Citation: Hirt, C., S.J. Claessens, T. Fecher, M. Kuhn, R. Pail, M. Rexer (2013), New ultra-high 1 resolution picture of Earth's gravity field, Geophysical Research Letters, 40(16), 4279-4283, doi: 2 10.1002/grl.50838. 3

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New ultra-high resolution picture of Earth's gravity field 5

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11

12 Abstract

We provide an unprecedented ultra-high resolution picture of Earth's gravity over all continents 13 and numerous islands within \pm 60 degree latitude. This is achieved through augmentation of new 14 15 satellite and terrestrial gravity with topography data, and use of massive parallel computation techniques, delivering local detail at ~200 m spatial resolution. As such, our work is the first-of-16 its-kind to model gravity at unprecedented fine scales yet with near-global coverage. The new 17 picture of Earth's gravity encompasses a suite of gridded estimates of gravity accelerations, 18 radial and horizontal field components and quasigeoid heights at over 3 billion points covering 19 80% of Earth's land masses. We identify new candidate locations of extreme gravity signals, 20 suggesting that the CODATA standard for peak-to-peak variations in free-fall gravity is too low 21 by about 40%. The new models are beneficial for a wide range of scientific and engineering 22 applications and freely available to the public. 23

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25 Keywords

Earth's gravity field, gravity, quasigeoid, vertical deflections, ultra-high resolution 26

27 28 **1** Introduction

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Precise knowledge of the Earth's gravity field structure with high resolution is essential for a 30 range of disciplines, as diverse as exploration and potential field geophysics [Jakoby and Smilde, 31 32 2009], climate and sea level change research [Rummel, 2012], surveying and engineering [Featherstone, 2008] and inertial navigation [Greiner-Brzezinska and Wang, 1998]. While there 33 34 is a strong scientific interest to model Earth's gravity field with ever-increasing detail, the resolution of today's gravity models remains limited to spatial scales of mostly 2-10 km globally 35 [Pavlis et al., 2012; Balmino et al., 2012], which is insufficient for local gravity field 36 37 applications such as modelling of water flow for hydro-engineering, inertial navigation or in-situ reduction of geophysical gravity field surveys. Up until now, gravity models with sub-km 38 resolution are unavailable for large parts of our planet. 39

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Here we provide an unprecedented ultra-high resolution view of five components of Earth's 41 gravity field over all continents, coastal zones and numerous islands within ± 60 degree latitude. 42

This is achieved through augmentation of new satellite and terrestrial gravity with topography 43

data [e.g., *Hirt et al.* 2010] and use of massive parallel computation techniques, delivering local 44 detail at 7.2 arc-seconds (~200 m in North-South direction) spatial resolution (Section 2). As

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such, our work is the first-of-its-kind to model gravity at ultra-fine scales yet with near-global 46

47 coverage. The new picture of Earth's gravity encompasses a suite of gridded estimates of gravity 48 accelerations, radial and horizontal field components and quasigeoid heights at over 3 billion 49 points covering 80% of Earth's land masses and 99.7% of populated areas (Section 3, 4). This 50 considerably extends our current knowledge of the gravity field. The gridded estimates are 51 beneficial for a range of scientific and engineering applications (Section 5) and freely available 52 to the public. Electronic supplementary materials are available providing full detail on the 53 methods applied in this study.

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55 **2 Data and Methods**

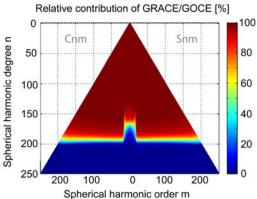
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Our ultra-high resolution picture of Earth's gravity field is a combined solution based on the
three key constituents GOCE/GRACE satellite gravity (providing the spatial scales of ~10000
down to ~100 km), EGM2008 (~100 to ~10 km) and topographic gravity, i.e., the gravitational
effect implied by a high-pass filtered terrain model (scales of ~10 km to ~250 m),

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Regarding the satellite component, we use the latest satellite-measured gravity data (release GOCE-TIM4) from the European Space Agency's GOCE satellite [*Drinkwater et al.*, 2003; *Pail et al.*, 2011], parameterized as coefficients of a spherical harmonic series expansion, that currently provides the highest-resolution picture of Earth's gravity ever obtained from a space gravity sensor. Resolving gravity field features at spatial scales as short as 80-100 km, GOCE confers new gravity field knowledge, most notably over poorly surveyed regions of Africa, South America and Asia [*Pail et al.*, 2011].

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70 Spherical harmonic order m
 71 Figure 1. Relative contribution of GOCE/GRACE data per spherical harmonic coefficient in the combination with
 72 EGM2008 data (in percent) for the degrees 0 to 250

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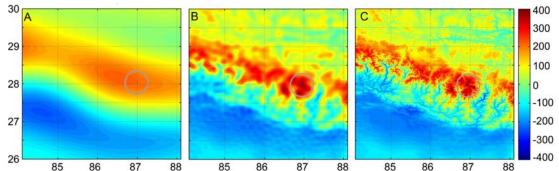
74 Compared to pure GOCE models, complementary GRACE satellite gravity [Mayer Guerr et al., 2010] are superior in the spectral range up to degrees 70-80 [Pail et al., 2010]. Therefore, first a 75 combined satellite-only combined solution based on full normal equations of GRACE (up to 76 degree 180) and GOCE (up to degree 250) is computed [see, e.g., Pail et al., 2010]. The 77 GRACE/GOCE combination is then merged with EGM2008 [Pavlis et al., 2012] using the 78 EGM2008 coefficients as pseudo-observations. Since for EGM2008 only the error variances are 79 available, the corresponding normal equations have diagonal structure. In our combination, 80 GRACE/GOCE data have dominant influence in the spectral band of harmonic degrees 0 to 180 81 with EGM2008 information taking over in the spectral range 200 to 2190, leaving the main 82 spectral range of transition from GRACE/GOCE to EGM2008 in spectral band of degrees 181 to 83

200. The relative contributions of EGM2008 and GRACE/GOCE satellite gravity are shown inFig. 1.

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89 The spherical-harmonic coefficients of the combined GRACE/GOCE/EGM2008 (GGE) gravity model were used in the spectral band of degrees 2 to 2190 to synthesize a range of frequently 90 91 used gravity field functionals at the Earth's surface. For accurate spherical harmonic synthesis at the Earth's surface, as represented through the SRTM topography, the gradient approach to fifth-92 order [Hirt 2012] was applied. This numerically efficient evaluation technique takes into account 93 the effect of gravity attenuation with height. Applying the gradient approach as described in *Hirt* 94 [2012] yielded numerical estimates for radial derivatives (gravity disturbances) and horizontal 95 derivatives (deflections of the vertical) of the disturbing potential and quasigeoid heights from 96 the GGE data set at 7.2 arc-sec resolution (about 3 billion surface points) within the SRTM data 97 98 coverage.

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100 E_0 858687888586878885868788101Figure 2. Gravity field at different levels of resolution over Mount Everest area. A: satellite-only (free-air) gravity102from GOCE and GRACE satellites, B: GGE gravity (satellite gravity combined with EGM2008 gravity), C:103GGMplus as composite of satellite gravity, EGM2008 and topographic gravity. Shown is the radial component of104the gravity field over a ~400 x 400 km area covering parts of the Southern Himalayas including the Mount Everest105summit area (marked), units in 10^{-5} m s⁻². The spatial resolution of the gravity modelling increases from ~100 km106(A), ~10 km (B) to ultra-fine ~200 m spatial scales (C).

