

# A cache-aware performance prediction framework for GPGPU computations

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Alexander Pöpli, Alexander Herz

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- Quantitative Evaluation

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# Introduction

## Motivation

- OpenCL is used for running heterogeneous HPC applications
- It is low level, fairly explicit, and has manual task management

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<sup>1</sup> Cédric Augonnet et al. "StarPU: A Unified Platform for Task Scheduling on Heterogeneous Multicore Architectures". English. In: **Euro-Par 2009 Parallel Processing**. Ed. by Henk Sips, Dick Epema, and Hai-Xiang Lin. Vol. 5704. Lecture Notes in Computer Science. Springer Berlin Heidelberg, 2009, pp. 863–874. ISBN: 978-3-642-03868-6. DOI: 10.1007/978-3-642-03869-3\_80. URL: [http://dx.doi.org/10.1007/978-3-642-03869-3\\_80](http://dx.doi.org/10.1007/978-3-642-03869-3_80).

<sup>2</sup> Gregory F. Diamos and Sudhakar Yalamanchili. "Harmony: An Execution Model and Runtime for Heterogeneous Many Core Systems". In: **Proceedings of the 17th International Symposium on High Performance Distributed Computing**. HPDC '08. Boston, MA, USA: ACM, 2008, pp. 197–200. ISBN: 978-1-59593-997-5. DOI: 10.1145/1383422.1383447. URL: <http://doi.acm.org/10.1145/1383422.1383447>.

# Introduction

## Motivation

- OpenCL is used for running heterogeneous HPC applications
- It is low level, fairly explicit, and has manual task management
- Hence runtime systems with schedulers, such as StarPU<sup>1</sup> or Harmony<sup>2</sup> have been developed
- These schedule tasks onto heterogeneous hardware based on expected runtime.
- High-quality estimations crucial for efficient schedules.

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<sup>1</sup> Cédric Augonnet et al. "StarPU: A Unified Platform for Task Scheduling on Heterogeneous Multicore Architectures". English. In: **Euro-Par 2009 Parallel Processing**. Ed. by Henk Sips, Dick Epema, and Hai-Xiang Lin. Vol. 5704. Lecture Notes in Computer Science. Springer Berlin Heidelberg, 2009, pp. 863–874. ISBN: 978-3-642-03868-6. DOI: 10.1007/978-3-642-03869-3\_80. URL: [http://dx.doi.org/10.1007/978-3-642-03869-3\\_80](http://dx.doi.org/10.1007/978-3-642-03869-3_80).

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# Introduction

## Motivation

- Performance Prediction models already exist, and work well with earlier GPU architectures.
- Introduction of Caches complicate predictions.
- GPU memory Hierarchy needs to be considered.

# Introduction

## Contributions

- Categorization of memory accesses into classes with distinct performance characteristics.
- Fully static OpenCL computation prediction model.
- Evaluation using randomly generated OpenCL kernels shows that a cache-aware model improves predictions.

# Introduction

## Example

- Popular operation: **Stencil operations**
- Array of size:  $n * m$

$$b(i, j) = a(i, j)^2 - a(1, j)$$

# Introduction

## Example

- 1:  $n_{WI} = m * n$
- 2:  $mem_{GPU}^{input} \leftarrow device.alloc(n_{WI} * s_{WI})$
- 3:  $mem_{GPU}^{output} \leftarrow device.alloc(n_{WI} * s_{WI})$
- 4:  $copyDataToGPU(\rightarrow mem_{GPU}^{input})$
- 5:  $device.kernel(n_{WI}, n_{WG}, m, n)$   
 $\Rightarrow \forall id \in \{0, \dots, n_{WI}\}. sq\_mod(mem_{GPU}^{input}, mem_{GPU}^{output}, m, n)$
- 6:  $copyDataFromGPU(\rightarrow mem_{GPU}^{output})$

# Introduction

## Example

```
kernel void sq_mod(global float * matrix,
                    global float * res,
                    unsigned int m, unsigned int n) {
    size_t current_pos = get_global_id(0);
    unsigned int current_row = current_pos / n;
    unsigned int current_col = current_pos % n;
    res[current_pos] = matrix[current_row * n
                                + current_col]
                        * matrix[current_row * n + current_col]
                        - matrix[current_col];
}
```

