right\|_{k, j=0}^{N}, \quad N \in \mathbb{Z}_{+} \tag{7}
\end{equation*}
$$

In the indicated terms, we can formulate the following result:
Theorem 2. Suppose that $\mathcal{H}$ is an infinite-dimensional separable Hilbert space and that $\left\{e_{k}\right\}_{k \in \mathbb{Z}_{+}}$is an orthonormal basis in this space. In order that a sequence $\left\{s_{k, m}\right\}_{k, m \in \mathbb{Z}_{+}}$possess a generalized moment representation of the form

$$
\begin{equation*}
s_{k+j, m+n}=\left\langle x_{k, m}, y_{j, n}\right\rangle, \quad k, j, m, n \in \mathbb{Z}_{+} \tag{8}
\end{equation*}
$$

where

$$
\langle x, y\rangle=\sum_{m=0}^{\infty}\left(x, e_{m}\right)\left(y, e_{m}\right)
$$

and the elements $\left\{x_{k, m}\right\}_{k, m \in \mathbb{Z}_{+}} \subset \mathcal{X}$ and $\left\{y_{j, n}\right\}_{j, n \in \mathbb{Z}_{+}} \subset \mathcal{X}$ have the form

$$
\begin{align*}
x_{k, m}=\sum_{p=0}^{c(k, m)} \alpha_{p}^{(k, m)} e_{p}, & \alpha_{c(k, m)}^{(k, m)} \neq 0, \quad(k, m) \in \mathbb{Z}_{+}^{2},  \tag{9}\\
y_{j, n} & =\sum_{p=0}^{c(j, n)} \beta_{p}^{(j, n)} e_{p}, \tag{10}
\end{align*} \quad \beta_{c(j, n)}^{(j, n)} \neq 0, \quad(j, n) \in \mathbb{Z}_{+}^{2}, ~ l, ~ l
$$

it is necessary and sufficient that all determinants $\tilde{H}_{N}=\operatorname{det} \tilde{S}_{N}, N \in \mathbb{Z}_{+}$, of the matrices given by relations (7) be nonzero. Moreover, the relations

$$
\begin{equation*}
\alpha_{c(k, m)}^{(k, m)} \beta_{c(k, m)}^{(k, m)}=\frac{\tilde{H}_{c(k, m)}}{\tilde{H}_{c(k, m)-1}}, \quad(k, m) \in \mathbb{Z}_{+}^{2}, \quad \tilde{H}_{-1}:=1 \tag{11}
\end{equation*}
$$

are true and if the sequences of nonzero numbers

$$
\left\{\alpha_{p}^{(l(p), r(p))}\right\}_{p \in \mathbb{Z}_{+}} \quad \text { and } \quad\left\{\beta_{p}^{(l(p), r(p))}\right\}_{p \in \mathbb{Z}_{+}}
$$

satisfying (11) are fixed, then the other coefficients in (9) and (10) are uniquely determined by the relations

$$
\alpha_{p}^{(k, m)}=\alpha_{c(k, m)}^{(k, m)} \frac{\tilde{S}_{c(k, m)}\left(\begin{array}{ccccc}
0 & 1 & \ldots & p-1 & c(k, m)  \tag{12}\\
0 & 1 & \ldots & p-1 & p
\end{array}\right)}{\tilde{H}_{c(k, m)}}, \quad p=\overline{0, c(k, m)}, \quad(k, m) \in \mathbb{Z}_{+}^{2},
$$

$$
\beta_{p}^{(j, n)}=\beta_{c(j, n)}^{(j, n)} \frac{\tilde{S}_{c(j, n)}\left(\begin{array}{ccccc}
0 & 1 & \ldots & p-1 & p  \tag{13}\\
1 & 2 & \ldots & p-1 & c(j, n)
\end{array}\right)}{\tilde{H}_{c(j, n)}}, \quad p=\overline{0, c(j, n)}, \quad(j, n) \in \mathbb{Z}_{+}^{2}
$$