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For the Mount Everest region, Fig. 2 exemplifies the associated resolution of GOCE/GRACE satellite gravity (A) and their combination with EGM2008 gravity (B). The spatial resolution of the GGE gravity field functionals is limited to about ~10 km (or harmonic degree of 2190) which leaves the problem of modelling the field structures at short scales, down to few 100 m resolution at any of the surface points.

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Because ground gravity measurements at a spatial density commensurate with our model 114 115 resolution do not exist over most parts of Earth [e.g., Sansò and Sideris, 2013] - and will not become available in the foreseeable future - alternative solutions are required to estimate the 116 gravity field signals at scales shorter than 10 km. High-resolution topography data is widely 117 considered the key to ultra-high resolution gravity modelling and used successfully as effective 118 means to estimate short-scale gravity effects [Sansò and Sideris, 2013; Tziavos and Sideris, 119 120 2013, Pavlis et al., 2012; Forsberg and Tscherning, 1981]. This is because the short-scale gravity field is dominated by the constituents generated by the visible topographic masses 121

122 [*Forsberg and Tscherning*, 1981]. However, forward estimation of the short-scale gravity field 123 constituents from elevation models near-globally at ultra-high (few 100 metres) resolution is 124 computationally demanding. Yet we have accomplished this challenge for the first time through 125 advanced computational resources.

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Massive parallelization and the use of Western Australia's iVEC/Epic supercomputing facility allowed us to convert topography from the Shuttle Radar Topography Mission (SRTM), cf. *Jarvis et al.* [2008] – along with bathymetric information along coastlines [*Becker et al.*, 2009] – to topographic gravity at 7.2 arc-sec resolution everywhere on Earth between \pm 60° latitude with SRTM data available. Based on non-parallelized standard computation techniques, the calculation of topographic gravity effects would have taken an estimated 20 years, which is why previous efforts were restricted to regional areas [*Kuhn et al.*, 2009; *Hirt*, 2012].

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The conversion of topography to topographic gravity is based on the residual terrain modelling 135 technique [Forsberg, 1984], with the topography high-pass filtered through subtraction of a 136 spherical harmonic reference surface (of degree and order 2160) prior to the forward-modelling. 137 We treated the ocean water masses and those of the major inland water bodies (Great Lakes, 138 Baikal, Caspian Sea) using a combination of residual terrain modelling with the concept of rock-139 equivalent topography [Hirt, 2013], whereby the water masses were 'compressed' to layers 140 equivalent to topographic rock. These procedures yield short-scale topographic gravity that is 141 suitable for augmentation of degree-2190 spherical harmonic gravity models beyond their 142 associated 10 km resolution, cf. Hirt [2010; 2013]. The topographic gravity is based on a mass-143 density assumption of 2670 kg m⁻³ and provides the spatial scales of \sim 10 km to \sim 250 m, which is 144 complementary to the GGE gravity (spatial scales from ~10000 km to ~10 km). 145

146 147 **3 Results**

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Addition of both components (GGE and topographic gravity) result in the ultra-high resolution model GGMplus (Global Gravity Model, with plus indicating the leap in resolution over previous 10 km resolution global gravity models). The modelled gravity field components and their descriptive statistics are reported in Table 1.

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¹⁵⁴**Table 1.** Descriptive statistics of the GGMplus model components calculated at 3,062,677,383 land and155near-costal points within \pm 60° geographic latitude. RMS is the root-mean-square of the component.

neur costar points "rann 200" geographie lattade. Rivis is the foot mean square of the component.						
Gravity model component		Min	Max	RMS	Unit	
Gravity	Free-fall acceleration	976392	981974	980133	10 ⁻⁵ m s ⁻²	
	Radial component	-456	714	48.0	10 ⁻⁵ m s ⁻²	
Horizontal components	North-South	-108	94	6.9	arc-sec	
	East-West	-83	79	6.8	arc-sec	
	Total (magnitude)	0	109	9.4	arc-sec	
Quasigeoid		-99.26	86.60	29.91	m	

¹⁵⁶

expected gravity signatures of small-scale topographic features – such as mountain peaks and

valleys – which are otherwise masked in 10 km resolution models. This adds much local detail to
 the gravity maps (compare Figs. 2B and 2C) and yields a spectrally more complete and accurate

161 description of the gravity field [e.g., *Hirt*, 2012].

¹⁵⁷ This world-first ultra-high resolution modelling over most of Earth's land areas delivered us the

Gravity component	Minimum/	Latitude/	Geographic feature/
	Maximum	Longitude	location
Gravity acceleration	9.76392 m s ⁻²	-9.12°/ -77.60°	Huascarán, Peru
	9.83366 m s ⁻²	86.71°/61.29°	*Arctic Sea
Radial component	$-456 \times 10^{-5} \text{ m s}^{-2}$	29.71°/95.36°	Gandengxiang, China
	$714 \times 10^{-5} \text{ m s}^{-2}$	10.83°/-73.69°	Pico Cristóbal Colón, Columbia
Horizontal component ⁺	109 arc-sec	28.45°/84.13°	~10 km South of Annapurna II
			Nepal
Quasigeoid	-106.59 m	4.71°/78.79°	*Laccadive Sea, South of Sr
			Lanka
	86.60 m	-8.40°/147.35°	Puncak Trikora, Papua, Indonesia

162 **Table 2.** Candidate locations for extreme values of Earth's gravity field

* offshore area, value estimated without topographic gravity using GGE-only (10 km resolution, also see electronic supplement)

⁺ total component computed as magnitude from the North-South and East-West components

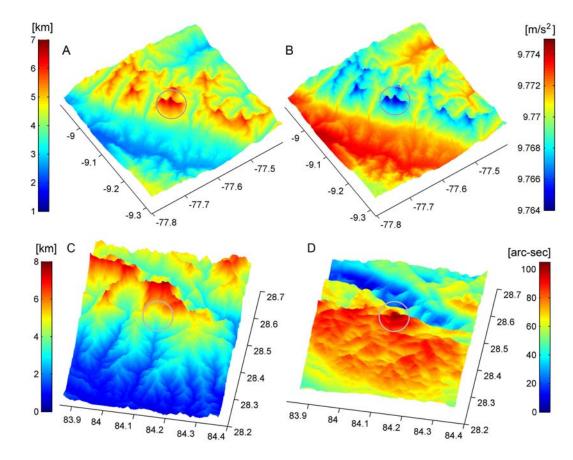


Figure 3. Candidate locations of some extreme signals in Earth's gravity in the Andes (A,B) and Himalaya regions
(C,D). Top: Topography (A) and free-fall gravity accelerations (B) over the Huascarán region (Peru), where
GGMplus gravity accelerations are as small as ~9.764 m s⁻² (B). Bottom: Topography (C) and GGMplus total
horizontal field component (D) over the Annapurna II region (Nepal). The gravitational attraction of the Annapurna
II masses is expected to cause an extreme slope of the quasi/geoid with respect to the Earth ellipsoid of up to ~109
arc-seconds (D).