# Model

## Execution Time Computation — Computation of the Runtime

$$t(n_{WI}, s_{WI}, n_{WG}) = t_{Transfer}(n_{WI}, s_{WI}) + t_{Kernel}(n_{WI}, n_{WG})$$

$$t_{Kernel}(n_{WI}, n_{WG}) = \frac{t_{Base}(n_{WI}) + \sum_{Op \in \text{Expr.-Types}} W_{Op}(n_{Op}) t_{Op}(n_{WI})}{U(n_{WG}, n_{XU})}$$

$n_{WI}$  Number of work-items

$n_{WG}$  Number of work-items per work-group

$s_{WI}$  Size of a work-item in bytes

$n_{XU}$  Number of execution units on the GPU

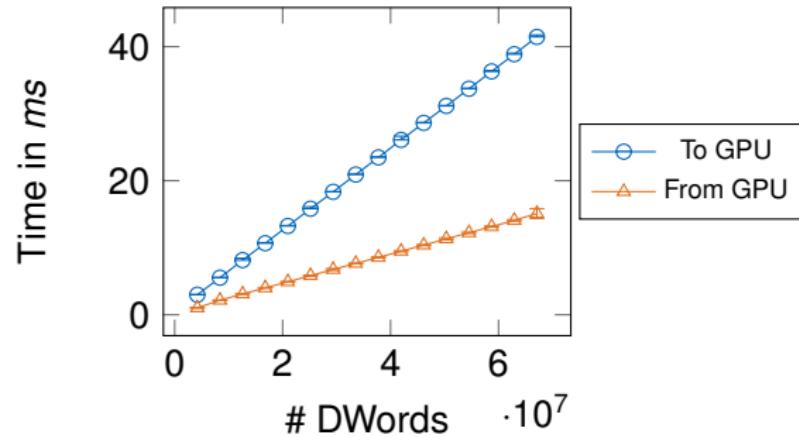
# Model

## Memory Transfer

- GPUs have a dedicated portion of memory for their computations
- Time for memory transfer governed by two variables
  - $bw$  Bandwidth
  - $l_{prop}$  Propagation latency

# Model

## Memory Transfer

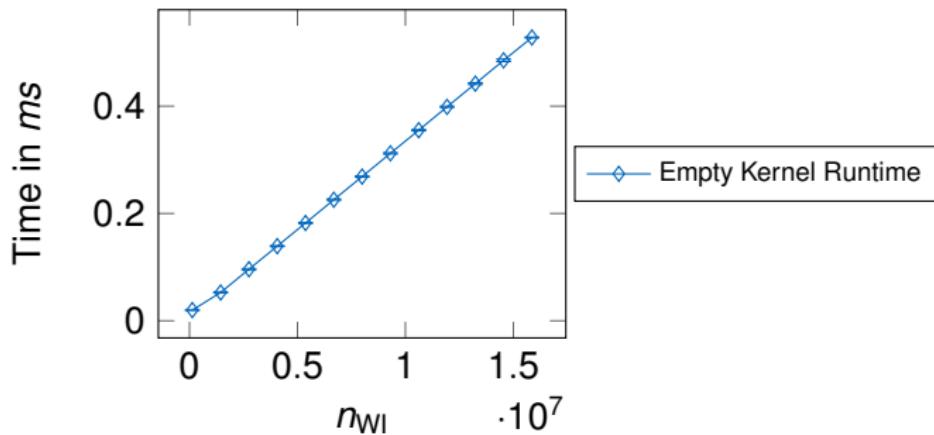


**Figure:** Memory Transfer times

- $t_{\text{trans}}^{\text{to}}(n_{\text{WI}}) = bw_{\text{to}}^{-1} n_{\text{WI}} + l_{\text{to}}$
- $t_{\text{trans}}^{\text{from}}(n_{\text{WI}}) = bw_{\text{from}}^{-1} n_{\text{WI}} + l_{\text{from}}$