Proof. It is easy to see that, in view of (9) and (10), equalities (8) are equivalent to the equalities

$$
\begin{equation*}
s_{k+j, m+n}=\sum_{p=0}^{\min \{c(k, m), c(j, n)\}} \alpha_{p}^{(k, m)} \beta_{p}^{(j, n)}, \quad k, m, j, n \in \mathbb{Z}_{+}, \tag{14}
\end{equation*}
$$

and, in turn, equalities (14) are equivalent to a family of matrix equalities

$$
\tilde{S}_{N}=A_{N} \cdot B_{N}, \quad N=\overline{0, \infty},
$$

where $A_{N}$ is a lower triangular matrix of the form

$$
A_{N}=\left\|a_{j, k}\right\|_{k, j=0}^{N}, \quad a_{j, k}= \begin{cases}\alpha_{j}^{(l(k), r(k))} & \text { for } k \geq j, \\ 0 & \text { for } k<j,\end{cases}
$$

and $B_{N}$ is an upper triangular matrix of the form

$$
B_{N}=\left\|b_{j, k}\right\|_{k, j=0}^{N}, \quad b_{j, k}= \begin{cases}0 & \text { for } k>j, \\ \beta_{j}^{(l(k), r(k))} & \text { for } k \leq j\end{cases}
$$

Therefore,

$$
\tilde{H}_{N}=\operatorname{det} \tilde{S}_{N}=\prod_{p=0}^{N} \alpha_{p}^{(l(p), r(p))} \cdot \prod_{q=0}^{N} \beta_{q}^{(l(q), r(q))} \neq 0 .
$$

This yields the necessity of the assertion of the theorem. Its sufficiency is a corollary of the theorem on factorization of a nonsingular matrix in triangular factors (see [8, p. 50]).

Similarly, we can establish a condition for the existence of $d$-dimensional generalized moment representations.
Definition 3 [6]. A generalized moment representation of a d-dimensional number sequence $\left\{s_{\mathbf{k}}\right\}_{\mathbf{k} \in \mathbb{Z}_{+}^{d}}$ on the product of linear spaces $\mathcal{X} \times \mathcal{Y}$ is defined as a collection of equalities

$$
s_{\mathbf{k}+\mathbf{j}}=\left\langle x_{\mathbf{k}}, y_{\mathbf{j}}\right\rangle, \quad \mathbf{k}, \mathbf{j} \in \mathbb{Z}_{+}^{d},
$$

where $\left\{x_{\mathbf{k}}\right\}_{\mathbf{k} \in \mathbb{Z}_{+}^{d}} \subset \mathcal{X},\left\{y_{\mathbf{j}}\right\}_{\mathbf{j} \in \mathbb{Z}_{+}^{d}} \subset \mathcal{Y}$, and $\langle\cdot, \cdot\rangle$ is a bilinear form on $\mathcal{X} \times \mathcal{Y}$.
It is known (see [7, p. 14]) that one can find a function

$$
c^{d}: \mathbb{Z}_{+}^{d} \rightarrow \mathbb{Z}_{+}
$$

that bijectively maps $\mathbb{Z}_{+}^{d}$ onto $\mathbb{Z}_{+}$and, in addition, the inverse functions $l_{1}, l_{2}, \ldots, l_{d}: \mathbb{Z}_{+} \rightarrow \mathbb{Z}_{+}$are uniquely defined and such that

$$
c^{d}\left(l_{1}(n), l_{2}(n), \ldots, l_{d}(n)\right) \equiv n, \quad l_{i}\left(c^{d}\left(n_{1}, \ldots, n_{i}, \ldots, n_{d}\right)\right)=n_{i}, \quad i=\overline{1, d}, \quad n \in \mathbb{Z}_{+} .
$$

Thus, for any $d$-dimensional number sequence $\left\{s_{\mathbf{k}}\right\}_{\mathbf{k} \in \mathbb{Z}_{+}^{d}}$, we can construct a sequence of matrices

$$
\begin{equation*}
\tilde{S}_{N}=\left\|s_{l_{1}(k)+l_{1}(j), l_{2}(k)+l_{2}(j), \ldots, l_{d}(k)+l_{d}(j)}\right\|_{k, j=0}^{N}, \quad N \in \mathbb{Z}_{+} \tag{15}
\end{equation*}
$$