Our gridded estimates portray the subtle variations of gravity (Fig. 3) which are known to depend 174 on factors such as location, height and presence of mass-density anomalies. GGMplus reveals a 175 candidate location for the minimum gravity acceleration on Earth: the Nevado Huascarán summit 176 (Peru) with an estimated acceleration of 9.76392 m s⁻² (Fig 3A, 3B, and Table 2). A candidate 177 location for Earth's maximum gravity acceleration was identified - outside the SRTM area, based 178 on GGE-only – in the Arctic sea with an estimated 9.83366 m s⁻². This suggests a variation range 179 (peak-to-peak variation) for gravity accelerations on Earth of about ~ 0.07 m s^{-2} , or 0.7 %, which 180 is about 40 % larger than the variation range of 0.5 % implied by standard models based on a 181 rotating mass-ellipsoid (gravity accelerations are 9.7803 m s⁻² (equator) 9.8322 m s⁻² (poles) on 182 the mass-ellipsoid, cf. Moritz [2000]). So far such a simplified model is also used by the 183 Committee on Data for Science and Technology (CODATA) to estimate the variation range in 184 free-fall acceleration on Earth [Mohr and Taylor, 2005]. However, due to the inhomogeneous 185 186 structure of Earth, presence of topographic masses, and decay of gravity with height the actual variations in free-fall accelerations are ~40% larger at the Earth's surface (Table 2). 187

188

189 GGMplus free-air gravity – the radial component of Earth's gravity field – varies within a range 190 of ~0.011 m s⁻² (~0.1% of gravity accelerations) with its minimum value of -456×10^{-5} m s⁻² 191 located in China and its maximum of 714×10^{-5} m s⁻² expected for the Pico Cristóbal Colón 192 summit in Colombia. The higher variability of gravity accelerations over free-air gravity reflects 193 the well-known fact that gravity accelerations include the gravitational attraction and centrifugal 194 effect due to Earth rotation.

195

The horizontal components of the gravitational field describe in approximation the North-South 196 and East-West inclination of the quasi/geoid with respect to the reference ellipsoid. The variation 197 range of the horizontal field components (also known as deflections of the vertical) is about ~200 198 199 arc-seconds in North South, and ~160 arc-seconds in East-West, respectively (Table 1). 200 GGMplus reveals a candidate location for Earth's largest deflection of the vertical: about 10 km South of Annapurna II, Nepal, the plumb line is expected to deviate from the ellipsoid normal by 201 an angle as large as ~109 arc-seconds (Fig. 3C and 3D). This translates into a most extreme 202 203 quasi/geoid slope of about 0.5 m over 1 km.

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205 4 Model evaluation

We have comprehensively compared GGMplus gravity field maps with in-situ (direct) observations of Earth's gravity field from gravimetry, astronomy, and surveying (see electronic supplementary materials). Over well-surveyed areas of North America, Europe and Australia, the comparisons suggest an accuracy level for free-air gravity and gravity accelerations of ~5 × 10^{-5} m s⁻², for horizontal field components of about 1 arc-second, and for quasigeoid heights of 0.1 m or better.

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214 Despite the improvements conferred by recent satellite gravity to our model, the GGMplus 215 accuracy deteriorates by a factor of ~3 to ~5 over Asia, Africa and South America which are 216 regions with limited or very limited ground gravity data availability. Comparisons suggest a 217 decrease in accuracy down to ~ 20×10^{-5} m s⁻² for gravity, ~5 arc-seconds for horizontal field 218 components, and ~0.3 m for quasigeoid heights. The reduced accuracy estimates mainly reflect 219 the limited availability of gravity observations at spatial scales of ~100 to ~10 km. The accuracy of GGMplus gravity accelerations will always be lower than that of free-air gravity. This is because accelerations are directly affected by errors in the elevation data, with an elevation error of 10 m equivalent to about 3×10^{-5} m s⁻².

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Given that any gravity field signals originating from local mass-density variations are not 224 225 represented by the topographic gravity, our gravity maps cannot provide information on geological units at scales less than 10 km. This is akin to EGM2008 at spatial scales of ~30 to 226 ~10 km over many land areas where gravity measurements are unavailable or of proprietary 227 nature [Pavlis et al., 2012]. Any global, regional or local gravity map or quasi/geoid model can 228 only be geologically interpreted down to a resolution commensurate with the gravity 229 230 observations used to construct the model. Nevertheless, incorporation of topographic gravity to approximate gravity field features at spatial scales of ~10 km to ~250 m significantly improves 231 GGMplus gravity and horizontal components when compared to 10 km-resolution maps. 232 Depending on the terrain ruggedness, the observed improvement rates mostly range between 40 233 to 90% for radial and horizontal field components (Supplementary Tables 6 and 8), while the 234 235 quasigeoid improvement is best observable over rugged areas (up to 40 % improvement, Supplementary Table 9). 236

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238 **5** Applications

Apart from enhancing our knowledge of Earth's gravity and its variations, there are several
scientific and engineering applications that require high-resolution and largely complete gravity
knowledge, which is now available through GGMplus gravity maps.

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The quasi/geoid plays a crucial role in modern determination of topographic heights with Global 243 Navigation Satellite Systems (such as the Global Positioning System GPS), allowing the 244 measurement of heights above mean sea level rather than heights above the ellipsoid [e.g., Meyer 245 et al., 2006; Featherstone, 2008; Hirt et al., 2011]. While several regional-size quasi/geoid 246 models of good quality are available at mostly ~2 km resolution over well-surveyed land areas 247 (e.g., Europe, USA, Australia), GGMplus is capable of providing improved quasi/geoid 248 249 information over those parts of Asia, Africa and South America, where no other source of highresolution gravity (e.g., from airborne gravity) is available. The GGMplus quasigeoid can be 250 suitable for water flow modelling (e.g., as required in hydro-engineering), and height transfer 251 with satellite systems, and can be of utility for the determination of offsets among continental 252 height systems (e.g., Australia and Europe) and their unification [e.g., Flury and Rummel, 2005; 253 254 Rummel, 2012]. This in turn will allow for a more consistent comparison of sea level observations at tide gauges across the oceans. Because of incorporation of newer GOCE and 255 GRACE satellite gravity, the GGMplus quasigeoid confers improvements at ~100 km spatial 256 scales over parts of Asia, South America and Africa, while consideration of short-scale 257 quasigeoid effects from topography data improves the resolution of quasigeoid heights over 258 259 rugged terrain [Hirt et al., 2010].

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261 GGMplus gravity accelerations and free-air gravity are a promising data source for screening and

outlier-detection of terrestrial gravity databases and aid in planning of local precision gravimetric
 surveys. Gravity accelerations as provided by our maps are required e.g., as a correction in the

- context of geodetic height systems [e.g., *Meyer et al.*, 2006], for accurate topographic mapping,
- in metrology for calibration of precision scales [Torge, 1989] and seismometers, and in

observational astronomy for meteorological corrections [Corbard et al., 2013]. For geophysics 266 and the exploration industry, GGMplus may prove beneficial as novel data source for in-situ 267 reduction of detailed gravimetric surveys, revealing locations of interest for mineral prospectivity 268 without the need to calculate and apply further rather time-consuming reductions [Jakoby and 269 Smilde, 2009] Finally, horizontal field components are required to correct the impact of the 270 271 Earth's irregular gravity field, e.g., for inertial navigation at or near the Earth's surface [Grejner-Brzezinska and Wang, 1998], or in the context of civil engineering (e.g., precision surveys for 272 273 tunnel alignment), Featherstone and Rüeger [2000]. All of these applications require spectrally 274 most complete information on the gravity field.