# Model

## Empty Kernels

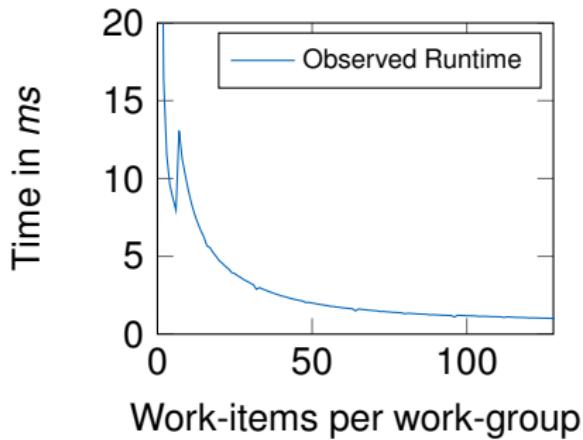


**Figure:** Execution times for empty kernels.

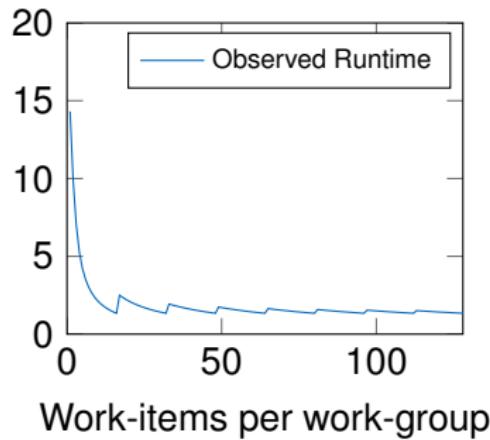
- $t_{\text{Base}}(n_{\text{WI}}) = c_{\text{Base}} n_{\text{WI}} + c_{\text{Base}}^{\text{fixed}}$

# Model

## Workgroup Size



(a) NVidia GT-650M



(b) Intel HD Graphics 4000

**Figure:** Execution time for different work-group sizes. The kernel we used to evaluate this behavior performs one read from and write to the global memory, and one floating point division.

# Model

## Workgroup Size — Modelling the behavior

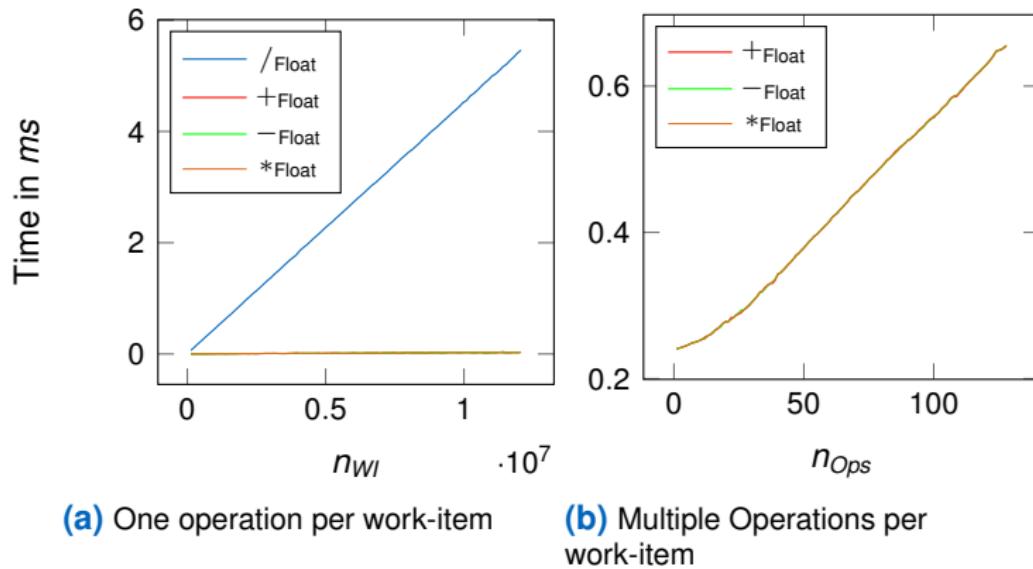
- Periodic spikes in execution time.
- Especially visible on the HD 4000.