The following assertion is true:
Theorem 3. Suppose that $\mathcal{H}$ is an infinite-dimensional separable Hilbert space and $\left\{e_{k}\right\}_{k \in \mathbb{Z}_{+}}$is an orthonormal basis in this space. In order that a sequence $\left\{s_{\mathbf{k}}\right\}_{\mathbf{k} \in \mathbb{Z}_{+}^{d}}$ possess a generalized moment representation of the form

$$
\begin{equation*}
s_{\mathbf{k}+\mathbf{j}}=\left\langle x_{\mathbf{k}}, y_{\mathbf{j}}\right\rangle, \quad \mathbf{k}, \mathbf{j} \in \mathbb{Z}_{+}^{d}, \tag{16}
\end{equation*}
$$

where

$$
\langle x, y\rangle=\sum_{m=0}^{\infty}\left(x, e_{m}\right)\left(y, e_{m}\right)
$$

and elements $\left\{x_{\mathbf{k}}\right\}_{\mathbf{k} \in \mathbb{Z}_{+}^{d}}$ and $\left\{y_{\mathbf{j}}\right\}_{\mathbf{j} \in \mathbb{Z}_{+}^{d}}$ have the form

$$
\begin{align*}
x_{\mathbf{k}} & =\sum_{p=0}^{c^{d}(\mathbf{k})} \alpha_{p}^{(\mathbf{k})} e_{p}, \quad \alpha_{c^{d}(\mathbf{k})}^{(\mathbf{k})} \neq 0, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d},  \tag{17}\\
y_{\mathbf{j}} & =\sum_{p=0}^{c^{d}(\mathbf{j})} \beta_{p}^{(\mathbf{j})} e_{p}, \quad \beta_{c^{d}(\mathbf{j})}^{(\mathbf{j})} \neq 0, \quad \mathbf{j} \in \mathbb{Z}_{+}^{d}, \tag{18}
\end{align*}
$$

it is necessary and sufficient that all determinants $\tilde{H}_{p}=\operatorname{det} \tilde{S}_{N}, N \in \mathbb{Z}_{+}$, of the matrices $\tilde{S}_{N}$ given by relations (15) be nonzero.

Moreover, the relations

$$
\begin{equation*}
\alpha_{c^{d}(\mathbf{k})}^{(\mathbf{k})} \beta_{c^{d}(\mathbf{k})}^{(\mathbf{k})}=\frac{\tilde{H}_{c^{d}(\mathbf{k})}}{\tilde{H}_{c^{d}(\mathbf{k})-1}}, \quad \tilde{H}_{-1}:=1, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d} \tag{19}
\end{equation*}
$$

are true and if the sequences of nonzero numbers

$$
\left\{\alpha_{p}^{(1(p))}\right\}_{p \in \mathbb{Z}_{+}} \quad \text { and } \quad\left\{\beta_{p}^{(1(p))}\right\}_{p \in \mathbb{Z}_{+}}
$$

where $\mathbf{l}(p)=\left(l_{1}(p), l_{2}(p), \ldots, l_{d}(p)\right)$, satisfying (19) are fixed, then the remaining coefficients in (17) and (18) are uniquely determined by the relations

$$
\begin{align*}
& \alpha_{p}^{(\mathbf{k})}=\alpha_{c^{d}(\mathbf{k})}^{(\mathbf{k})} \frac{\tilde{S}_{c^{d}(\mathbf{k})}\left(\begin{array}{ccccc}
0 & 1 & \ldots & p-1 & c^{d}(\mathbf{k}) \\
0 & 1 & \ldots & p-1 & p
\end{array}\right)}{\tilde{H}_{c^{d}(\mathbf{k})}}, \quad p=\overline{0, c^{d}(\mathbf{k})}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d},  \tag{20}\\
& \beta_{p}^{(\mathbf{j})}=\beta_{c^{d}(\mathbf{j})}^{(\mathbf{j})} \frac{\tilde{S}_{c^{d}(\mathbf{j})}\left(\begin{array}{ccccc}
0 & 1 & \ldots & p-1 & p \\
0 & 1 & \ldots & p-1 & c^{d}(\mathbf{j})
\end{array}\right)}{\tilde{H}_{c^{d}(\mathbf{j})}}, \quad p=\overline{0, c^{d}(\mathbf{j})}, \quad \mathbf{j} \in \mathbb{Z}_{+}^{d} . \tag{21}
\end{align*}
$$