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276 6 Conclusions

278 GGMplus provides the most complete description of Earth's gravity at ultra-high resolution and near-global coverage to date. This confers immediate benefits to many applications in 279 280 engineering, exploration, astronomy, surveying, and potential field geophysics. While GGMplus provides moderate additional information (because of the ultra-high resolution short-scale 281 modelling) over areas with dense coverage of gravity stations (e.g., North America, Europe, 282 Australia), significant improvements are provided over areas with sparse ground gravity 283 284 coverage (e.g., Asia, Africa, South America). For the latter regions, GGMplus provides for the 285 first time a complete coverage with gravity at ultra-high spatial resolution, thus providing scientific aid to many developing countries. In addition, GGMplus provides crucial information 286 to revise current standards for the maximum range of free-fall gravity accelerations over the 287 Earth's surface. The computerized GGMplus gravity field maps are freely available for science, 288 education and industry via and http://ddfe.curtin.edu.au/gravitymodels/GGMplus. 289

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Acknowledgements We are grateful to the Australian Research Council for funding (DP120102441). This work was made feasible through using advanced computational resources of the iVEC/Epic supercomputing facility (Perth, Western Australia). We thank all developers and providers of data used in this study. Full methods, and detailed evaluation results are available in the electronic supplementary information, and information on data access via the project's website <u>http://geodesy.curtin.edu.au/research/models/GGMplus</u>.

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Electronic supplementary material for

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New ultra-high resolution picture of Earth's gravity field

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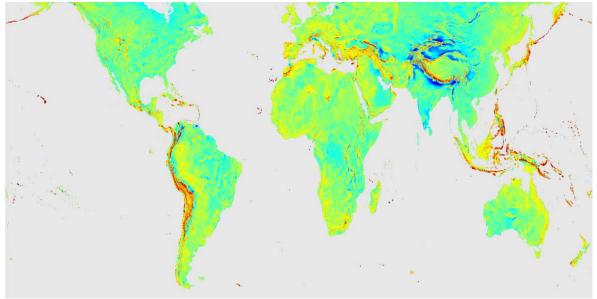
The development of GGMplus was driven by our vision to provide for the first time widely complete gravity field knowledge on a near-global scale to users of the scientific and engineering community as well as for education purposes based on freely-available data sources.

385

The model development was facilitated by the availability of new satellite observations of Earth's gravity field, as well as detailed topographic elevation data (Sect. 2), availability of suitable and efficient methods for highest-resolution gravity modelling (Sect. 3) and, importantly, made possible through advanced supercomputing resources provided by the iVEC/Epic supercomputing centre of Western Australia.

- 391
- 392 *Coverage*393

394 GGMplus provides computerized gravity field maps at 7.2 arc-seconds (0.002° or ~224 m in 395 latitude direction) resolution for all land areas of Earth within \pm 60° geographic latitude (as 396 represented by SRTM, with the exception of the Southern part of Greenland), and an adjoining 397 ~10 km marine zone along the coast lines (Fig. 1). The target resolution of GGMplus of 7.2 arc-398 seconds translates into a total of ~3 billion computation points within our working area. The 399 chosen resolution allows representing the short-scale variations of the radial (gravity) and 400 horizontal field components (deflections of the vertical).



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Figure 1. Coverage of GGMplus. Shown are mean values of the radial component of the gravity field over land and near-coastal areas between $\pm 60^{\circ}$ geographic latitude.

406	Technical definitions
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408 The five gravity field functionals provided by GGMplus are

- Free-fall gravity accelerations (i.e. gravitational plus centrifugal accelerations)
- Gravity disturbances (radial derivatives of the disturbing potential), denoted as radial component of the gravity field in the manuscript
- North-South deflection of the vertical in Helmert definition (latitudinal derivative of the disturbing potential), denoted as horizontal component of the gravity field in the manuscript
- East-West deflection of the vertical in Helmert definition (longitudinal derivative of the disturbing potential), denoted as horizontal component of the gravity field in the manuscript

• and Molodenski quasigeoid heights.

All quantities are given at the Earth's surface as defined through the SRTM (Shuttle Radar
Topography Mission) topography. Users wishing to use geoid heights instead of quasigeoid
heights can do so by applying standard conversion as described, e.g., *Rapp* [1997].

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425 **2 Data sets used**

426

A complete list of data sets used for the development of GGMplus is given in Table 1. The use ofthese data is further detailed in Section 3.

- 429
- 430
 Table 1. Data sets used for the development of GGMplus

 Dataset
 Ressource
 Citation

GRACE satellite gravity model ITG2010s	http://icgem.gfz-potsdam.de/ICGEM	<i>Mayer-Gürr et al.</i> [2010]
GOCE-TIM4 satellite gravity model	http://icgem.gfz-potsdam.de/ICGEM/	Pail et al., [2011]
EGM2008 gravity model	http://earth-info.nga.mil/ GandG/wgs84/gravitymod/egm2008/	Pavlis et al., [2012]
Gridded 250 m SRTM V4.1 release over land	http://srtm.csi.cgiar.org/	Jarvis et al., [2008]
Gridded SRTM30_PLUS V7 bathymetry offshore	http://topex.ucsd.edu/WWW_html/srtm 30_plus.html	Becker et al., [2009]
RET2012 spherical harmonic rock-equivalent topography model	http://www.geodesy.curtin.edu.au/resear ch/models, file Earth2012.RET2012.SHCto2160.zip	Hirt et al., [2012]
Earth2012 Topo/Air spherical harmonic model of Earth's physical surface	http://www.geodesy.curtin.edu.au/resear ch/models, file Earth2012.topo_air.SHCto2160.zip	Hirt et al., [2012]

432 **3 Methods**

433

GGMplus is constructed as a composite model of GOCE and GRACE satellite gravity,
EGM2008 and topographic gravity in the space domain. The following steps were taken to
develop the model:

- Combination of GOCE and GRACE satellite gravity (Sect. 3.1)
- Combination of GOCE-GRACE combined model with EGM2008 (Sect. 3.2)
 - Spherical harmonic synthesis of gravity field quantities (Sect. 3.3)
 - Forward-modelling of gravity field quantities (Sect. 3.4)
 - Calculation of normal gravity at the Earth's surface (Sect. 3.5)
- Combination of synthesis and forward-modelling results (Sect. 3.6)
- 443

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441

The 250 m resolution SRTM topography [Jarvis et al., 2008] is consistently used to represent 444 Earth's physical surface in the gravity field synthesis (Sect. 3.3), forward-modelling (Sect. 3.4) 445 and calculation of normal gravity (Sect. 3.4). In approximation, SRTM elevations are physical 446 heights above mean sea level. In processing steps 3.3 and 3.5, heights of the topography above 447 the ellipsoid (ellipsoidal heights) are required. These were obtained in approximation as sum of 448 SRTM and the EGM2008 quasigeoid [Pavlis et al., 2012]. The geoid-quasigeoid separation was 449 450 not accounted for in the construction of SRTM ellipsoidal heights, because this effect is mostly small (cm-dm-level, up to 1-2 m in the high mountains), which play a neglegible role in 3D 451 spherical harmonic synthesis. The parameters of the GRS80 geodetic reference system [Moritz, 452 2000] were consistently used throughout the GGMplus model development. 453

The satellite-only combination model has been computed by addition of full normal equations ofGRACE and GOCE.