## Influence of Work-Group size

$$U(n_{WG}, n_{XU}) = \underbrace{\left\lfloor \frac{n_{WG}}{n_{XU}} \right\rfloor}_{A} + \underbrace{\frac{n_{WG} \bmod n_{XU}}{n_{XU}} \left[ \frac{n_{WG}}{n_{XU}} \right] - \left\lfloor \frac{n_{WG}}{n_{XU}} \right\rfloor}_{B}$$

# Model

## Basic Operations



**Figure:** Progression of the execution time for basic operations.

# Model

## Basic Operations

$$W_{\text{op}}^{\text{type}}(n_{\text{Ops}}) = \begin{cases} a n_{\text{Ops}}^b + c & : n_{\text{Ops}} \leq n_{\text{Ops}}^{\text{sat}} \\ a' n_{\text{Ops}} + c' & : n_{\text{Ops}} > n_{\text{Ops}}^{\text{sat}} \end{cases}$$
$$t_{\text{op}}^{\text{type}}(n_{\text{WI}}) = c_{\text{op}}^{\text{type}} n_{\text{WI}}$$

- $a, a', b, c, c'$  are obtained by fitting  $W_{\text{op}}^{\text{type}}(n_{\text{Ops}})$  to 4b
- $c_{\text{op}}^{\text{type}}$  is obtained by fitting  $t_{\text{op}}^{\text{type}}(n_{\text{WI}})$  to 4a.

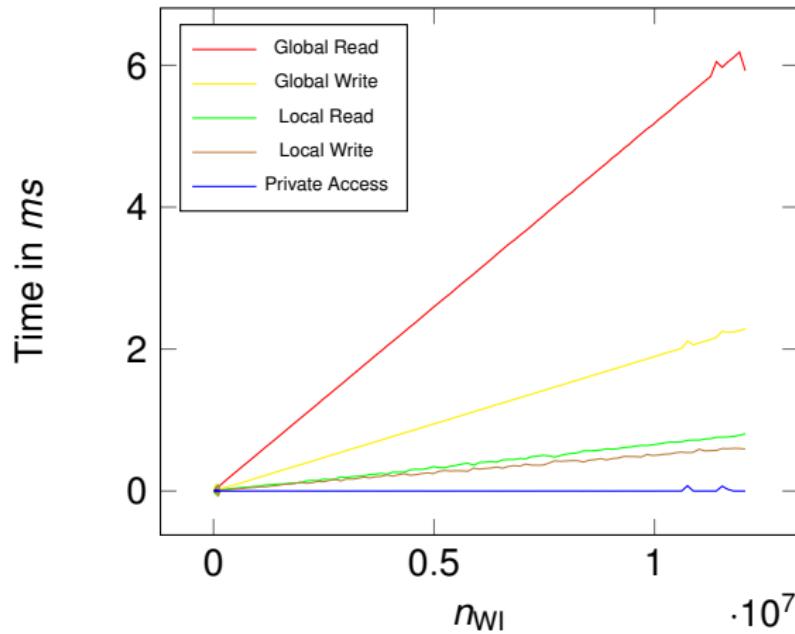
# Model

## Memory accesses

- In OpenCL, **3** different kinds of memory accesses are available
  - **private:** Used for local variables, parameters.
  - **local:** Shared between work-items within a work-group
  - **global:** Shared amongst all work-items
- Usually implemented using different kinds of memory.