It is known (see [2]) that the problem of generalized moment representations can be formulated in terms of linear operators. Indeed, if we have a generalized moment representation of the form (1) and, in the space $\mathcal{X}$, one can find a linear operator $A: \mathcal{X} \rightarrow \mathcal{X}$ such that

$$
\begin{equation*}
A x_{k}=x_{k+1}, \quad k \in \mathbb{Z}_{+}, \tag{22}
\end{equation*}
$$

whereas in the space $\mathcal{Y}$, there exists a linear operator $A^{*}: \mathcal{Y} \rightarrow \mathcal{Y}$ adjoint to the operator $A$ with respect to the bilinear form $\langle\cdot, \cdot\rangle$ in a sense that

$$
\langle A x, y\rangle=\left\langle x, A^{*} y\right\rangle \quad \forall x \in \mathcal{X} \quad \forall y \in \mathcal{Y},
$$

then the representation of the form (1) is equivalent to the representation

$$
\begin{equation*}
s_{k}=\left\langle A^{k} x_{0}, y_{0}\right\rangle, \quad k \in \mathbb{Z}_{+} . \tag{23}
\end{equation*}
$$

If, in addition, the spaces $\mathcal{X}$ and $\mathcal{Y}$ are Banach spaces, the bilinear form $\langle\cdot, \cdot\rangle$ is separately continuous, and the operator $A$ is bounded, then the series

$$
\sum_{k=0}^{\infty} s_{k} z^{k}
$$

converges in a neighborhood of the origin to an analytic function $f$, which can be represented in the form

$$
\begin{equation*}
f(z)=\left\langle\mathcal{R}_{z}(A) x_{0}, y_{0}\right\rangle, \tag{24}
\end{equation*}
$$

where $\mathcal{R}_{z}(A)=(I-z A)^{-1}$ is the resolvent function of the operator $A$.
This leads to the problem of existence of representations of the form (23), (24). Actually, this problem was solved in [9] prior to the appearance of the method of generalized moment representations.

Theorem 4 [9]. For any function $f$ analytic in the disk $K_{R}=\{z:|z| \leq R\}, 0<R<\infty$, and any infinite-dimensional separable Hilbert space $\mathcal{H}$, there exist elements $x_{0}, y_{0} \in \mathcal{H}$ and a linear bounded operator $A: \mathcal{H} \rightarrow \mathcal{H}$ with the norm $\|A\|<\frac{1}{R}$ such that, for any $z \in K_{R}$,

$$
\begin{equation*}
f(z)=\left(\mathcal{R}_{z}(A) x_{0}, y_{0}\right) \tag{25}
\end{equation*}
$$

Remark. Representation (25) is equivalent to representation (24) with

$$
\langle x, y\rangle=\sum_{m=0}^{\infty}\left(x, e_{m}\right)\left(y, e_{m}\right)
$$

playing the role of bilinear form, where $\left\{e_{p}\right\}_{p \in \mathbb{Z}_{+}}$is an orthonormal basis in the space $\mathcal{H}$.
A similar result for entire functions was obtained in [4].
Theorem 5 [4]. For any entire function $f$ and any infinite-dimensional separable Hilbert space $\mathcal{H}$, there exist elements $x_{0}, y_{0} \in \mathcal{H}$ and a linear bounded operator $A: \mathcal{H} \rightarrow \mathcal{H}$ whose spectral radius is equal to zero such that the representation

$$
\begin{equation*}
f(z)=\left(\mathcal{R}_{z}(A) x_{0}, y_{0}\right) \tag{26}
\end{equation*}
$$

is true.

In addition, if the entire function has the order $\rho>0$, then the operator $A$ can be chosen so that, for any $n \in \mathbb{N}$,

$$
\begin{equation*}
\sqrt[n]{\left\|A^{n}\right\|} \leq \frac{C}{n^{\frac{1}{\rho}}} \tag{27}
\end{equation*}
$$

where $C$ is a constant.
These problems were also investigated in [10] where, in particular, the author considered representations of the form (25) with unbounded operators $A$.