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461

$$\begin{bmatrix} \sum_{i=1}^{4} (A^{T} \Sigma(l)^{-1} A)_{GOCE,i} + A^{T} \Sigma(l)^{-1} A)_{GRACE} \end{bmatrix} x =$$

$$\begin{bmatrix} \sum_{i=1}^{4} (A^{T} \Sigma(l)^{-1} l)_{GOCE,i} + A^{T} \Sigma(l)^{-1} l)_{GRACE} \end{bmatrix} \Leftrightarrow N_{sat} x = n_{sat}$$
(1)

462 463

The GRACE component consists of ITG-Grace2010s [Mayer-Gürr et al., 2010] up to 464 degree/order 180, which is based on GRACE K-band range rate and kinematic orbit data 465 covering the time span from August 2002 to August 2009. The GOCE component contains 466 reprocessed satellite gravity gradiometry data (main diagonal components V_{XX}, V_{YY} and V_{ZZ} and 467 off-diagonal component V_{XZ} of the gravity gradient tensor; summation i = 1, ...4 in Eq. (1)) from 468 November 2009 to June 2012, as they have also been used for the 4th release of the GOCE TIM 469 model [Pail et al., 2011]. In Eq. (1), l are the observations, and x the unknown spherical 470 harmonic coefficients (SHC). 471

472

In the frame of the gravity gradient reprocessing, among others an improved algorithm for
angular rate reconstruction has been applied [*Stummer et al.*, 2011], leading to a significant
improvement of the gravity gradient performance mainly in the low to medium degrees [*Pail et al.*, 2013]. The resulting GOCE gradiometry normal equations are resolved up to degree/order
250.

479 Special emphasis has been given to realistic stochastic modeling of observation errors as part of the assembling and solution of the individual normal equation systems, yielding realistic 480 variance-covariance information $\Sigma(l)$ for both GRACE and GOCE. In the case of GOCE, digital 481 auto-regressive moving average (ARMA) filters have been used to set-up the variance-482 483 covariance information of the gradient observations [Pail et al., 2011]. Technically, this is done by applying these filters to the full observation equation, i.e., both to the observations and the 484 columns of the Jacobian (design matrix A). Due to the realistic stochastic modeling, the two 485 normal equations could be combined with unit weight. Because of the further combination with 486 EGM2008 as described in section 3.2, regularization has not been applied. 487

488 489

490

3.2 GOCE/GRACE and EGM2008 combination

The combination of the GRACE/GOCE data with EGM2008 is done on the basis of the combined GRACE/GOCE normal equations (see Sect. 3.1). Here the EGM2008 SHCs are treated as a set of *a priori* known parameters introduced into a least-squares process of the form: 494

495
$$(w_1 N_{sat} + w_2 \Sigma (x_{EGM})^{-1}) x = w_1 n_{sat} + w_2 \Sigma (x_{EGM})^{-1} x_{EGM}$$
 (2)
496

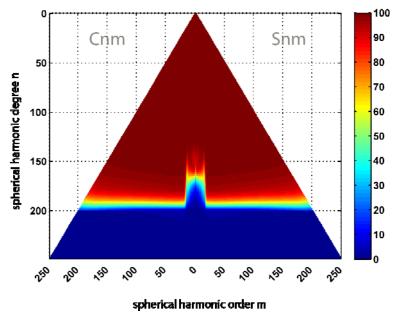
497 where x is the optimally combined set of SHCs from GRACE, GOCE and EGM2008. The 498 terms N_{sat} and n_{sat} denote the normal equation system of GRACE/GOCE combination (cf. 499 section 3.1), resolved up to degree/order 250.

500

The terms $\Sigma(x_{EGM})^{-1}$ and $\Sigma(x_{EGM})^{-1}x_{EGM}$ denote the system of normal equations, which relies 501 exclusively on the EGM2008 coefficients x_{EGM} up to degree/order 360, which are used as 502 pseudo-observations (the Jacobian is in this case an identity matrix). Since for EGM2008 only 503 the variances are available, the variance-covariance matrix $\Sigma(x_{EGM})^{-1}$ has a diagonal structure. 504 The weight for the satellite-only system is $w_1 = 1$, expressing the fact that we consider the formal 505 errors of this combined model as correctly scaled, and the weight of EGM2008 has been 506 assigned empirically with $w_2 = 0.16$, and the EGM2008 formal errors have been down-scaled by 507 a factor of 1 increasing linearly to 10 in range of degrees 180 to 200. In this way, the 508 combination is tuned giving GRACE/GOCE data dominant influence in the degrees 0 to 180 and 509 510 forcing EGM2008 information to take over in the spectral range 200 to 2190, leaving the main spectral range of transition from GRACE/GOCE to EGM2008, where both components 511 contribute significantly, between degrees 180 to 200. Figure 2 shows the relative contributions of 512 GOCE/GRACE data (red for more than 80% GOCE/GRACE impact) and indirectly the 513 EGM2008 model contribution (blue for more than 80% EGM2008 impact) per spherical 514 harmonic coefficient C_{nm} / S_{nm} in the combination (for degrees 0 to 250). 515



Relative Contribution of GRACE/GOCE to solution [%]



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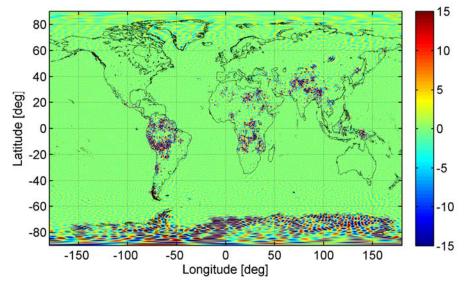
Figure 2. Relative contribution of GOCE/GRACE data per spherical harmonic coefficient C_{nm} / S_{nm} in the combination with EGM2008 data (in percent) for the degrees 0 to 250

From Fig. 2, the transition for certain harmonic orders (say -20 < m < +20) is differently than the other orders (say m < -20, m > +20). This is related to the lower accuarcy for the determination of the near-zonal spherical harmonic coefficients using GOCE gradiometry (known as the polar gap problem due to the GOCE satellite's orbit inclination of 96.6 degrees). he lack of observations in the polar regions worsens the accuracy in the determination of a certain group of spherical harmonic coefficients, which is the near-zonal group (e.g., Sneeuw and Gelderen, 1997). Consequently in the combined solution EGM2008 has a higher influence in for those coefficients where GOCE shows a lower performance (and thus a higher standard deviation).

529

The outcome of this processing step is a combined GRACE/GOCE/EGM2008 coefficient data set here denoted as GGE. Figure 3 shows the differences between gravity disturbances from GGE and EGM2008, revealing significant discrepancies at the 10-20 mGal-level over Africa, Asia and South America, while there is agreement in the mGal range over most parts of Europe, Australia and North-America. The larger discrepancies are interpreted as improvements over EGM2008 conferred by recent GRACE and GOCE data to GGMplus, see also *Pail et al.*, [2011] and *Hirt et al.*, [2012].