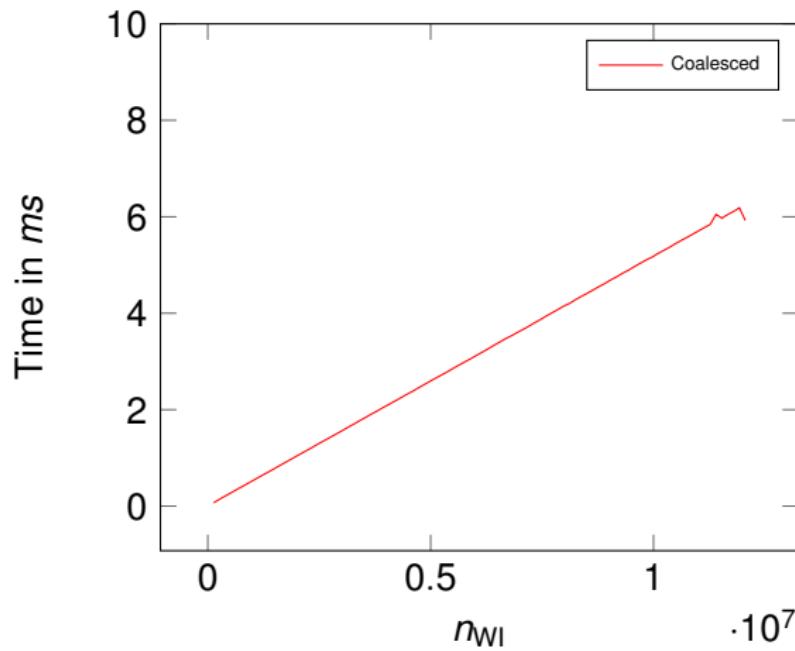
# Model

## Memory accesses



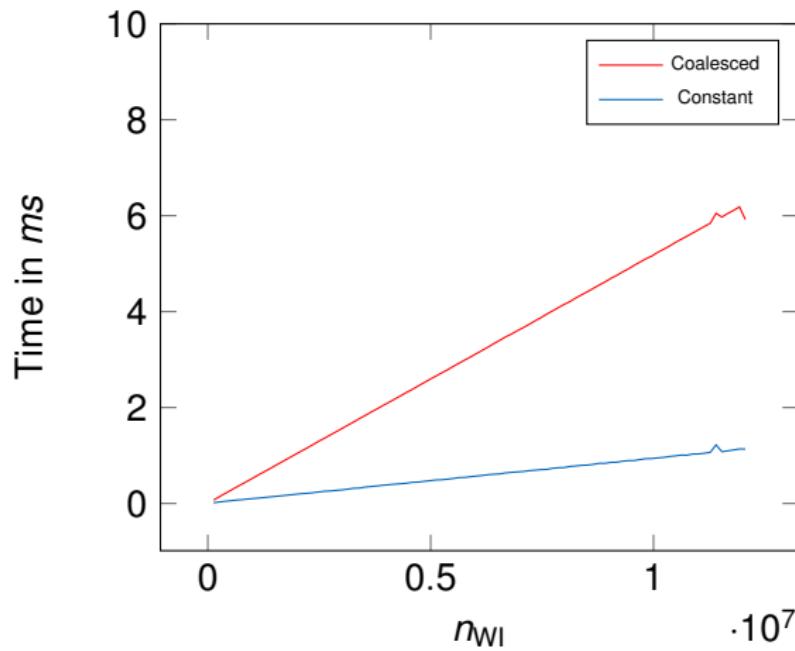
# Model

## Memory accesses — Coalesced Accesses



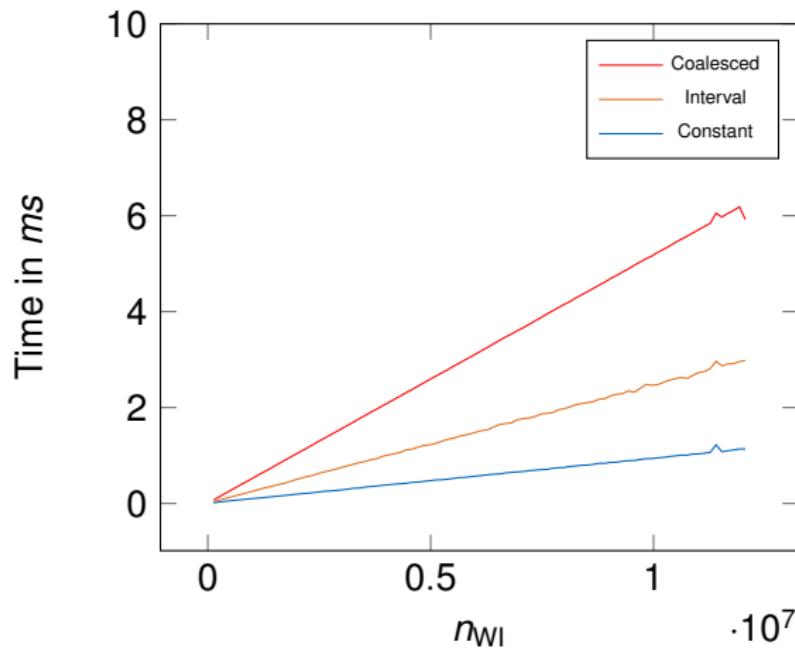
# Model

## Memory accesses — Constant Accesses



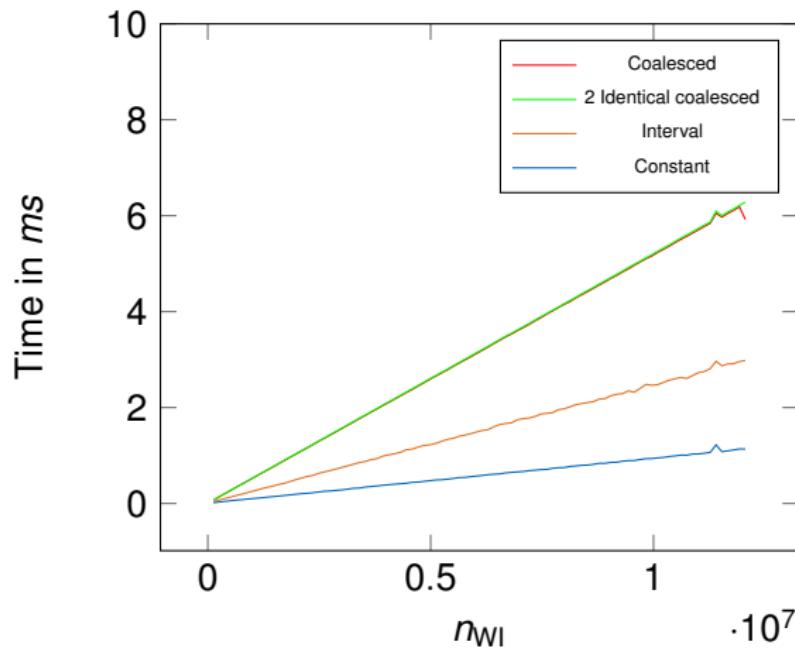
# Model

## Memory accesses — Interval Accesses



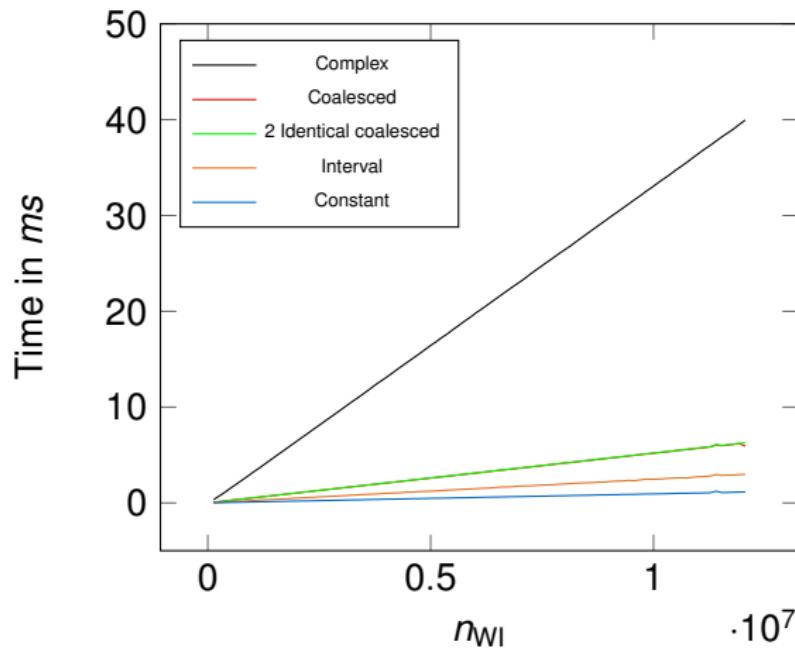
# Model

## Memory accesses — Two Identical Accesses



# Model

## Memory accesses — Complex Accesses



# Evaluation

## Qualitative Evaluation

- Static prediction of the execution time given the following data:
  - Kernel Source Code
  - Data about GPU characteristics
  - Number of work-items  $n_{WI}$