As in the one-dimensional case, the problem of generalized moment representations for greater dimensions can be formulated in terms of linear operators (see [5, 6]). Indeed, if we have a generalized moment representation of the form (16) and, in the space $\mathcal{X}$, one can find commuting linear operators $A_{j}: \mathcal{X} \rightarrow \mathcal{X}, j=\overline{1, d}$, such that

$$
A_{j} x_{\mathbf{k}}=x_{\mathbf{k}+\delta_{\mathbf{j}}}, \quad j=\overline{1, d}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d}
$$

where

$$
\boldsymbol{\delta}_{j}=\left(\delta_{j, 1}, \delta_{j, 2}, \ldots, \delta_{j, d}\right), \quad \delta_{j, k}= \begin{cases}1, & j=k \\ 0, & j \neq k\end{cases}
$$

and, in the space $\mathcal{Y}$, there exist linear operators $A_{j}^{*}: \mathcal{Y} \rightarrow \mathcal{Y}, j=\overline{1, d}$, adjoint to the operators $A_{j}, j=\overline{1, d}$, with respect to the bilinear form $\langle\cdot, \cdot\rangle$, then the representation of the form (16) is equivalent to the representation

$$
\begin{equation*}
s_{\mathbf{k}}=\left\langle A_{1}^{k_{1}} A_{2}^{k_{2}} \ldots A_{d}^{k_{d}} x_{\mathbf{0}}, y_{\mathbf{0}}\right\rangle, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d} . \tag{28}
\end{equation*}
$$

Moreover, if $\mathcal{X}$ and $\mathcal{Y}$ are Banach spaces, the bilinear form $\langle\cdot, \cdot\rangle$ is separably continuous, and the operators $A_{j}, j=\overline{1, d}$, are bounded, then the series

$$
\sum_{\mathbf{k} \in \mathbb{Z}_{+}^{d}} s_{\mathbf{k}} \mathbf{z}^{\mathbf{k}}=\sum_{\mathbf{k} \in \mathbb{Z}_{+}^{d}} s_{\mathbf{k}} z_{1}^{k_{1}} z_{2}^{k_{2}} \ldots z_{d}^{k_{d}}
$$

converges in a neighborhood of the origin of coordinates to an analytic function $f$ of $d$ variables, which can be represented in the form

$$
f(\mathbf{z})=\left\langle\mathcal{R}_{z_{1}}\left(A_{1}\right) \mathcal{R}_{z_{2}}\left(A_{2}\right) \ldots \mathcal{R}_{z_{d}}\left(A_{d}\right) x_{0}, y_{0}\right\rangle
$$

Theorems 4 and 5 can be generalized to the case of functions of several variables.
Theorem 6. For any function $f$ analytic in a semidisk

$$
K_{\mathbf{R}}=K_{R_{1}} \times K_{R_{2}} \times \ldots \times K_{R_{d}}, \quad 0<R_{j}<\infty, \quad j=\overline{1, d}
$$

and any infinite-dimensional separable Hilbert space $\mathcal{H}$, there exist elements $x_{0}, y_{0} \in \mathcal{H}$ and commuting linear bounded operators $A_{j}: \mathcal{H} \rightarrow \mathcal{H}$ with the norms

$$
\left\|A_{j}\right\|<\frac{1}{R_{j}}, \quad j=\overline{1, d}
$$

such that, for any $\mathbf{z} \in K_{\mathbf{R}}$,

$$
\begin{equation*}
f(\mathbf{z})=\left\langle\mathcal{R}_{z_{1}}\left(A_{1}\right) \mathcal{R}_{z_{2}}\left(A_{2}\right) \ldots \mathcal{R}_{z_{d}}\left(A_{d}\right) x_{0}, y_{0}\right\rangle \tag{29}
\end{equation*}
$$

Proof. Assume that a function $f$ can be expanded in a power series

$$
f(\mathbf{z})=\sum_{\mathbf{k} \in \mathbb{Z}_{+}^{d}} s_{\mathbf{k}} z_{1}^{k_{1}} z_{2}^{k_{2}} \ldots z_{d}^{k_{d}}
$$

in the neighborhood of the origin.
Under the conditions of the theorem, by the Cauchy-Hadamard inequality, we get

$$
\left|s_{\mathbf{k}}\right| \leq \frac{M}{\left(R_{1}+\varepsilon_{1}\right)^{k_{1}}\left(R_{2}+\varepsilon_{2}\right)^{k_{2}} \ldots\left(R_{d}+\varepsilon_{1}\right)^{k_{d}}}
$$

where

$$
M=\sup _{\mathbf{z} \in K_{\mathbf{R}}}|f(\mathbf{z})|, \quad \varepsilon_{1}, \varepsilon_{2}, \ldots, \varepsilon_{d}>0
$$