537



538

Figure 3. Gravity disturbance differences between the GRACE/GOCE/EGM2008 merger GGE
 and EGM2008-only in the spectral band of degrees 2 to 250, units in mGal

541542 *3.3 Synthesis*

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The spherical-harmonic coefficients (SHCs) of the combined GGE model were used in the spectral band of degrees 2 to 2190 to synthesize gravity field functionals at the Earth's surface, as represented through the 3D-coordinates (latitude, longitude, height). Accurate evaluation of the SHCs requires taking into account the ellipsoidal height of the evaluation points which were obtained from SRTM at 7.2 arc-second resolution. The zonal harmonics of the GRS80 normal gravity field were subtracted from the GGE-model SHCs as described in *Smith* [1998]. The tide system used in the synthesis is zero-tide, which is compatible with GRS80 [*Moritz*, 2000].

551

Spherical harmonic synthesis of gravity field functionals at the Earth's surface – known as 3D
 synthesis – is computationally extraordinarily demanding, because efficient SHS operations

cannot be used [Holmes, 2003]. Therefore we used the gradient approach to higher order [Hirt, 554 2012] which offers an efficient yet accurate approximate solution for 3D synthesis at densely-555 spaced surface points, represented through the elevation model. We used a modification of the 556 harmonic_synth software [Holmes and Pavlis, 2008] to synthesize quasigeoid heights, gravity 557 disturbances, North-South and East-West deflections of the vertical at a reference height of 4 km 558 559 above the GRS80 reference ellipsoid at 1 arc-min resolution. For all four functionals radial derivatives were computed up to 5th-order at the same reference height and resolution. These 560 were bicubically interpolated to 7.2 arc-second resolution and continued from the reference 561 height to the Earth's surface with 5th-order Taylor series expansions (cf. generic formulations 562 provided in *Hirt* [2012]), yielding numerical estimates of gravity functionals at 3 billion surface 563 points in the spectral band of degrees 2 to 2190. 564

565

Using the gradient approach as described, the 3D synthesis of the four gravity field functionals took about 6 weeks of computation time using an in-house Sun Ultra 45 workstation. By comparison, 3D synthesis with conventional point-by-point evaluation methods [*Holmes*, 2003] would have taken an estimated 60 years of computation time. This estimate is based on an observed performance of 100 points/ minute using the same workstation and parameters. The 3D synthesis as applied here is therefore one of the key innovations that made the construction of GGMplus feasible within acceptable computation times.

573

We note that the gradient approach is an approximate technique for 3D-SHS, whereby 574 approximation errors decrease with increasing order of the Taylor series applied. From analysis 575 of the 0th to 5th-order contributions over 3 billion points, the contribution made by subsequent 576 orders (e.g., 0th and 1st, 1st and 2nd) differs by a factor of about 4 to 5 (see also Table 2). Given 577 maximum contributions of 2 mm. 0.6 mGal and 0.1 arc-sec for the 5th-order, maximum 578 approximation errors (due to truncation of the Taylor series after the 5th-order) will be generally 579 smaller than 0.6 mm, 0.2 mGal and 0.03 arc-sec anywhere in our working area. Hence, the 580 581 Taylor series as applied for GGMplus converge sufficiently, and approximation errors are 582 negligible for practical applications.

583

Table 2. RMS (root-mean-square) and maximum values of the 4th-order and 5th-order terms of the Taylor expansions used for gravity field continuation to the Earth's surface. Also given are the estimated RMS and maximum approximation errors. Values reported for the functionals quasigeoid, gravity disturbances and deflections of the vertical.

Functional	Contribution of		Contribu	Contribution of		Estimated	
	4 th –orde	4 th –order term 5 th –order term approxima		nation error			
	RMS	Max	RMS	Max	RMS	Max	
Quasigeoid [mm]	0.24	9.88	0.05	2.07	0.01	0.52	
Gravity [mGal]	0.06	2.54	0.01	0.59	0.00	0.15	
NS deflection of the vertical [arc-sec]	0.01	0.31	0.00	0.08	0.00	0.02	
EW deflection of the vertical [arc-sec]	0.01	0.34	0.00	0.08	0.00	0.02	

⁵⁸⁸

589 For quasigeoid heights, the C1B correction term [*Rapp*, 1997], see also [*Hirt*, 2012], was applied

590 to take into account the change in normal gravity with height. For gravity disturbances, the

ellipsoidal correction was applied [*Claessens*, 2006]. For the North-South deflection of the
vertical, corrections for the curvature of the plumbline and for the ellipsoidal effect were taken
into account as described in [*Jekeli*, 1999].

594 595

597

596 *3.4. Forward-modelling*

598 Gravity forward-modelling based on high-resolution topography is a frequently-used technique to derive information on the short-scale gravity field in approximation [Forsberg, 1984; Pavlis et 599 al., 2007; Hirt, 2012]. The short-scale (i.e., 10 km to ~250 m) gravity signals of the GGMplus 600 model are based on forward-modelling using the 7.5 arc-sec resolution (~250m) SRTM V4.1 601 topography [Jarvis et al., 2008] over land and the 30 arc-sec resolution SRTM30 PLUS V7.0 602 603 bathymetry [Becker et al., 2009] over sea. A small number of bad data areas (about 0.002% of the total area covered by GGMplus as shown in Fig. 1) was identified and removed from both 604 605 data sets through simple hole-filling.

606

The forward-modelling approach applied here follows the description given in *Hirt* [2013]. In brief, we converted the SRTM30_plus bathymetry to rock-equivalent depths before merging with the 250m SRTM V4.1 topography. The merger was high-pass filtered by subtracting heights from the RET2012 rock-equivalent topography model to degree and order 2160 (publicly available from <u>http://geodesy.curtin.edu.au/research/models/Earth2012/</u>, Earth2012.RET2012.SHCto2160.dat).

613

We applied brute-force numerical integration techniques [Forsberg, 1984] to convert the high-614 pass filtered topography (and rock-equivalent depths over sea) to topography-implied gravity, 615 geoid and vertical deflections. The forward-modelled gravity signals possess spectral energy at 616 spatial scales of ~10 km to ~250 m which augments GGE gravity information beyond 10 km 617 618 resolution. The numerical integration was accomplished with a variant of the TC software [Forsberg, 1984] and an integration cap radius of 200 km around any of the ~3 billion 619 computation points, and the correction for Earth's curvature applied, as described in *Forsberg* 620 [1984]. Given the oscillating nature of the high-pass filtered topography, the effect of remote 621 622 masses largely cancels out as pointed out by Forsberg and Tscherning [1981]. The integration radius chosen is suitable for forward-modelling of high-frequency gravity effects [Hirt et al., 623 2010; Hirt, 2012]. 624

625

The forward-modelling exercise was partitioned into ~19,000 computationally 'manageable' 626 areas of 1 deg x 1 deg extension covering land areas everywhere on Earth between $\pm 60^{\circ}$ -latitude 627 with SRTM data available. Each 1 deg x 1 deg tile is composed of 625,000 computation points at 628 utilized the iVEC/Epic 629 7.2 arc-seconds resolution. We supercomputing facility 630 (http://www.ivec.org/) along with massive parallelization (simultaneous use of up to 1100 central processing units (CPUs)) to accomplish the forward-modelling for the first time near-globally. 631 632 Based on non-parallelized standard computation techniques and a single CPU, the calculation of topographic gravity effects had taken an estimated 20 years, which is why all previous efforts 633 were inevitably restricted to regional areas. 634