# Evaluation

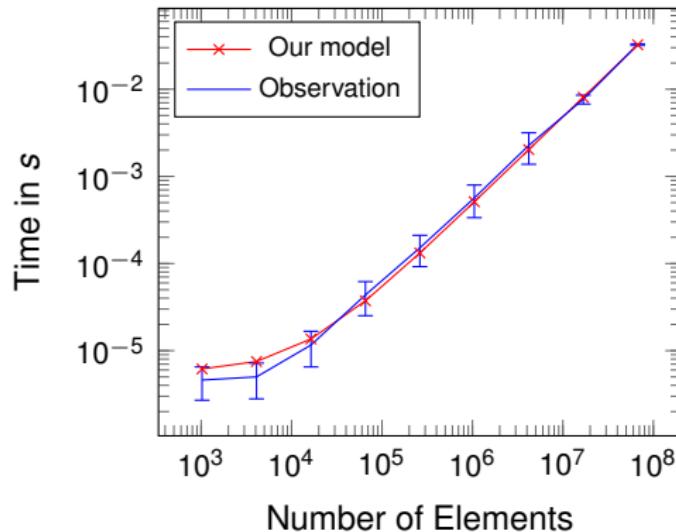
## Qualitative Evaluation

- Static prediction of the execution time given the following data:
  - Kernel Source Code
  - Data about GPU characteristics
  - Number of work-items  $n_{WI}$

Cost Type	# in Kernel	Time in $\mu s$
-float	1	74.16
*float	1	74.54
+int	1	55.13
*int	7	81.04
/ int	4	1506
private access	1	0.0
interval global read access	1	770.9
continuous global read access	1	2335
base cost	1	3191
work-group size	1024	-
<b>final prediction</b>		<b>8089</b>

# Evaluation

## Qualitative Evaluation



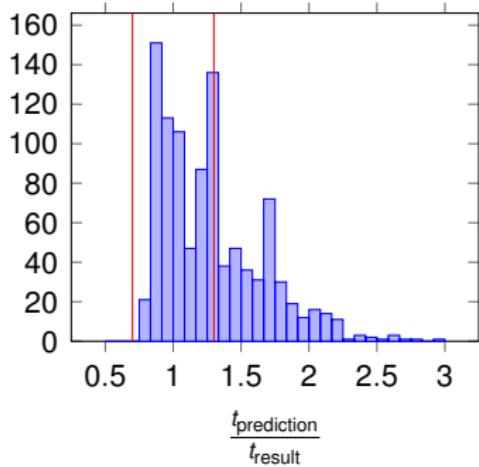
# Evaluation

## Quantitative Evaluation

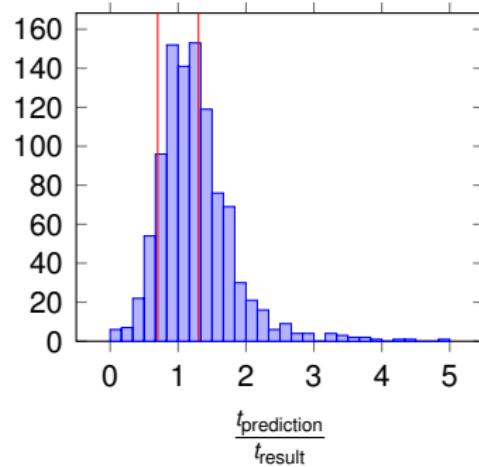
- Quantitative evaluation through generated OpenCL Kernels
- 2 Sets of kernels, **Unrestricted** and “**Realistic**”
- Unrestricted Set
  - Little restrictions on complexity
  - Complex memory access patterns possible
  - $((xxx[((y + x) + 454) \& 0x7F] / (matrix[x][y] * x)) - (matrix[x][y] + (matrix[x][y] + ((matrix[((44190 * (20 + x)) \% HEIGHT] [1094 \% WIDTH] - xxx[71632 \& 0x7F]) - ((162.82883f * (x - y)) + (785.19073f / (((((matrix[x][y] - matrix[x][y]) - xxx[(y * x) \& 0x7F]) + 77.578835f) + matrix[x][y])) + 550.7608f)))))) + xxx[x \& 0x7F]$
- Realistic Set
  - Complexity restricted, limited number of nodes in syntax tree
  - No overly complex memory access patterns
  - $((x / (xxx[x \& 0x7F] / (matrix[1 \% HEIGHT] [361 \% WIDTH] * matrix[x][y]))) * xxx[y \& 0x7F]) + 747.18744f$