(see [11, p. 62]).
We fix certain numbers $\tilde{R}_{j} \in\left(R_{j}, R_{j}+\varepsilon_{j}\right), j=\overline{1, d}$, and, for any orthonormal basis $\left\{e_{p}\right\}_{p \in \mathbb{Z}_{+}}$of the space $\mathcal{H}$, consider a $d$-dimensional sequence of elements

$$
x_{\mathbf{k}}=\frac{1}{\tilde{R}_{1}^{k_{1}} \tilde{R}_{2}^{k_{2}} \ldots \tilde{R}_{d}^{k_{d}}} e_{c^{d}(\mathbf{k})}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d} .
$$

We now define the action of the linear operators $A_{j}, j=\overline{1, d}$, upon the elements of the basis $\left\{e_{p}\right\}_{p \in \mathbb{Z}_{+}}$:

$$
A_{j} e_{m}=\frac{1}{\tilde{R}_{j}} e_{c^{d}\left(l_{1}(m), l_{2}(m), \ldots, l_{j}(m)+1, \ldots, l_{d}(m)\right)}, \quad m \in \mathbb{Z}_{+}
$$

We see that, first,

$$
A_{j} x_{\mathbf{k}}=x_{\mathbf{k}+\boldsymbol{\delta}_{j}}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d},
$$

and, second,

$$
\left\|A_{j}\right\|=\frac{1}{\tilde{R}_{j}}<\frac{1}{R_{j}}
$$

In addition, it is clear that the operators $A_{j}, j=\overline{1, d}$, are commuting.
We now define an element $y_{0} \in \mathcal{H}$ in the form of a series

$$
y_{0}=\sum_{p=0}^{\infty} \tilde{R}_{1}^{l_{1}(p)} \ldots \tilde{R}_{d}^{l_{d}(p)} \bar{s}_{l_{1}(p), l_{2}(p), \ldots, l_{d}(p)} e_{p}
$$

We check that $y_{0} \in \mathcal{H}$. Indeed,

$$
\left\|y_{0}\right\|^{2}=\sum_{p=0}^{\infty} \tilde{R}_{1}^{2 l_{1}(p)} \ldots \tilde{R}_{d}^{2 l_{d}(p)}\left|s_{l_{1}(p), l_{2}(p), \ldots, l_{d}(p)}\right|^{2}<\infty
$$

On the other hand,

$$
\left(x_{\mathbf{k}}, y_{0}\right)=\left(\frac{1}{\tilde{R}_{1}^{k_{1}} \tilde{R}_{2}^{k_{2}} \ldots \tilde{R}_{d}^{k_{d}}} e_{c^{d}(\mathbf{k})}, \sum_{p=0}^{\infty} \tilde{R}_{1}^{l_{1}(p)} \ldots \tilde{R}_{d}^{l_{d}(p)} \bar{s}_{l_{1}(p), l_{2}(p), \ldots, l_{d}(p)} e_{p}\right)=s_{\mathbf{k}}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d},
$$

and, hence, representation (28) is true.
Example. Assume that a function $f$ admits the following representation:

$$
\begin{equation*}
f(\mathbf{z})=\int_{\mathbb{I}^{d}} \prod_{p=1}^{d} \frac{1}{1-\frac{z_{p} t_{p}}{R_{p}}} d \mu(\mathbf{t}), \tag{30}
\end{equation*}
$$

where $\mathbb{I}^{d}=[0,1]^{d}$ and $\mu$ is a Borel measure on $\mathbb{I}^{d}$.
As operators $A_{j}, j=\overline{1, d}$, we can take the operators of multiplication by independent variables

$$
\left(A_{j} \varphi\right)(\mathbf{t})=\frac{t_{j}}{R_{j}} \varphi(\mathbf{t})
$$

with the norms

$$
\left\|A_{j}\right\|=\frac{1}{R_{j}}
$$

Theorem 7. For any entire function $f$ of $d$ variables and any infinite-dimensional separable Hilbert space $\mathcal{H}$, there exist elements $x_{0}, y_{0} \in \mathcal{H}$ and commuting linear bounded operators $A_{j}: \mathcal{H} \rightarrow \mathcal{H}, j=\overline{1, d}$, with spectral radius equal to zero and such that

$$
f(\mathbf{z})=\left(\mathcal{R}_{z_{1}}\left(A_{1}\right) \mathcal{R}_{z_{2}}\left(A_{2}\right) \ldots \mathcal{R}_{z_{d}}\left(A_{d}\right) x_{0}, y_{0}\right) .
$$