The topographic gravity effects calculations are based on the assumptions of constant mass-636 density (standard rock density 2670 kg/m³) and isostatically uncompensated topography, which 637 should well be justified given the spatial scales (less than 10 km) modelled here from 638 topographic information (e.g., Torge, [2001]; Watts, [2001]; Wieczorek, [2007]). Given that any 639 gravity field signals originating from mass-density variations [with respect to standard rock 640 641 density] are not represented by the topographic gravity, our GGMplus gravity maps cannot provide geological information at scales less than 10 km. However, the same limitations apply to 642 EGM2008 at spatial scales less than ~27 km over many developing countries [Pavlis et al., 643 2012] and to any other gravity field model with topographic information used to increase the 644 resolution among observed gravity. 645

646

Due to the chosen constant mass-density - often used as standard mass-density for gravity 647 reductions in geophysics and geodesy - the chosen value should approximates well the 648 topographically-induced gravitational attraction over granite rock (2700 kg m⁻³), while the 649 approximation may introduce errors up to 7% over areas of volcanic rock (2900 kg m⁻³), and 650 about ~26 % where sediments prevail (2000 kg m⁻³). While inclusion of detailed mass-density 651 maps in the forward-modelling can reduce these errors, a detailed modelling of mass-density 652 variations was not attempted in this work because high-resolution density maps were not 653 654 available everywhere in our working area.

655

From comparisons with ground-truth data sets, a range of studies [e.g., Hirt et al., 2010; Hirt, 656 2012; Šprlák et al., 2012] demonstrate that short-scale topographic gravity effects are capable of 657 representing a significant portion (in some cases as high as 90 %) of real gravity field features 658 over rugged terrain, see also evaluation results in Section 5. 659

660

3.5 Calculation of normal gravity at the Earth's surface 661

662 663 For the construction of gravity acceleration maps, normal gravity (i.e., the gravitational attraction and centrifugal acceleration generated by an oblate equipotential ellipsoid of revolution) was 664 calculated at the Earth's surface. We used the parameters of the GRS80 reference ellipsoid 665 [Moritz, 2000] along with the standard second-order Taylor expansion (Torge [2001], p 110, Eq. 666 4.63) to calculate normal gravity at the ellipsoidal heights of the Earth's surface, as represented 667 through the SRTM topography at 7.2 arc-sec spatial resolution. Beside the gravitational 668 attraction and centrifugal acceleration of the GRS80 mass-ellipsoid, the resulting normal gravity 669 values also contain the effect of gravity attenuation with height (free-air effect), because we 670 evaluated at the Earth's surface. 671

- 673
- 674

672

3.6 Combination of synthesis results, forward-modelling and normal gravity

All GGMplus gravity field functionals (quasigeoid heights, gravity disturbances, vertical 675 deflections) are the sum of 676

- 677 • Synthesized functionals from the GGE SHCs (providing the spatial scales of ~10000 km down to ~ 10 km, Sect. 3.3) and 678
- Forward-modelled functionals from high-pass filtered topography/bathymetry data 679 • 680 (providing the spatial scales from ~ 10 km down to ~ 250 m, Sect. 3.4).

681 GGMplus gravity accelerations were obtained as the sum of GGMplus gravity disturbances and 682 normal gravity values (Sect 3.5).

683

684 4 Gravity estimation outside working area

684 685

686 Due to Earth's flattening, obvious candidate locations for Earth's maximum gravity acceleration 687 are expected near the poles, which is outside the $\pm 60^{\circ}$ -SRTM latitude band. To include a likely 688 location for Earth's maximum gravity acceleration in our work, we obtained gravity 689 accelerations globally at 5-arc-min resolution without short-scale topographic gravity estimates, 690 as follows:

- We constructed a 5-arcmin grid of approximate ellipsoidal heights of the Earth's surface
 as the sum of elevations from the Earth2012 Topo/Air model (representing Earth's physical surface as lower interface of the atmosphere above mean sea level) and the EGM2008 quasigeoid applied as a correction.
- We applied the gradient approach for harmonic synthesis (Sect. 3.3) to fifth-order,
 yielding gravity disturbances at the Earth's surface in spectral band 2 to 2190 using the
 GGE coefficients (Sect 3.1).
- We calculated normal gravity at the ellipsoidal heights of the Earth's surface as described
 in Sect 3.5) and added the gravity disturbances, yielding gravity accelerations at 5 arc min resolutions.

701 Steps 1 and 2 were applied to calculate a global 5 x 5 arc-min grid of quasigeoid heights which 702 was then used to locate where the quasigeoid is likely to be furthest below the ellipsoid. The 703 locations of the minimum and maximum gravity accelerations and quasigeoid heights are 704 reported in Tables S3 and S4.

705

706 Table 3. Extreme values of gravity accelerations estimated based on 5 arc-min reso	ution
--	-------

Extreme value	Latitude	Longitude	Value [mGal]	Comment
Minimum gravity acceleration	-9.88	-77.21	976790	GGMplus suggests a smaller value at a nearby location.
Maximum gravity acceleration	86.71	61.29	983366	Located offshore in the Arctic sea, not covered by GGMplus. Location and value reported in Table 1 in the main paper.

707 708

Table 4. Extreme values of quasigeoid heights estimated based on 5 arc-min resolution

Extreme value	Latitude	Longitude	Value [m]	Comment
Minimum	4.71	78.79	-106.59	Located offshore (Laccadive Sea
quasigeoid				South of Sri Lanka), not covered
height				by GGMplus. Location and value
				reported in Table 1 in the main
				paper.
Maximum	-4.21	138.71	86.48	GGMplus suggests a larger value
quasigeoid				at another location.
height				

710 **5. Model evaluation**

711

We have evaluated GGMplus gravity field functionals using (i) gravity accelerations from terrestrial gravimetry, (ii) deflections of the vertical from geodetic-astronomical observations, and (iii) observed quasigeoid heights from GPS ellipsoidal heights and geodetic levelling (GPS/levelling). The data sets used are summarized in Table 5. Each set of observations is compared against the three modelling variants

- 717
- 718 719
- satellite-only gravity (GRACE combined with 4th-GOCE release) to degree and order 200 (resolution of ~100 km)
- satellite gravity combined with EGM2008 (GGE), to degree 2190 (resolution of ~10 km)
- GGMplus (resolution of ~200 m)
- 721 722

720

The descriptive statistics of the differences "observation minus model" are reported in Tables 6 723 and 7 for gravity disturbances, in Table 8 for deflections of the vertical and in Table 9 for 724 725 quasigeoid heights. From the comparisons over North America, Europe and Australia - areas with good ground gravity coverage - the accuracy of GGMplus is at the 3-5 mGal, 1 arc-sec and 726 727 5-7 cm level or somewhat better for gravity, deflections of the vertical and quasigeoid heights, respectively. The RMS-improvements conferred by the short-scale gravity modelling (compare 728 GGMplus with GGE) range between ~20 to ~90 % for the radial (gravity) and horizontal field 729 components (deflections of the vertical), and is lower (non-significant to ~40% over Switzerland 730 as an example of a mountainous region) for quasigeoid heights. Fig. 4 exemplifies the good 731 732 agreement between observed gravity and GGMplus over Australia. The differences mostly reflect the effect of local mass-density variations, and can be used for geophysical interpretation. 733 Fig. 4 also shows oscillations of 1-2 mGal amplitude and ~200 km full-wavelength which are 734 735 likely to reflect the error level of GOCE satellite observations used in GGMplus.