# Evaluation

## Quantitative Evaluation — GT-650M



(a) Realistic Set

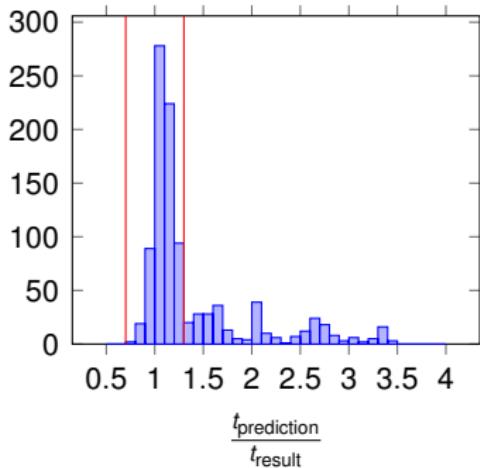


(b) Unrestricted Set

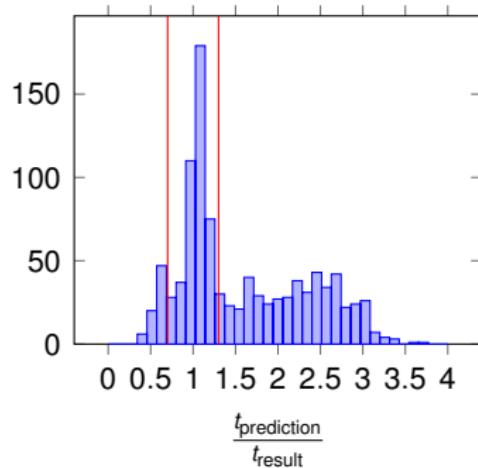
- $0.7 < \frac{t_{\text{prediction}}}{t_{\text{result}}} < 1.3$  for 63% of all samples for the restricted set.
- $0.7 < \frac{t_{\text{prediction}}}{t_{\text{result}}} < 1.3$  for 50% of all samples for the unrestricted set.

# Evaluation

## Quantitative Evaluation — Quadro K4000



(c) Realistic Set

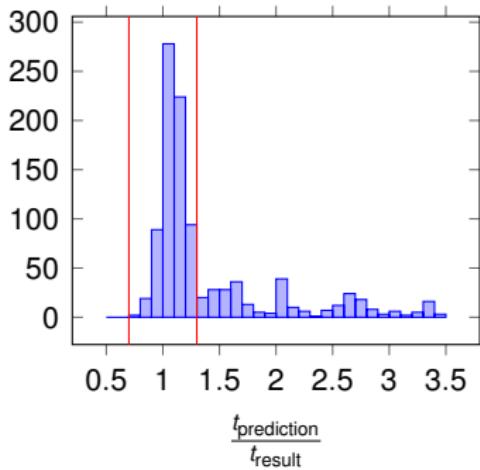


(d) Unrestricted Set

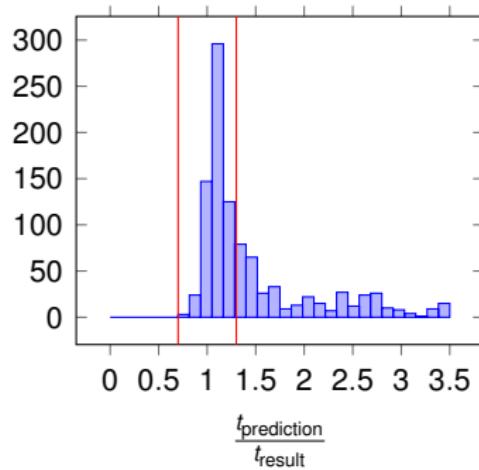
- $0.7 < \frac{t_{\text{prediction}}}{t_{\text{result}}} < 1.3$  for 71% of all samples for the restricted set.
- $0.7 < \frac{t_{\text{prediction}}}{t_{\text{result}}} < 1.3$  for 43% of all samples for the unrestricted set.

# Evaluation

## Quantitative Evaluation — Comparison



(e) Cache-Aware Model



(f) Simple Model

- $0.7 < \frac{t_{\text{prediction}}}{t_{\text{result}}} < 1.3$  for 71% of all samples for our model.
- $0.7 < \frac{t_{\text{prediction}}}{t_{\text{result}}} < 1.3$  for 61% of all samples for the simpler model.

# Further Work

- Improve predictions, expand onto more architectures
- Support more language constructs, e.g. `if` or `for`
- Support intrinsic operations, e.g. `sin()`, `sqrt()`

# Thank you for your attention

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