Moreover, if the orders of increase of the function $f$ (see [11, p. 390]) with respect to the variables $z_{j}, j=\overline{1, d}$, are equal to $\rho_{j}>0, j=\overline{1, d}$, respectively, then the operators $A_{j}, j=\overline{1, d}$, can be chosen so that

$$
\begin{equation*}
\sqrt[p]{\left\|A_{j}^{p^{p}}\right\|} \leq \frac{C_{j}}{p^{\frac{1}{\rho_{j}}}}, \quad j=\overline{1, d} \tag{31}
\end{equation*}
$$

for any $p \in \mathbb{N}$, where $C_{j}, j=\overline{1, d}$, are constants.
Proof. Assume that the function $f$ can be expanded in a power series

$$
f(\mathbf{z})=\sum_{\mathbf{k} \in \mathbb{Z}_{+}^{d}} s_{\mathbf{k}} \mathbf{z}^{\mathbf{k}}
$$

Under the conditions of the theorem, we obtain

$$
\limsup _{|\mathbf{k}| \rightarrow \infty} \sqrt[|\mathbf{k}| \mid]{\left|s_{\mathbf{k}}\right|}=0, \quad \text { where } \quad|\mathbf{k}|=k_{1}+k_{2}+\ldots+k_{d}
$$

Therefore, we can choose a sequence of positive numbers $\left\{\gamma_{p}\right\}_{p \in \mathbb{Z}_{+}}$monotonically decreasing to zero and such that, for any $\mathbf{k} \in \mathbb{Z}_{+}^{d}$,

$$
\sqrt[|k|]{\left|s_{\mathbf{k}}\right|} \leq \gamma_{|\mathbf{k}|}
$$

and, hence,

$$
\left|s_{\mathbf{k}}\right| \leq\left(\gamma_{|\mathbf{k}|}\right)^{|\mathbf{k}|}
$$

For any orthonormal basis $\left\{e_{p}\right\}_{p \in \mathbb{Z}_{+}}$any any $\lambda>1$, we consider a $d$-dimensional sequence of elements

$$
x_{\mathbf{k}}=\left(\lambda \gamma_{|\mathbf{k}|}\right)^{|\mathbf{k}|} e_{c^{d}(\mathbf{k})}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d}
$$

On the elements of the basis $\left\{e_{p}\right\}_{p \in \mathbb{Z}_{+}}$, we define linear operators $A_{j}, j=\overline{1, d}$, as follows:

$$
\begin{equation*}
A_{j} e_{p}=\lambda \frac{\left(\gamma_{|1(p)|+1}\right)^{|1(p)|+1}}{\left(\gamma_{|1(p)|}\right)^{|1(p)|}} e_{c^{d}\left(\mathbf{l}(p)+\delta_{j}\right)} . \tag{32}
\end{equation*}
$$

Thus, we get

$$
A_{j} x_{\mathbf{k}}=x_{\mathbf{k}+\delta_{j}}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d}, \quad j=\overline{1, d}
$$

It follows from equality (32) that

$$
A_{j}^{m} e_{p}=\lambda^{m} \frac{\left(\gamma_{|1(p)|+m}\right)^{|1(p)|+m}}{\left(\gamma_{|\mathbf{1}(p)|}\right)^{|1(p)|}} e_{c^{d}\left(\mathbf{l}(p)+m \boldsymbol{\delta}_{j}\right)}
$$

and, hence,

$$
\left\|A_{j}^{m}\right\|=\sup _{p \in \mathbb{Z}_{+}} \lambda^{m} \frac{\left(\gamma_{|\mathbf{1}(p)|+m}\right)^{|\mathbf{1}(p)|+m}}{\left(\gamma_{|1(p)|}\right)^{|\mathbf{1}(p)|}} \leq\left(\lambda \gamma_{m}\right)^{m}
$$

and

$$
\sqrt[m]{\left\|A_{j}^{m}\right\|} \leq \lambda \gamma_{m} \rightarrow 0 \quad \text { as } \quad m \rightarrow \infty
$$

i.e., the spectral radius of the operators $A_{j}, j=\overline{1, d}$, is equal to zero.