736

737 Over less well-surveyed areas, the differences increase to ~8 to ~23 mGal, as is indicated by the few ground gravity observations available. Given that the forward-modelling of gravity effects at 738 spatial scales of ~10 km to 200 m is based on a homogeneous procedure everywhere between \pm 739 60° geographic latitude, there is no reason to assume a reduced performance over Asia, Africa 740 and South America. The deterioration rather reflects the limited data availability for EGM2008 at 741 spatial scales of ~100 to 10 km. The accuracy of GGMplus gravity field functionals is therefore 742 743 largely dependent on the EGM2008 model commission errors, which can be as high as ~30-35 cm for quasigeoid heights, and ~4 arc-seconds for deflections of the vertical [Pavlis et al., 2012]. 744 745 We therefore expect the GGMplus accuracy to deteriorate by factor 3-5 from well-surveyed to poorly-surveyed continents. 746

748

Observation type	Country/ Area	# Stations	Data source/provider
Gravity accelerations and disturbances	United States	1,277,637	University of Texas at el Paso http://research.utep.edu/default.aspx?tabi d=37229 2012 release
from terrestrial	Australia	1,625,018	Geoscience Australia

gravimetry				-	w.geoscien	ice.gov.au	
				2013 rele			
	Switzer		31,598		o, Dr U Ma		
	Central	Africa	41,148		-	ue Internatio	onal,
				Dr S Bor	ivalot		
	India/H	limalayas	7,562	Bureau C	Gravimétriq	ue Internatio	onal,
				Dr S Bor	nvalot		
	Norther	m	12,150	Bureau C	Gravimétriq	ue Internatio	onal,
	South-A	America		Dr S Bor	nvalot		
Deflections of	United	States	3,396	National	Geodetic S	urvey,	
the vertical				Drs D Sr	nith and Y	Wang	
from geodetic-	Austral	Australia		Geoscien	ce Australi	a/	
astronomical				Dr W Fe	atherstone (Curtin Univ	ersity)
observations	Europe		1,056	ETZ Zur	ich, Dr B B	ürki; Swisst	opo, Dr
	_	1		U Marti;	first author	's own obse	rvations
GPS/levelling/	United	States	18972	National	Geodetic S	urvey,	
quasigeoid				http://ww	w.ngs.noaa		ataExpl
heights				orer/		•	
0	German	ny	675	Bundesa	mt für	Kartograph	ie und
		2		Geodäsie	e, U Schirm		
	Switzer	·land	193	Swisstop	o, Dr U Ma	rti	
Table 6. Descri Terrestrial d	•	stics of the differe Model	ences obs Mi	-	vity minus r Max	nodels, units Mean	s in mGal RMS
US gravity		Satellite-only	-	238.85	204.19	6.83	27.41
		GGE	-	271.88	110.10	-2.70	10.80
		GGMplus	-	303.39	88.84	-0.68	3.49
Australian g	ravity	Satellite-only	-	179.98	118.24	-1.14	14.88
		GGE	-	194.33	82.65	-1.07	5.03
		GGMplus		193.15	81.06	-0.71	2.90
Swiss gravit	у	Satellite-only	-	235.04	131.13	-35.49	67.21
		GGE	-	226.64	93.38	-17.59	39.72
		GGMplus		-91.23	28.71	-0.60	4.41
Table 7. Descri	ptive stati	stics of the differe	ences obs	served grav	vity minus r	nodels, units	s in mGal
Terrestrial d	ata	Model		Min	Max	Mean	RMS
Central Afri	ca	Satellite-only		228.79	394.56	- 1.33	26.91
		GGE		-275.02	403.27	-0.15	9.68
		GGMplus		-284.41	399.87	0.37	8.24
India+ Hima	layas	Satellite-only		-329.51	365.47	-5.23	43.53
	•	GGE		-184.46	341.92	0.04	21.84
		GGMplus		-182.44	309.74	2.45	13.76
Northern So	uth-	Satellite-only		-247.71	365.75	-11.66	66.52
America		GGE		-224.32	361.48	-4.60	26.18
		CCMplue		224 27	264.00	0.02	22 60

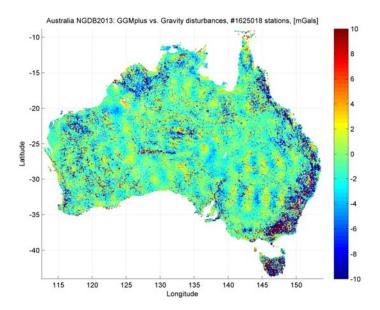
GGMplus

364.00

-234.27

22.69

-0.03



756 Figure 4. Differences between observed gravity accelerations and GGMplus over Australia, units

in mGal.

Table 8. Descriptive statistics of the differences observed deflection of the vertical (DoV) minus models, units in arc-seconds

Terrestrial data	Model	Min	Max	Mean	RMS
US North-South DoVs	Satellite-only	-19.59	22.62	0.20	3.27
	GGE	-12.55	21.29	0.09	1.11
	GGMplus	-12.58	20.97	-0.02	0.84
US East-West DoVs	Satellite-only	-22.66	23.41	0.29	3.78
	GGE	-13.57	12.38	0.10	1.14
	GGMplus	-6.19	9.90	0.12	0.78
Australian North-South DoVs	Satellite-only	-11.58	11.76	-0.14	2.21
	GGE	-5.00	3.44	-0.23	0.81
	GGMplus	-5.13	2.61	-0.19	0.66
Australian East-West DoVs	Satellite-only	-18.01	11.68	-0.14	2.63
	GGE	-4.87	3.60	-0.11	1.04
	GGMplus	-5.05	4.05	-0.13	0.97
Europe North-South DoVs	Satellite-only	-19.49	26.96	0.88	6.41
	GGE	-15.06	15.62	0.05	3.02
	GGMplus	-4.86	5.51	-0.05	1.06
Europe East-West DoVs	Satellite-only	-24.05	24.97	0.90	5.87
	GGE	-11.58	15.65	0.38	2.98
	GGMplus	-4.29	4.99	0.23	1.09

Table 9. Descriptive statistics of the differences observed quasigeoid height minus models, units
in m. In case of US GPS/levelling data, observed geoid heights were converted to quasigeoid
heights applying Rapp's (1997) formalism [1] prior to comparison with the three modelling
variants, A bias (Germany, Switzerland), and tilted plane (US) were subtracted.

Terrestrial data	Model	Min	Max	RMS
US GPS/lev	Satellite-only	1.80	2.72	0.367
	GGE	-0.34	0.42	0.070
	GGMplus	-0.36	0.43	0.070
German GPS/lev	Satellite-only	-1.07	1.42	0.315
	GGE	-0.11	0.17	0.042
	GGMplus	-0.10	0.14	0.041
Swiss GPS/lev	Satellite-only	-1.27	1.86	0.605
	GGE	-0.24	0.18	0.076
	GGMplus	-0.17	0.13	0.046

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