Setting

$$
y_{0}=\sum_{p=0}^{\infty} \frac{1}{\left(\lambda \gamma_{p}\right)^{p}} s_{1(p)} e_{p}
$$

we obtain

$$
\left\|y_{0}\right\|^{2}=\sum_{p=0}^{\infty} \frac{1}{\left(\lambda \gamma_{p}\right)^{2 p}}\left|s_{l(p)}\right|^{2} \leq \sum_{p=0}^{\infty} \frac{1}{\lambda^{2 p}}=\frac{\lambda^{2}}{\lambda^{2}-1}<\infty
$$

Therefore, $y_{0} \in \mathcal{H}$.

On the other hand,

$$
\left(x_{\mathbf{k}}, y_{0}\right)=\left(\left(\lambda \gamma_{\mathbf{k}}\right)^{\mathbf{k}} e_{c^{d}(\mathbf{k})}, \sum_{p=0}^{\infty} \frac{1}{\lambda \gamma_{p}{ }^{p}} s_{1(p)} e_{p}\right)=s_{\mathbf{k}}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d},
$$

and, hence, representation (28) is true.
If the orders of increase of the function $f$ with respect to the variables $z_{j}, j=\overline{1, d}$, are equal to $\rho_{j}, j=\overline{1, d}$, respectively, then

$$
\left|s_{\mathbf{k}}\right| \leq \frac{C_{j}^{\mathbf{k}}}{|\mathbf{k}|^{\left(\frac{k_{1}}{\rho_{1}}+\frac{k_{2}}{\rho_{2}}+\ldots+\frac{k_{d}}{\rho_{d}}\right)}} \leq \prod_{j=1}^{d}\left(\frac{C_{j}}{k_{j}^{\frac{1}{\rho_{j}}}}\right)^{k_{j}}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d},
$$

where $C_{j}>0, j=\overline{1, d}$, are constants.
For a certain fixed $\lambda>1$, we set

$$
x_{\mathbf{k}}=\lambda^{|\mathbf{k}|} \prod_{j=1}^{d}\left(\frac{1}{k_{j}^{\frac{1}{\rho_{j}}}}\right)^{k_{j}} e_{c^{d}(\mathbf{k})} .
$$

On the vectors of the basis $\left\{e_{p}\right\}_{p \in \mathbb{Z}_{+}}$, we set

$$
A_{j} e_{p}=\lambda\left(\frac{l_{j}(p)^{l_{j}(p)}}{\left(l_{j}(p)+1\right)^{l_{j}(p)+1}}\right)^{\frac{1}{\rho_{j}}} e_{c^{d}\left(\mathbf{l}(p)+\boldsymbol{\delta}_{j}\right)}
$$

Thus, we get

$$
\begin{gathered}
A_{j} x_{\mathbf{k}}=x_{\mathbf{k}+\boldsymbol{\delta}_{j}}, \quad \mathbf{k} \in \mathbb{Z}_{+}^{d}, \quad j=\overline{1, d}, \\
A_{j}^{m} e_{p}=\lambda^{m}\left(\frac{l_{j}(p)^{l_{j}(p)}}{\left(l_{j}(p)+m\right)^{l_{j}(p)+m}}\right)^{\frac{1}{\rho_{j}}} e_{c^{d}\left(\mathbf{1}(p)+m \boldsymbol{\delta}_{j}\right)}
\end{gathered}
$$

and, hence,

$$
\left\|A_{j}^{m}\right\|=\sup _{p \in \mathbb{Z}_{+}} \lambda^{m}\left(\frac{l_{j}(p)^{l_{j}(p)}}{\left(l_{j}(p)+m\right)^{l_{j}(p)+m}}\right)^{\frac{1}{\rho_{j}}} \leq\left(\frac{\lambda}{m^{\rho_{j}}}\right)^{m} .
$$

This yields inequality (31).

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